

# Deep Neural Network-Based Canopy Image Classification

Research and Development Project



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## Problem Statement for this project



In this work, the aim was to develop a deep neural network based canopy image classification framework for identifying different diseases and nutrient deficiencies in maize crop and also to identify and explore different optimizations to synergistically use the available compute hardware in the edge devices such that faster and reliable real time image inferencing can be done in the edge device itself rather than sending it to the cloud or a remote server.

# Related Work

## 1. Classification of Macronutrient Deficiencies in Maize Plant Using Machine Learning

**Journal:** International Journal of Electrical and Computer Engineering (IJECE)

**Dataset:** Not available publicly. They used a set of only 100 images (75 for train & 25 for test)

### **Classification Classes:**

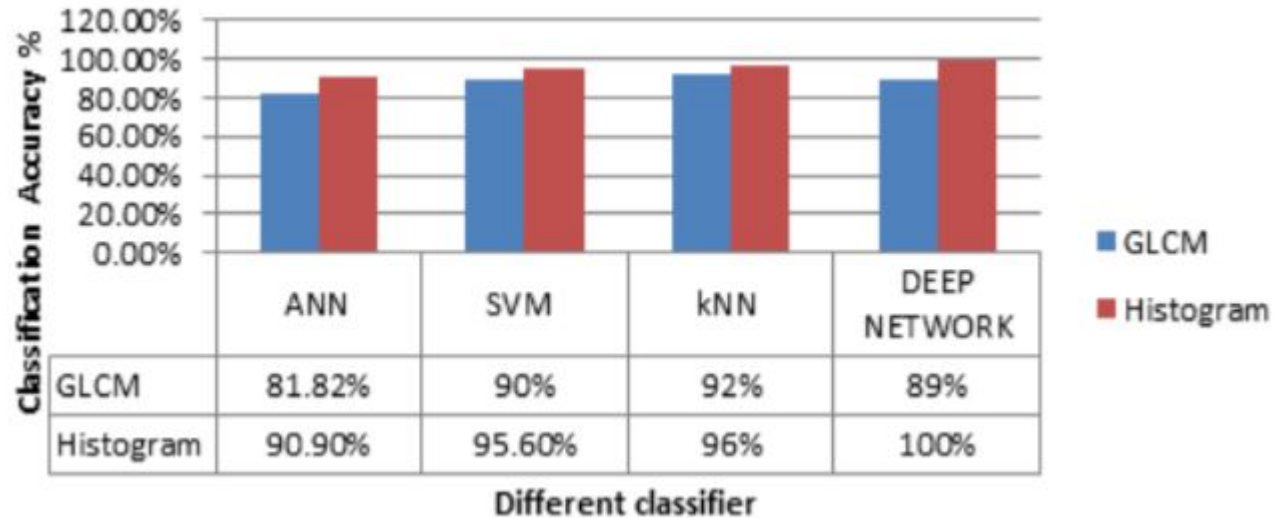
- a) Nitrogen Deficient
- b) Phosphorus Deficient
- c) Potassium Deficient
- d) Healthy


### **Methods Used:**

- a) ANN Classifier
  - b) SVM Classifier
  - c) kNN Classifier
  - d) Autoencoders
- (No DNN used)

**Handheld Device for validating:** No

## Result





## 2. Real-time detection of maize crop disease via a deep learning-based smartphone app

- Journal: SPIEDigitalLibrary.org/conference-proceedings-of-spie
- Dataset: Plant Village Dataset used for Healthy (1000 images) and Northern Leaf Blight (463 images).
- Classification Classes: Healthy leaf and Northern Leaf Blight
- Methods Used: Modified Deep CNN ResNet50 model (Input image size = 256x256x3)

Handheld Device for validating: Yes Android + iOS App.

Accuracy on Validation Dataset: 0.99



### 3. Corzea: Portable Maize (Zea Mays L.) Nutrient Deficiency Identifier

- **Journal and Issue Date:** INTERNATIONAL JOURNAL OF SCIENTIFIC & TECHNOLOGY RESEARCH VOLUME 9, ISSUE 02, FEBRUARY 2020
- **Dataset:** Training set - 5000 images, Test set - 200 images obtained from online resource [www.image-net.org](http://www.image-net.org) and from actual field (not publicly available)
- CNN Model
- **Classes:**
  - Phosphorus Deficient
  - Potassium Deficient
  - Nitrogen Deficient
  - Magnesium Deficient



Evaluation Metric:

$$Accuracy = \frac{(TN + TP)}{(TN + TP + FN + FP)} = \frac{NUMBER\ OF\ CORRECT\ ASSESSMENT}{NUMBER\ OF\ ALL\ ASSESSMENTS}$$

Result:

CLASSIFICATION RESULTS						
Nutrient Deficient	Corn Leaf Samples	TP	TN	FP	FN	Accuracy
Phosphorus	50	47	0	6	0	94%
Potassium	50	47	0	10	0	94%
Nitrogen	50	42	0	12	0	84%
Magnesium	50	47	0	11	0	94%





## 4. Identification of Maize Leaf Diseases Using Improved Deep Convolutional Neural Networks

**Dataset:** 500 images from Plant Village Dataset and Google (Using Data Augmentation, 3060 images created for training and testing)

**Classification Classes:**

- a) Southern leaf blight
- b) Brown spot
- c) Curvularia leaf spot
- d) Rust
- e) Dwarf mosaic
- f) Gray leaf spot
- g) Round spot
- h) Northern leaf blight
- i) Healthy

**Methods Used:** Modified Deep CNN GoogLeNet model (Input image size = 224x224x3)

**Handheld Device for validating:** No

**Accuracy on Validation Dataset:** 0.989



# Maize Deficiency Detection

## INTRODUCTION

- This is a binary classification with TensorFlow Model Garden Object Detection detecting any kind of nutrient deficiency in a maize plant leaf.

Visit: [<https://github.com/tensorflow/models>]

## DATASET USED

- Dataset provided by Prof. Gayathri. (Images clicked at UAS Dharwad)

360 (260 train and 100 test)

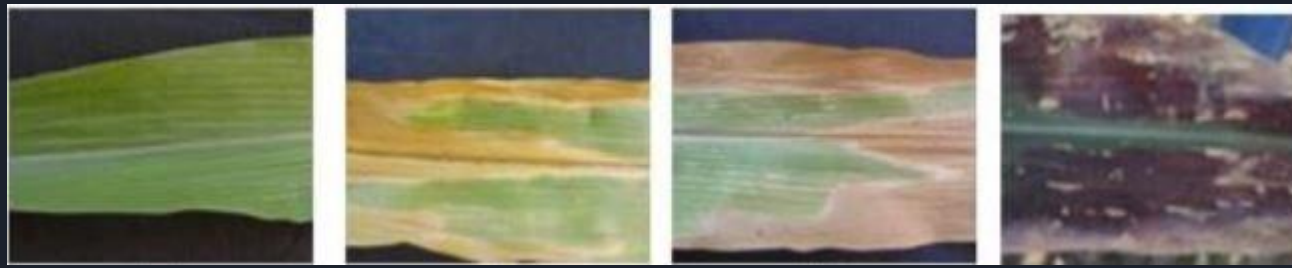


Fig: a.) Healthy, b.) Nitrogen Deficiency Leaf, c.) Phosphorous Deficiency ,d.) Potassium Deficiency

## LABELING IMAGES IN DATASET

- Images labeled using “labelImg” [Visit: <https://pypi.org/project/labelImg/>]

**TensorFlow Object detection Api used for training and detecting that a maize crop has nutrient deficiency or it's a healthy plant.**

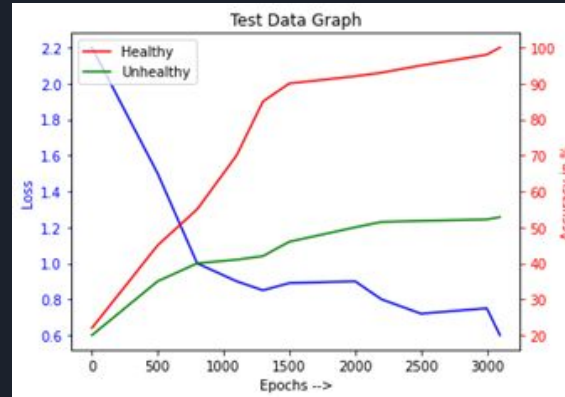
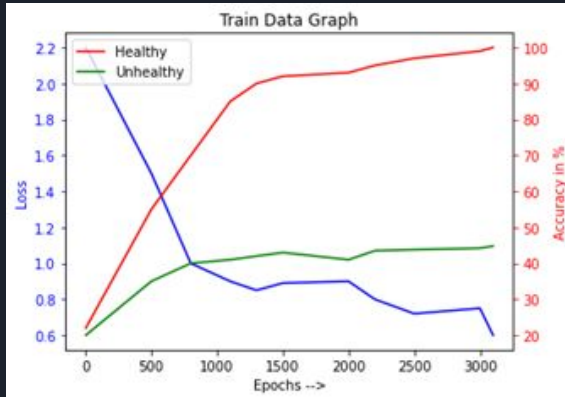
Since TensorFlow object Detection API predicts only Detection Box so by the following way the class of an image is predicted.

- 1 = 'healthy' and 2 = 'unhealthy'
- weights\_healthy = sum of detection score of all healthy box predicted
- weights\_unhealthy = sum of all detection score of all unhealthy box predicted
- Class = roundoff  $\left( \frac{(1 * \text{weights\_healthy}) + (2 * \text{weights\_unhealthy})}{\text{Total weights}} \right)$

# Models Trained :

- Efficientnet D3 (3100 steps, loss = 0.6)

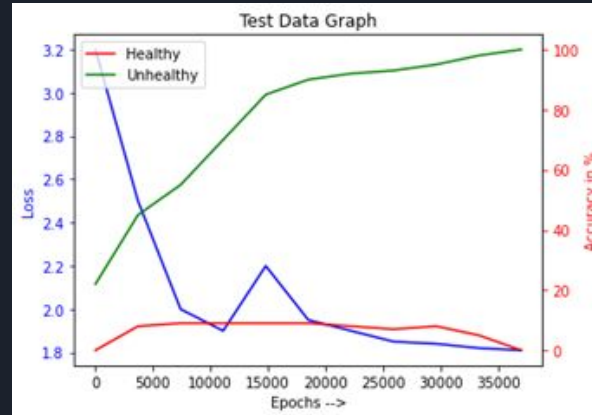
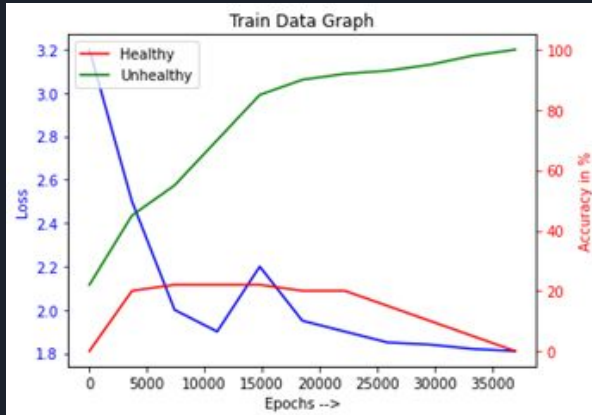
Healthy Train	100%
Unhealthy Train	44.25%
Healthy Test	100%
Unhealthy Test	52.85%



# Models Trained :

- SSD Mobile net V2 320x320 (40000 steps, loss = 1.8)

Healthy Train	0%
Unhealthy Train	100%
Healthy Test	0%
Unhealthy Test	100%





# Result for Maize Nutrient Deficiency Detection

Model 1 :

- Unhealthy is harder to train.
- Healthy accuracy is very high, maybe we should test more healthy images.

Model 2 :

- Overfitting on unhealthy images maybe because they were more in number



# Models Trained :

- SSD MobileNet FPNLite (25000 steps, loss = 0.318)

Healthy Train	94.3%
Unhealthy Train	64.36%
Healthy Test	100%
Unhealthy Test	67%

- Observation
  - Unhealthy is harder to train
  - Healthy accuracy is very high, maybe we should test more healthy images



# Models Trained :

- R-CNN inception (30900 steps, loss = 1.562)

Healthy Train	0%
Unhealthy Train	99.42%
Healthy Test	0%
Unhealthy Test	100%

- Observation
  - Very small dataset for such a large network
  - Overfitting on unhealthy images maybe because they were more in number





# Limitation in Nutrient Deficient

Here, we had shortage of data due to which all models were suffering and not performing good at all.

Unavailability of large dataset

1. Only 260 images for training
2. Deep Learning works only with large dataset



# Maize Disease Detection

## Introduction →

- Insufficient means of detecting/diagnosing diseases in crops is a big issue faced nationwide in fact worldwide, leading to scarce crop restoration procedures.
- In this application, we have worked on a solution that can be deployed in the field with ease and has the ability of recognizing diseases in maize (corn) leaf images, thus permitting pre-emptive corrective actions prior to significant yield loss.
- My approach is based on deep learning involving a convolutional neural network for both feature extraction and image classification to identify specific diseases in crops.
- It also involves the real-time implementation of such networks on android platforms for field deployment.

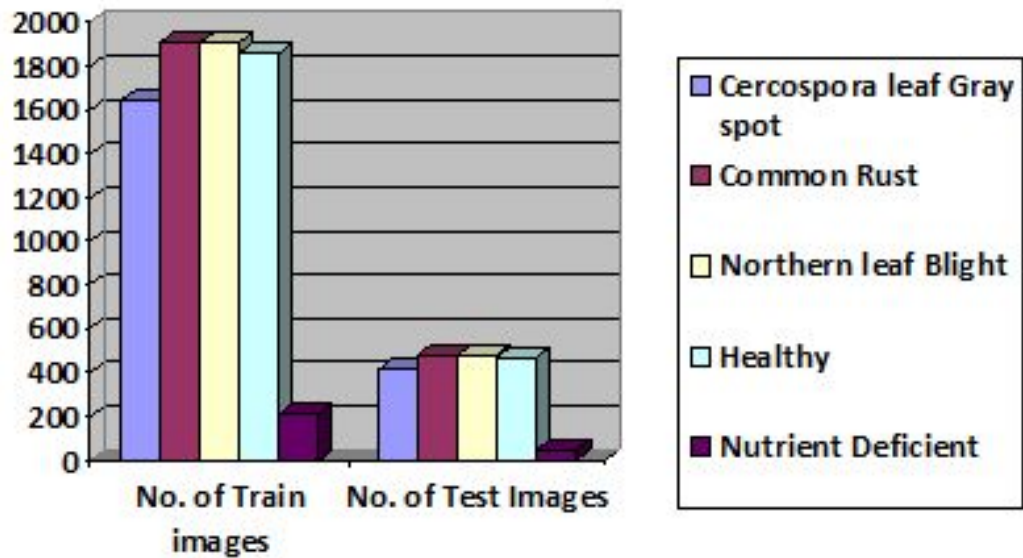
# Datasets used

- Dataset provided by Prof. Gayathri. (Images clicked at UAS Dharwad)  
360 (260 train and 100 test)
- Plant Village Dataset  
9509 (7580 train and 1929 test)




Fig: a.) Healthy, b.) Northern Leaf Blight, c.) Common Rust, d.) Cercospora Gray Leaf Spot  
e.) UnHealthy

# Dataset






For Maize Disease Detection, we used Modified Deep CNN VGG16 and MobileNet V2 with transfer learning using ImageNet Dataset weights on these models.

Dataset Loaded with custom method 

```
def create_dataset(img_folder):  
    img_data_array=[]  
    class_name=[]  
    for dir1 in os.listdir(img_folder):  
        print(dir1)  
        for file in os.listdir(os.path.join(img_folder, dir1)):  
            image_path= os.path.join(img_folder, dir1, file)  
            image= cv2.imread( image_path, cv2.COLOR_BGR2RGB)  
            image=cv2.resize(image, (IMG_HEIGHT, IMG_WIDTH),interpolation = cv2.INTER_AREA)  
            image=np.array(image)  
            image = image.astype('float32')  
            image /= 255  
            img_data_array.append(image)  
            class_name.append(dir1)  
    return img_data_array, class_name  
  
NUM_CLASSES = 5  
def convert_to_hot_encoded(t):  
    y_data = []  
    for index in range(len(t)):  
        y_data.append(t[index])  
    y_data_categorical = np_utils.to_categorical(y_data, NUM_CLASSES)  
    return y_data_categorical
```



```
] # Create x_train and y_train
img_data, class_name = create_dataset(train_data_dir)
target_dict={k: v for v, k in enumerate(np.unique(class_name))}
target_val= [target_dict[class_name[i]] for i in range(len(class_name))]
x_train = np.array(img_data)
y_train = convert_to_hot_encoded(np.array(target_val))
```

```
Corn_(maize)___Cercospora_leaf_spot Gray_leaf_spot
Corn_(maize)___Common_rust_
Corn_(maize)___Northern_Leaf_Blight
Corn_(maize)___healthy
Corn_(maize)___unhealthy
```

- In the above methods, train data and test data is loaded from 'train\_data\_dir' and 'test\_data\_dir' into NumPy arrays (x\_train, y\_train) and (x\_test, y\_test) which can be used for training a CNN model.
- Input images are read from directory and resized to 224x224x3 and then added to above NumPy arrays using the custom function 'create\_dataset'.

# Models Trained

- MODIFIED VGG16

```
model_vgg16_conv = VGG16(input_shape=IMG_SHAPE, pooling='avg', weights='imagenet', include_top=False)
X = model_vgg16_conv.layers[-1].output
X = Dense(512, activation='relu', input_dim = (512,))(X)
X = Dropout(0.1)(X)
X = Dense(256, activation='relu')(X)
X = Dense(128, activation='relu')(X)
X = BatchNormalization()(X)
X = Dense(64, activation='relu')(X)
X = Dense(5, activation='softmax')(X)
my_model = Model(model_vgg16_conv.layers[0].output,X)
my_model.summary()
```

=====

Total params: 15,150,661

Trainable params: 15,150,405

Non-trainable params: 256



- MODIFIED MobileNet V2

```
base_model = tf.keras.applications.MobileNetV2(input_shape=IMG_SHAPE,include_top=False,weights='imagenet')
X = base_model.layers[-1].output
X = tf.keras.layers.GlobalAveragePooling2D()(X)
X = Dense(5, activation='softmax')(X)
my_model = Model(base_model.layers[0].output,X)
my_model.summary()
```

=====

Total params: 2,264,389

Trainable params: 2,230,277

Non-trainable params: 34,112





## Optimizers Used

- ADAM
- SGD

## Learning Rate

- **0.01**
- **0.1**

```
sgd = tf.keras.optimizers.SGD(learning_rate=0.01)
adam = tf.keras.optimizers.Adam(learning_rate=0.01)
my_model.compile(optimizer=adam,
                  loss='categorical_crossentropy',
                  metrics=['accuracy'])
```

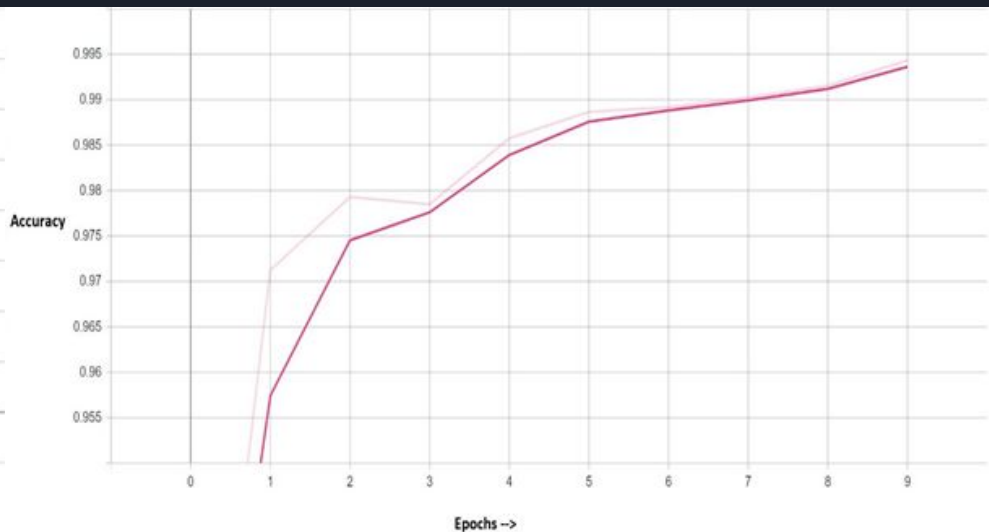
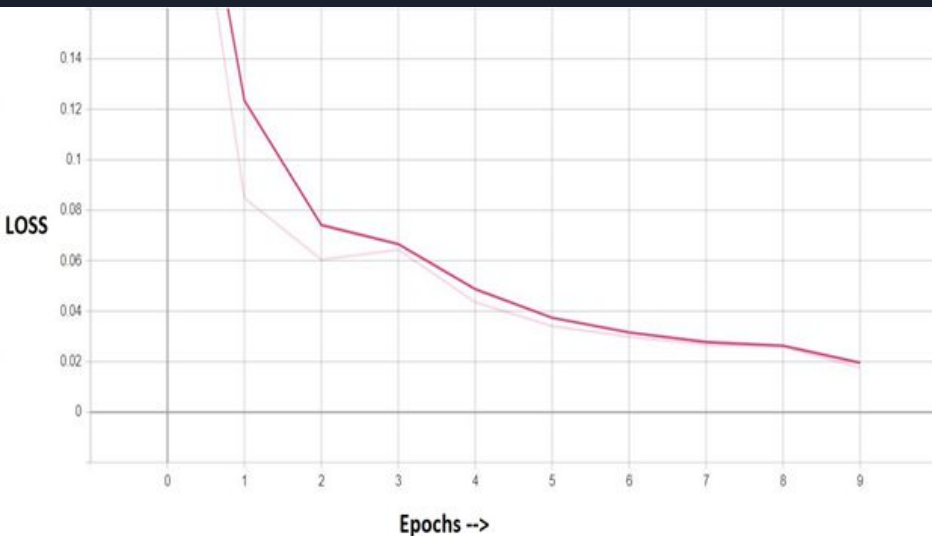
# RESULT

Model	Optimizer	Learning Rate	Train Accuracy	Test Accuracy
VGG16	SGD	0.01	99.8	98.76
		0.1	25.16	24.73
	Adam	0.01	25.71	25.66
		0.1	25.71	25.66
MobileNet V2	SGD	0.01	98.01	96.11
		0.1	97.8	73.20
	Adam	0.01	90.2	77.90
		0.1	25.71	25.66

- \*\* Train Accuracy is calculated from Tensorboard and also by importing saved model and then evaluating (x\_train, y\_train) on it.
- \*\* Test Accuracy is calculated by importing saved model and then evaluating (x\_test, y\_test) on it.

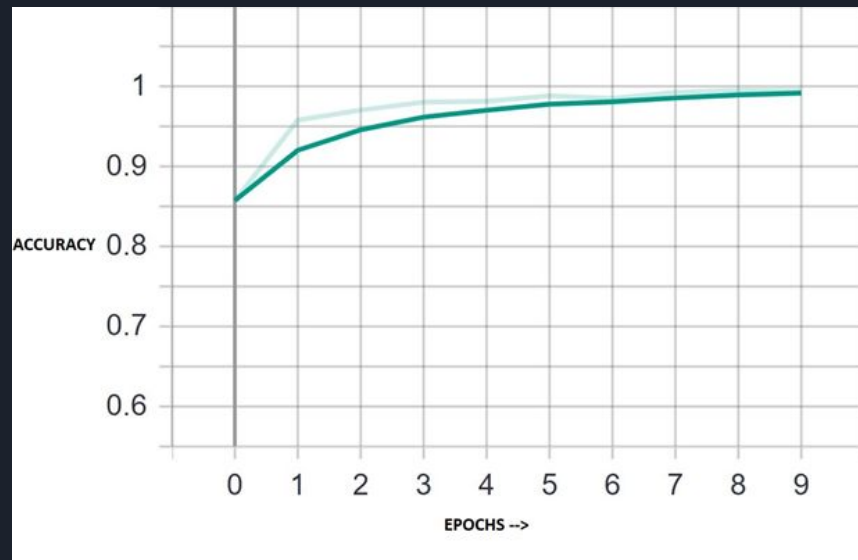
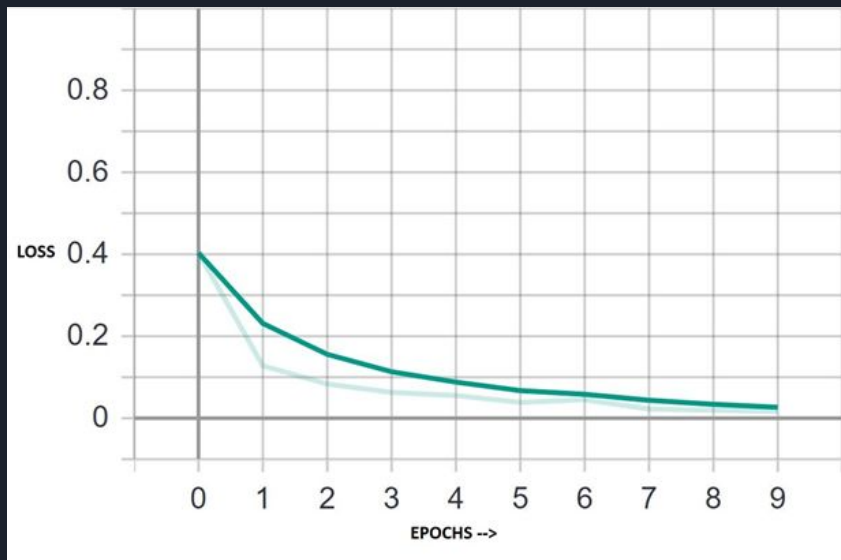
# Modified VGG16

- [Optimizer: SGD & Learning Rate: 0.01]



# Modified MobileNet V2

- [Optimizer: SGD & Learning Rate: 0.01]



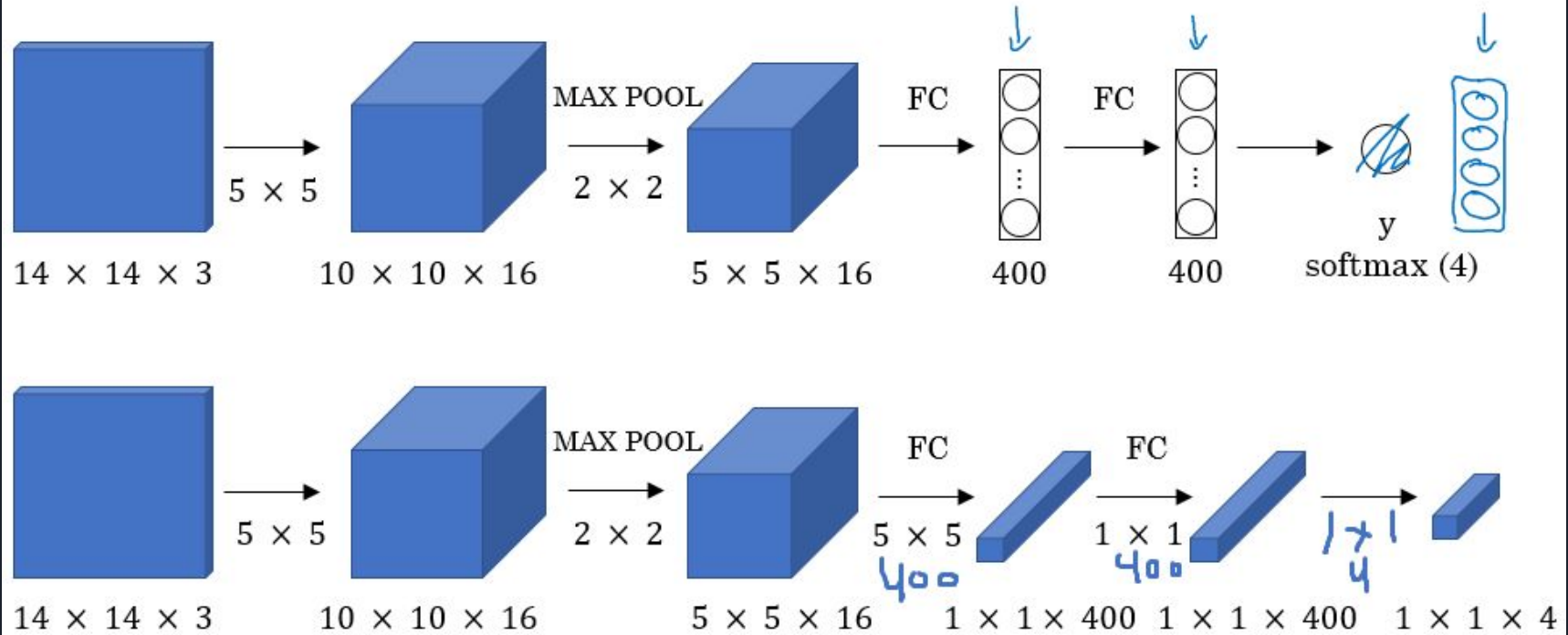


# OverFeat: Integrated Recognition, Localization and Detection using Convolutional Networks

- Integrated framework for Convolutional Networks for classification, localization and detection
- Solution for inefficiency caused by traditional sliding window
- Not a state of art anymore. So, why?
  - Nature of our dataset
  - We don't need exact boundary box

**Source:** <https://arxiv.org/abs/1312.6229>

# Turning Fully Connected layer to Convolution Layer



# Turning Fully Connected layer to Convolution Layer

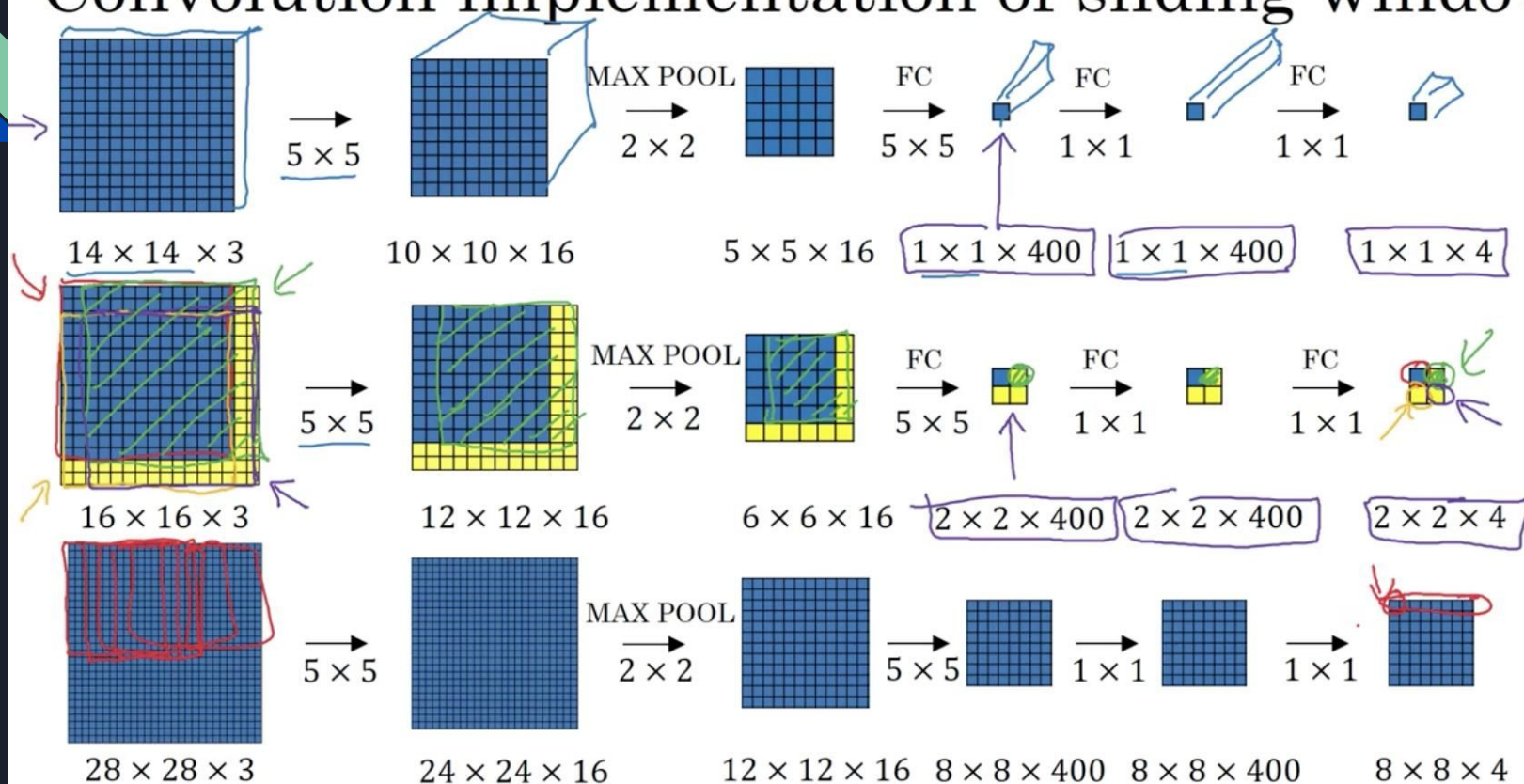
```
1 base_model = tf.keras.applications.MobileNetV2(input_shape=(256,256,3),include_top=False,weights='imagenet')
2 model = tf.keras.Sequential([
3     base_model,
4     tf.keras.layers.BatchNormalization(),
5     tf.keras.layers.Conv2D(filters=5,kernel_size=8,activation='softmax'),
6     tf.keras.layers.Reshape((1,5)),
7     tf.keras.layers.Activation('softmax')
8 ])
```

Model: "sequential\_3"

Layer (type)	Output Shape	Param #
=====		
mobilenetv2_1.00_224 (Function)	(None, 8, 8, 1280)	2257984
-----		
batch_normalization_3 (Batch Normalization)	(None, 8, 8, 1280)	5120
-----		
conv2d_3 (Conv2D)	(None, 1, 1, 5)	409605
-----		
reshape_3 (Reshape)	(None, 1, 5)	0
-----		
activation (Activation)	(None, 1, 5)	0
=====		

Total params: 2,672,709  
Trainable params: 2,636,037  
Non-trainable params: 36,672

# Convolution implementation of sliding windows



[Sermanet et al., 2014, OverFeat: Integrated recognition, localization and detection using convolutional networks]

Andrew Ng





# Final model in OverFeat implementation

Modified model with different Input shape

Layer (type)	Output Shape	Param #
=====		
mobilenetv2_1.00_224 (Function)	(None, 20, 20, 1280)	2257984
-----		
batch_normalization (Batch Normalization)	(None, 20, 20, 1280)	5120
-----		
conv2d (Conv2D)	(None, 13, 13, 5)	409605
=====		
Total params: 2,672,709		
Trainable params: 2,636,037		
Non-trainable params: 36,672		



# Methodology

- Loading Dataset

```
1 batch_size = 32
2 IMG_SIZE = (64,64)
```

```
1 data_dir = '/content/drive/My Drive/data/train'
2 train_ds = tf.keras.preprocessing.image_dataset_from_directory(
3     data_dir,
4     seed=123,
5     image_size=IMG_SIZE,
6     batch_size=batch_size)
```

Found 7520 files belonging to 5 classes.

```
1 test_dir = '/content/drive/My Drive/data/valid'
2 val_ds = tf.keras.preprocessing.image_dataset_from_directory(
3     test_dir,
4     image_size=IMG_SIZE,
5     batch_size=batch_size)
```

Found 1869 files belonging to 5 classes.

# Methodology

- Normalization

```
1 normalization_layer = tf.keras.layers.experimental.preprocessing.Rescaling(1./255)
2 normalized_ds = train_ds.map(lambda x, y: (normalization_layer(x), y))
3 image_batch, labels_batch = next(iter(normalized_ds))
4 first_image = image_batch[0]
5 print(np.min(first_image), np.max(first_image))
```

```
0.08529412 1.0
```

- Sequential Model

```
1 base_model = tf.keras.applications.DenseNet121(input_shape=(64,64,3),include_top=False,weights='imagenet')
2 model = tf.keras.Sequential([
3     base_model,
4     tf.keras.layers.BatchNormalization(),
5     tf.keras.layers.Conv2D(filters=5,kernel_size=2,activation='softmax'),
6     tf.keras.layers.Reshape((1,5)),
7     tf.keras.layers.Activation('softmax')
8 ])
```



# Methodology

- Decay Learning rate, loss function and compiling

```
initial_learning_rate = 0.01
lr_schedule = tf.keras.optimizers.schedules.ExponentialDecay(
    initial_learning_rate, decay_steps=50, decay_rate=0.96, staircase=False
)

def loss(labels, logits):
    return tf.keras.losses.sparse_categorical_crossentropy(labels, logits)
model.compile(optimizer=tf.keras.optimizers.SGD(learning_rate=initial_learning_rate), loss=loss, metrics='accuracy')
```

- Callbacks during training
  - Saving checkpoint
  - early stopping
  - tensorboard events data

# Methodology

```
checkpoint_dir = '/content/drive/My Drive/data/training7'
checkpoint_prefix = os.path.join(checkpoint_dir, "ckpt_{epoch}")
logdir = os.path.join("/content/drive/My Drive/logs7", datetime.datetime.now().strftime("%Y%m%d-%H%M%S"))
tensorboard_callback = tf.keras.callbacks.TensorBoard(logdir, histogram_freq=1)

early_stopping_cb = tf.keras.callbacks.EarlyStopping(
    patience=10, restore_best_weights=True
)

checkpoint_callback=tf.keras.callbacks.ModelCheckpoint(
    filepath=checkpoint_prefix,
    save_weights_only=True,verbose=2,
    save_best_only=True)
```

- Model Training

```
1 history = model.fit(train_ds,epochs=30,
2 | | | | | validation_data=val_ds,callbacks=[tensorboard_callback,checkpoint_callback,early_stopping_cb])
```

# Result - Hyper Parameter set 1

- Base Model – MobileNet V2
- Model summary
- Input Image Size (256, 256)
- Normalization: True
- Decay learning rate
  - Initial learning rate = 0.01
  - Decay steps = 50
  - Decay rate = 0.96
- Optimizer – SGD

```
Model: "sequential_3"
```

Layer (type)	Output Shape	Param #
mobilenetv2_1.00_224 (Func	(None, 8, 8, 1280)	2257984
batch_normalization_3 (Batch	(None, 8, 8, 1280)	5120
conv2d_3 (Conv2D)	(None, 1, 1, 5)	409605
reshape_3 (Reshape)	(None, 1, 5)	0
activation (Activation)	(None, 1, 5)	0

```
Total params: 2,672,709  
Trainable params: 2,636,037  
Non-trainable params: 36,672
```

# Result - Hyper Parameter set 1

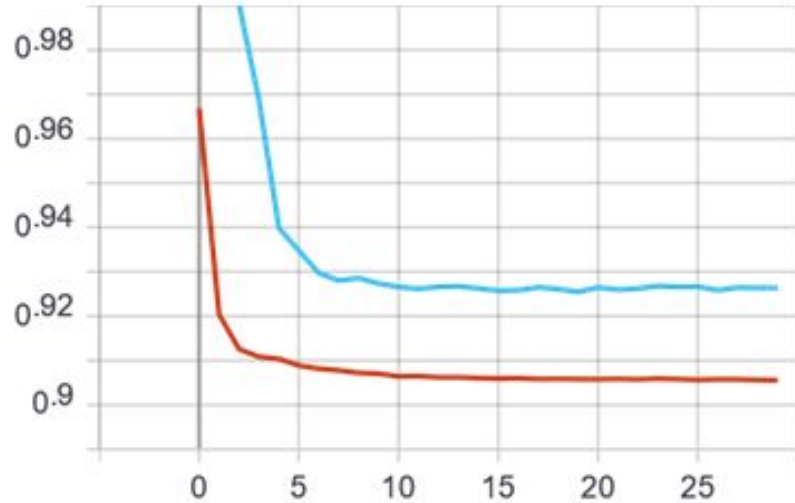


Figure 3: Epoch loss graph: Red - Training set, Blue - Test set

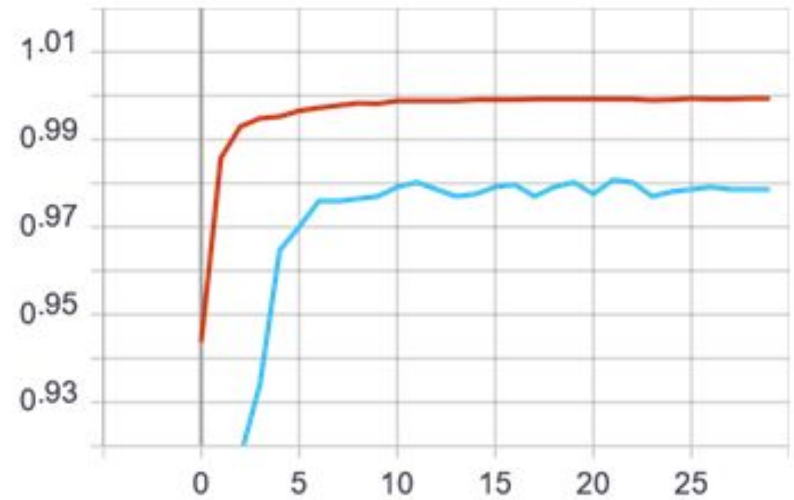


Figure 4: Epoch accuracy: Red - Training set, Blue - Test set

Best model is at 20th epoch with 99.92% accuracy on training set and 98.02% accuracy on test set.

# Result - Hyper Parameter set 2

- Base Model – DenseNet121
- Input Image Size (64, 64)
- Model Summary
- Normalization: True
- Decay learning rate
  - Initial learning rate = 0.01
  - Decay steps = 50
  - Decay rate = 0.96
- Optimizer – SGD

Layer (type)	Output Shape	Param #
=====	=====	=====
densenet121 (Functional)	(None, 2, 2, 1024)	7037504
batch_normalization (Batch Normalization)	(None, 2, 2, 1024)	4096
conv2d (Conv2D)	(None, 1, 1, 5)	20485
reshape (Reshape)	(None, 1, 5)	0
activation (Activation)	(None, 1, 5)	0
=====	=====	=====
Total params: 7,062,085		
Trainable params: 6,976,389		
Non-trainable params: 85,696		



## Result - Hyper Parameter set 2

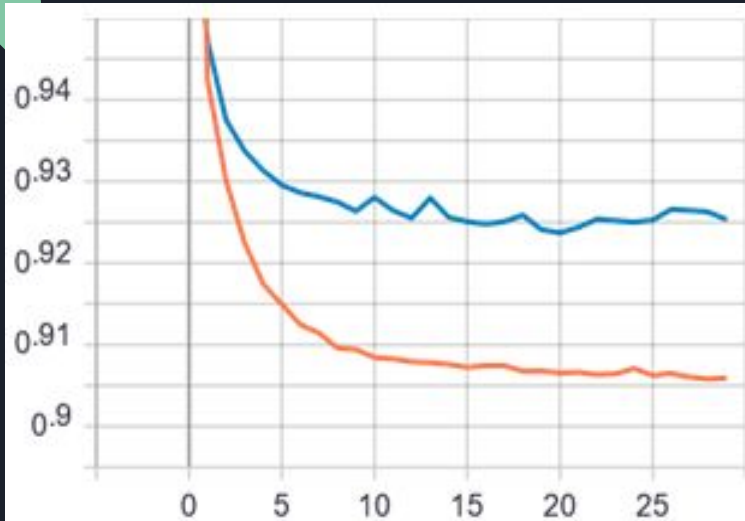


Figure 5 Epoch loss graph: Orange-Train, Blue- Test

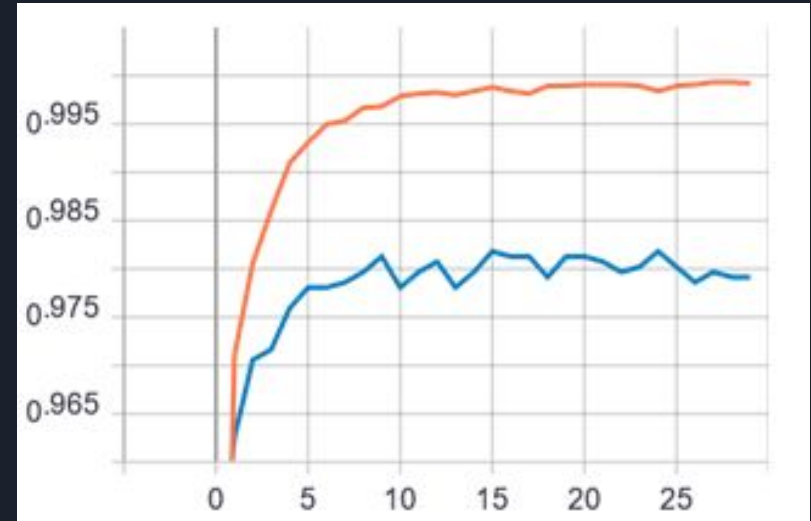


Figure 6 Epoch accuracy graph: Orange-Train, Blue- Test

Best model is at 20th epoch with 99.89% accuracy on training set and 98.13% accuracy on test set.

# Result - Hyper Parameter set 3

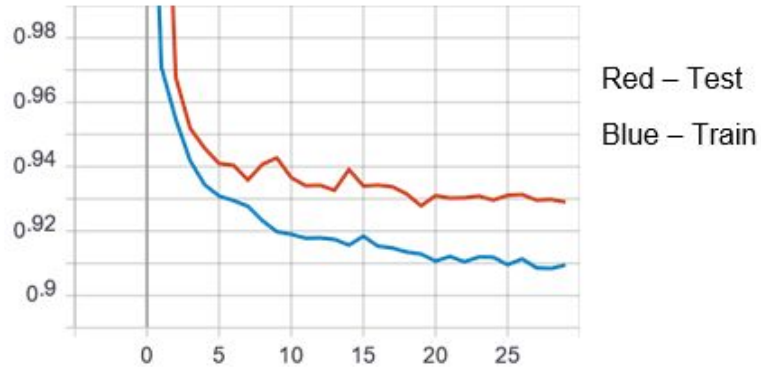
- Base Model – MobileNet V2
- Model Summary
- Input Image Size (64,64)
- Normalization: True
- Decay learning rate
- Initial learning rate = 0.01
  - Decay steps = 50
  - Decay rate = 0.96
- Optimizer – SGD

Model: "sequential"

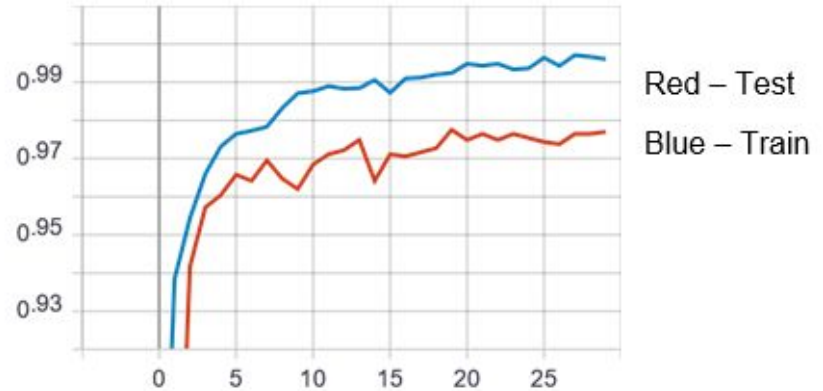
Layer (type)	Output Shape	Param #
=====		
mobilenetv2_1.00_224 (Function)	(None, 2, 2, 1280)	2257984
-----		
batch_normalization (Batch Normalization)	(None, 2, 2, 1280)	5120
-----		
conv2d (Conv2D)	(None, 1, 1, 5)	25605
-----		
reshape (Reshape)	(None, 1, 5)	0
-----		
activation (Activation)	(None, 1, 5)	0
=====		
Total params: 2,288,709		
Trainable params: 2,252,037		
Non-trainable params: 36,672		

# Result - Hyper Parameter set 3

Epoch loss graph



Epoch accuracy graph



Best test accuracy of model is at 20th epoch with 99.24% accuracy on training set and 97.75% accuracy on test set.

# Result - Hyper Parameter set 4

- Base Model – DenseNet121
- Input Image Size (256, 256)
- Model Summary
- Normalization: True
- Decay learning rate
  - Initial learning rate = 0.001
  - Decay steps = 50
  - Decay rate = 0.96
- Optimizer - SGD

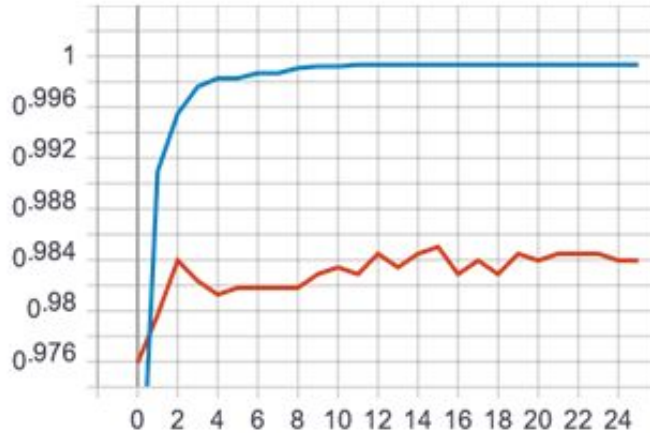
Model: "sequential"

Layer (type)	Output Shape	Param #
=====	=====	=====
densenet121 (Functional)	(None, 8, 8, 1024)	7037504
batch_normalization (Batch Normalization)	(None, 8, 8, 1024)	4096
conv2d (Conv2D)	(None, 1, 1, 5)	327685
reshape (Reshape)	(None, 1, 5)	0
activation (Activation)	(None, 1, 5)	0
=====	=====	=====
Total params: 7,369,285		
Trainable params: 7,283,589		
Non-trainable params: 85,696		

## Result - Hyper Parameter set 4

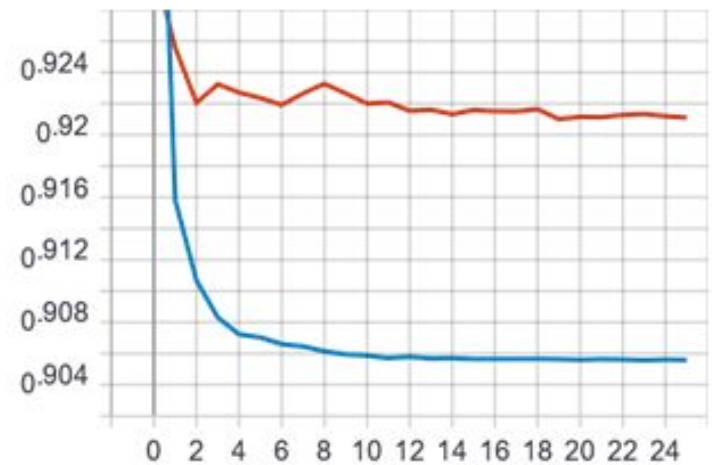
Epoch accuracy graph

Red – Test, Blue – Train



Epoch loss graph

Red – Test, Blue – Train



Best test accuracy of model is at 20th epoch with 99.93% accuracy on training set and 98.45% accuracy on test set.



## Result - Hyper Parameter set 5

- Base model - MobileNet V2
- Input Image Size (256, 256)
- Normalization: True
- Decay learning rate
  - Initial learning rate = 0.001
  - Decay steps = 50
  - Decay rate = 0.96
- Optimizer - Adam
- **Train accuracy - 74.84%**
- **Test accuracy- 75.49%**

## Result - Hyper Parameter set 5

Orange – Train, Blue- Test

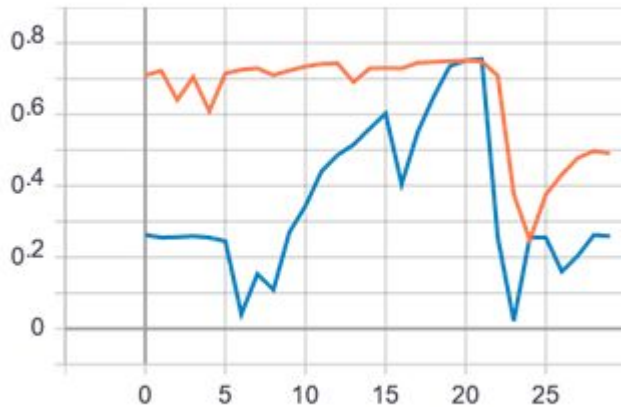


Figure 7: epoch accuracy

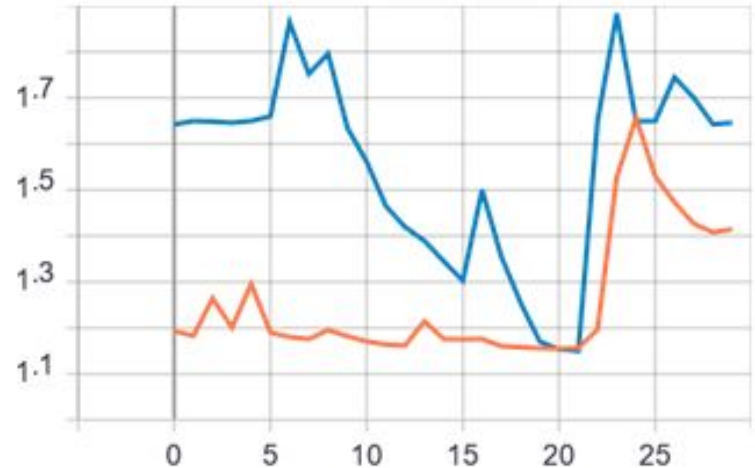


Figure 8: epoch loss

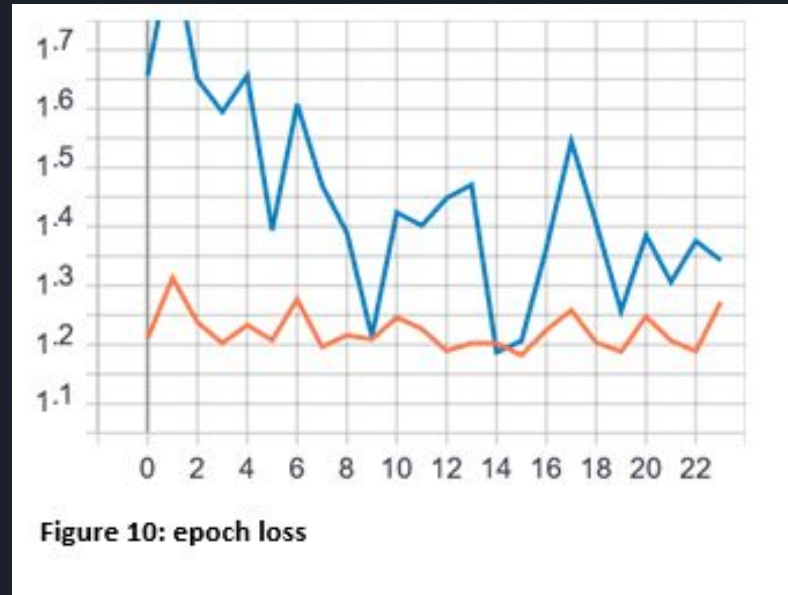
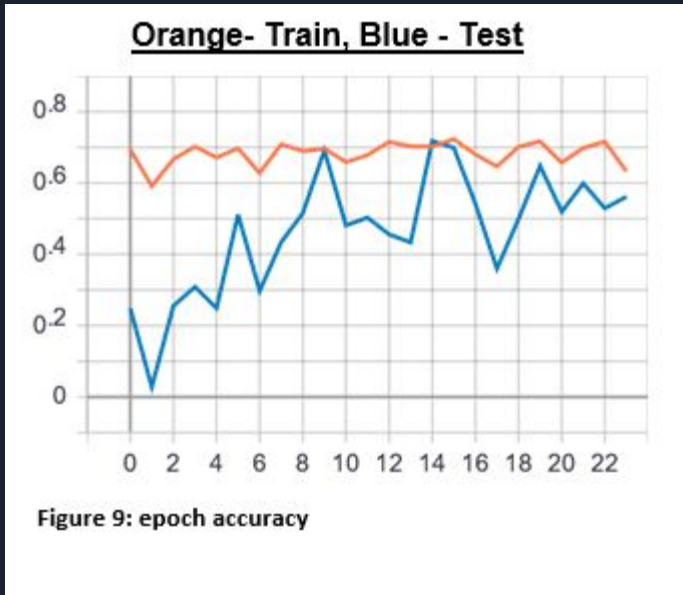


## Result - Hyper Parameter set 6

- Base model – MobileNet V2
- Input Image Size (256, 256)
- Normalization: True
- Fixed learning rate = 0.001
- Optimizer - Adam
- **Train accuracy – 70.24%**
- **Test accuracy- 71.80%**



## Result - Hyper Parameter set 6





# General Observation

- SGD optimizers perform much better than Adam
- Adam optimizer performance is unsatisfactory.
- Decay learning rate is better than fixed learning rate
- DenseNet which has more depth perform better than MobileNet model
- Input size (256,256) perform better than (64,64)



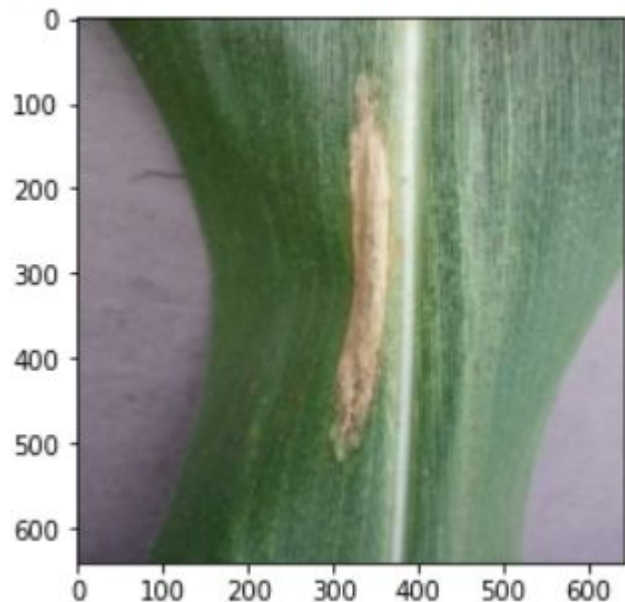
# Candidate Model

	MobileNetv2	DenseNet121
Input Size	(256,256,3)	(256,256,3)
No. of parameters	2.2 M	7.3 M
Depth	88	121
Test Accuracy	98.02%	98.45%
Hyperparameter	Set1	Set4

# Final model in OverFeat implementation

Input (640,640,3)

tf.Tensor(2, shape=(), dtype=int32)



Output

```
[ [3. 3. 3. 3. 3. 3. 3. 2. 3. 3. 3. 3. 0.]  
  [3. 3. 3. 3. 3. 3. 2. 2. 2. 3. 3. 3. 3.]  
  [3. 3. 3. 3. 3. 3. 2. 2. 2. 3. 3. 3. 0.]  
  [3. 3. 3. 3. 3. 3. 2. 2. 2. 2. 3. 3. 0.]  
  [3. 3. 3. 3. 3. 3. 3. 2. 2. 3. 3. 3. 3.]  
  [3. 3. 3. 0. 0. 3. 3. 2. 2. 3. 3. 3. 0.]  
  [3. 3. 4. 3. 0. 0. 2. 2. 2. 3. 0. 3. 3.]  
  [3. 3. 4. 3. 2. 2. 2. 2. 2. 0. 0. 3. 3.]  
  [3. 3. 3. 3. 2. 2. 2. 2. 2. 0. 2. 3. 3.]  
  [3. 3. 3. 3. 2. 2. 2. 2. 2. 0. 0. 3. 3.]  
  [3. 3. 3. 3. 0. 2. 2. 2. 2. 2. 2. 3. 3.]  
  [3. 3. 0. 0. 3. 2. 2. 2. 2. 0. 3. 3. 3.]  
  [3. 3. 3. 0. 0. 0. 0. 2. 0. 0. 3. 3. 3.] ]
```

## Deployment in Android

The best Model is VGG16 [SGD,0.01] whose Test Accuracy is 98.76 %.

And 2nd best MobileNetV2 [SGD,0.01] whose Test Accuracy is 96.11%

MobileNetV2 has just 2,264,389 Parameters as compared VGG16 which has 15,150,661 Parameters.

**\*\* Best for Mobile App: MobileNetV2 [SGD,0.01]**

- In order to use Trained model in Android App, we need to convert TensorFlow Model into .tflite Model

```
[ ] # Converting a SavedModel to a TensorFlow Lite model.  
import tensorflow as tf  
saved_model_dir = '/content/gdrive/My Drive/tensorflow/data/saved_model/MN_SGD_0point01/'  
# Convert the model  
converter = tf.lite.TFLiteConverter.from_saved_model(saved_model_dir) # path to the SavedModel directory  
tflite_model = converter.convert()  
# Save the model.  
with open('MN.tflite', 'wb') as f:  
    f.write(tflite_model)
```

# Dependencies →

```
dependencies {  
    implementation fileTree(dir: "libs", include: ["*.jar"])  
    implementation 'androidx.appcompat:appcompat:1.2.0'  
    implementation 'androidx.constraintlayout:constraintlayout:2.0.4'  
    testImplementation 'junit:junit:4.12'  
    androidTestImplementation 'androidx.test.ext:junit:1.1.2'  
    androidTestImplementation 'androidx.test.espresso:espresso-core:3.3.0'  
  
    //Custom Here  
    implementation('org.tensorflow:tensorflow-lite:0.0.0-nightly') { changing = true }  
    implementation('org.tensorflow:tensorflow-lite-gpu:0.0.0-nightly') { changing = true }  
    implementation('org.tensorflow:tensorflow-lite-support:0.0.0-nightly') { changing = true }  
  
    implementation 'com.camerakit:camerakit:1.0.0-beta3.11'  
    implementation 'com.camerakit:jpegkit:0.1.0'  
    implementation 'org.jetbrains.kotlin:kotlin-stdlib-jdk7:1.3.0'  
    implementation 'org.jetbrains.kotlinx:kotlinx-coroutines-android:1.0.0'  
}
```



In order to use camera in our app, we used an open source library 'CameraKit'.

Link: <https://github.com/CameraKit/camerakit-android>

Website: <https://camerakit.io/>

```
imageButton.setOnClickListener((v) -> {  
    cameraKitView.captureImage((cameraKitView, capturedImage) -> {  
        Bitmap bitmap = BitmapFactory.decodeByteArray(capturedImage, offset: 0, capturedImage.length);  
        Bitmap resized = Bitmap.createScaledBitmap(bitmap, dstWidth: 224, dstHeight: 224, filter: true);  
        Global.setCapturedImage(capturedImage);  
        Global.setBitmap(resized);  
        //MediaStore.Images.Media.insertImage(getContentResolver(), resized, "test.jpg", "New");  
        startActivity(new Intent( packageContext MainActivity.this, ImageClickedActivity.class));  
    });  
});
```

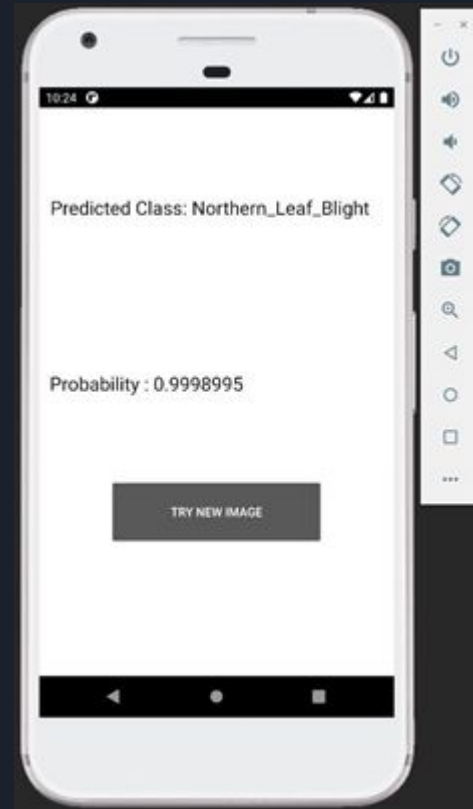
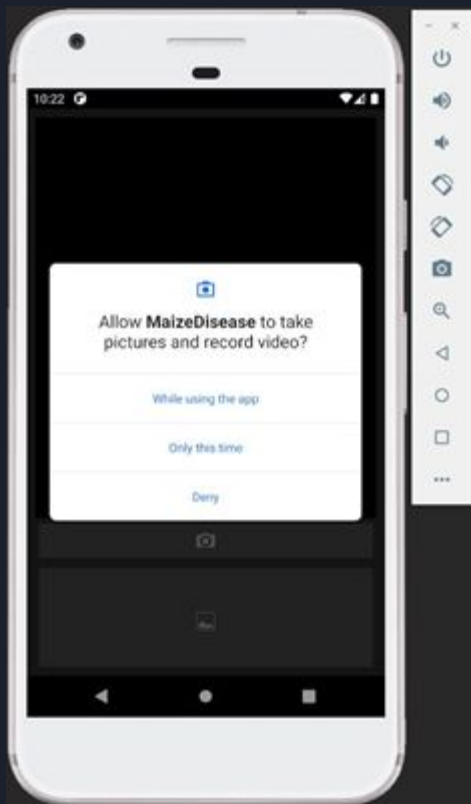
In order to use TensorFlow model, we used [org.tensorflow:tensorflow-lite:0.0.0-nightly library](#).

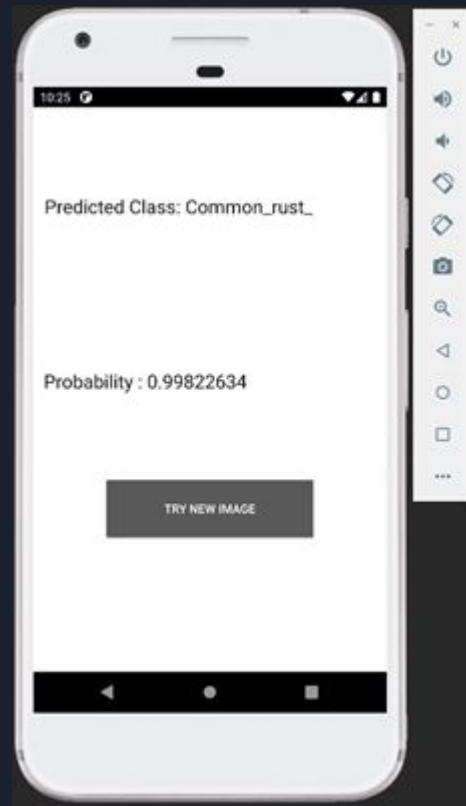
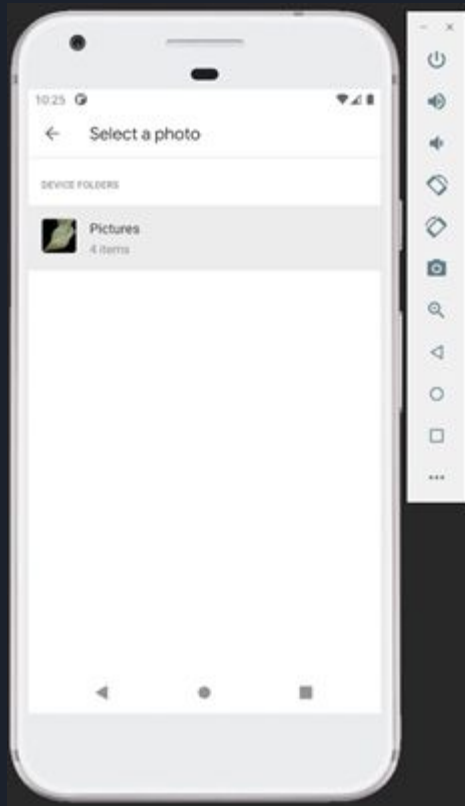
```
try {
    tfliteModel = FileUtil.loadMappedFile( context: ImageClickedActivity.this, modelFile);
    labels = FileUtil.loadLabels( context: ImageClickedActivity.this, label);
    tflite = new Interpreter(tfliteModel);
} catch (IOException e) {
    e.printStackTrace();
}

ByteBuffer byteBuffer = convertBitmapToByteBuffer(Global.getBitmap());
ByteBuffer outputBuffer = ByteBuffer.allocateDirect(4*5);
outputBuffer.order(ByteOrder.nativeOrder());
float[][] out = new float[1][5];
Object[] input = {byteBuffer};
Map<Integer, Object> outputs = new HashMap();
outputs.put(0, out);
tflite.runForMultipleInputsOutputs(input, outputs);
```



# Some Screenshots from the app:







# Time taken

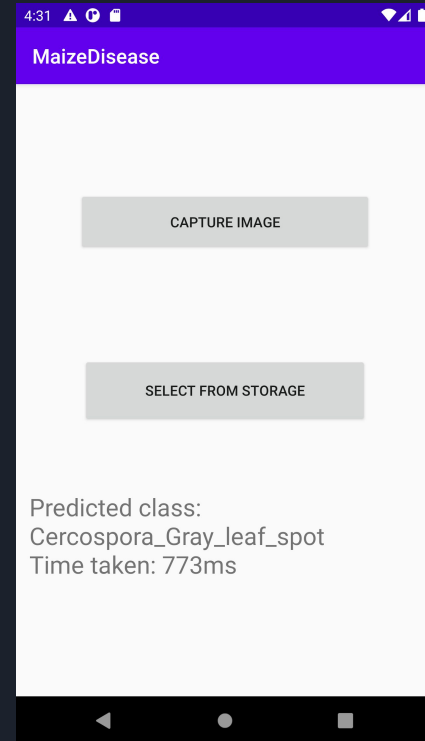
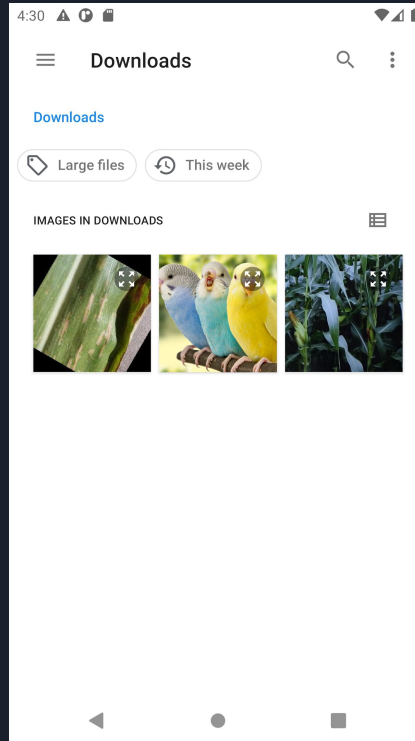
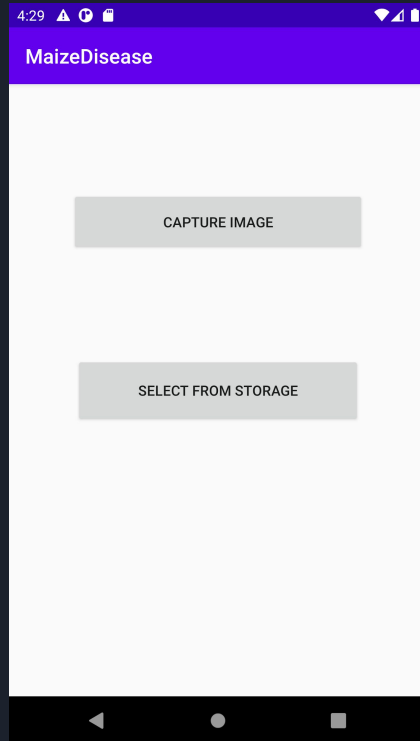
```
E/CameraException: Flash: FLASH_AUTO is not supported in this version of CameraKit.  
I/CameraManagerGlobal: Connecting to camera service  
W/Gralloc4: allocator 3.x is not supported  
W/le.maizediseas: [SurfaceTexture-1-30579-0] bindTextureImage: clearing GL error: 0x506  
I/tflite: Initialized TensorFlow Lite runtime.  
I/System.out: Time taken is : 121  
I/System.out: [[0.38069108, 0.5560788, 0.01831147, 0.034575313, 0.010343308]]  
I/System.out: 0.5560788  
Common_rust_  
E/CameraException: Flash: FLASH_AUTO is not supported in this version of CameraKit.  
I/System.out: Time taken is : 116  
[[0.0067165573, 0.991814, 2.6594407E-8, 0.0014694561, 4.4564953E-8]]  
0.991814  
I/System.out: Common_rust_  
E/CameraException: Flash: FLASH_AUTO is not supported in this version of CameraKit.  
I/System.out: Time taken is : 113  
I/System.out: [[0.17339978, 0.14660782, 8.1591206E-5, 0.6798944, 1.6378313E-5]]  
0.6798944  
Northern_Leaf_Blight|
```

## Deployment in Android

- Model trained with Hyperparameter set 1 is used in Android app

```
try {  
    MappedByteBuffer tfliteModel  
        = FileUtil.loadMappedFile( context: MainActivity.this,  
        filePath: "model_set1.tflite");  
    Interpreter tflite = new Interpreter(tfliteModel);  
    DataType myImageDataType = tflite.getInputTensor( inputIndex: 0).dataType();  
    TensorImage tImage = new TensorImage(myImageDataType);  
    tImage.load(bitmap);  
    tImage = imageProcessor.process(tImage);  
    float[][][][] out = new float[1][13][13][5];  
    long startTimeForLoadImage = SystemClock.uptimeMillis();  
    tflite.run(tImage.getBuffer(), out);  
    long endTimeForLoadImage = SystemClock.uptimeMillis();  
}
```

# Deployment in Android



# Conversion of Tflite Model to C Header file used in MicroProcessors



```
# This function converts a TFLite Model to C Header File used for Some MicroProcessors
def hex_to_c_array(hex_data, var_name):
    c_str = ''
    # Create header guard
    c_str += '#ifndef ' + var_name.upper() + '_H\n'
    c_str += '#define ' + var_name.upper() + '_H\n\n'
    # Add array length at top of file
    c_str += '\nunsigned int ' + var_name + '_len = ' + str(len(hex_data)) + ';\n'
    # Declare C variable
    c_str += 'unsigned char ' + var_name + '[] = {'
    hex_array = []
    for i, val in enumerate(hex_data):
        # Construct string from hex
        hex_str = format(val, '#04x')
        # Add formatting so each line stays within 80 characters
        if (i + 1) < len(hex_data):
            hex_str += ','
        if (i + 1) % 12 == 0:
            hex_str += '\n '
        hex_array.append(hex_str)
    # Add closing brace
    c_str += '\n ' + format(' '.join(hex_array)) + '\n};\n\n'
    # Close out header guard
    c_str += '#endif //' + var_name.upper() + '_H'
    return c_str
```

```
# Write TFLite model to a C source (or header) file
c_model_name = 'model'
with open(c_model_name + '.h', 'w') as file:
    file.write(hex_to_c_array(tflite_model, c_model_name))
```



# Questions?