

# AN ALGORITHM FOR FINDING GRÖBNER BASES IN INFINITE DIMENSIONAL POLYNOMIAL RINGS

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ABSTRACT. We give an explicit algorithm to find Gröbner bases for symmetric ideals in infinite dimensional polynomial rings. This allows for symbolic computation in a new class of rings.

## 1. INTRODUCTION

Let  $X = \{x_1, x_2, \dots\}$  be an infinite collection of indeterminates, indexed by the positive integers, and let  $\mathfrak{S}_\infty$  be the group of permutations of  $X$ . For a positive integer  $N$ , we will also let  $\mathfrak{S}_N$  denote the set of permutations of  $\{1, \dots, N\}$ . Fix a field  $K$  and let  $R = K[X]$  be the polynomial ring in the indeterminates  $X$ . The group  $\mathfrak{S}_\infty$  acts naturally on  $R$ : if  $\sigma \in \mathfrak{S}_\infty$  and  $f \in K[x_1, \dots, x_n]$ , then

$$(1.1) \quad \sigma f(x_1, \dots, x_n) = f(x_{\sigma 1}, \dots, x_{\sigma n}) \in R.$$

We let  $R[\mathfrak{S}_\infty]$  be the (left) group ring of  $\mathfrak{S}_\infty$  over  $R$  with multiplication given by  $f\sigma \cdot g\tau = fg(\sigma\tau)$  for  $f, g \in R$  and  $\sigma, \tau \in \mathfrak{S}_\infty$ , and extended by linearity. The action (1.1) naturally gives  $R$  the structure of a (left) module over the ring  $R[\mathfrak{S}_\infty]$ . An ideal  $I \subseteq R$  is called *invariant under  $\mathfrak{S}_\infty$*  (or simply *invariant*) if

$$\mathfrak{S}_\infty I := \{\sigma f : \sigma \in \mathfrak{S}_\infty, f \in I\} \subseteq I.$$

Invariant ideals are then simply the  $R[\mathfrak{S}_\infty]$ -submodules of  $R$ .

The following says that while ideals of  $R$  are too big in general, those with extra structure have finite presentations.

**Theorem 1.1.** *Every invariant ideal of  $R$  is finitely generated as an  $R[\mathfrak{S}_\infty]$ -module. In other words,  $R$  is a Noetherian  $R[\mathfrak{S}_\infty]$ -module.*

For the purposes of this work, we will use the following notation. Let  $B$  be a ring and let  $G$  be a subset of a  $B$ -module  $M$ . Then  $\langle f : f \in G \rangle_B$  will denote the  $B$ -submodule of  $M$  generated by the elements of  $G$ .

**Example 1.2.**  $I = \langle x_1, x_2, \dots \rangle_R$  is an invariant ideal of  $R$ . Written as a module over the group ring  $R[\mathfrak{S}_\infty]$ , it has the compact presentation  $I = \langle x_1 \rangle_{R[\mathfrak{S}_\infty]}$ .

**Theorem 1.3.** *Let  $G$  be a Gröbner basis for an invariant ideal  $I$ . Then  $f \in I$  if and only if  $f$  has normal form 0 with respect to  $G$ .*

**Example 1.4.** Let  $I = \langle x_1 + x_2, x_1 x_2 \rangle_{R[\mathfrak{S}_\infty]}$ . Then, a Gröbner basis for  $I$  is given by  $G = \{x_1\}$ . It is important to note that we may not simply restrict consideration to  $K[x_1, x_2]$  to produce this result since

$$\langle x_1 + x_2, x_1 x_2 \rangle_{R[\mathfrak{S}_2]} \neq \langle x_1 \rangle_{R[\mathfrak{S}_2]}.$$

**Example 1.5.** The ideal  $I = \langle x_1^3x_3 + x_1^2x_2^3, x_2^2x_3^2 - x_2^2x_1 + x_1x_3^2 \rangle_{R[\mathfrak{S}_\infty]}$  has a Gröbner basis given by:

$$G = \mathfrak{S}_3 \cdot \{x_3x_2x_1^2, x_3^2x_1 + x_2^4x_1 - x_2^2x_1, x_3x_1^3, x_2x_1^4, x_2^2x_1^2\}.$$

Once  $G$  is found, testing whether a polynomial  $f$  is in  $I$  is computationally fast.  $\square$

The normal form reduction we are talking about here is a modification of the standard notion in polynomial theory and Gröbner bases; we describe it in more detail in Section ???. Unfortunately, the techniques used to prove finiteness in [?] are nonconstructive and therefore do not give methods for computing Gröbner bases in  $R$ . Our main result is an algorithm for finding these bases.

**Theorem 1.6.** *Let  $I = \langle f_1, \dots, f_n \rangle_{R[\mathfrak{S}_\infty]}$  be an invariant ideal of  $R$ . There exists an effective algorithm to compute a finite minimal Gröbner basis for  $I$ .*

**Corollary 1.7.** *There exists an effective algorithm to solve the ideal membership problem for symmetric ideals in the infinite dimensional ring  $K[x_1, x_2, \dots]$ .*

## 2. ALGORITHMS

We postpone the proof of correctness of the algorithms above until Section 4

## 3. EXAMPLES

Here we list some examples of our algorithm.<sup>1</sup>

Consider  $F = \{x_1 + x_2, x_1x_2\}$  from the introduction. One iteration of Algorithm ?? with  $i = 2$  gives  $F' = \{x_1 + x_2, x_1^2\}$ . The next two iterations produce  $\{x_1\}$  and thus the algorithm returns with this as its answer.

## 4. PROOF OF CORRECTNESS

Here we prove that our algorithm terminates and produces a Gröbner basis for an ideal  $I$ .

## REFERENCES

- [1] D. Cox, J. Little, D. O’Shea, *Using algebraic geometry*, Springer, New York, 1998.

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<sup>1</sup>Code that performs the calculations in this section can be found at ??.