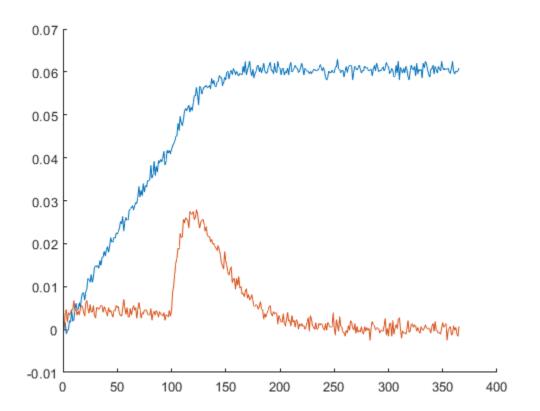
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Load data and plot



Setup

```
A = [0 0 0 .99 .99 .99 .99];
b = 1;
Af = [0 0 0 1 1 1 1];
bf = 1;
ub = [1 1 1 1 1 1 1]';
lb = [0 0 0 0 0 0 0]';
x0 = [0 0 0 1 0 0 0];
```

First Segment: Days 1-100

```
t = 100;
seg1 = data(1:100,:);

fun1= @(x)siroutput(x,t,seg1);
x1 = fmincon(fun1,x0,A,b,Af,bf,lb,ub);
Y_fit_1 = siroutput_full(x1,t);

New1(1) = Y_fit_1(100, 1);
New1(2) = Y_fit_1(100, 2);
New1(3) = Y_fit_1(100, 3);
New1(4) = Y_fit_1(100, 4);
```

Local minimum found that satisfies the constraints.

Optimization completed because the objective function is non-decreasing in feasible directions, to within the value of the optimality tolerance, and constraints are satisfied to within the value of the constraint tolerance.

Second Segment

```
t = 25;
seg2 = data(101:125, :);
fun2= @(x)siroutput(x,t,seg2);
params2 = [0 0 0 New1(1) New1(2) New1(3) New1(4)];
x2 = fmincon(fun2, x1, A, b, Af, bf, lb, ub);
Y_fit_2 = siroutput_full(x2, t);
New2(1) = Y_fit_2(25, 1);
New2(2) = Y_fit_2(25, 2);
New2(3) = Y_fit_2(25, 3);
New2(4) = Y_fit_2(25, 4);
```

Local minimum possible. Constraints satisfied.

fmincon stopped because the size of the current step is less than the value of the step size tolerance and constraints are

satisfied to within the value of the constraint tolerance.

Third Segment

```
t = 50;
    peak

seg3 = data(126:175, :);
fun3= @(x)siroutput(x,t,seg3);
params3 = [0 0 0 New2(1) New2(2) New2(3) New2(4)];
x3 = fmincon(fun3, x2, A, b, Af, bf, lb, ub);
Y_fit_3 = siroutput_full(x3, t);

New3(1) = Y_fit_3(50, 1);
New3(2) = Y_fit_3(50, 2);
New3(3) = Y_fit_3(50, 3);
New3(4) = Y_fit_3(50, 4);
```

Local minimum possible. Constraints satisfied.

Local minimum possible. Constraints satisfied.

fmincon stopped because the size of the current step is less than the value of the step size tolerance and constraints are satisfied to within the value of the constraint tolerance.

Fourth Segment

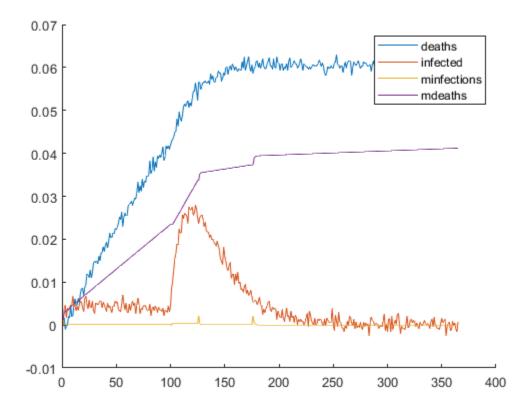
fmincon stopped because the size of the current step is less than the value of the step size tolerance and constraints are

satisfied to within the value of the constraint tolerance.

Plot

```
Y_fit = cat(1,Y_fit_1,Y_fit_2,Y_fit_3,Y_fit_4); % Put 3 fits together

diff1 = Y_fit(100,4) - Y_fit(101,4);
diff2 = Y_fit(126,4) - Y_fit(125,4);
```



Rob Sample

```
% %Model section for segment 1
% segment_1 = coviddata(1:100,:);
% funl= @(x)siroutput(x,100,segment_1);
% x1 = fmincon(fun1,x0,A,b,Af,bf,lb,ub);
% Y_fit_1 = siroutput_full(x1, 100);
%
% &determine new parameters for next segment
% New1(1) = Y_fit_1(100, 1);
% New1(2) = Y_fit_1(100, 2);
% New1(3) = Y_fit_1(100, 3);
% New1(4) = Y_fit_1(100, 4);
%
% *model section for segment 2 using new parameters
```

```
% segment_2 = coviddata(101:250, :);
% fun2= @(x)siroutput(x,150,segment_2);
% params2 = [0 0 0 New1(1) New1(2) New1(3) New1(4)];
% x2 = fmincon(fun2, params2, A, b, Af, bf, lb, ub);
% Y_fit_2 = siroutput_full(x2, 150);
```

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