

# Sedemac Hook

---

Development of a scalable prototype IoT (Internet of Things) system for automobiles

# Goal

---

The project involves construction (either from scratch or by integrating devices available off the shelf) of a system which can acquire CAN (controller area network) data from a SEDEMAC automobile ECU and transmit the same to a server at SEDEMAC (through GSM for example). The idea is to explore the possibilities that \*big data\* offers for automotive data.

# What exactly?

---

Logging CAN data from vehicles, analyzing the data and presenting the insights from data in such a way that is beneficial to automobile manufacturers

# PLAN

---

- 1) Convert CAN signals to some things we can understand
- 2) Send that understood data to a secure place
- 3) Saving data in a proper format to bridge efficiently between 2) and 4)
- 4) Presenting data and making it accessible (Data Analytics).

# Problem 1

---

Convert CAN signal to something you understand.

Sol: Connect the two CAN pins to an OBD port. Do some logic level shifts to the output of OBD port to make it Arduino understandable.  
You understand OBD signal format!

Problem 1.1 : No CAN Signal

—  
Sol : Emulator

# Peak CAN

---

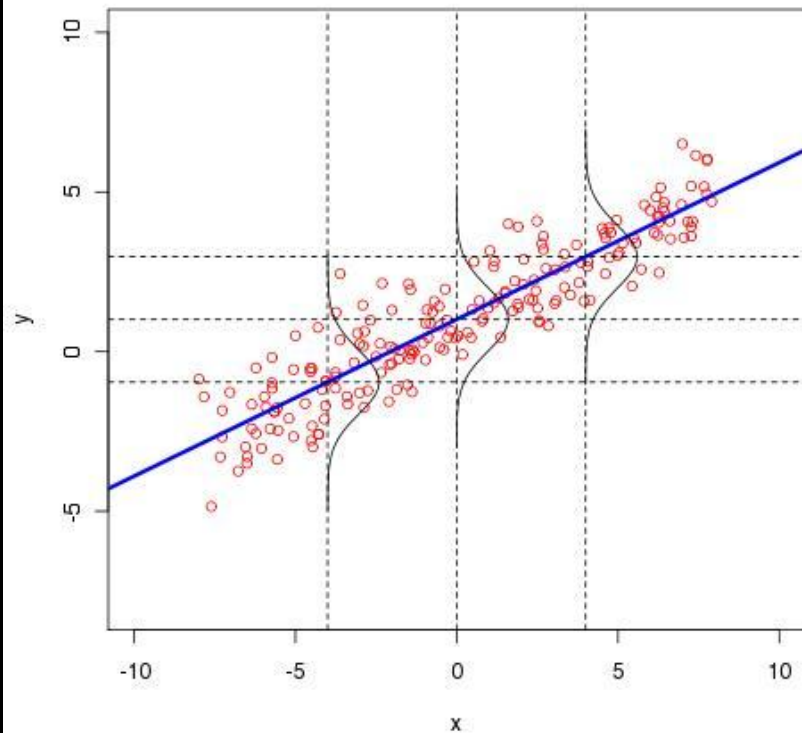


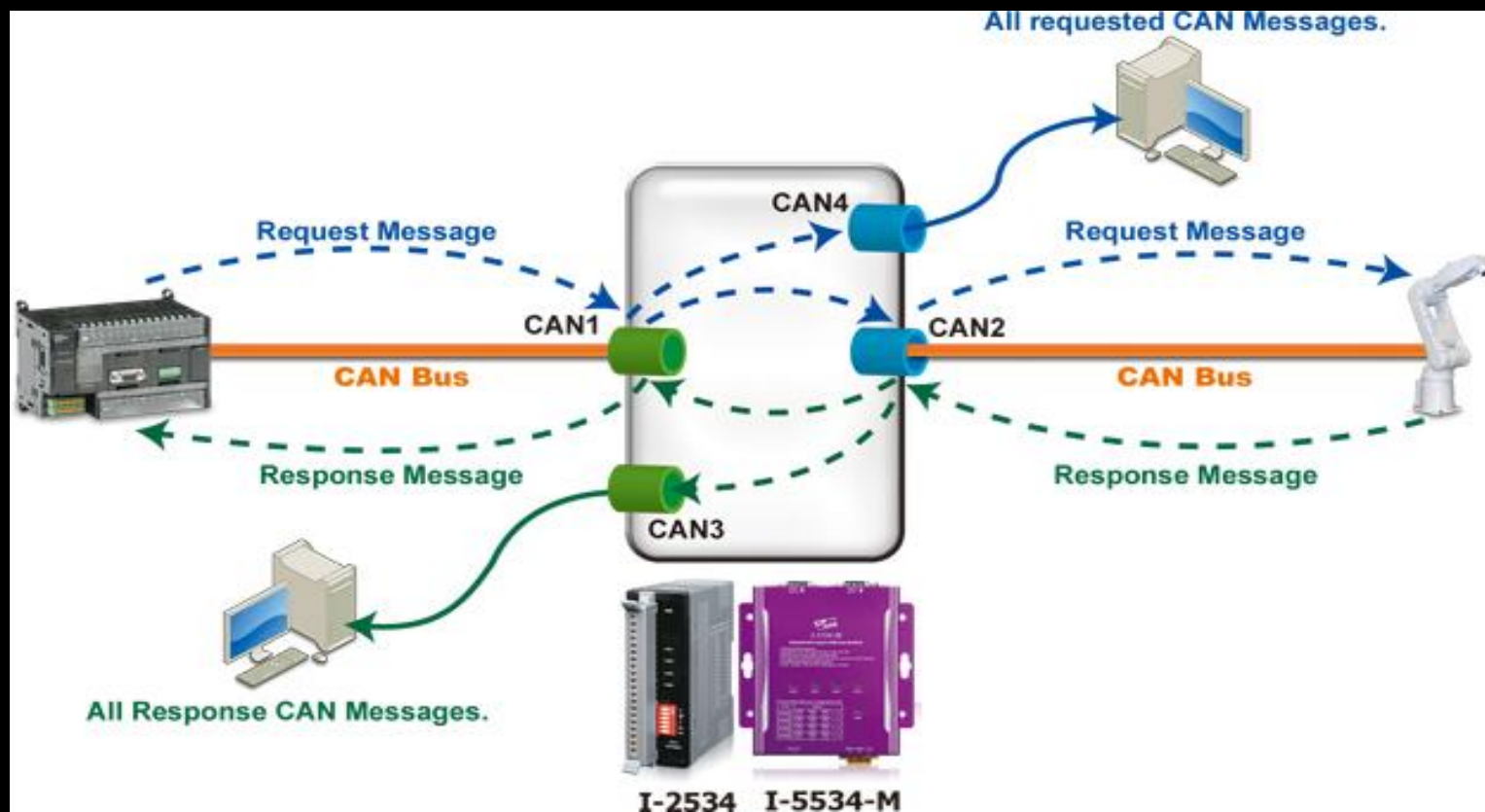




|

*Classical Linear Regression  
with Gaussian errors*





## OBD-II MESSAGE (response)

11

bit

64

bit

Identifier  
(e.g. 7E8)

#Bytes  
(e.g. 03)

Mode  
(e.g. 41)

PID  
(e.g. 0D)

Ah  
(e.g. 32)

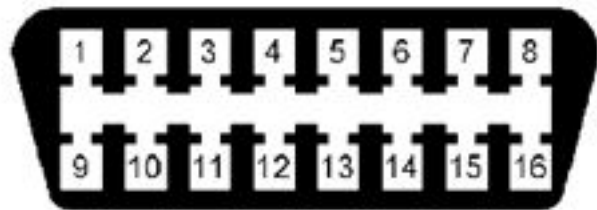
Bh  
(e.g. aa)

Ch  
(e.g. aa)

Dh  
(e.g. aa)

*Unused*  
(e.g. aa)

<http://www.csselectronics.com>



| PIN | DESCRIPTION       | PIN | DESCRIPTION       |
|-----|-------------------|-----|-------------------|
| 1   | Vendor Option     | 9   | Vendor Option     |
| 2   | J1850 Bus +       | 10  | J1850 Bus -       |
| 3   | Vendor Option     | 11  | Vendor Option     |
| 4   | Chassis Ground    | 12  | Vendor Option     |
| 5   | Signal Ground     | 13  | Vendor Option     |
| 6   | CAN (J-2234) High | 14  | CAN (J-2234) Low  |
| 7   | ISO 9141-2 K-Line | 15  | ISO 9141-2 L-Line |
| 8   | Vendor Option     | 16  | Battery Power     |

**OBD-II Connector and Pinout**

| DTC   | Description   | Domestic<br>RPC L82 |
|-------|---|---------------------|
| P0101 | Mass Air Flow (MAF) System Performance                                      | A                   |
| P0102 | Mass Air Flow (MAF) Sensor Circuit Low Frequency                            | A                   |
| P0103 | Mass Air Flow (MAF) Sensor Circuit High Frequency                           | A                   |
| P0107 | Manifold Absolute Pressure (MAP) Sensor Circuit Low Voltage                 | B                   |
| P0108 | Manifold Absolute Pressure (MAP) Sensor Circuit High Voltage                | B                   |
| P0112 | Intake Air Temperature (IAT) Sensor Circuit Low Voltage                     | B                   |
| P0113 | Intake Air Temperature (IAT) Sensor Circuit High Voltage                    | B                   |
| P0117 | Engine Coolant Temperature (ECT) Sensor Circuit Low Voltage                 | B                   |
| P0118 | Engine Coolant Temperature (ECT) Sensor Circuit High Voltage                | B                   |
| P0121 | Throttle Position (TP) System Performance                                   | A                   |
| P0122 | Throttle Position (TP) Sensor Circuit Low Voltage                           | A                   |
| P0123 | Throttle Position (TP) Sensor Circuit High Voltage                          | A                   |
| P0125 | Engine Coolant Temperature (ECT) Excessive Time to Closed Loop Fuel Control | B                   |
| P0131 | HO2S Circuit Low Voltage Sensor 1   | B                   |
| P0132 | HO2S Circuit High Voltage Sensor 1  | B                   |
| P0133 | HO2S Slow Response Sensor 1   | B                   |
| P0134 | HO2S Circuit Insufficient Activity Sensor 1                                 | B                   |
| P0135 | HO2S Heater Circuit Sensor 1  | B                   |
| P0137 | HO2S Circuit Low Voltage Sensor 2   | B                   |
| P0138 | HO2S Circuit High Voltage Sensor 2  | B                   |
| P0140 | HO2S Circuit Insufficient Activity Sensor 2                                 | B                   |
| P0141 | HO2S Heater Circuit Sensor 2  | B                   |
| P0171 | Fuel Trim System Lean   | B                   |
| P0172 | Fuel Trim System Rich   | B                   |
| P0201 | Injector 1 Control Circuit  | B                   |
| P0202 | Injector 2 Control Circuit  | B                   |
| P0203 | Injector 3 Control Circuit  | B                   |
| P0204 | Injector 4 Control Circuit  | B                   |
| P0205 | Injector 5 Control Circuit  | B                   |
| P0206 | Injector 6 Control Circuit  | B                   |
| P0230 | Fuel Pump Control Circuit   | D                   |
| P0300 | Engine Misfire Detected   | B                   |
| P0325 | Knock Sensor Circuit  | D                   |
| P0327 | Knock Sensor Circuit Bank 1   | D                   |
| P0336 | 18X Reference Signal  | B                   |
| P0341 | CMP Sensor Circuit Performance  | B                   |
| P0401 | EGR System Flow Insufficient  | A                   |

Problem 2 :

—

Reading & Sending Data.

# Solved

---



# Features:

- 
- 1) OBD port + GPS
  - 2) Arduino
  - 3) SIM800A
  - 4) SD card

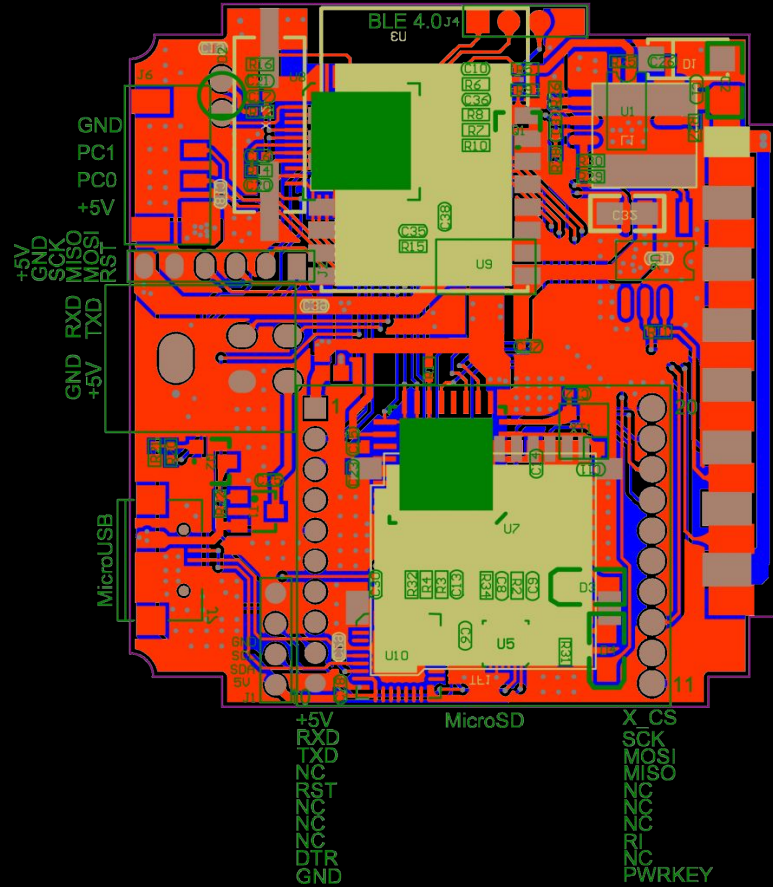
# Inside

---



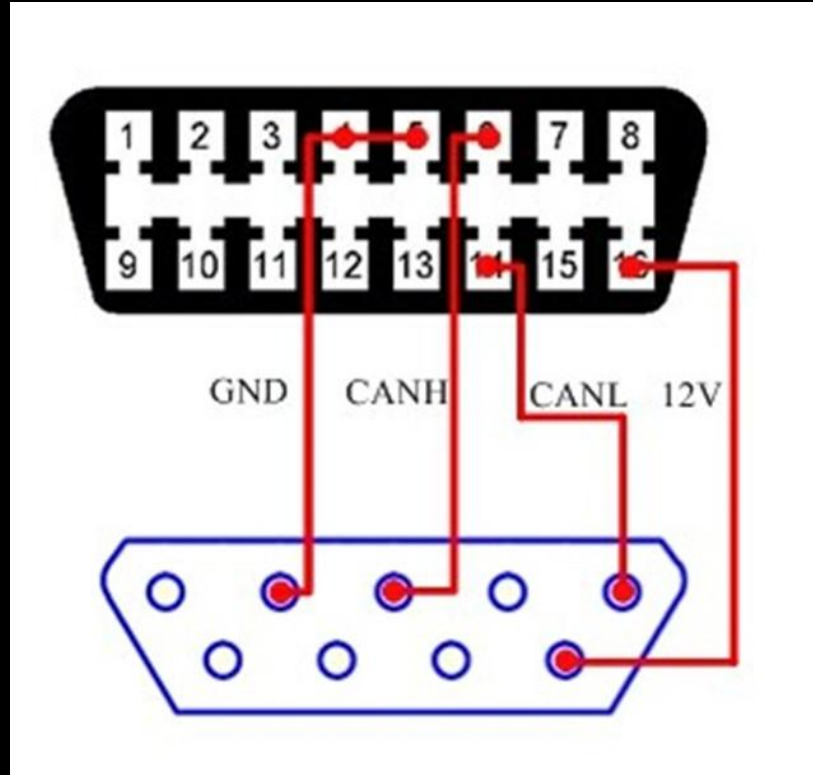


# Circuit

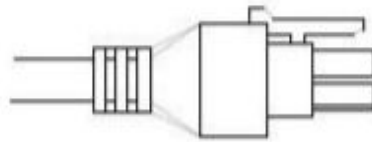


# Connections :

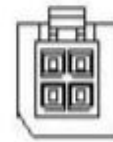
## 1) Read CAN



## 2) GPS



3 Vcc  
1 GND



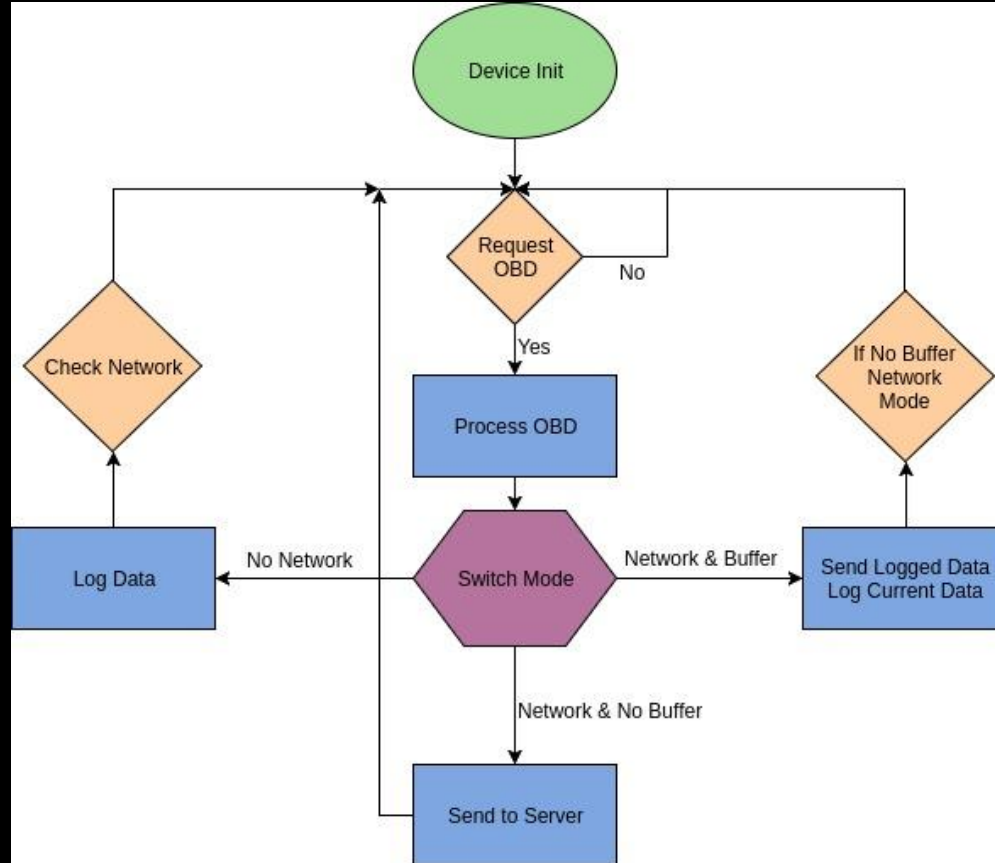
4 RXD  
2 TXD

Molex Connector

### 3) SIM & SD



# Algo : —



Complications :

—

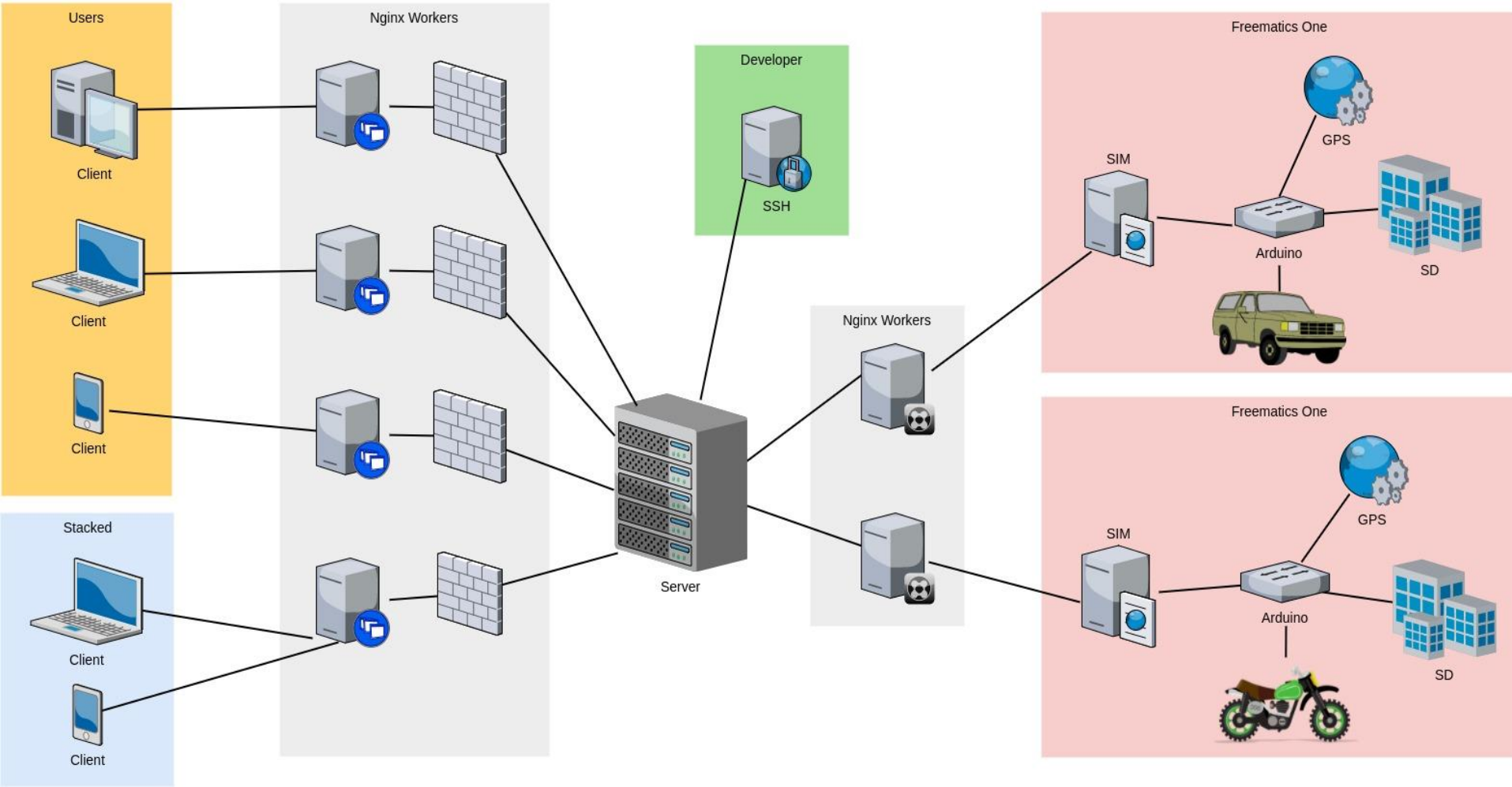
2kB dynamic memory.

SD card takes 512 bytes.

Device crashed.

GPS takes long to init.

# Project Architecture



# Server (Backend)

---

Objectives :-

- I. Scalable backend to accommodate ever increasing number of users
- II. Structured database for easier and quick SQL transactions
- III. API endpoints to serve multiple purposes
- IV. Easy development of frontend platforms over the backend
  - A. Web-Frontend
  - B. Mobile App
  - C. Customised Scripts for Data Analytics



# Server specifications (Backend)

---

- I. Digitalocean cloud server
- II. Nginx is used to deploy our Flask-App
- III. Server side is developed on Flask (a python based framework)
- IV. Database designed in postgresQL
- V. API endpoints developed to serve the required purposes

# Database Structure

---

## Aim

1. Easily understandable
2. Fast Query
3. Makes Data Analytics of individual as well as cumulative vehicles efficient

## Development so far

1. Separate table for individual vehicles to store raw data directly
2. Separate table to measure overall performance of vehicles
3. All the data transactions are done in JSON format which is easy to understand and access

# Objectives Achieved

---

1. Multiple devices : Nginx server with ability to handle multiple simultaneous requests is used to host our server
2. Fast Query : The database is structured in three layers for easier access and efficient data analytics
3. Data Analytics : API endpoints developed to serve data from database directly in JSON format for easy interpretation and custom scripts  
JSON Response Example: [http://139.59.38.17/data/<device\\_id>/details](http://139.59.38.17/data/<device_id>/details)
4. Python based Flask Framework is completely scalable

# Three Layers of Table

---

1. Primary Table :- Used to directly store raw data coming from device. Every device has it's own primary table named as DeviceID. For example Device1 and Device2
2. Secondary Table :- Used to store trip wise details of a particular vehicle. Will be helpful to analyse trip parameters like average trip distance or average trip speed. Every device will have its own secondary table named as device\_derivedID. For example device\_derived1, device\_derived2
3. Tertiary Table :- Used to store cumulative record of all the vehicles together. Will make overall analytics of all the vehicles much more simpler and efficient. Each device will have one row for it in this table.

# Data as sent by device

| —                 | Vehicle_1 | Vehicle_2 |
|-------------------|-----------|-----------|
| erpm              | 2100      | 3200      |
| engine_load       | 25        | 29        |
| Vehicle_speed     | 32        | 39        |
| Throttle_position | 25        | 45        |
| Runtime_crank     | 300       | 420       |
| Latitude          | 18.5204   | 18.7904   |
| Longitude         | 73.8567   | 73.9766   |
| Altitude          | 350       | 450       |
| data_time         | 12:10:34  | 12:10:45  |
| data_date         | 29/06/17  | 29/06/17  |
| New_data          | 1         | 0         |

# Primary Table

| Serial | erpm | engine_load | runtime | throttle_pos | latitude | longitude | altitude | speed | date     | time     |
|--------|------|-------------|---------|--------------|----------|-----------|----------|-------|----------|----------|
| 1      | 1200 | 23          | 460     | 33           | 18.2345  | 27.6789   | 540      | 43    | 29/06/17 | 13:10:00 |
| 2      | 1260 | 25          | 470     | 36           | 18.3012  | 27.7777   | 530      | 47    | 29/06/17 | 13:10:10 |
| 3      | 1300 | 29          | 480     | 41           | 18.3113  | 28.1234   | 550      | 49    | 29/06/17 | 13:10:20 |

Format in which Raw data is stored in Primary Table

# Secondary Table

| Serial | trip_duration<br>_____ | distance | avg_speed | avg_erpm | avg_load | latitude | longitude | altitude | start_time | date     | end_time |
|--------|------------------------|----------|-----------|----------|----------|----------|-----------|----------|------------|----------|----------|
| 1      | 00:50:00               | 10       | 460       | 2500     | 45       | 18.2345  | 27.6789   | 540      | 12:20:00   | 29/06/17 | 13:10:00 |
| 2      | 01:00:10               | 8        | 470       | 1900     | 34       | 18.3012  | 27.7777   | 530      | 12:10:00   | 29/06/17 | 13:10:10 |
| 3      | 00:23:00               | 25       | 480       | 3300     | 65       | 18.3113  | 28.1234   | 550      | 12:46:40   | 29/06/17 | 13:10:20 |

Format in which trip-wise details are stored in Secondary Table

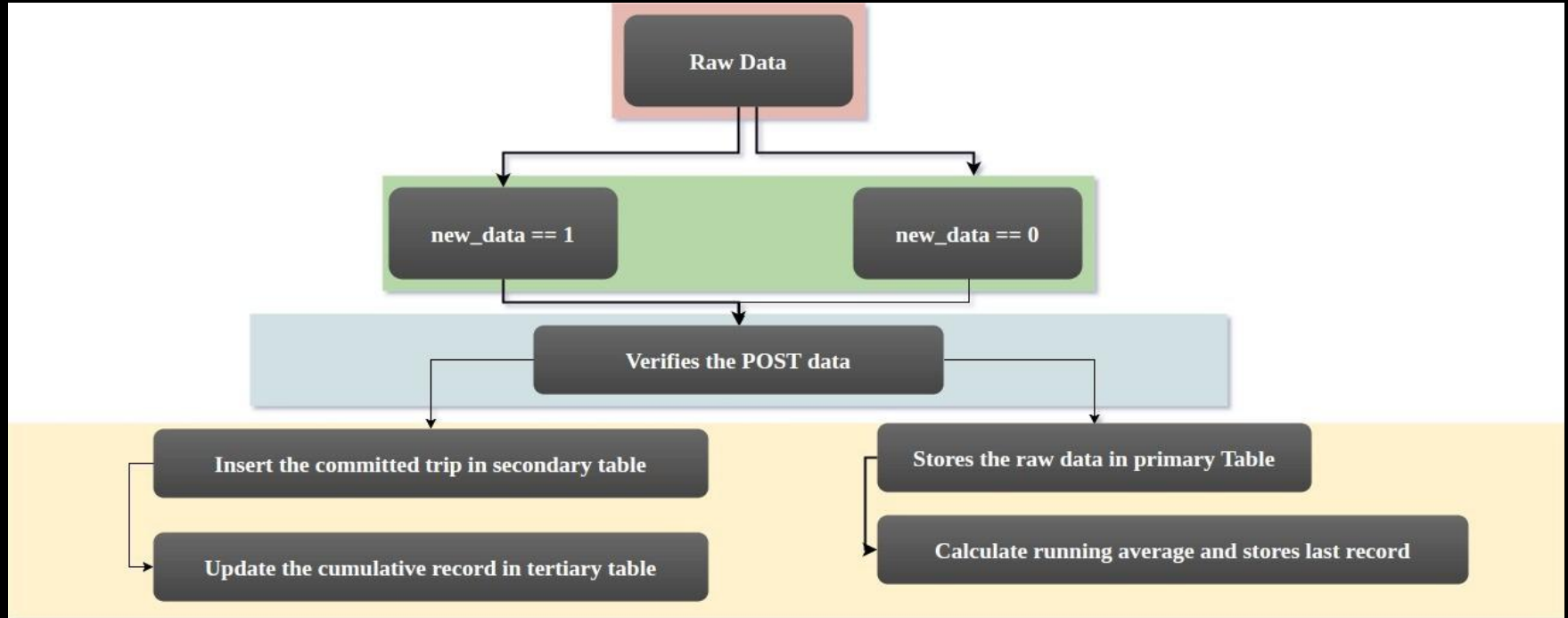
# Tertiary Table

| ID | <u>trips_no</u> | avg_durtn | avg_dist | avg_speed | avg_erpm | avg_load | avg_throttle | latitude | longitude | total_dist | total_duratn |
|----|-----------------|-----------|----------|-----------|----------|----------|--------------|----------|-----------|------------|--------------|
| 1  | 200             | 00:35:34  | 15       | 23        | 2500     | 45       | 32           | 18.2345  | 27.6789   | 3000       | 13:10:00     |
| 2  | 23              | 01:00:54  | 25       | 37        | 1900     | 34       | 41           | 18.3012  | 27.7777   | 575        | 13:10:10     |
| 3  | 134             | 02:01:41  | 33       | 41        | 3300     | 65       | 23           | 18.3113  | 28.1234   | 4422       | 13:10:20     |

Format in which cumulative records are stored in Tertiary Table



# Data Flow Map



# Server - API

Few examples :

---

Our URL : 139.59.38.17

API endpoint to fetch data :

139.59.38.17/data/<device\_id>/charts/<chart\_id>

API endpoint for location: http://139.59.38.17/data/location

API endpoint for last trip path : http://139.59.38.17/data/<device\_id>/trip/<trip\_id>

API endpoint to POST new data to server : 139.59.38.17/new

# Problem 4

---

Sol: 139.59.38.17

# Frontend

---

Phi-Matrix. Pixel Perfect.

Google Charts. Reliable.

Google Material Design. Responsive.

# Track

---

Login.

Location.

Raw Data.

Visualization.

# GITHUB

---

Github Repo : <https://github.com/krpratik/sedemac-iot.git>