California State University, Sacramento The College of Engineering and Computer Science

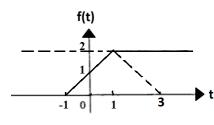
EEE 180 Signals & Systems

	Final Exam	
	Spring 2023	
Student Name:		

(1). T	he signal y is defined b	by: $y = \int_0^\infty \delta(t) dt$	then which answer
	below is correct?		
	A. y=1	B. $y = \omega$	C. y = u(t)
(2).	The discrete-time signa	1 y=2 cos(1.5 π k + $\frac{\pi}{2}$	$\frac{7}{4}$) is periodic. Which N value
ł	below can be used as the	ne period of y?	
	A. N=1	B. N=2	C. $N = 4$
(3). A	bounded-input and bo	unded-output system i	s called a system.
	A. Causal	B. Stable	C. Linear
(4).		signal y=2 cos(6 π t will the aliasing proble	$+\frac{\pi}{4}$). When the sampling
	A. Yes	B. No	
(5).			$\sin(t)$ and $y2 = \sin(t) / t$.
	Are they even or odd	signals?	
	A. y1: even, y2: ev B. y1: even, y2: oc		C. y1: odd, y2: even D. y1: odd, y2: odd
(6).	The unilateral Laplac	the transform of $\delta(t)$ is	
	D. 1 B. 0	C. π/2 D.	None of above
(7).		ned by the following eq = $x(t)$. Is this a linear	
	A. Yes	B. No	

1.[24 points] Select one correct answer for Each of the following questions. Each question below has only one correct answer.

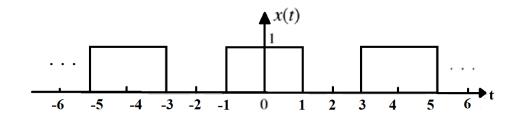
(8). The solid line below shows the waveform for f(t). What is the signal in the dashed line?



A. f(-t)

- B. f(-t+2)
- C. f(-t-2)

- 2.[36 points]
- (1). Find the Exponential Fourier Series of the following periodic signal with a period of 4.



(2). Find the energy of the following signal:

$$x(t) = e^{-5t}u(t),$$

(3). Find the Fourier Transform of the following signal:

$$x(t) = e^{-5t}u(t)$$

(4). Find the z-transform of the sequence $x[n] = (0.2)^n u[n]$, and determine the region of convergence.

(1). Suppose the unilateral z-transform of f(t) is F(z), and the ROC is |z| > 20.

$$F(z) = \frac{z}{(z-10)(z-20)}$$
 . Find the f(t) signal equation.

The unilateral z-transform pair table is given below.

Unilate	ral z-transform Pair T	able
	f[k]	F[z]
1	$\delta[k-j]$	z^{-j}
2	u[k]	$\frac{z}{z-1}$
3	ku[k]	$\frac{z}{(z-1)^2}$
4	$k^2u[k]$	$\frac{z(z+1)}{(z-1)^3}$
5	$k^3u[k]$	$\frac{z(z^2+4z+1)}{(z-1)^4}$
6	$\gamma^{k-1}u[k-1]$	$\frac{1}{z-\gamma}$

(2). The discrete time input signal $x[k] = \, \delta[k] + 2\delta[k-2] + 2\,\delta[k-3]$

The discrete time signal system impulse response signal

$$h[k] = u[k] - u[k-2]$$

Draw the waveforms of x[k] and h[k].

(3). For the above question (3), the system output response signal is defined as the convolution result of y[k] = x[k] * h[k]. Find the values of y[k].

(4). For an LTIC system described by the transfer function

$$H(s) = \frac{s + 0.5}{s + 1}$$

Find the steady-state system response y(t) to the input signal of f(t) = 2 u(t).