

# CALIFORNIA STATE UNIVERSITY SACRAMENTO



DEPARTMENT OF ELECTRICAL AND ELECTRONIC ENGINEERING

## **EEE 117 Network Analysis**

**Text:** Electric Circuits by J. Nilsson and S. Riedel Prentice Hall

**Lecture Set 2: Sinusoidal Steady State Power Analysis**

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## *Sinusoidal Steady-State Power Analysis*

- Instantaneous Power
- Average, Active or Real power
- Reactive power
- Apparent Power
- Complex Power
- Effective Power
- Power factor and reactive factor
- Power for Circuit elements
- Maximum Power Transfer
- Mutual Inductance
- Transformer
- Ideal Transformer

## Instantaneous Power

- Instantaneous power is the power at any one moment.

Let's say at any instance "t"

$$v(t) = V_m \cos(\omega t + \Theta_v) \quad \text{and} \quad i(t) = I_m \cos(\omega t + \Theta_i)$$

$\Theta_v$  = phase angle of voltage

$\Theta_i$  = phase angle of current

- Instantaneous power  $p(t)$  can be defined as:

$$p(t) = V_m \cos(\omega t + \Theta_v) * I_m \cos(\omega t + \Theta_i)$$

After using the trig. identities, we get

$$p = \frac{V_m I_m}{2} \cos(\theta_v - \theta_i) + \frac{V_m I_m}{2} \cos(\theta_v - \theta_i) \cos(2\omega t) - \frac{V_m I_m}{2} \sin(\theta_v - \theta_i) \sin(2\omega t)$$

EQ-1

### Derivation of eq-1:

$$p = vi = V_m \cos(\omega t + \theta_v) I_m \cos(\omega t + \theta_i)$$

$$p = V_m \cos(\omega t + \theta_v - \theta_i) I_m \cos(\omega t + \theta_i - \theta_i)$$

$$= V_m \cos(\omega t + \theta_v - \theta_i) I_m \cos(\omega t)$$

$$= V_m I_m \cos(\omega t + \theta_v - \theta_i) \cos(\omega t)$$

Now use a trig identity

$$\cos \alpha \cos \beta = \frac{1}{2} \cos(\alpha - \beta) + \frac{1}{2} \cos(\alpha + \beta)$$

And we get

$$p = V_m I_m \left[ \frac{1}{2} \cos \left( \underbrace{\omega t + \theta_v - \theta_i}_{\alpha} - \underbrace{\omega t}_{\beta} \right) + \frac{1}{2} \cos \left( \underbrace{\omega t + \theta_v - \theta_i}_{\alpha} + \underbrace{\omega t}_{\beta} \right) \right]$$

$$= \frac{V_m I_m}{2} \cos(\theta_v - \theta_i) + \frac{V_m I_m}{2} \cos(2\omega t + \theta_v - \theta_i)$$

We will again use another trig identity to simplify the 2<sup>nd</sup> term.

$$\cos(\alpha + \beta) = \cos \alpha \cos \beta - \sin \alpha \sin \beta$$

$$p = \underbrace{\frac{V_m I_m}{2} \cos(\theta_v - \theta_i)}_{P_{avg} = p \text{ at DC}} + \underbrace{\frac{V_m I_m}{2} \cos(\underbrace{\theta_v - \theta_i}_{\alpha}) \cos(\underbrace{2\omega t}_{\beta})}_{p \text{ at } 2\omega} - \underbrace{\frac{V_m I_m}{2} \sin(\underbrace{\theta_v - \theta_i}_{\alpha}) \sin(\underbrace{2\omega t}_{\beta})}_{\text{Reactive power from C or L}}$$

### **Some observations:**

- First term is always less than  $V \cdot I$  because of  $\cos \Phi$ .
- First term is fixed and does not depend on time.
- 2<sup>nd</sup> and 3<sup>rd</sup> terms can go up to  $V \cdot I$  and also  $-V \cdot I$ .
- Resultant can also be a negative value.
- Eq.1 has three terms and can be rewritten as

$$p(t) = P + P \cos(2\omega t) - Q \sin(2\omega t)$$

- “P” is called average, real, true or active power measured in watts.
- “Q” is called reactive power measured in VAR.
- First term is non oscillating while 2<sup>nd</sup> and 3<sup>rd</sup> terms are oscillating.

## Average, Real, True or Active power

“P” is called average, real, true or active power measured in watts.

$$P_{\text{avg}} = \frac{V_m I_m}{2} \cos(\theta_v - \theta_i)$$

Take the average of the equation 1.

First term is non oscillating while 2<sup>nd</sup> and 3<sup>rd</sup> terms are oscillating.

$$P_{\text{avg}} = \frac{1}{T} \int_0^T p(t) dt \quad \text{Since area under oscillating terms} = 0$$

$$\begin{aligned} P_{\text{avg}} &= \frac{1}{T} \int_0^T \left( \frac{V_m I_m}{2} \right) \cos(\theta_v - \theta_i) dt \\ &= (V_m I_m / 2) \cos(\theta_v - \theta_i) \times \frac{1}{T} \int_0^T dt \end{aligned}$$

$$P_{\text{avg}} = (V_m I_m / 2) \cos(\theta_v - \theta_i) \times \frac{1}{T} \times T$$

$$P_{\text{avg}} = (V_m I_m / 2) \cos(\theta_v - \theta_i) = V_{\text{rms}} I_{\text{rms}} \cos(\theta_v - \theta_i)$$

*It is called:*

- *Average power:* Because it is the average of all the instantaneous values in one time period and is defined as the average power delivered to a circuit.
- *Real power:* Because it is the power which cause the energy to flow. This is the power which is generated, transmitted, distributed and consumed.
- *True power:* Because this is the power which actually exists in the system.
- *Active power:* because this is the power which do the work.



## Reactive Power

- In equation 1, “Q” is called Reactive power measured in VAR (volt-ampere-reactive)

$$Q = \frac{V_m I_m}{2} \sin(\theta_v - \theta_i) = V_{\text{rms}} I_{\text{rms}} \sin(\theta_v - \theta_i)$$

- Reactive power comes from apparent and real power.
- Reactive power is just a hypothetical term, an imaginary quantity, does not actually exist and used only for mathematical reason.
- If the consumed reactive power (Q) is positive, then the load is inductive. If the consumed reactive power (Q) is negative, then the load is capacitive.

## Complex Power

- Complex power is the complex sum of real and reactive power measured in Volt-Ampere (VA).
- Complex power is a complex number where its real and imaginary parts determine the active and reactive powers consumed by the load, respectively. Complex power is given as

$$S = P + jQ$$

- Real part of the complex power is real power

$$\text{Re} \{ S \} = P = \frac{V_m I_m}{2} \cos(\theta_v - \theta_i)$$

- Imaginary part of the complex power is reactive power.

$$\text{Im} \{ S \} = Q = \frac{V_m I_m}{2} \sin(\theta_v - \theta_i)$$

- The magnitude of the complex power is given as:

$$S = |S| = \sqrt{P^2 + Q^2} \quad \Theta = \tan^{-1} \left( \frac{Q}{P} \right)$$

- Consider the equation of complex power:

$$S = P + jQ$$

$$S = \frac{V_m I_m}{2} \cos(\theta_v - \theta_i) + j \frac{V_m I_m}{2} \sin(\theta_v - \theta_i)$$

$$= \frac{V_m I_m}{2} [\cos(\theta_v - \theta_i) + j \sin(\theta_v - \theta_i)]$$

$$S = \frac{V_m I_m}{2} [\cos(\theta_v - \theta_i) + j \sin(\theta_v - \theta_i)]$$

$$S = \frac{V_m I_m}{2} e^{j(\theta_v - \theta_i)} = V_{eff} e^{j\theta_v} I_{eff} e^{-j\theta_i}$$

$$S = V_{eff} I_{eff}^*$$

Where \* indicates the complex conjugate of the angle.

- In terms of the maximum voltage ( $V_m$ ) and current ( $I_m$ )

$$S = \frac{1}{2} V I^*$$

- and in terms of the rms voltage ( $V_{rms}$ ) and current ( $I_{rms}$ )

$$S = V I^*$$

## Apparent Power

- The magnitude of the complex power is called apparent power

$$|S| = \sqrt{P^2 + Q^2} \quad \Theta = \tan^{-1} \left( \frac{Q}{P} \right)$$

$$P = |S| \cos \theta$$

$$Q = |S| \sin \theta$$

- It is the power that we expect would exist in the system, measured in volt-ampere (VA) and denoted by  $|S|$ .
- BUT note, the power actually exist in the system is always real power.
- Apparent power  $>$  real power
- OR real power  $<$  apparent power
- It means system is under-utilized.
- This leads us to the concept of power factor.

## Power factor and Reactive factor

- Power factor is the fraction of system capability that can be actually utilized.
- Total power of the system is  $V_{\text{rms}} I_{\text{rms}}$
- Useful power is  $V_{\text{rms}} I_{\text{rms}} \cos(\Theta_v - \Theta_i)$

$$\text{pf} = \frac{V_{\text{rms}} I_{\text{rms}} \cos(\Theta_v - \Theta_i)}{V_{\text{rms}} I_{\text{rms}}} = \frac{\text{active power}}{\text{apparent power}} = \frac{P}{S} = \cos(\Theta_v - \Theta_i)$$

- Ideal value of  $\text{pf} = 1$  and practically cannot be achieved.
- The phase angle between the voltage and current is called the power factor angle.
- The sinusoidal power factor (pf) is defined as

$$\text{pf} = \cos(\theta_v - \theta_i)$$

- Since  $\cos(+\Theta) = \cos(-\Theta)$ , we need to add the term lagging to the power factor for an inductive load where current lags the voltage.
- We add the term leading to the power factor for a capacitive load where current leads the voltage.
- The sinusoidal reactive factor is defined as

$$rf = \sin(\theta_v - \theta_i)$$

## Power in Circuit elements

### Power in purely resistive circuit:

$$p = \frac{V_m I_m}{2} \cos(\theta_v - \theta_i) + \frac{V_m I_m}{2} \cos(\theta_v - \theta_i) \cos(2\omega t) - \frac{V_m I_m}{2} \sin(\theta_v - \theta_i) \sin(2\omega t)$$

- For resistors, voltage and currents are in phase.

$$\theta_v - \theta_i = 0$$

- So, for a resistor (which can only absorb power “+”), we have the instantaneous power as

$$p = P_{avg} + P_{avg} \cos(2\omega t)$$

Since total of 2<sup>nd</sup> part is zero

$$p(t) = \frac{V_m I_m}{2} = V_{rms} I_{rms}$$

$$\text{Active Power} = \frac{V_m I_m}{2} = V_{rms} I_{rms}$$

### Power in purely Inductive circuit:

$$p = \frac{V_m I_m}{2} \cos(\theta_v - \theta_i) + \frac{V_m I_m}{2} \cos(\theta_v - \theta_i) \cos(2\omega t) - \frac{V_m I_m}{2} \sin(\theta_v - \theta_i) \sin(2\omega t)$$

- For inductor, voltage leads currents by  $90^\circ$

$$\theta_v - \theta_i = +90^\circ$$

$$p(t) = - \frac{V_m I_m}{2} \sin(2\omega t)$$

- which is a sinusoidal function with frequency twice of supply.

$$p(t) = 0$$

- So, an ideal inductor does not dissipate real power but only stores or delivers reactive power as required by the circuit.
- Inductors demand (absorb) magnetizing VARs.



### Power in purely capacitive circuit:

$$p = \frac{V_m I_m}{2} \cos(\theta_v - \theta_i) + \frac{V_m I_m}{2} \cos(\theta_v - \theta_i) \cos(2\omega t) - \frac{V_m I_m}{2} \sin(\theta_v - \theta_i) \sin(2\omega t)$$

- For capacitor, voltage lags currents by  $90^\circ$

$$\theta_v - \theta_i = -90^\circ$$

$$p(t) = - \frac{V_m I_m}{2} \sin(2\omega t)$$

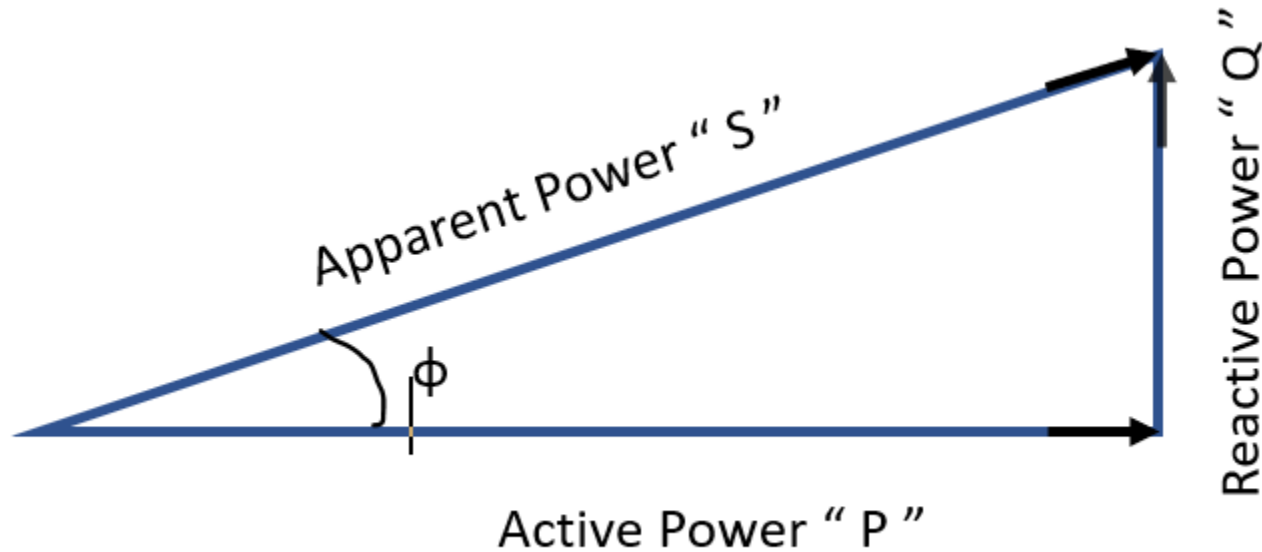
- which is a sinusoidal function with frequency twice of supply.

$$p(t) = 0$$

- So, an ideal capacitor does not dissipate real power but only stores or delivers reactive power as required by the circuit.
- Capacitors furnish (deliver) magnetizing VARs.

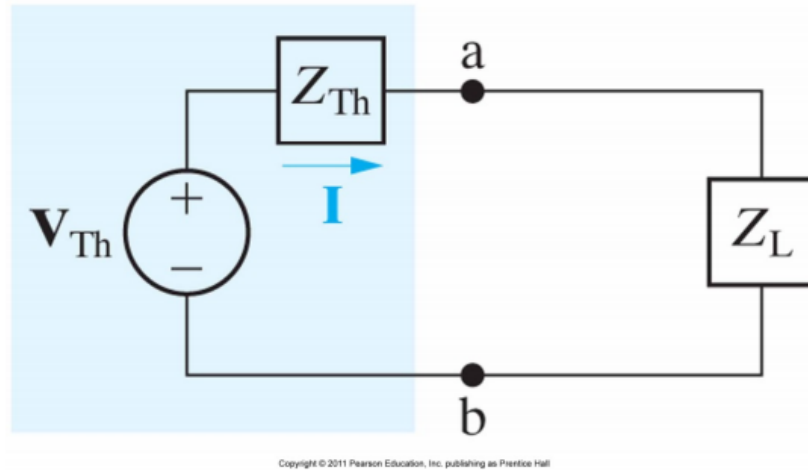
## Power Triangle

**Power Triangle:** Power triangle is a pictorial method to represent and calculate the powers in the system.



## Maximum Power Transfer

- Maximum power is transferred to a load when the load resistance equals the Thévenin resistance of the source.



$$R_{load} \equiv R_{Th}$$

- In the complex case, we must “cancel out” the reactive components.

$$Z_{load} \equiv Z_{Th}^*$$

- Thus

$$P_{\max} = \frac{|V_{Th}|^2 R_L}{4R_L^2} = \frac{|V_{Th}|^2}{4R_L}$$

- If  $V_{Th}$  is expressed in terms of the maximum voltage  $V_m$  rather than rms values then

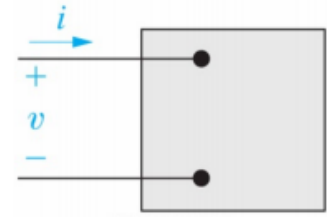
$$P_{\max} = \frac{V_m^2}{8R_L}$$

- What about the case when the load cannot be fully manipulated by varying both  $R_L$  and  $X_L$  but the magnitude can be adjusted?
- Then the closest approach to maximum power is when the magnitudes of the load and the Thévenin equivalent are made equal.

$$|Z_L| = |Z_{Th}|$$

## Examples

**Ex-1:** If  $v = 100 \cos(\omega t + 15^\circ)$  V and  
 $i = 4 \sin(\omega t - 15^\circ)$  A then



- a) Calculate the power factor.
- b) Calculate the active power.
- c) Calculate the reactive power.

$$v = 100 \cos(\omega t + 15^\circ) = 100 \text{ L } 15^\circ \text{ V}$$

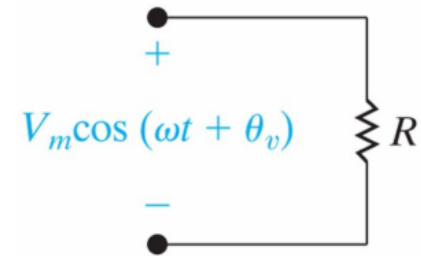
$$i = 4 \sin(\omega t - 15^\circ) = 4 \cos(\omega t - 15^\circ - 90^\circ) \text{ A}$$

$$i = 4 \cos(\omega t - 105^\circ) = 4 \text{ L } -105^\circ \text{ A}$$

- a) Power factor (pf) =  $\cos[15 - (-105)] = -0.5$
- b)  $P = \frac{1}{2} * 100 * 2 * \cos[15 - (-105)] = -100 \text{ W}$  (-ve, Delivering)
- c)  $Q = \frac{1}{2} * 100 * 2 * \sin[15 - (-105)] = 173.21 \text{ VAR}$  (+ve, Absorbing)

**-100 mean its delivering the active power instead of absorbing.**

**Ex-2:** If  $v = 625 \cos(\omega t)$  V and  
 $R = 50 \Omega$  then



Find the average power delivered to the resistor.

$$v = 625 \cos(\omega t) = 625 \mathbf{L} 0^\circ \text{ V}$$

$$R = 50 \mathbf{L} 0^\circ$$

$$i = \frac{v}{R} = \frac{625 \mathbf{L} 0}{50 \mathbf{L} 0} = 12.5 \mathbf{L} 0^\circ \text{ A}$$

$$P = \frac{1}{2} * 625 * 12.5 * \cos[0-0] = 3906.25 \text{ W}$$

**Ex-3:** An electrical load operates at 240 V<sub>rms</sub>. The load absorbs an average power of 8 kW at a lagging power factor of 0.8

- Calculate the complex power of the load.

pf = 0.8 lagging  $\implies$  so load is inductive.

pf = Cos  $\Theta$  = 0.8  $\implies \Theta = 36.87^\circ \implies \text{Sin}\Theta = 0.6$

$$P = 8 \text{ kW} = 8000 \text{ W}$$

We know:  $P = |S| \text{ Cos } \Theta = |S| * \text{pf}$  So

$$|S| = \frac{P}{\text{pf}} = \frac{8000}{0.8} = 10000 \text{ VA} = 10 \text{ kV}$$

$$Q = |S| \sin \Theta = 10000 * 0.6 = 6000 \text{ VAR} = 6 \text{ KVAR}$$

$$\overline{S} = 8000 + j6000 = 10 \angle 36.87^\circ \text{ VA}$$

**Ex-4:** If  $v = 100 \cos(\omega t + 15^\circ)$  V and

$i = 4 \cos(\omega t - 105^\circ)$  A then

- Calculate the complex power using phasor form.

$$v = 100 \cos(\omega t + 15^\circ) = 100 \angle 15^\circ \text{ V}$$

$$i = 4 \cos(\omega t - 105^\circ) = 4 \angle -105^\circ \text{ A}$$

$$i^* = 4 \angle 105^\circ \text{ A}$$

$$\overline{S} = \frac{1}{2} VI^* = \frac{1}{2} (100 \angle 15^\circ) (4 \angle -105^\circ) \text{ VA}$$

$$\overline{S} = 200 \angle 120^\circ = -100 + j173.2 \text{ VA}$$



**Ex-5:** A single-phase load with an impedance of  $Z = 1.25 \angle 60^\circ \Omega$  is connected to a sinusoidal source with  $v(t) = 100 \cos(\omega t)$ .

Determine:

- a) The instantaneous current  $i(t)$  and
- b) The instantaneous power  $p(t)$
- c) The power for  $\omega t = 0$  and  $\omega t = 2\pi$

$$v(t) = 100 \cos(\omega t) = 100 \angle 0^\circ \text{ V}$$

$$Z = 1.25 \angle 60^\circ \Omega$$

$$i(t) = \frac{v}{Z} = \frac{100 \angle 0}{1.25 \angle 60} = 80 \angle -60^\circ = 80 \cos(\omega t - 60^\circ)$$

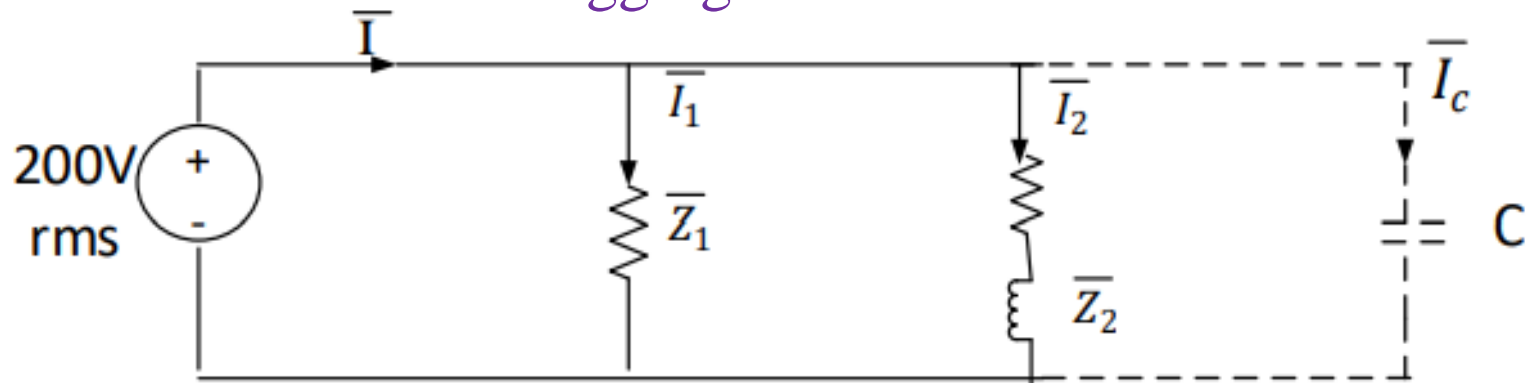
$$p(t) = v(t) i(t) = [100 \cos(\omega t)] \times [80 \cos(\omega t - 60^\circ)]$$

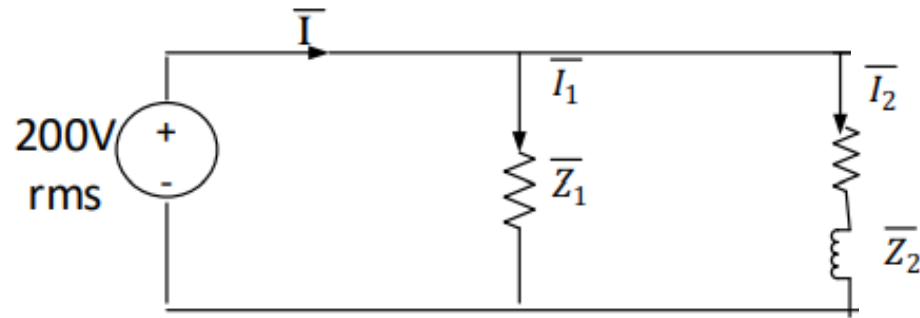
$$p(t) = [2000(1 + \cos 2\omega t)] + [2000\sqrt{3} \sin(2\omega t)]$$

$$p(\omega=0) = 4000 \text{ VA} \qquad p(\omega=2\pi) = 4000 \text{ VA}$$

**Ex-6:** The following figure shows two parallel single-phase loads connected to a source. The first load has a resistance of  $100\ \Omega$  and the second load has an impedance of  $10 + j20\ \Omega$ . Determine:

- The total active and reactive power generated by the source.
- The power factor at the source.
- The total current  $I$ .
- Assuming the same active power consumption found in (a), derive the amount of capacitance  $C$  needed to improve the power factor at the source to 0.8 lagging.





$$V_{rms} = 200 \angle 0^\circ$$

$$\mathbf{Z}_1 = 100 + j0 = 100 \angle 0^\circ \, \Omega$$

$$\mathbf{Z}_2 = 10 + j20 = 22.36 \angle 63.43^\circ \, \Omega$$

$$\mathbf{I}_1 = \frac{v}{z_1} = \frac{200 \angle 0^\circ}{100 \angle 0^\circ} = 2 \angle 0^\circ = 2 + j0$$

$$\mathbf{I}_1^* = 2 \angle 0^\circ = 2 - j0$$

$$\mathbf{I}_2 = \frac{v}{z_2} = \frac{200 \angle 0^\circ}{22.36 \angle 63.43^\circ} = 8.944 \angle -63.43^\circ = 4 - j8$$

$$\mathbf{I}_2^* = 8.944 \angle 63.43^\circ = 4 + j8$$

$$S_1 = VI_1^* = (200 \angle 0^\circ) (2 \angle 0^\circ) = 400 \angle 0^\circ = 400 + j0 \text{ VA}$$

$$S_2 = VI_2^* = (200 \angle 0^\circ) (8.944 \angle -63.43^\circ) = 1788.8 \angle -63.43^\circ = 800 - j1600 \text{ VA}$$

$$S = S_1 + S_2 = (400 + j0) + (800 - j1600) \text{ VA}$$

$$S = 1200 + j1600 = 2000 \angle 53.13^\circ \text{ VA}$$

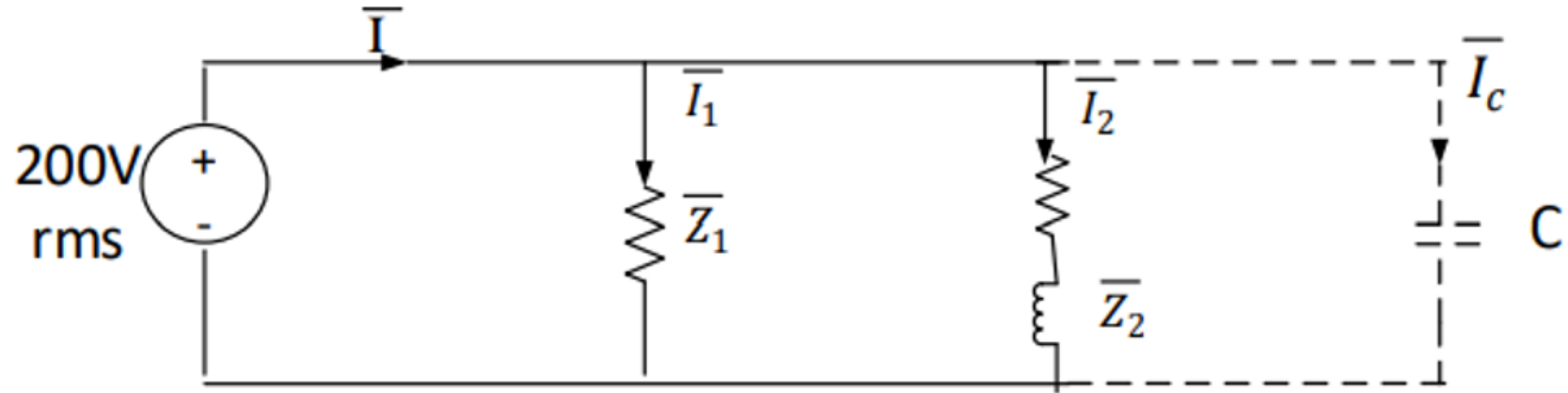
a)  $\text{So, } P = 1200 \text{ att and } Q = 1600 \text{ VAR}$

b)  $\text{Power factor (pf)} = \cos \theta = \cos (53.13^\circ) = 0.6$

$$I = I_1 + I_2 = (2 + j0) + (4 - j8) \text{ VA}$$

c)  $I = 6 - j8 = 10 \angle -53.13^\circ \text{ VA}$

d)



$$pf = \cos \theta = 0.8 \implies \theta = 36.87^\circ \implies \sin \theta = 0.6$$

$$P = 1200$$

We know:  $P = |S| \cos \theta = |S| \times pf$  So

$$|S| = \frac{P}{pf} = \frac{1200}{0.8} = 1500 \text{ VA}$$

$$Q = |S| \sin \theta = 1500 * 0.6 = 900 \text{ VAR}$$

Note Q has been reduced from 1600 to 900 VAR.

so

$$\text{Compensated } Q_c = 1600 - 900 = 700 \text{ VAR}$$

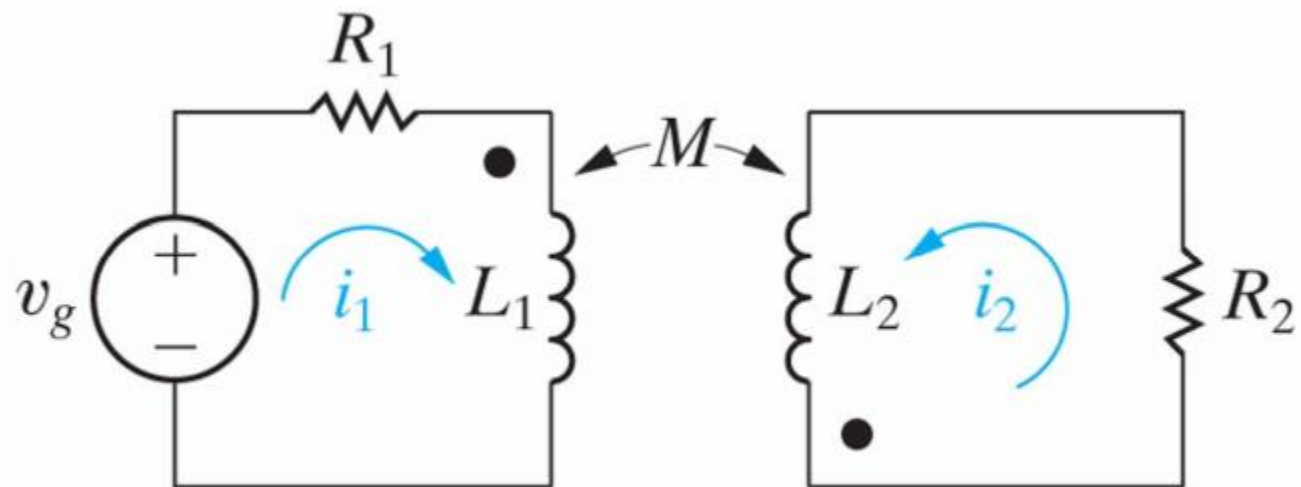
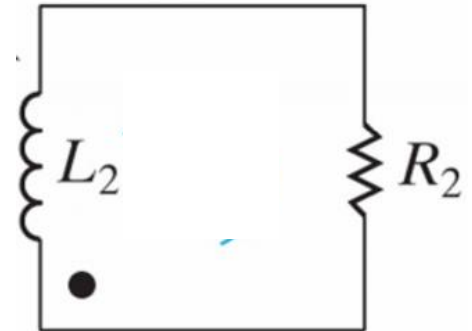
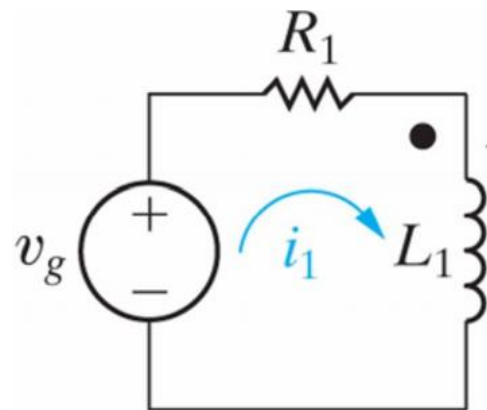
$$X_c = V^2 / Q_c = (200)^2 / 700 = 57.14 \, \Omega$$

$$\frac{1}{2\pi f C} = 57.14 \implies C = \frac{1}{2\pi(60)(57.14)} = 46.42 \, \mu\text{F}$$

Note: Assuming  $f=60 \text{ Hz}$

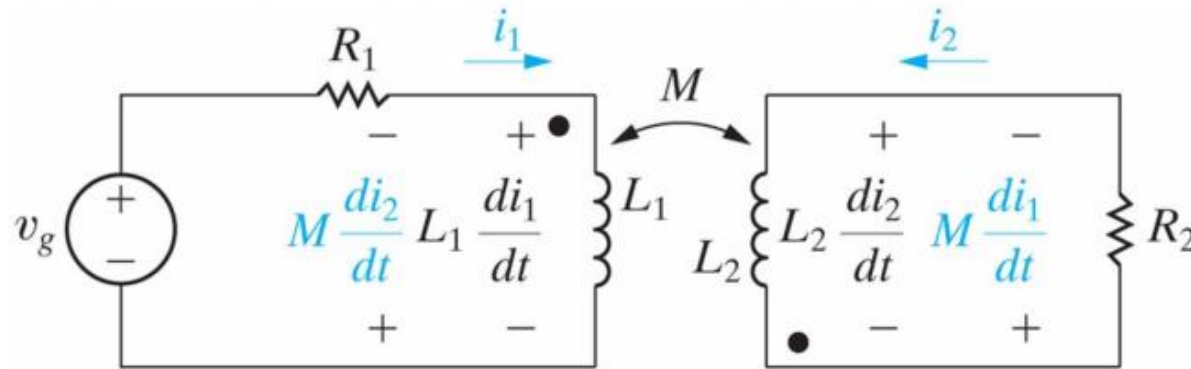
## Mutual Inductance

- We previously looked at the effect of a moving charge (current) creating a magnetic field which is called inductance and since the effect was the current in a single circuit, it should be properly called **self-inductance**.
- Here in this section, we will investigate the situation where the magnetic field created by a time varying current in one circuit is linked with the other circuit and induce voltage. This phenomenon is known as **mutual inductance**.
- The polarity of mutually induced voltage depends on the way the coils are wound in relation to the reference direction of coil currents.
- Dots are placed on the terminals to carry the polarity information schematically (rather than knowing righty or lefty directions).
- Hence for mutual inductance, we also rely on the dot convention. we will discuss it later in following section.





- Let's analyze the following mutual inductance circuit.



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KVL on the left hand side gives us

$$-v_g + i_1 R_1 + L_1 \frac{di_1}{dt} - M \frac{di_2}{dt} = 0$$

**Note:**  $M_{12} = M_{21}$

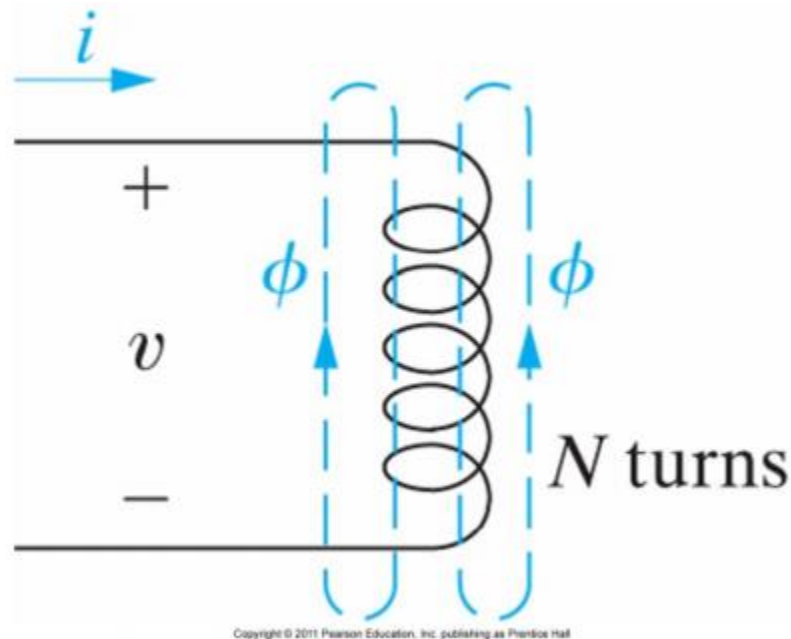
KVL on the right hand side gives us

$$-L_2 \frac{di_2}{dt} - i_2 R_2 + M \frac{di_1}{dt} = 0$$

Or equally (multiply last result by -1)

$$L_2 \frac{di_2}{dt} + i_2 R_2 - M \frac{di_1}{dt} = 0$$

The voltage induced by the magnetic field surrounding a current carrying conductor is described by Faraday's Law:



$$\begin{aligned}
 v &= \frac{d\lambda}{dt} = \frac{d(N\phi)}{dt} \\
 &= N \frac{d\phi}{dt} = N \frac{d}{dt}(\mathcal{P}Ni) \\
 &= N^2 \mathcal{P} \frac{di}{dt} = L \frac{di}{dt},
 \end{aligned}$$

- Where  $\lambda$  is called the magnetic flux linkage – measured in weber-turns.
- The flux linkage  $\lambda$  is the product of the magnetic field ( $\phi$ ) and the number of turns linked ( $N$ ).

$$\lambda = N\phi$$

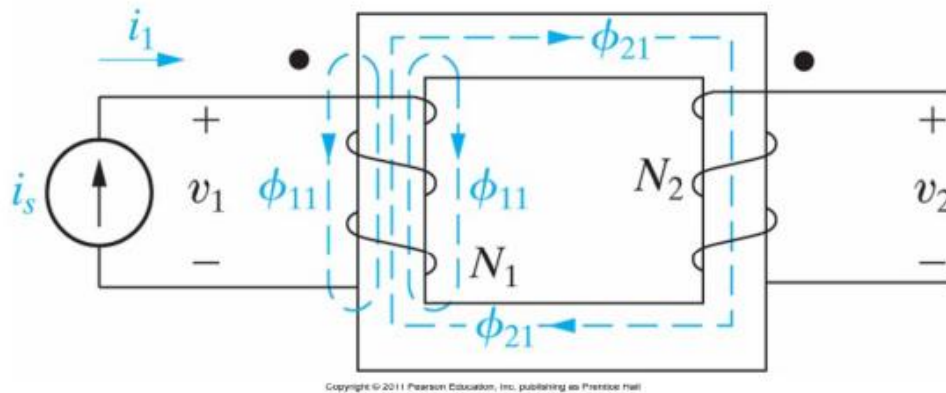
- The magnetic field strength per unit volume depends on the material in that space - described by the permeance of the material.
- The text has more details, but the important message is the magnetic coupling  $M$  may not be perfect.
- Thus, we introduce a coefficient of coupling  $k$  which can be used to better model a specific physical circumstance.
- The value of  $k$  depends on what fraction of flux is linking to the other coil.

$$M = k\sqrt{L_1L_2}$$

Where  $0 \leq k \leq 1$ .

In general,  $k$  is found by experimental measurement.

- We thus have the following view of a mutually coupled circuit:



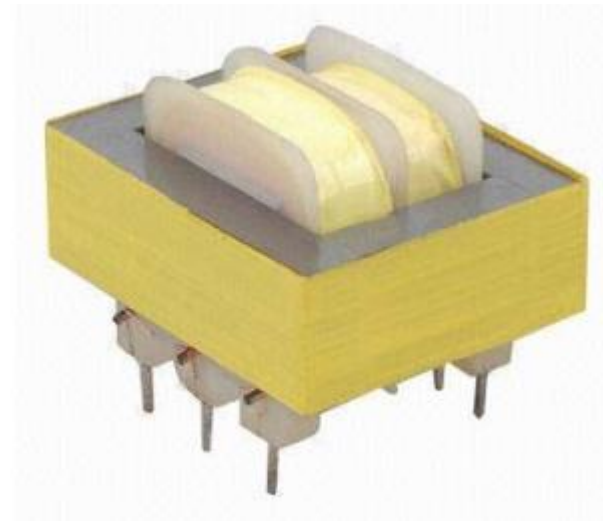
$$M = k\sqrt{L_1L_2}$$

The energy stored in these two coils (self-inductance) and the energy stored in the coupled magnetic fields (mutual inductance) has the form:

$$w(t) = \frac{1}{2}L_1i_1^2 + \frac{1}{2}L_2i_2^2 \pm Mi_1i_2$$

# Transformer

- A transformer is a device that is based on magnetic coupling.
- In communications, a transformer can be used to match impedance between two circuits and to eliminate dc signals.
- A very common use of transformers is in power systems to raise or lower voltage levels.



## Ideal Transformer:

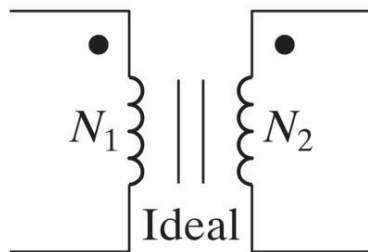
- An ideal transformer is an imaginary transformer, consists of two magnetically coupled coils having:
- $N_1$  turns around the coil on the primary side.
- $N_2$  turns around the coil on the secondary side.
- Coefficient of coupling  $k = 1$ . Perfect coupling.
- The self-inductance of each coil is infinite.  $L_1 = L_2 = \infty$
- The resistance of each coil is negligible. Parasitic resistance  $\rightarrow$  zero.
- There are no copper losses (no winding resistance).
- There is no iron loss in core.
- There is no leakage flux.
- an ideal transformer gives output power exactly equal to the input power.
- Efficiency of an idea transformer is 100%.
- It is impossible to have such a transformer in practice, but ideal transformer model makes problems easier.

### Dot Convention:

Dot convention is a method to define the polarity of voltage and current in a mutually coupled circuit and can be summarized as:

- If the coil voltages  $V_1$  and  $V_2$  are both positive or both negative at the dot-marked terminal, then use a plus sign. Otherwise, use a minus sign.
- If the coil currents  $I_1$  and  $I_2$  are both directed into or both directed out of the dot-marked terminal, then use a minus sign. Otherwise, use a plus sign.

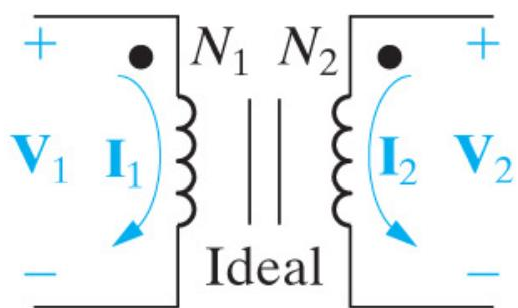
Let's consider the following four cases of an ideal transformer to determine the correct polarity of voltages and currents.



$$\frac{V_1}{N_1} = (\pm) \frac{V_2}{N_2}$$

$$I_1 N_1 = (\pm) I_2 N_2$$

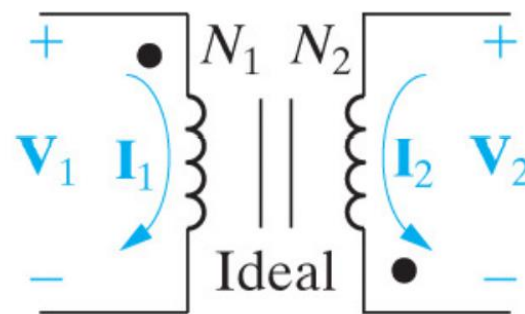
**Case 1:** Both voltages are positive at the dot-marked terminal.  
Both currents are into the dot-marked terminal.



$$\frac{V_1}{N_1} = \frac{V_2}{N_2},$$

$$N_1 \mathbf{I}_1 = -N_2 \mathbf{I}_2$$

**Case 1**



$$\frac{V_1}{N_1} = -\frac{V_2}{N_2},$$

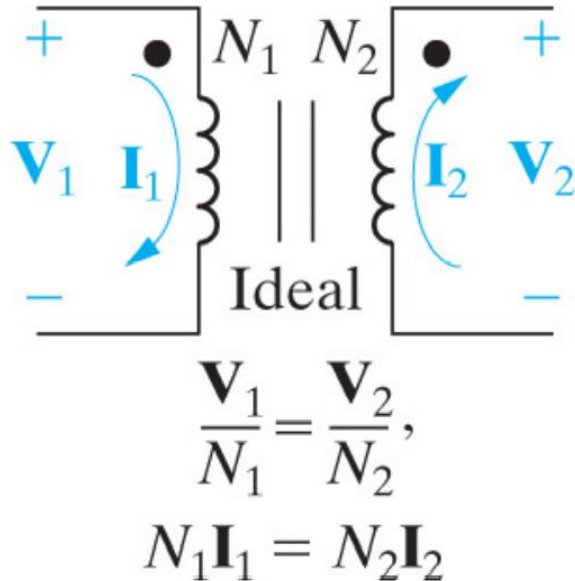
$$N_1 \mathbf{I}_1 = N_2 \mathbf{I}_2$$

**Case 2**

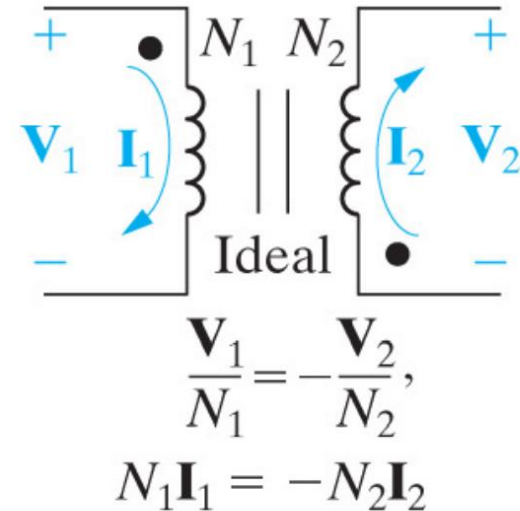
**Case 2:** Only one voltage is positive at the dot-marked terminal.  
Only one current is into the dot-marked terminal.



**Case 3:** Both voltages are positive at the dot-marked terminal.  
Only one current is into the dot-marked terminal.



**Case 3**



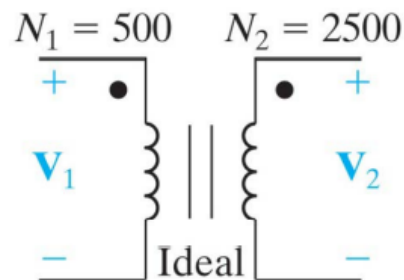
**Case 4**

**Case 4:** Only one voltage is positive at the dot-marked terminal.  
Both currents are into the dot-marked terminal.

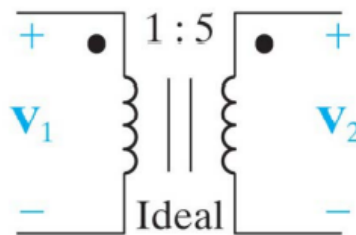
The ratio of turns on the two windings may be defined as either

$N_1/N_2$  or as  $N_2/N_1$ . Here we will use  $a = \frac{N_2}{N_1}$

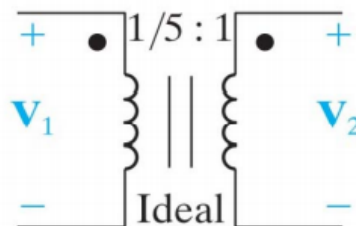
Equivalent ways to show the turns ratio.



$$a = \frac{N_2}{N_1} = \frac{2,500}{500} = 5$$



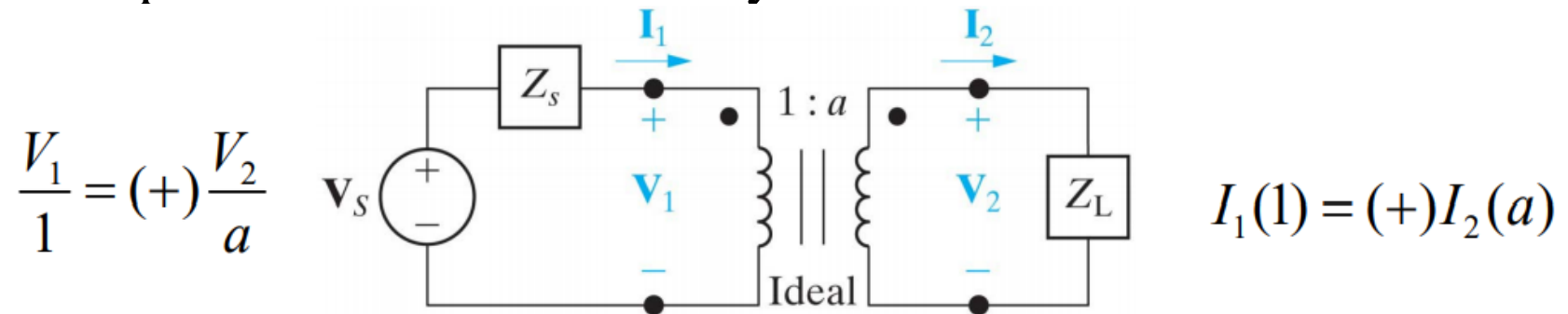
$$1:a$$



$$\frac{1}{a}:1$$

## Impedance Matching:

- Ideal transformers can be used to raise or lower the impedance of load as seen by the source.



Thus the input impedance is (leave out the source impedance  $Z_s$ )

$$Z_{in} \equiv \frac{V_1}{I_1}$$

$$Z_L \equiv \frac{V_2}{I_2}$$

$$Z_{in} = \frac{V_1}{I_1} = \frac{\frac{V_2}{a}}{aI_2} = \frac{1}{a^2} \frac{V_2}{I_2} = \frac{1}{a^2} Z_L$$

- Thus, the ideal transformer's secondary coil reflects the load impedance back to the primary coil with a scaling factor.
- The magnitude is scaled, but the phase induced by the load is not altered!
- If the phase of  $Z_L$  cannot be changed, the greatest power is delivered to the load is when the magnitudes of the Thévenin and load impedances are equal.

$$|Z_{TH}| = |Z_L|$$

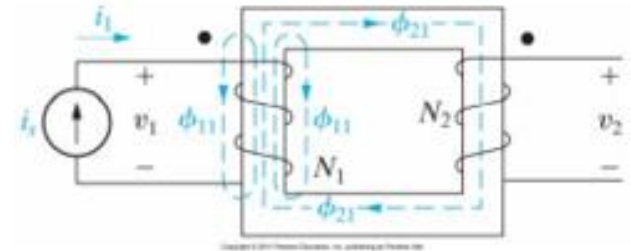
- Impedance matching with ideal transformers allow us to create the above condition.

**Ex-7:** Two magnetically coupled coils have:

$$L_1 = 60 \text{ mH} \quad L_2 = 9.6 \text{ mH} \quad M = 22.8 \text{ mH}$$

What is the coefficient of coupling?

What is the largest value of  $M$ ?



Find K:

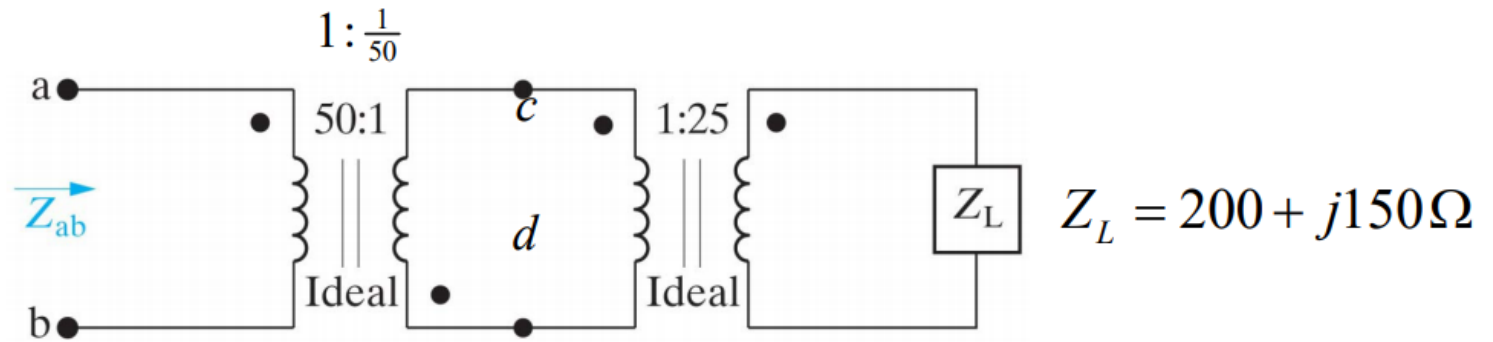
$$K = \frac{M}{\sqrt{L_1 L_2}} = \frac{22.8 \times 10^{-3}}{\sqrt{60 \times 10^{-3} \times 9.6 \times 10^{-3}}} = 0.95$$

Find largest value of M:

$M$  is Max.<sup>um</sup> when  $K = 1$ .

$$M = 1 \sqrt{60 \times 10^{-3} \times 9.6 \times 10^{-3}} = 24.0 \text{ mH}$$

**Ex-8:** Find the impedance  $Z_{ab}$ ?



$$Z_{cd} = \left( \frac{N_{cd}}{N_L} \right)^2 \cdot Z_L = \left( \frac{1}{25} \right)^2 \cdot (200 + j150).$$

$$Z_{ab} = \left( \frac{N_{ab}}{N_{cd}} \right)^2 \cdot Z_{cd} = \left( \frac{50}{1} \right)^2 \left[ \frac{1}{25^2} (200 + j150) \right]$$

$$Z_{ab} = 800 + j600 = 1000 \angle 36.87^\circ$$

$\Omega$