

California State University, Sacramento
The College of Engineering and Computer Science

EEE 180 Signals & Systems

Midterm 2

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Unilateral Laplace Transform Table			Unilateral Z-transform Pair Table	
			$f[k]$	$F[z]$
1	$\delta(t)$	1	1	$\delta[k-j]$
2	$u(t)$	$\frac{1}{s}$	2	$u[k]$
3	$tu(t)$	$\frac{1}{s^2}$	3	$ku[k]$
4	$t^n u(t)$	$\frac{n!}{s^{n+1}}$	4	$k^2 u[k]$
5	$e^{\lambda t} u(t)$	$\frac{1}{s-\lambda}$	5	$k^3 u[k]$
			6	$\gamma^{k-1} u[k-1]$
			7	$\gamma^k u[k]$

1.[25 points]

The discrete system equation and initial conditions are given below:

$$y[k+2] + \frac{3}{2} y[k+1] + \frac{1}{2} y[k] = 0, \quad y[-1] = -3, \quad y[-2] = 1.$$

Please find the system output response for the above discrete-time system by using the following three steps.

(1). What is the characteristic polynomial equation for the above system?

$$\lambda^2 + 3/2 \lambda + 1/2 = 0$$

(2). What are the values of the two roots of the characteristic polynomial equation for this system?

$$(\lambda + 1)(\lambda + 1/2) = 0$$

$$\lambda = -1, -1/2$$

(3). Find the output system response of this discrete time system.

$$y[k] = B_1 (-1)^k + B_2 (-1/2)^k$$

FOR $y[-1] = -3$:

$$B_1 (-1)^{-1} + B_2 (-1/2)^{-1} = -3$$

$$-B_1 - 2B_2 = -3$$

FOR $y[-2] = 1$:

$$B_1 (-1)^{-2} + B_2 (-1/2)^{-2} = 1$$

$$B_1 + 4B_2 = 1$$

$$\begin{cases} -B_1 - 2B_2 = -3 \\ B_1 + 4B_2 = 1 \end{cases} \quad \begin{matrix} B_1 = 5 \\ B_2 = -1 \end{matrix}$$

$$y[k] = 5(-1)^k - (-1/2)^k$$

2. [35 points]

(1). Determine the Inverse Laplace transform of $F(s) = \frac{5}{s+3} + \frac{8}{s-4}$ by using the unilateral Laplace transform table.

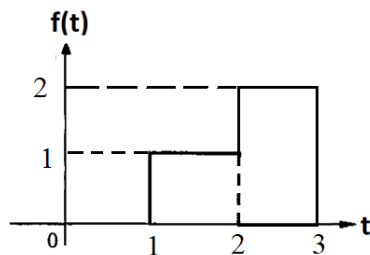
Your solution: $f(t) = (5e^{-3t} + 8e^{4t})u(t)$ ✓

(2). Determine the Inverse Laplace transform of $F(s) = 2 + \frac{2}{s^2}$ by using the unilateral Laplace transform table.

Your solution: $f(t) = 2\delta(t) + 2tu(t)$ ✓

(3). Calculate Laplace transform $F(s) = \int_0^\infty f(t) e^{-st} dt$ of the following signal and find the region of convergence.

$$f(t) = \begin{cases} 1, & 1 \leq t < 2 \\ 2, & 2 \leq t < 3 \end{cases}$$



$$\begin{aligned} F(s) &= \int_0^\infty f(t) e^{-st} dt \\ &= \int_0^1 0 e^{-st} dt + \int_1^2 1 e^{-st} dt + \int_2^3 2 e^{-st} dt \\ &= 0 + \left[-\frac{1}{s} (e^{-st}) \right]_1^2 + \left[-\frac{2}{s} (e^{-st}) \right]_2^3 \\ &= -\frac{1}{s} (e^{-2s} - e^{-s}) - \frac{2}{s} (e^{-3s} - e^{-2s}) \\ &= -\frac{1}{s} (-e^{-s} - e^{-2s} + 2e^{-3s}) \\ &= \frac{1}{s} (e^{-s} + e^{-2s} - 2e^{-3s}) \end{aligned}$$
 ✓

Missing ROC x -2

3. [40 points]

(1). The discrete-time system is described by

$$y[k+1] + 2y[k] = f[k], \text{ with } f[k] = u[k] \text{ and } y[0] = 0.$$

Solve the above equation iteratively to determine $y[1]$ and $y[2]$ values.

$$y[k+1] + 2y[k] = f[k]$$

when $k=0$:

$$y[1] + 2y[0] = f[0]$$

$$y[1] + 2(0) = u(0)$$
 ✓

$$y[1] = 0$$
 ✗

when $k=1$:

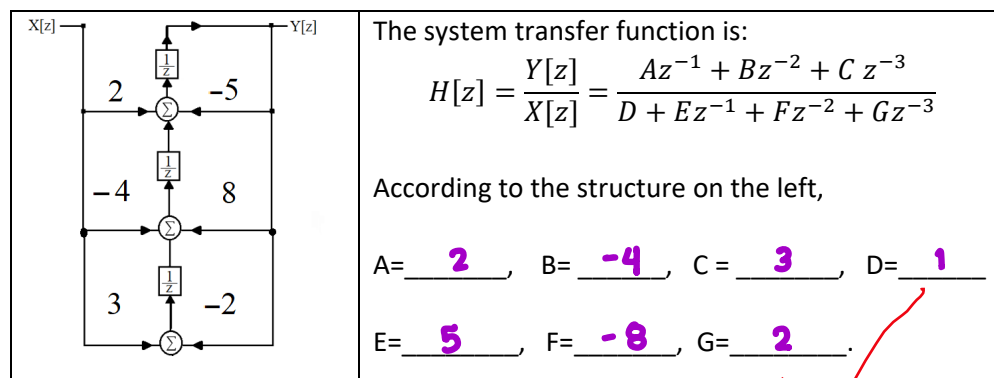
$$y[2] + 2y[1] = f[1]$$
 ✓

$$y[2] + 2(0) = 1$$

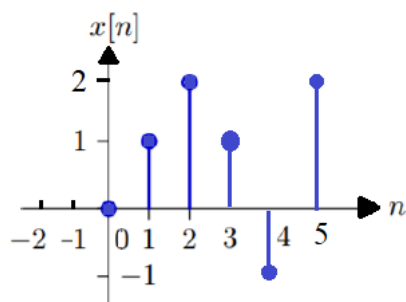
$$y[2] = 1$$
 ✗

-2

(2). The transformed direct form II structure is shown below.



(3). Find the z-transform for the following discrete-time signal.



$$\begin{aligned}
 x[z] &= 0 + \frac{1}{z} + \frac{2}{z^2} + \frac{1}{z^3} - \frac{1}{z^4} + \frac{2}{z^5} \\
 &= z^{-1} + 2z^{-2} + z^{-3} - z^{-4} + 2z^{-5}
 \end{aligned}$$

(4). Find the inverse z-transform of the following function with ROC: $|z| > 4$.

$$F[z] = \frac{z(z-3)}{z^2 - 6z + 8}$$

$$F[z] = \frac{z(z-3)}{z^2 - 6z + 8} = \frac{A}{z-4} + \frac{B}{z-2}$$

$$z-3 = A(z-2) + B(z-4)$$

$$\text{when } z=2: -1 = A(0) + B(-2) \longrightarrow B = 1/2$$

$$z=4: 1 = A(2) + B(0) \longrightarrow A = 1/2$$

$$F[z] = \frac{1/2 z}{z-4} + \frac{1/2 z}{z-2}$$

$$f[k] = \frac{1}{2} [(4)^k + (2)^k] u[k]$$