California State University, Sacramento The College of Engineering and Computer Science

EEE 180 Signals & Systems

Final Exam

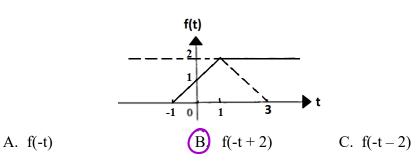
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Student Name: VIGOMAR KIM ALGADOR

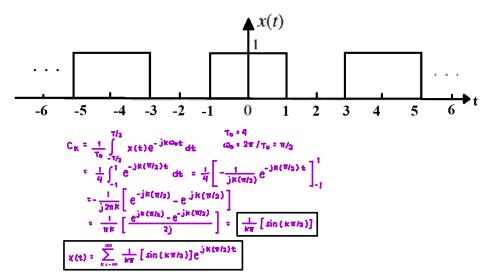
(1). Tl	he signal y is defined b	by: $y = \int_0^\infty \delta(t) dt$, then which answer	
	below is correct?			
	A. y=1	B. $y = \omega$	C.y = u(t)	
(2). T	The discrete-time signa	1 y=2 cos(1.5 π k -	$+\frac{\pi}{4}$) is periodic. Which N value	
b	elow can be used as the	ne period of y?		
	A. N=1	B. N=2	$ \overset{\bullet}{\mathbf{C}} $ $N=4$	
(3). A bounded-input and bounded-output system is called a system.				
	A. Causal	B. Stable	C. Linear	
(4).	The continuous-time	signal y=2 cos(6 7	$\tau t + \frac{\pi}{4}$). When the sampling	
	frequency is 10 Hz,	will the aliasing pro	blem show up?	
	A. Yes	B. No		
(5).	Two continuous time	e signals are: y1	$=\sin(t)$ and $y2=\sin(t)/t$.	
Are they even or odd signals?				
	A. y1: even, y2: ev B. y1: even, y2: oc		C. y1: odd, y2: even D. y1: odd, y2: odd	
(6).	The unilateral Laplac	ce transform of $\delta(t)$ i	s	
	D 1 B. 0	C. π/2	D. None of above	
(7).	The system is governed by the following equation: $dy(t)/dt + 3 y(t) + 2 = x(t)$. Is this a linear system?			
	A. Yes	B.No		

1.[24 points] Select one correct answer for Each of the following questions. Each question below has only one correct answer.

(8). The solid line below shows the waveform for f(t). What is the signal in the dashed line?



- 2.[36 points]
- (1). Find the Exponential Fourier Series of the following periodic signal with a period of 4.



(2). Find the energy of the following signal:

$$E = \int_{-\infty}^{\infty} |x(t)|^{2} dt$$

$$= \int_{-\infty}^{\infty} |e^{-5t} u(t)|^{2} dt = \int_{0}^{\infty} e^{-10t} dt$$

$$= \left[-\frac{e^{-10t}}{10} \right]_{0}^{\infty} = \frac{1}{10}$$

 $x(t) = e^{-5t}u(t).$

(3). Find the Fourier Transform of the following signal:

$$x(t) = e^{-5t}u(t)$$

$$x(\omega) = \int_{-\infty}^{\infty} e^{-5t} u(t) e^{-j\omega t} dt$$

$$= \int_{0}^{\infty} e^{-5t} e^{-j\omega t} dt$$

$$= \int_{0}^{\infty} e^{-(j\omega+5)t} dt = \left[-\frac{1}{j\omega+5} e^{-(j\omega+5)t}\right]_{0}^{\infty}$$

$$= \frac{1}{j\omega+5}$$

(4). Find the z-transform of the sequence $x[n] = (0.2)^n u[n]$, and determine the region of convergence.

$$z\{(0.2)^{n}u[n]\} = \sum_{n=0}^{\infty} (0.2)^{n}z^{-n}$$

$$= \sum_{n=0}^{\infty} (5z)^{-n} = \frac{1}{1 - \frac{1}{5}z^{-1}} = \frac{z}{z - 0.2}$$

$$ROC: |z| > 0.2$$

(1). Suppose the unilateral z-transform of f(t) is F(z), and the ROC is |z| > 20.

$$F(z) = \frac{z}{(z-10)(z-20)}$$
 . Find the f(t) signal equation.

The unilateral z-transform pair table is given below.

Unilate	ral z-transform Pair	Table
	f[k]	F[z]
1	$\delta[k-j]$	z^{-j}
2	u[k]	$\frac{z}{z-1}$
3	ku[k]	$\frac{z}{(z-1)^2}$
4	$k^2u[k]$	$\frac{z(z+1)}{(z-1)^3}$
5	$k^3u[k]$	$\frac{z(z^2+4z+1)}{(z-1)^4}$
6	$\gamma^{k-1}u[k-1]$	$\frac{1}{z-\gamma}$

$$\frac{F[Z]}{Z} = \frac{Z}{(z-10)(z-20)} = \frac{A}{Z-10} + \frac{B}{Z-20}$$

$$1 = A(Z-20) + B(Z-10)$$
when $z = 20$: $1 = B(10) \longrightarrow B = \frac{1}{10}$
when $z = 10$: $1 = A(-10) \longrightarrow A = -\frac{1}{10}$

$$\frac{F[Z]}{Z} = \frac{-\frac{1}{10}}{Z-10} + \frac{\frac{1}{10}}{Z-20}$$

$$F[Z] = -\frac{1}{10} \left(\frac{Z}{Z-10}\right) + \frac{1}{10} \left(\frac{Z}{Z-20}\right)$$

$$f[K] = [-\frac{1}{10}(10)^{K} + \frac{1}{10}(20)^{K}] u(K)$$

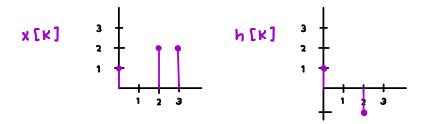
$$= \frac{1}{10} \left[20^{K} - 10^{K}\right] u(K)$$

(2). The discrete time input signal $x[k] = \, \delta[k] + 2\delta[k-2] + 2\,\delta[k-3]$

The discrete time signal system impulse response signal

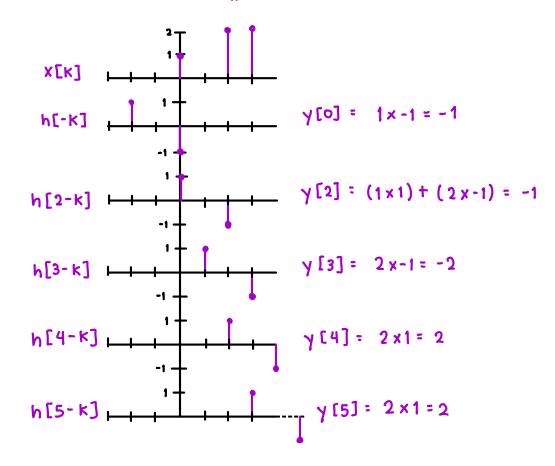
$$h[k] = u[k] - u[k-2]$$

Draw the waveforms of x[k] and h[k].



(3). For the above question (3), the system output response signal is defined as the convolution result of y[k] = x[k] * h[k]. Find the values of y[k].

$$y[k] = x[k] \cdot h[k] = \sum_{k=-\infty}^{\infty} x[n]h[k-n]$$



(4). For an LTIC system described by the transfer function

$$H(s) = \frac{s + 0.5}{s + 1}$$

Find the steady-state system response y(t) to the input signal of f(t) = 2 u(t).

$$H(j\omega) = \frac{j\omega + 0.5}{j\omega + 1}$$

$$|H(j\omega)| = \frac{\sqrt{\omega^2 + 0.25}}{\sqrt{\omega^2 + 1}}$$

$$|H(j\omega)| = \frac{1/2}{\sqrt{\omega^2 + 1}}$$

$$\angle H(j\omega) = 0$$

$$\angle H(j\omega) = \tan^{-1}\left(\frac{\omega}{0.5}\right) - \tan^{-1}\left(\frac{\omega}{1}\right)$$
Output response $\gamma(t) = 2 \cdot \frac{1}{2} \cdot u(t)$

$$= 1 \cdot u(t)$$

$$= 1 \cdot u(t)$$