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Review T/F
IT
2 F (x could be 0)
4 F Calmost every matrix is a counter example =)
5 T Cif it's not invertible then bloits square there's a non-zero
       vector in its null space)
6.T
 7 F ([20], [63])
8 F (again almost any matrix will be a counter example)
 9 F (det A3 = (det A)3 = 8)
to F (again x could be 0)
 11 F (9) and (6) both correspond to 2=2 for (20)
 12 T
 13 T
 14 F (it has area 5, the parallelogram has area 10)
 15 F (true if its a diagonal matrix)
  16 T (det(ATA) = det(AT) det(A) = det(A)2 >0)
  17 T
  18 F (counter-example: any time the coefficient matrix
      is not invertible ble then det(A)=0 and you can't
          divide by it)
  19 T (0 = det(A3) = (det(A))3 → det(A)=0)
  20 F (det (A-1) = det (A) - so just pick an A with det + ±1)
  21 F (don't do this!!)
Cayley Hamiton
1. That any square matrix satisfies its own characteristic
  polynomial (eg XA(A) = 0)
    1-2 -1
              = 2-42+5 -> So by C.H. A2-4A+5I=0
                              \rightarrow rearranging: A(4-A) = I

\rightarrow so A^{-1} = (4-A)/s.
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Cayley Hamilton cont.

3. The determinant of a matrix is the product of its eigenvalues (with multiplication) so det(A) = (i)(-i)(-i) + 0 so A is invertible. By C.H. (A-i)(A+i)(A+1) = 0

- A<sup>3</sup>+A<sup>2</sup>+A+I=0-> A.(-A<sup>2</sup>-A-I)=I so A<sup>-1</sup>=-A<sup>2</sup>-A-I.

In the second rase det(A) = 0 so A is not invertible.

More EV and Diagonalization.

the basis formed by the columns of matrix

- I (a) Yup (b) Yes, from vectors in terms of B into vectors in terms of the standard basis. This is denoted seb.
  - (d) So BCB-1 takes vectors in terms of the standard basis, rewrites them to be in terms of the basis B, applies C to them in this form and then B translates the output back into the standard basis.

this is a lot to digest so give your -seif time:)

- -9 So A = BCB-1 means they are secretly the same linear transformation, just A is written in terms of the standard basis and C in terms of the basis B.
- (e) If C is diagonal then this all means the linear transformation behind A can be written in terms of another basis as a diagonal matrix this is great ble diagonal matrices are really easy to understand, eg what does (400) do on an arbitrary vector (x,y,z)<sup>T</sup>?

## Eigenvectors / Diagonalization Cont-

2. All vectors in the xy-plane are fixed so these belong to the eigenspace with  $\chi=1$ . The line  $\chi=\gamma=0$  (eg the z-axis) is also an eigenspace with  $\chi=-1$ .

This rotation has no non-trivial eigenvectors! Ctechnically the eigenspace is £03 but remember that ō still isn't an eigenvector!)

- 3. Yup det (A) = (1)(-2)(3)(-3) = 18. In the second case
  bloothere are only 3 eigenvalue, but the matrix is
  4x4, we don't know their multiplicaties (and remember
  the determinant is the product with multiplicates,
  think about the diagonal matrix case to semember this).
- 4. Since  $(A-cI)^T = A^T (cI)^T = A^T cI$  we have  $clet(A^T cI) = clet(A-cI)^T = clet(A-cI)$ .  $\rightarrow so yer A_iA^T$  have the same eigenvalues.
- 5. Since A is diagonalizable A = SDS-1 for diagonal D. Since A is nil potent O = An = SDnS-1 (using that (SDS-1)h = SDnS-1).

  For D = (didz O ) Dn = (didz O ) dn )

So, ble 
$$0 = 8D^nS^{-1} \rightarrow 8^{-1}OS = D^n \rightarrow 0 = D^n$$
  
we can conclude  $d_1 = d_2 = \dots = d_n = 0$ .  
So  $D = 0$ , so  $A = SOS^{-1} = 0$  too!

6. Char poly is (a-λ)(d-λ)-bc -> rearrange and apply
the quadratic formula, roots = (a+d) ± √(a-d)²+4bc = after
so get 2 distinct real e.v. 4 if 2

(a-d)²-4bc > 0!