


True/False

1. T (by definition)
2. F (the "closest point" definition of the projection explains why this is true)
3. T (by definition)
4. F, $UU^T x$ is the projection of x onto the subspace spanned by the columns of U , but this will not be all of \mathbb{R}^n unless $p=n$.
5. F, the vectors in $\text{Row}(A)$ are orthogonal to $\text{Null}(A)$, those of $\text{Col}(A)$ are orthogonal to $\text{LNull}(A)$.
6. T, though note if we had said orthonormal instead this would be false -
7. T
8. T, by construction (hard to explain but easier to see from the examples on pg 356)
9. T (eg $[1,1]$ and $[1,0]$ in \mathbb{R}^2)
10. T (bc Q orthogonal $\Rightarrow Q^T Q = I \Rightarrow Q^T A = Q^T Q R = R$)
11. T this is the great thing about orthogonal bases, just project onto them to get the weights
12. F orthogonality is preserved by scaling
13. T (weird question)
14. F, $\|y - \hat{y}\|$ is, 
15. T
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 once you've projected the first time the output is already in the subspace you're projecting into and so is unchanged by further projection.

Problems

1. Note W_2 is given in terms of an orthogonal basis, so it's much easier to compute the projection onto it.
We just compute $c_1 = \frac{[3, -2, 10] \cdot [5, -2, 1]}{[5, -2, 1] \cdot [5, -2, 1]} = \frac{29}{30}$

$$\text{and } C_2 = \frac{[3, -2, 1] \cdot [1, 2, -1]}{[1, 2, -1] \cdot [1, 2, -1]} = \frac{-11}{6}$$

So the projection is $\frac{29}{30}[3, -2, 1] + \frac{-2}{6}[1, 2, -1]$.

$$\begin{aligned} 2-(a) \quad -1 &= m(-1) + b \\ 0 &= m(1) + b \\ 4 &= m(2) + b \end{aligned}$$

$$(c) \begin{pmatrix} -1 & 1 & 2 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix}$$

$$= \begin{pmatrix} 6 & 2 \\ 2 & 3 \end{pmatrix} = A^T A$$

$$(b) \begin{pmatrix} -1 & 1 \\ 1 & 1 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} m \\ b \end{pmatrix} = \begin{pmatrix} -1 \\ 0 \\ 4 \end{pmatrix}$$

\uparrow A \uparrow y

$$(d) \frac{1}{14} \begin{pmatrix} 3 & -2 \\ -2 & 6 \end{pmatrix} \text{ so}$$

$$\begin{aligned} \begin{pmatrix} m \\ b \end{pmatrix} &= \frac{1}{14} \begin{pmatrix} 3 & -2 \\ -2 & 6 \end{pmatrix} \begin{pmatrix} -1 & 1 & 2 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} -1 \\ 1 \\ 4 \end{pmatrix} \\ &= \frac{1}{14} \begin{pmatrix} 3 & -2 \\ -2 & 6 \end{pmatrix} \begin{pmatrix} 9 \\ 3 \end{pmatrix} = \frac{1}{14} \begin{pmatrix} 21 \\ 0 \end{pmatrix} \\ &= \begin{pmatrix} 3/2 \\ 0 \end{pmatrix} \end{aligned}$$

$$(e) \quad y = 3/2 x$$

$$\begin{aligned} 3(a) \quad v_1 &= (3, 1, -1, 3)^T, \quad v_2 = x_2 - \frac{(-5, 1, 5, -7) \cdot (3, 1, -1, 3)}{(3, 1, -1, 3) \cdot (3, 1, -1, 3)} (3, 1, -1, 3) \\ &= x_2 - \frac{(-40)}{20} (3, 1, -1, 3) = (1, 3, 3, -1) \end{aligned}$$

$$v_3 = x_3 - \frac{v_2 \cdot x_3}{v_2 \cdot v_2} v_2 - \frac{v_1 \cdot x_3}{v_1 \cdot v_1} v_1 = (-3, 1, 1, 3)$$

$$(b) \frac{(1, 2, 3, 4) \cdot (3, 1, -1, 3)}{(3, 1, -1, 3) \cdot (3, 1, -1, 3)} = \frac{14}{20} \quad \frac{(1, 2, 3, 4) \cdot (1, 3, 3, -1)}{(1, 3, 3, -1) \cdot (1, 3, 3, -1)} = \frac{12}{20}$$

$$\frac{(1, 2, 3, 4) \cdot (-3, 1, 1, 3)}{(-3, 1, 1, 3) \cdot (-3, 1, 1, 3)} = \frac{14}{20} \quad \text{so } \bar{x} = \frac{7}{10} \bar{v}_1 + \frac{6}{10} \bar{v}_2 + \frac{7}{10} \bar{v}_3$$

3(c) Yes, then we'd probably want to compute the matrix from class $P = A(A^T A)^{-1} A^T$. For the dimensions you can either examine $A(A^T A)^{-1} A^T$ directly, or remember that P sends vectors from \mathbb{R}^n into the column space of A (where n is the length of vectors in the column space of A) so P is $n \times n$.

$$4. \begin{bmatrix} 2 & 1 \\ -3 & -4 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 4 \\ 5 \end{bmatrix} = \begin{bmatrix} 13 \\ -32 \\ 22 \end{bmatrix}, \quad \begin{bmatrix} 2 & 1 \\ -3 & -4 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 6 \\ -5 \end{bmatrix} = \begin{bmatrix} 7 \\ 2 \\ 8 \end{bmatrix}$$

$\uparrow b_1$ $\uparrow b_2$

So if b_i were the least squares solution we'd have $b - b_i$ orthogonal to the column space of A (b/c b_i would be the closest point in the column space to b).

$$b_1 - b = \begin{bmatrix} 8 \\ -36 \\ 18 \end{bmatrix} \text{ dot with } \begin{bmatrix} 2 \\ -3 \\ 3 \end{bmatrix} \text{ to get } 178 \neq 0$$

$$b_2 - b = \begin{bmatrix} 2 \\ -2 \\ 4 \end{bmatrix} \text{ dot with } \begin{bmatrix} 2 \\ -3 \\ 3 \end{bmatrix} \text{ to get } 22 \neq 0$$

→ so no it's not possible.

(a basis for)

5. Row reduce to find the row space and null space of A .

$$\begin{bmatrix} 1 & -2 & -4 \\ 2 & -5 & -3 \\ 3 & -7 & -7 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -14 \\ 0 & 1 & -5 \\ 0 & 0 & 0 \end{bmatrix} \text{ so the row space has dimension 2, while the null space only has dim = 1 (one free variable)}$$

→ so it's easier to project onto the null space = $\text{Span}\{(14, 5, 1)^T\}$

$$\frac{x \cdot v}{v \cdot v} \bar{v} = \frac{214}{222} = \frac{107}{111} \text{ also } x - \frac{107}{111} v = w \text{ then } \boxed{x = \frac{107}{111} v + w}$$