

1. F (unless  $A$  is  $\Delta$ )
2. F (unless you're just adding one row to another)
3. T
4. T
5. F, T if they meant  $|\det A|$ .
6. F  $\det A^T = \det A$
7. T
8. F  $\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$  has  $\lambda_1=1, \lambda_2=0$ ,  $\begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$  has  $\lambda=0$  only.
9. T
10. F (T if  $A$  is diagonalizable!)
11. F (T if  $D$  is diagonal)
12. F (eg  $\begin{pmatrix} 3 & 1 \\ 0 & 2 \end{pmatrix}$ )
13. F ( $\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$  is diagonalizable)
14. F (T if they are linearly indep)
15. F (eg  $\begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}$ )
16. F ( $P$  could be the zero matrix)
17. F ( $\begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix}$  is invertible b/c  $\det \neq 0$  but not diagonalizable)
18. F ( $P$  is made up of a basis of eigenvectors, and any other basis of eigenvectors would work too eg scale all the vectors by 2)

### Diagonalization

1.  $A$  can have 0 to 3 eigenspaces, and their dimensions can be any 3 (or fewer) numbers whose sum is less than or equal to 3.
2.  $\det(A) = 1 \cdot 2 \cdot 3 = 6$ ,  $\text{Tr}(A) = 1 + 2 + 3 = 6$
3.  $Ax = \lambda x$  for some  $x$ , conjugating:  $\bar{A}\bar{x} = \bar{\lambda}\bar{x}$ . Assuming  $A$  is real,  $\bar{A} = A$  so  $A\bar{x} = \bar{\lambda}\bar{x}$ .  
 $\rightarrow [1-2i, -1+i, 0]$ .

4. (a)  $\lambda_1 = 4+i$ ,  $\lambda_2 = 4-i$

$$v_1 = \begin{bmatrix} 1+i \\ 1 \end{bmatrix} \quad v_2 = \begin{bmatrix} 1-i \\ 1 \end{bmatrix}$$

(b)  $A = \begin{bmatrix} 1+i & 1-i \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 4+i & 0 \\ 0 & 4-i \end{bmatrix} \begin{bmatrix} -i/2 & (1+i)/2 \\ i/2 & (1-i)/2 \end{bmatrix}$

$\lambda = \lambda_1$  so  $a=4$ ,  $b=-1$

(c)  $P = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$   $C = \begin{bmatrix} 4 & 1 \\ -1 & 4 \end{bmatrix}$   $P^{-1} = \begin{bmatrix} 0 & 1 \\ 1 & -1 \end{bmatrix}$

check:  $\begin{bmatrix} 5 & -2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 4 & 1 \\ -1 & 4 \end{bmatrix}$  ✓

### Inner Products and Orthogonality

1. (a) T (b) F (they could be orthogonal!)  
(c) T (b/c it'll all be squares)

2.  $BA = \begin{bmatrix} b_1 a_1 & b_1 a_2 & b_1 a_3 \\ b_2 a_1 & b_2 a_2 & b_2 a_3 \\ b_3 a_1 & b_3 a_2 & b_3 a_3 \end{bmatrix}$

3. Consider a vector  $\vec{v} = \begin{pmatrix} a \\ b \end{pmatrix}$ . Pictorially:  
by pythagoras  $|\vec{v}|^2 = a^2 + b^2$  so  
indeed  $|\vec{v}| = \sqrt{a^2 + b^2}$



4.  $\vec{u} - \vec{v} = (3, 4, 5)$  so  $\|\vec{u} - \vec{v}\| = \sqrt{9 + 16 + 25}$

5.  $\|(-30, 40)\| = 50 \rightarrow \begin{bmatrix} -30/50 \\ 40/50 \end{bmatrix}$

6.  $\vec{u} + \vec{v} = (2, 1, 1)$  so  $\|\vec{u} + \vec{v}\| = \sqrt{4+1+1} = \sqrt{6}$

$\|\vec{u}\| = \sqrt{1+4} = \sqrt{5}$ ,  $\|\vec{v}\| = \sqrt{3}$

→ not equal, but they would be if  $\vec{v} \cdot \vec{u} = 0$ .

$\vec{u} \cdot \vec{v} = 1 - 2 = -1$  so  $|\vec{u} \cdot \vec{v}| = 1$ .  $\|\vec{u}\| \|\vec{v}\| = \sqrt{15}$ .

→ not equal, but would be if  $\vec{v}, \vec{u}$  were parallel.

7.  $8 \cdot (-2) + (-5)(-3) = -1$  so no.

8. Any vector in the span is of the form  $c_1 \vec{u} + c_2 \vec{v}$  so

$\vec{w} \cdot (c_1 \vec{u} + c_2 \vec{v}) = c_1 \underbrace{\vec{w} \cdot \vec{u}}_{=0} + c_2 \underbrace{\vec{w} \cdot \vec{v}}_{=0} = 0$

↖ ↗ b/c  $\vec{w}$  orthogonal to  $\vec{u}, \vec{v}$ .

9. Say  $\vec{x} \in W$  and  $W^\perp$ .

b/c  $\vec{x} \in W^\perp$ , for all  $\vec{y} \in W$ ,  $\vec{x} \cdot \vec{y} = 0$ . In particular,

$\vec{x} \cdot \vec{x} = 0$ . But this can only happen when  $\vec{x} = \vec{0}$

(b/c  $\vec{x} \cdot \vec{x} = x_1^2 + x_2^2 + \dots + x_n^2$ .)

10. Want  $(x, y, z)$  such that  $x + y + z = 0$  and  $2x - z = 0$  eg something in the nullspace of

$A = \begin{pmatrix} 1 & 1 & 1 \\ 2 & 0 & -1 \end{pmatrix}$ . Reduce:  $A \sim \begin{pmatrix} 1 & 1 & 1 \\ 0 & -2 & -3 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & -1/2 \\ 0 & 1 & 3/2 \end{pmatrix}$

→  $x = 1/2 z$ ,  $y = -3/2 z$ ,  $z = z$  →  $\begin{pmatrix} 1/2 \\ -3/2 \\ 1 \end{pmatrix}$  is a basis for  $W^\perp$ .

$x \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + y \begin{pmatrix} 2 \\ 0 \\ -1 \end{pmatrix} + z \begin{pmatrix} 1 \\ -3 \\ 2 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \\ -3 \end{pmatrix}$  ← Scaled by 2 for neatness

↳  $\underbrace{-\frac{1}{2} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}}_W + \underbrace{\frac{3}{2} \begin{pmatrix} 2 \\ 0 \\ -1 \end{pmatrix}}_{W^\perp} - \frac{1}{2} \begin{pmatrix} 1 \\ -3 \\ 2 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \\ -3 \end{pmatrix}$  } row reduce