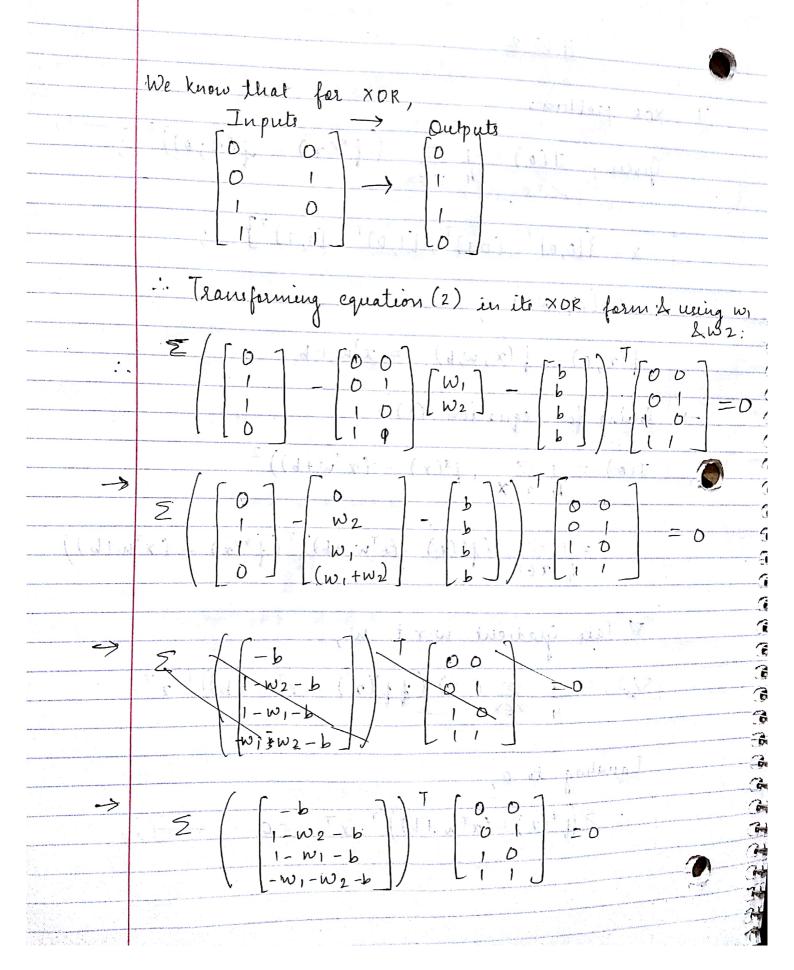
H.W 2 XDR problem: Given; $J(0) = \frac{1}{4} \sum_{x \in X} (f^*(x) - f(x; 0))^2$; $X = \{[0,0]^T, [0,1]^T, [1,0]^T, [1,1]^T\}$ $w = [w_i, w_2]^2$ (s) northuge principles $f(x;0) = f(x;w,b) = x^{T}w + b$ $J(0) = \int \frac{1}{4} \left(f^{*}(x) - (x^{T}w + b) \right)^{2}$ $= \frac{1}{4} \frac{1}{2} \left(\int_{-\infty}^{\infty} (x^{T} x) - (x^{T} w + b) \right)^{T} \left(\int_{-\infty}^{\infty} (x^{T} w + b) \right)$ $\nabla_{w}J = \frac{1}{4} \sum_{\alpha \in X} (-2) \left(\frac{1}{4} \int_{\alpha}^{X} (\alpha) - (\alpha^{T}w + b) \right)^{T} \alpha^{T}$



-.p 1-W2-b 1-W1-b -W1-W2-b =0 10 1 1 $-\frac{1}{2}$ $1-w_1-b-w_1-w_2-b=0$ (3) $l = 1 - w_2 - b - w_1 - w_2 - b = 0$ Taking Gradient wirt by Lequaling to o, $\frac{1}{4} \frac{\sum (-2) \left(f^*(x) - (x^T w + b) \right)^T}{2}$ 00 =0 $2(1-w_1-w_2-2b)$ =0 · + 2mm 2ms - 1-w1-w2-2b=0 (5) $w_1 + w_2 + 2b = 0$ Substituting equation (5) in (3); 1-2w,-w2-2b=0 .'. $2 w_1 + w_1 + w_2 + 2b = 1$ W1+ 1=1 W1 =0

Similarly, substituting equation (3) in (2); $-1 - w_1 - 2w_2 - 2b = 0$ $W_1 + 2W_2 + 2b = 1$ $W_2+(W_1+W_2+2b)=1$ $W_2 + 1 = 1$ $W_2 = \overline{U}$ Substituting values of w. I wz in equation (5), = 0+0+2b= 21 b=1/2 -- b=0.5 Hence, we can say that the values for w, Sh minemize the XDR

homework2_ktapedia_jkkothari

January 24, 2018

Deep Learning Home Work 2

0.1 Team Members :-

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```
In [15]: import numpy as np
         from matplotlib import pyplot as plt
In [16]: train_faces = np.load('smile_data/trainingFaces.npy')
         train_labels = np.load('smile_data/trainingLabels.npy')
         test_faces = np.load('smile_data/testingFaces.npy')
         test_labels = np.load('smile_data/testingLabels.npy')
         train_labels = train_labels.reshape(2000,1)
         test_labels = test_labels.reshape(test_labels.shape[0],1)
In [17]: #This function computes the cost 'J' (equation is given in Method 1)
         def J(w,x,y,alpha=0):
             wt = np.matrix.transpose(w)
             j = np.sum((np.dot(x,wt)-y)**2)
             return j/2
In [18]: #This is a function that reports costs
         def report_cost(w,alpha):
             print("Training Cost :", J(w, train_faces, train_labels, alpha), "\n")
             print("Testing Cost :", J(w, test_faces, test_labels, alpha), "\n")
In [19]: #This is a function that would calculate the Gradient
         #of Cost function for Methods 1 and 2
         def gradJ(w,x,y,alpha):
             try:
                 wt,xt = np.matrix.transpose(w[:]), np.matrix.transpose(x[:])
                 h = np.dot(x,wt)
                 loss = h-y
                 grad_j = np.dot(xt,loss)
                 return grad_j
             except:
                 print(xt.shape)
```

0.2 Question 2: Method 1

Set Gradient to 0 and Solve

```
In [21]: def method1(train_faces,train_labels,test_faces,test_labels):
    # Computing 'w' - weights
    w_transpose = np.matrix.transpose(np.dot(np.linalg.pinv(train_faces),train_labels))
#Computing Testing Phase
# y = w transpose * x
return w_transpose
```

0.3 Question 2: Method 2

Gradient Descent - using epsilon (learning rate) and tolerance

```
In [22]: def method2(train_faces,train_labels,test_faces,test_labels,alpha):
    w = np.random.randn(1,train_faces.shape[1])
    tolerance = 10
    epsilon = 8e-6
    while tolerance > 0.001:
        prev_cost = J(w,train_faces,train_labels,alpha)
        prev_gradJ = gradJ(w,train_faces,train_labels,alpha)
        u = np.dot(prev_gradJ,epsilon)
        w = np.subtract(w,u.transpose())
        curr_cost = J(w,train_faces,train_labels,alpha)
        tolerance = np.absolute(prev_cost-curr_cost)
    test_cost = J(w,test_faces,test_labels,0)
    return w
```

0.4 Question 2: Method 3

Using Penalty alpha(alpha = 1000) and epsilon (learning rate = 1e-6)

```
In [23]: def method3(train_faces,train_labels,alpha=1e3):
    w = np.random.randn(1,train_faces.shape[1])
    tolerance = 10
    epsilon = 1e-6
    while tolerance > 0.001:
        penalty = (alpha/2)*np.dot(w,np.matrix.transpose(w))
        prev_cost = J(w,train_faces,train_labels,alpha)+penalty
        prev_gradJ = gradient_descent(w,train_faces,train_labels,alpha)
        u = np.dot(prev_gradJ,epsilon)
```

```
w = np.subtract(w,u.transpose())
                curr_cost = J(w,train_faces,train_labels,alpha)+penalty
                tolerance = np.absolute(prev_cost-curr_cost)
            test_cost = J(w,test_faces,test_labels,1e3)
            norm_w = np.linalg.norm(w)
            return w
In [26]: print("----Results for Method 1----\n")
        w1 = method1(train_faces, train_labels, test_faces, test_labels)
        report_cost(w1,0)
        print("----Results for Method 2----\n")
        w2 = method2(train_faces,train_labels,test_faces,test_labels,0)
        report_cost(w2,0)
        print("----Results for Method 3----\n")
        w3 = method3(train_faces,train_labels,1e3)
        report_cost(w3,1000)
        print("----")
        print("Norm of W in Method 2 : ",np.linalg.norm(w2)**2,"\n")
        print("Norm of W in Method 3 : ",np.linalg.norm(w3)**2,"\n")
-----Results for Method 1----
Training Cost : 112.722612528
Testing Cost : 190.375513314
-----Results for Method 2----
Training Cost : 114.207086934
Testing Cost : 191.921492989
-----Results for Method 3----
Training Cost : 139.874835971
Testing Cost : 149.952408751
Norm of W in Method 2 : 20.4521547085
Norm of W in Method 3 : 0.052674369434
```

0.4.1 Output Description:

1) The above output shows the Testing and Training costs for all the three Methods

- 2) Cost for Method 1 is obtained by directly setting the gradient zero and computing the weights
- 3) We use learning rates like epsilon = 8e-6 for Method 2 and epsilon = 1e-6 for Method 3
- 4) If you compare method 2 and 3, training cost is higher in method 3, whereas testing cost is lower in Method 3 as compared to Method 2.
- 5) The Output also has the Norm vales of W in methods 2 and 3