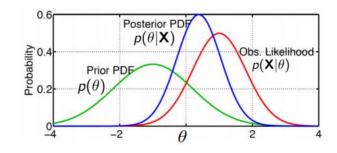
Bayesian Inference for Some Simple Models

CS698X: Topics in Probabilistic Modeling and Inference
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Recap: Bayesian Inference

■ Given data **X** from a model m with parameters θ , the posterior over θ

$$p(\theta|\mathbf{X},m) = \frac{p(\mathbf{X}|\theta,m)p(\theta|m)}{p(\mathbf{X}|m)} = \frac{p(\mathbf{X}|\theta,m)p(\theta|m)}{\int p(\mathbf{X}|\theta,m)p(\theta|m)d\theta} = \frac{\text{likelihood} \times \text{prior}}{\text{marginal likelihood}}$$



Often a useful way to compute PPD for some models without finding the posterior explicitly

Another interesting interpretation: PPD is the ratio of two marginal likelihoods

"(x, X|m)

$$p(\mathbf{x}_*|\mathbf{X},m) = \frac{p(\mathbf{x}_*,\mathbf{X}|m)}{p(\mathbf{X}|m)}$$

- Can use the posterior for various purposes, e.g.,
 - Getting <u>point estimates</u> e.g., mode (though direct point estimation is easier)
 - Uncertainty in our estimates of θ (variance, credible intervals, etc)
 - Computing the posterior predictive distribution (PPD) for new data, e.g.,

$$p(\mathbf{x}_*|\mathbf{X},m) = \int p(\mathbf{x}_*|\theta,m)p(\theta|\mathbf{X},m) d\theta$$

Marginalization using the posterior distribution of θ

Equivalent to marginalizing heta from the plug-in predictive

Caveat: Computing posterior/PPD is in general hard (due to the intractable integrals)

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Recap: Marginal Likelihood and Its Usefulness

- Likelihood $\underline{\mathsf{vs}}$ Marginal Likelihood: $p(\mathbf{X}|\theta,m)$ vs $p(\mathbf{X}|m)$
 - lacktriangle Prob. of **X** for a single $m{ heta}$ under model m vs prob. of **X** averaged over all $m{ heta}$'s under model m
- Can use marg. lik. p(X|m) to select the <u>best model</u> from a finite set of models

$$\hat{m} = \arg \max_{m} p(m|\mathbf{X}) = \arg \max_{m} p(\mathbf{X}|m)p(m) = \arg \max_{m} p(\mathbf{X}|m), \text{ if } p(m) \text{ is uniform}$$

- \blacksquare Also useful for estimating hyperparam of a model (if m denotes hyperparams)
 - lacktriangle Suppose hyperparams of likelihood are $lpha_\ell$ and that of prior are $lpha_p$ (so here $m=\{lpha_\ell,lpha_p\}$)
 - Assuming prior $p(\alpha_{\ell}, \alpha_{\eta})$ is uniform, hyperparams can be estimated via MLE-II

$$\{\hat{\alpha}_{\ell}, \hat{\alpha}_{p}\} = \arg\max_{\alpha_{\ell}, \alpha_{p}} p(\mathbf{X}|\alpha_{\ell}, \alpha_{p}) = \arg\max_{\alpha_{\ell}, \alpha_{p}} \int p(\mathbf{X}|\theta, \alpha_{\ell}) p(\theta|\alpha_{p}) d\theta$$

- Again, note that the integral here may be intractable and may need to be approximated
- Can also compute model posterior p(m|X) and do Bayesian Model Averaging

$$p(\mathbf{x}_*|\mathbf{X}) = \sum_{m=1}^{M} p(\mathbf{x}_*|\mathbf{X}, m)p(m|\mathbf{X})$$



Bayesian Inference for Multinoulli/Multinomial

- Assume N discrete obs $\mathbf{X} = \{x_1, x_2, ..., x_N\}$ with each $x_n \in \{1, 2, ..., K\}$, e.g.,
 - $lacktriangleright x_n$ represents the outcome of a dice roll with K faces
 - x_n represents the class label of the n^{th} example in a classification problem (total K classes)
 - x_n represents the identity of the n^{th} word in a sequence of words

These sum to 1

• Assume likelihood to be multinoulli with unknown params $\pi = [\pi_1, \pi_2, ..., \pi_K]$

$$p(x_n|\pi) = \text{multinoulli}(x_n|\pi) = \prod_{k=1}^K \pi_k^{\mathbb{I}[x_n=k]}$$

Generalization of Bernoulli to K>2 discrete outcomes

- $lacktriangleright \pi$ is a vector of probabilities ("probability vector"), e.g.,
 - \blacksquare Biases of the K sides of the dice
 - Prior class probabilities in multi-class classification $(p(y_n = k) = \pi_k)$
 - lacktriangle Probabilities of observing each word of the K words in a vocabulary

Called the concentration parameter of the Dirichlet (assumed known for now)

,

Large values of α will give a Dirichlet peaked

around its mean (next

slide illustrates this)

Each $\alpha_k \geq 0$

lacktriangle Assume a conjugate prior (Dirichlet) on $m{\pi}$ with hyperparams $m{lpha} = [\alpha_1, \alpha_2, ..., \alpha_K]$

$$p(\boldsymbol{\pi}|\boldsymbol{\alpha}) = \mathsf{Dirichlet}(\boldsymbol{\pi}|\alpha_1, \dots, \alpha_K) = \frac{\Gamma(\sum_{k=1}^K \alpha_k)}{\prod_{k=1}^K \Gamma(\alpha_k)} \prod_{k=1}^K \pi_k^{\alpha_k - 1} = \frac{1}{B(\boldsymbol{\alpha})} \prod_{k=1}^K \pi_k^{\alpha_k - 1} = \frac{1}{B(\boldsymbol{\alpha})} \prod_{k=1}^K \pi_k^{\alpha_k - 1}$$

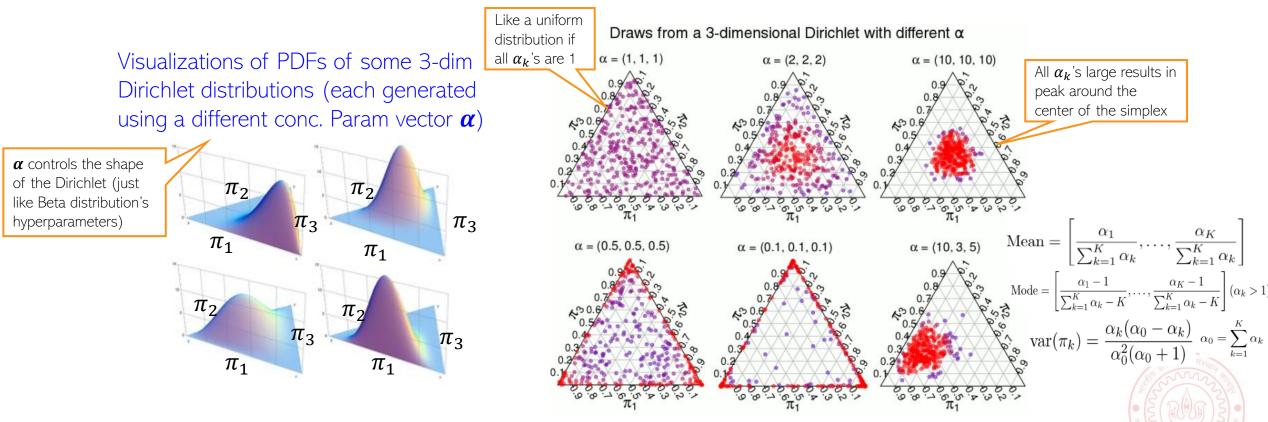
Generalization of Beta to *K*-dimensional probability vectors

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Brief Detour: Dirichlet Distribution

Basically, probability vectors

- lacktriangle An important distribution. Models non-neg. vectors π that also sum to one
- A random draw from K-dim Dirich. will be a point under (K-1)-dim probability simplex



■ Interesting fact: Can generate a K-dim Dirichlet random variable by independently generating K gamma random variables and normalizing them to sum to 1 CS698X: TPMI

Bayesian Inference for Multinoulli

Likelihood

Prior

• Posterior $p(\pi|X)$ is easy to compute due to conjugacy b/w multinoulli and Dir.

$$p(\boldsymbol{\pi}|\mathbf{X},\boldsymbol{\alpha}) = \frac{p(\boldsymbol{\pi},\mathbf{X}|\boldsymbol{\alpha})}{p(\mathbf{X}|\boldsymbol{\alpha})} = \frac{p(\boldsymbol{\pi}|\boldsymbol{\alpha})p(\mathbf{X}|\boldsymbol{\pi},\boldsymbol{\alpha})}{p(\mathbf{X}|\boldsymbol{\alpha})} = \frac{p(\boldsymbol{\pi}|\boldsymbol{\alpha})p(\mathbf{X}|\boldsymbol{\pi},\boldsymbol{\alpha})}{p(\mathbf{X}|\boldsymbol{\alpha})} = \frac{p(\boldsymbol{\pi}|\boldsymbol{\alpha})p(\mathbf{X}|\boldsymbol{\pi})}{p(\mathbf{X}|\boldsymbol{\alpha})}$$
Don't need to compute for this case because of conjugacy marg-lik = $\int p(\boldsymbol{\pi}|\boldsymbol{\alpha})p(\mathbf{X}|\boldsymbol{\pi})d\boldsymbol{\pi}$

- Assuming x_n 's are i.i.d. given π , $p(\mathbf{X}|\boldsymbol{\pi}) = \prod_{n=1}^N p(x_n|\boldsymbol{\pi})$, and therefore

$$p(\boldsymbol{\pi}|\mathbf{X},\boldsymbol{\alpha}) \propto \prod_{k=1}^{K} \pi_k^{\alpha_k - 1} \times \prod_{n=1}^{N} \prod_{k=1}^{K} \pi_k^{\mathbb{I}[x_n = k]} = \prod_{k=1}^{K} \pi_k^{\alpha_k + \sum_{n=1}^{N} \mathbb{I}[x_n = k] - 1}$$

- ullet Even without computing marg-lik, $p(\mathbf{X}|\boldsymbol{\alpha})$, we can see that the posterior is Dirichlet
- lacktriangle Denoting $N_k = \sum_{n=1}^N \mathbb{I}[x_n = k]$, number of observations with with value k

$$p(\boldsymbol{\pi}|\mathbf{X},\boldsymbol{\alpha}) = \text{Dirichlet}(\boldsymbol{\pi}|\alpha_1 + N_1, \alpha_2 + N_2, ..., \alpha_K + N_K)$$

■ Note: N_1 , N_2 ..., N_K are the sufficient statistics for this estimation problem

Similar to number of heads and tails for the coin bias estimation problem

 We only need the suff-stats to estimate the parameters and values of individual observations aren't needed (another property from exponential family of distributions – more on this later)

Bayesian Inference for Multinoulli

- Finally, let's also look at the posterior predictive distribution for this model
- PPD is the prob distr of a new $x_* \in \{1,2,...,K\}$, given training data $\mathbf{X} = \{x_1,x_2,...,x_N\}$

Will be a multinoulli. Just need each of the K outcomes

to estimate the probabilities of each of the
$$K$$
 outcomes $p(x_*|X,\alpha) = \int p(x_*|\pi)p(\pi|X,\alpha)d\pi$

- $p(\mathbf{x}_*|\boldsymbol{\pi}) = \text{multinoulli}(\mathbf{x}_*|\boldsymbol{\pi}), \ p(\boldsymbol{\pi}|\mathbf{X},\boldsymbol{\alpha}) = \text{Dirichlet}(\boldsymbol{\pi}|\alpha_1 + N_1, \alpha_2 + N_2, \dots, \alpha_K + N_K)$
- \blacksquare Can compute the posterior predictive <u>probability</u> for each of the K possible outcomes

$$p(\mathbf{x}_* = k | \mathbf{X}, \boldsymbol{\alpha}) = \int p(\mathbf{x}_* = k | \boldsymbol{\pi}) p(\boldsymbol{\pi} | \mathbf{X}, \boldsymbol{\alpha}) d\boldsymbol{\pi}$$

$$= \int \pi_k \times \text{Dirichlet}(\boldsymbol{\pi} | \alpha_1 + N_1, \alpha_2 + N_2, ..., \alpha_K + N_K) d\boldsymbol{\pi}$$

$$= \frac{\alpha_k + N_k}{\sum_{k=1}^K \alpha_k + N} \text{ (Expectation of } \pi_k \text{ w.r.t the Dirichlet posterior)}$$

Thus PPD is multinoulli with probability vector $\left\{\frac{\alpha_k + N_k}{\sum_{k=1}^K \alpha_k + N}\right\}_{k=1}^K$ Note how these probabilities have been "smoothened" due to the use of the prior + the averaging over the posterior

$$\left\{ \frac{\alpha_k + N_k}{\sum_{k=1}^K \alpha_k + N} \right\}_{k=1}^K$$

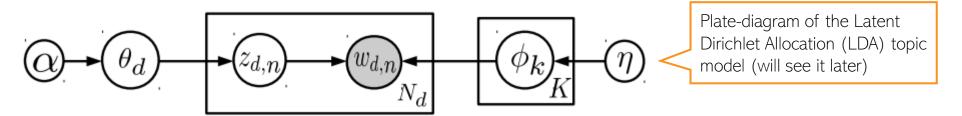
A similar effect was achieved in the Beta-Bernoulli model, too

- Plug-in predictive will also be multinoulli but with prob vector given by the point estimate of π

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Applications?

- Beta-Bernoulli and Dirichlet-Multinoulli/Multinomial models are widely used
- Now know how to do fully Bayesian inference (or point estimation) if our model has such sub-components, and how to compute plug-in/posterior predictive distributions



- Some popular examples are
 - Models for text data: Each document can be modeled as a bag-of-words (Beta-Bernoulli) or a sequence of token (Dirichlet-Multinoulli)
 - Bayesian inference for class prior probabilities in generative classification models: Class labels of training examples are observations and class prior probabilities are to be estimated
 - Bayesian inference for mixture models: Cluster ids are our (latent) "observations" of Dir-Mult model and mixing proportions are to be estimated
 - .. and several others