

Introduction to Probabilistic Modeling and Inference

CS698X: Topics in Probabilistic Modeling and Inference

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Why a Probabilistic Approach?

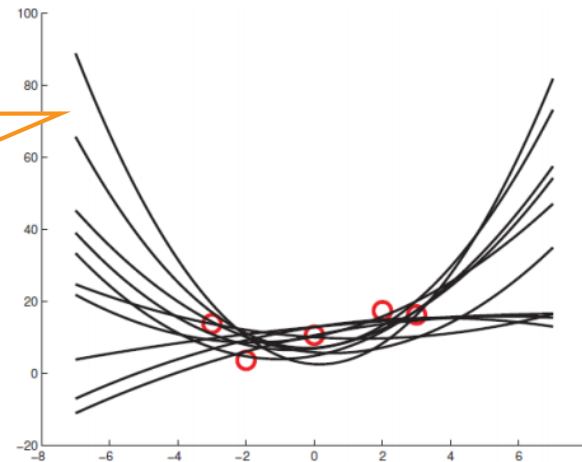
- In machine learning or learning from data in general, we usually want to
 - Learn a model for the data (model usually is defined by some parameters θ)
 - Use the learned model to make predictions
- How (un)certain we are about the model/parameters we have learned?
 - Crucial if we have limited data to learn from
- How (un)certain we are about the predictions made by the model?
 - Crucial if our model/parameters are uncertain
- How (un)certain we are about the data itself?
 - Important if the process that generated data is noisy/uncertain/unknown
- Also, many problems require us to make probabilistic/soft predictions, e.g.,
 - Predict the probability that a transaction is fraud, or that a person has cancer
- A probabilistic approach can naturally handle all of the above (and more)



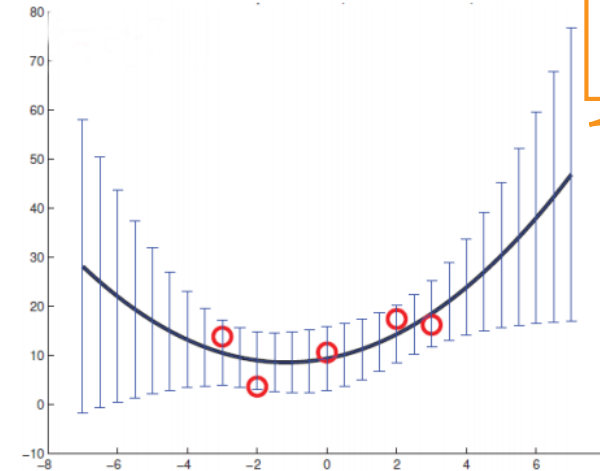
Why a Probabilistic Approach (Contd)?

- Uncertainty about parameter estimates
 - Don't report a single best parameter but a prob. distr. $p(\theta|D)$ over params given data

Each of these curves is generated by sampling from the learned probability distribution $p(\theta|D)$ of the parameters θ given data D



At the time of making predictions for test inputs, each of these curves will be used to predict the output and we will take a weighted average (will see later how the weighting is done)



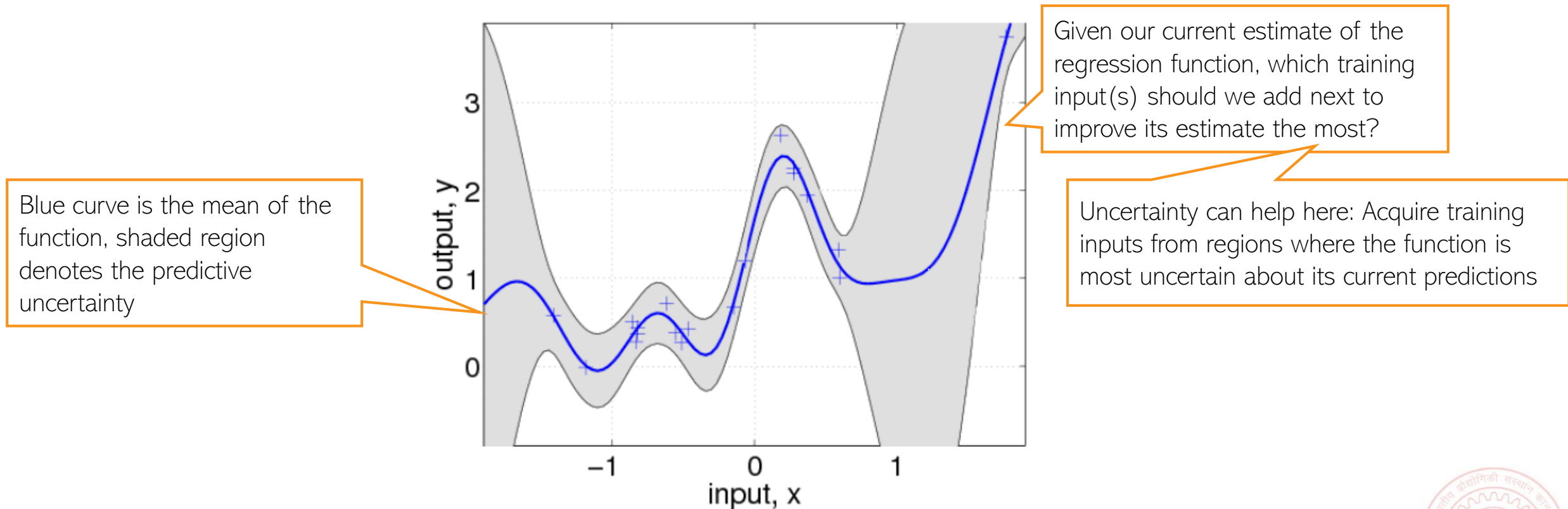
Predictions with error bars
(mean with std deviation
for each prediction)

- Uncertainty about predictions
 - Output a probability distribution or report uncertainty estimate for the predictions

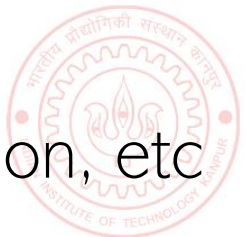


Why a Probabilistic Approach (Contd)?

- Sequential decision-making: Information about uncertainty can “guide” us, e.g.,



- Applications in active learning, reinforcement learning, Bayesian optimization, etc



Why a Probabilistic Approach (Contd)?

- Often wish to learn the underlying probability distribution $p(\mathbf{x})$ of the data
- Useful for many tasks, e.g.,
 - Outlier/novelty detection: Outliers will have low probability under $p(\mathbf{x})$
 - Can sample from this distribution to generate new “artificial” but realistic-looking data



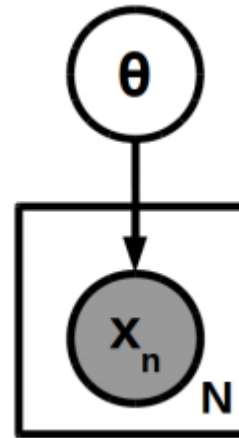
Several models, such as generative adversarial networks (GAN), variational auto-encoders (VAE), etc can do this



Modeling Data Probabilistically: A Simplistic View ⁶

- Assume data $\mathbf{X} = \{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N\}$ generated from a prob. model with params θ

$$\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N \sim p(\mathbf{x}|\theta)$$



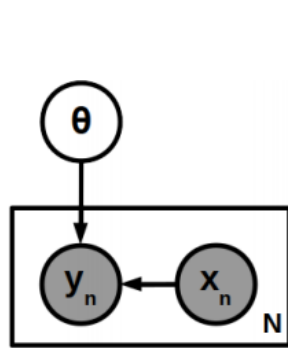
A plate diagram of this simplistic model

- Note: Shaded nodes = observed; unshaded nodes = unknown/unobserved
- Goal: To estimate the unknowns (θ in this case), given the observed data \mathbf{X}
 - Many ways to do this (point estimate or the posterior distribution of θ)
- Can use the parameter estimates to make predictions, e.g.,
 - Probability density of a new input \mathbf{x}_* under this model

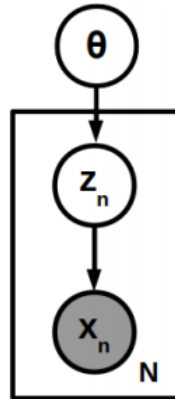


Modeling Data Probabilistically

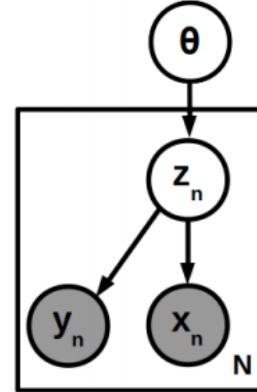
- This previous problem set-up can be generalized in various ways



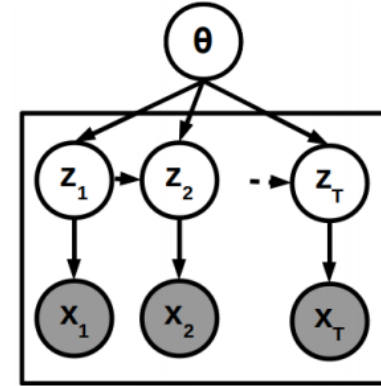
A simple supervised learning model



A latent variable model for unsupervised learning



A latent variable model for supervised learning



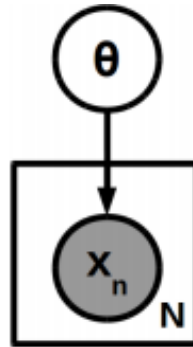
A latent variable model for sequential data

- Any node (even if observed) we are uncertain about is modeled by a prob. distribution
 - These nodes become the random variables of the model
- The full model is specified via a [joint prob. distribution](#) over all random variables
- The goal is to infer the distribution of unknowns of the model, given the observed data



Modeling Data Probabilistically

- Specification of prob. models requires two key ingredients: Likelihood and prior

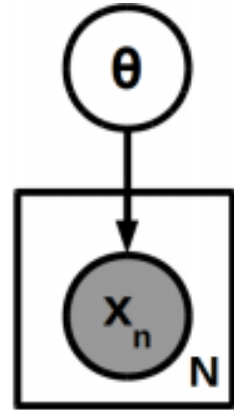


- **Likelihood** $p(\mathbf{x}|\theta)$ or the “observation model” specifies how data is generated
 - Measures data fit (or “loss”) w.r.t. the given parameter θ
- **Prior distribution** $p(\theta)$ specifies how likely different parameter values are *a priori*
 - Also corresponds to imposing a “regularizer” over θ
- **Domain knowledge** can help in the specification of the likelihood and the prior
 - A key benefit of probabilistic modeling



Estimation/Inference in Probabilistic Models

- A simple way: Find θ for which the observed data is most likely or most probable



$$\hat{\theta} = \arg \max_{\theta} \log p(\mathbf{X}|\theta)$$

This “point estimate”, however, does not provide us any information about uncertainty in θ

- **More desirable:** Estimate the full posterior distribution over θ to get the uncertainty

Fully Bayesian inference. In general, an intractable problem, except for some simple cases (will study how to solve such problems)

$$p(\theta|\mathbf{X}) = \frac{p(\mathbf{X}|\theta)p(\theta)}{p(\mathbf{X})} \propto \text{Likelihood} \times \text{Prior}$$

- When making predictions, can use the full posterior rather than a single best θ
 - This is typically referred to as posterior averaging



Posterior Averaging

10

$$p(\mathbf{x}_*|\mathbf{X}) = \int p(\mathbf{x}_*, \theta|\mathbf{X}) d\theta$$

Assuming observations
are i.i.d. given θ

$$= \int p(\mathbf{x}_*|\theta, \mathbf{X})p(\theta|\mathbf{X}) d\theta$$

$$= \int p(\mathbf{x}_*|\theta)p(\theta|\mathbf{X}) d\theta$$

- Can use the posterior over parameters to compute “averaged prediction”, e.g.,

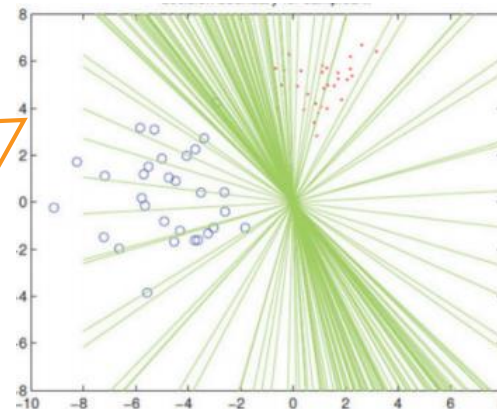
$$p(\mathbf{x}_*|\mathbf{X}) = \int p(\mathbf{x}_*|\theta)p(\theta|\mathbf{X})d\theta$$

Posterior predictive distribution (obtained by doing an importance-weighted averaging over the posterior)

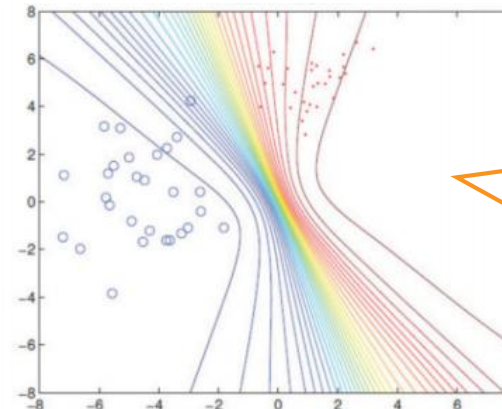
Plug-in predictive distribution

Tells us how important this value of θ is

- Posterior averaging yields more robust predictions since we aren't trusting a single “optimal” value of θ (can also think of it as giving an ensemble of models)



Samples of linear separators drawn from the posterior of a probabilistic binary classification model (each line will have a different importance in computing the posterior predictive)

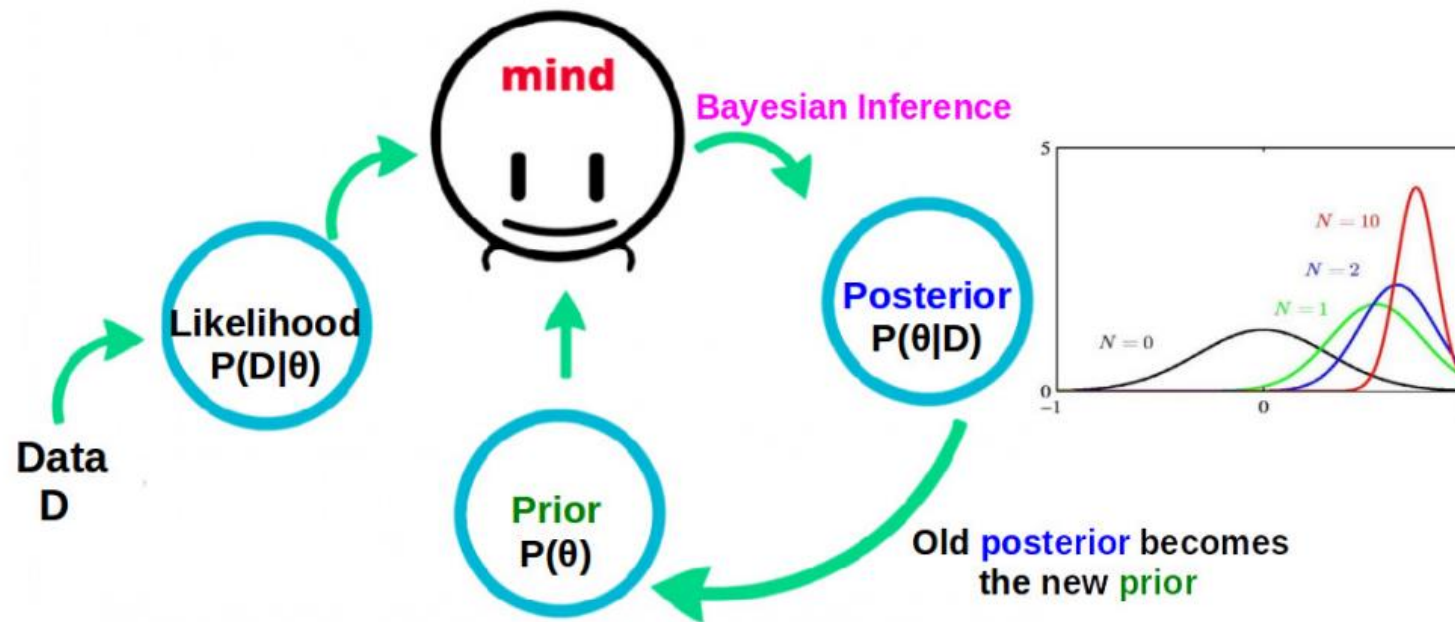


Effect of posterior averaging (each curve is an equal-probability contour, and is not a straight line!)



Bayesian Inference

- Bayesian inference can be seen in a sequential fashion



- Our belief about θ keeps getting updated as we see more and more data
 - Posterior keeps getting updates as more and more data is observed
 - Note: Updates may not be straightforward and approximations may be needed



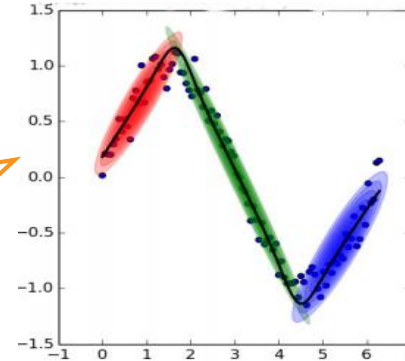
Some Other Benefits



Modular Construction of Complex Models

- Can combine multiple simple probabilistic models to learn complex patterns

A combination of a mixture model for clustering and a probabilistic linear regression model: Result is a probabilistic nonlinear regression model



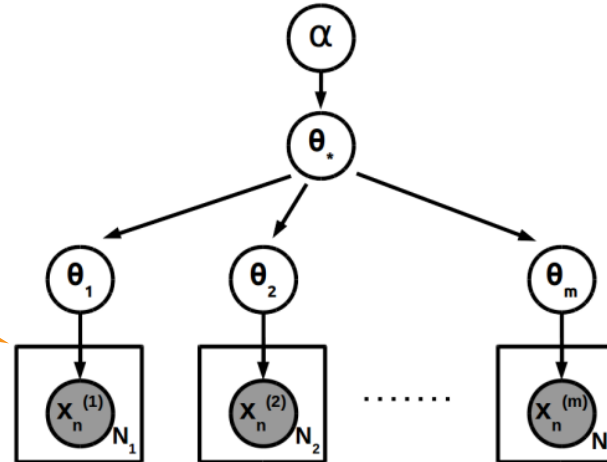
Can design a latent variable model to do this

Essentially a “mixture of experts” model

- Can design models that can jointly learn from multiple datasets and share information across multiple datasets using shared parameters with a prior distribution

Example: Estimating the means of m datasets, assuming the means are somewhat related. Can do this jointly rather than estimating independently

Easy to do it using a probabilistic approach with shared parameters (will see details later)

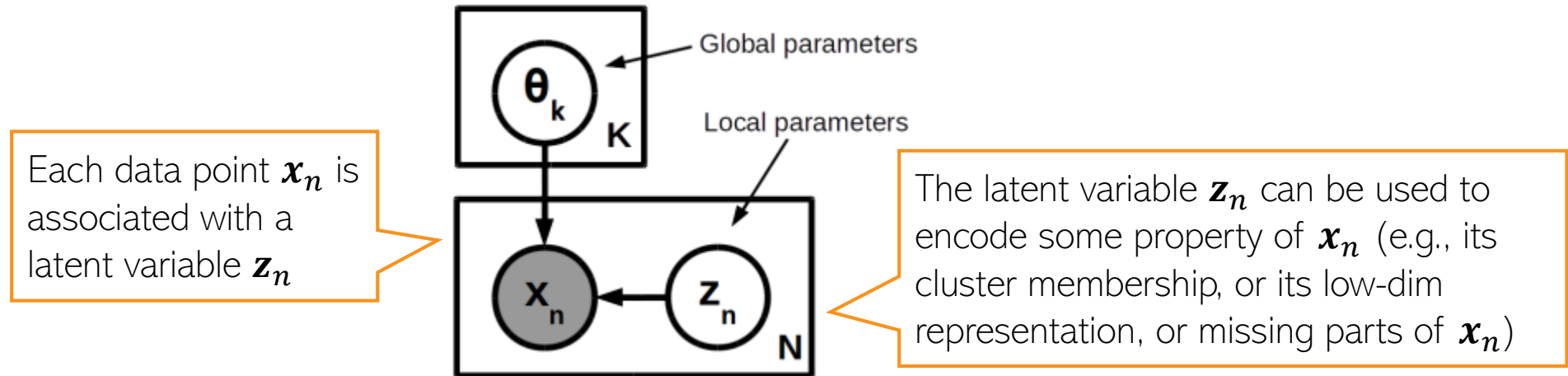


An example of transfer learning or multitask learning using a probabilistic approach



Generative Latent Variable Models

- Generative models of data can be naturally specified in a probabilistic framework

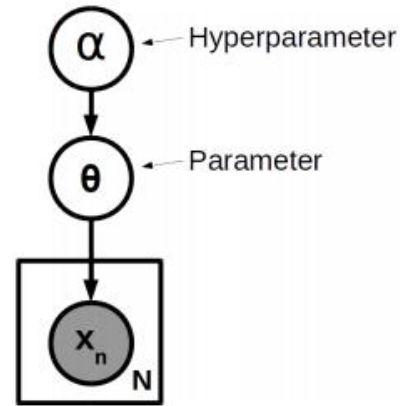


- Such models are used in many problems, especially unsupervised learning: Gaussian mixture model, probabilistic PCA, topic models, deep generative models, etc.
- We will look at several of these in this course and way to learn such models



Hyperparameter Estimation

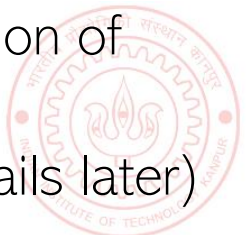
- ML models invariably have hyperparams, e.g., regularization h.p. in a linear regression model, or kernel h.p. in nonlinear regression or kernel SVM, etc.
- Can specify the hyperparams as additional unknown of the probabilistic model



A way to find the point estimate of the hyperparameters by maximizing the [marginal likelihood](#) of data (more on this later)

$$\begin{aligned}\hat{\alpha} &= \operatorname{argmax}_{\alpha} \log p(\mathbf{X}|\alpha) \\ &= \operatorname{argmax}_{\alpha} \log \int p(\mathbf{X}|\theta)p(\theta|\alpha)\theta\end{aligned}$$

- Can now estimate them, e.g., using a point estimate or a posterior distribution
 - To find point estimate of hyperparameters, we can write the probability of data as a function of hyperparameters and maximize this quantity w.r.t. the hyperparameters (details later)
 - Posterior can also be estimated if we specify a prior on the hyperparameters as well (details later)



Model Comparison

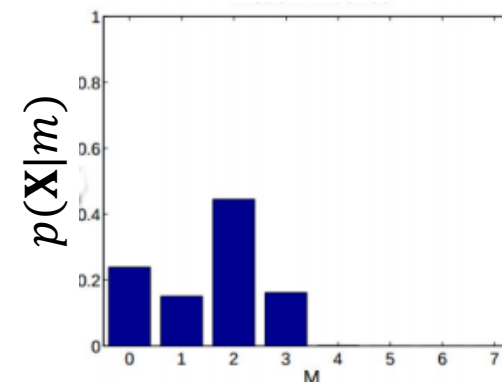
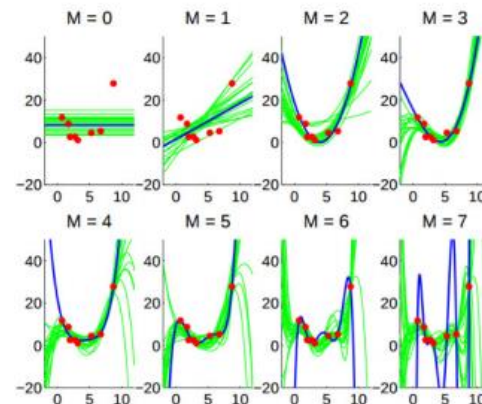
- Suppose we have a number of models $m = 1, 2, \dots, M$ to choose from
- The standard way to choose the best model is cross-validation
- Can also compute the posterior probability of each candidate model, using Bayes rule

May not be easy to do exactly but can compute it approximately

$$p(m|\mathbf{X}) = \frac{p(m)p(\mathbf{X}|m)}{p(\mathbf{X})}$$

Marginal likelihood of model m

- If all models are equally likely a priori ($p(m)$ is uniform) then the best model can be selected as the one with largest marginal likelihood



This doesn't require a separate validation set unlike cross-validation

Therefore also useful for doing model selection/comparison for unsupervised learning problems

Tentative Outline

- Basics of probabilistic modeling and inference
 - Common probability distributions
 - Basic point estimation (MLE and MAP)
- Bayesian inference (simple and not-so-simple cases)
- Probabilistic models for regression and classification
- Probabilistic Graphical Models
- Gaussian Processes (probabilistic modeling meets kernels)
- Latent Variable Models (for i.i.d., sequential, and relational data)
- Approximate Bayesian inference (EM, variational inference, sampling, etc)
- Bayesian Deep Learning
- Nonparametric Bayesian methods
- Misc topics, e.g., deep generative models, black-box inference, sequential decision-making, reinforcement learning, etc



Coming Up Next

- Basics of probabilistic modeling and inference
 - Terminology
 - Basic methods for parameter estimation (point estimation and posterior)
 - Some simple examples

