QUESTION

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Given Absolute loss regression problem with  $\ell_1$  regularization

$$\boldsymbol{\omega}_{\mathbf{opt}} = \underset{\boldsymbol{\omega}}{\operatorname{arg\,min}} \sum_{n=1}^{N} \left| y_n - \boldsymbol{\omega}^{\mathbf{T}} \mathbf{x_n} \right| + \lambda \left\| \boldsymbol{\omega} \right\|_1 \qquad \lambda > 0$$

we will use the following properties to prove its convexity:

- 1. Non-negative weighted sum of the convex functions are convex
- 2. All norms are convex functions
- 3. |x| is convex function
- consider  $|y_n \omega^T x_n|$  is convex using property (3)  $\implies \sum_{n=1}^N |y_n - \omega^T x_n|$  is also convex using property (1)
- also  $\|\boldsymbol{\omega}\|_1$  is convex using property (2)
- $\underset{\boldsymbol{\omega}}{\operatorname{arg\,min}} \sum_{n=1}^{N} \left| y_n \boldsymbol{\omega}^{\mathsf{T}} \mathbf{x_n} \right| + \lambda \left\| \boldsymbol{\omega} \right\|_1 \qquad \lambda > 0 \text{ is }$  convex using property (1)

Hence convexity is proved.

Sub gradient vector:

$$\frac{\partial}{\partial \boldsymbol{\omega}} \sum_{n=1}^{N} \left| y_n - \boldsymbol{\omega}^{\mathbf{T}} \mathbf{x_n} \right| + \lambda \sum_{d=1}^{D} \left| \boldsymbol{\omega}_d \right|$$

$$\sum_{n=1}^{N} \frac{\partial}{\partial \boldsymbol{\omega}} \left| y_n - \boldsymbol{\omega}^{\mathbf{T}} \mathbf{x_n} \right| + \lambda \sum_{d=1}^{D} \frac{\partial}{\partial \boldsymbol{\omega}} \left| \boldsymbol{\omega}_d \right| \qquad \lambda > 0$$
(1)

Consider  $\frac{\partial}{\partial \boldsymbol{\omega}} |y_n - \boldsymbol{\omega}^T \mathbf{x_n}|$ 

$$\frac{\partial}{\partial \boldsymbol{\omega}} |y_n - \boldsymbol{\omega}^{\mathbf{T}} \mathbf{x_n}| = \begin{cases} \mathbf{x_n} & if y_n - \boldsymbol{\omega}^{\mathbf{T}} \mathbf{x_n} > 0 \\ -\mathbf{x_n} & if y_n - \boldsymbol{\omega}^{\mathbf{T}} \mathbf{x_n} > 0 \\ C_1 \mathbf{x_n} & if y_n - \boldsymbol{\omega}^{\mathbf{T}} \mathbf{x_n} > 0; C_1 \in [-1, 1] \end{cases}$$

Consider  $\frac{\partial}{\partial \boldsymbol{\omega}} |\boldsymbol{\omega}_{\mathbf{d}}|$ 

$$\frac{\partial}{\partial \boldsymbol{\omega}} \left| \boldsymbol{\omega}_{\mathbf{d}} \right| = \begin{cases} [0, 0, ...0, 1, 0, ...]^T & if \boldsymbol{\omega}_d > 0, 1 \text{ at position } d \\ [0, 0, ...0, -1, 0, ...]^T & if \boldsymbol{\omega}_d > 0, -1 \text{ at position } d \\ [0, 0, ...0, C_2, 0, ...]^T & if \boldsymbol{\omega}_d = 0, C_2 \text{ at position } d, C_2 \in [-1, 1] \end{cases}$$

The above 2 sub solutions can be substituted back in the equation (1) to get the sub-gradient vector.

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Linear regression model with minimizing the squared loss function;

$$\sum_{n=1}^{N} (y_n - \mathbf{w}^{\mathsf{T}} \mathbf{x_n})^2$$

lets mask the features of  $\mathbf{x_n}$  by  $\widetilde{\mathbf{x_n}} = \mathbf{x_n} \circ \mathbf{m_n}$  with  $m_{nd} \sim \text{Bernoulli}(p)$  New loss function  $\sum_{n=1}^{N} (y_n - \mathbf{w^T} \widetilde{\mathbf{x_n}})^2$ 

Calculating the Estimate value of new loss function:

$$\begin{split} E(\sum_{n=1}^{N}(y_n - \mathbf{w^T\tilde{x}_n})^2) &= \sum_{n=1}^{N} E[(y_n - \mathbf{w^T\tilde{x}_n})^2] \\ &= \sum_{n=1}^{N} E[y_n^2 - 2y_n \mathbf{w^T\tilde{x}_n} + (\mathbf{w^T\tilde{x}_n})^2] \\ &= \sum_{n=1}^{N} y_n^2 - 2y_n E[\mathbf{w^T\tilde{x}_n}] + E[(\mathbf{w^T\tilde{x}_n})^2] \\ &= \sum_{n=1}^{N} y_n^2 - 2y_n p \mathbf{w^T\mathbf{x}_n} + E[(\mathbf{w^T\tilde{x}_n})^2] \\ &= \sum_{n=1} [(y_n - p \mathbf{w^T\mathbf{x}_n})^2] - \sum_{n=1}^{D} \{(p \mathbf{w^T\mathbf{x}_n})^2 + \sum_{i=1}^{D} E[(w_i\tilde{x}_{ni})^2] + \sum_{i \neq j \atop i,j \in [1,D]} E[w_ix_{ni}w_jx_{nj}]\} \\ &= \sum_{n=1} [(y_n - p \mathbf{w^T\mathbf{x}_n})^2] - \sum_{i=1}^{D} \{p^2(\sum_{i=1}^{D} w_i^2x_{ni}^2 + \sum_{i \neq j \atop i,j \in [1,D]} w_ix_{ni}w_jx_{nj}) \\ &+ p \sum_{i=1}^{D} w_i^2x_{ni}^2 + p^2 \sum_{i \neq j \atop i,j \in [1,D]} w_ix_{ni}w_jx_{nj}\} \\ &= \sum_{n=1} (y_n - p \mathbf{w^T\mathbf{x}_n})^2 + pq \sum_{n=1}^{N} \sum_{i=1}^{D} w_i^2x_{ni}^2 \\ &= \sum_{n=1} (y_n - p \mathbf{w^T\mathbf{x}_n})^2 + \sum_{n=1}^{D} w_i^2C_i \quad \text{where } C_i \text{ is const wrt } w \end{split}$$

The above equation is in the form of ridge regression. so minimizing the expected value of our new loss function is equivalent to minimizing the ridge regression

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My solution to problem 3 Given:

$$\begin{aligned} \{\mathbf{B}, \mathbf{S}\} &= \underset{\mathbf{B}, \mathbf{S}}{\operatorname{arg\,min}} \ \operatorname{Tr}[(\mathbf{Y} - \mathbf{X} \mathbf{B} \mathbf{S})^{\mathbf{T}} (\mathbf{Y} - \mathbf{X} \mathbf{B} \mathbf{S})] \\ \{\mathbf{B}, \mathbf{S}\} &= \underset{\mathbf{B}, \mathbf{S}}{\operatorname{arg\,min}} \ \operatorname{Tr}[\mathbf{Y}^{\mathbf{T}} \mathbf{Y} - \mathbf{Y}^{\mathbf{T}} \mathbf{X} \mathbf{B} \mathbf{S} - \mathbf{S}^{\mathbf{T}} \mathbf{B}^{\mathbf{T}} \mathbf{X}^{\mathbf{T}} \mathbf{Y} + \mathbf{S}^{\mathbf{T}} \mathbf{B}^{\mathbf{T}} \mathbf{X}^{\mathbf{T}} \mathbf{X} \mathbf{B} \mathbf{S}] \end{aligned}$$

Using ALT-OPT method initializing  $\mathbf{B} = \mathbf{B}^{(0)}$  and t = 0

$$\mathbf{S}^{(t+1)} = \operatorname*{arg\,min}_{\mathbf{S}} \ \mathcal{L}(\mathbf{B}^{(t)}, \mathbf{S})$$

Derivating with respect to S and equating to 0:

$$\frac{\partial}{\partial \mathbf{S}} \operatorname{Tr}[\mathbf{Y}^{\mathbf{T}}\mathbf{Y} - \mathbf{Y}^{\mathbf{T}}\mathbf{X}\mathbf{B}^{(\mathbf{t})}\mathbf{S} - \mathbf{S}^{\mathbf{T}}\mathbf{B}^{(\mathbf{t})}^{\mathbf{T}}\mathbf{X}^{\mathbf{T}}\mathbf{Y} + \mathbf{S}^{\mathbf{T}}\mathbf{B}^{(\mathbf{t})}^{\mathbf{T}}\mathbf{X}^{\mathbf{T}}\mathbf{X}\mathbf{B}^{(\mathbf{t})}\mathbf{S}] = 0$$

$$\implies \mathbf{0} - \mathbf{B}^{(\mathbf{t})}^{\mathbf{T}}\mathbf{X}^{\mathbf{T}}\mathbf{Y} - \mathbf{B}^{(\mathbf{t})}^{\mathbf{T}}\mathbf{X}^{\mathbf{T}}\mathbf{Y} + (\mathbf{B}^{(\mathbf{t})}^{\mathbf{T}}\mathbf{X}^{\mathbf{T}}\mathbf{X}\mathbf{B}^{(\mathbf{t})} + \mathbf{B}^{(\mathbf{t})}^{\mathbf{T}}\mathbf{X}^{\mathbf{T}}\mathbf{X}\mathbf{B}^{(\mathbf{t})})\mathbf{S} = 0$$

$$\implies (\mathbf{B}^{(\mathbf{t})}^{\mathbf{T}}\mathbf{X}^{\mathbf{T}}\mathbf{X}\mathbf{B}^{(\mathbf{t})})\mathbf{S} = \mathbf{B}^{(\mathbf{t})}^{\mathbf{T}}\mathbf{X}^{\mathbf{T}}\mathbf{Y}$$

$$\implies \mathbf{S} = (\mathbf{B}^{(\mathbf{t})}^{\mathbf{T}}\mathbf{X}^{\mathbf{T}}\mathbf{X}\mathbf{B}^{(\mathbf{t})})^{-1}\mathbf{B}^{(\mathbf{t})}^{\mathbf{T}}\mathbf{X}^{\mathbf{T}}\mathbf{Y}$$

Therefore  $\mathbf{S^{(t+1)}} = (\mathbf{B^{(t)}}^T \mathbf{X^T} \mathbf{X} \mathbf{B^{(t)}})^{-1} \mathbf{B^{(t)}}^T \mathbf{X^T} \mathbf{Y}$ 

Now next step in alt opt algorithm we update

$$\mathbf{B}^{(t+1)} = \underset{\mathbf{B}}{\operatorname{arg\,min}} \ \mathcal{L}(\mathbf{B}, \mathbf{S^{(t+1)}})$$

Derivating with respect to **B** and equating to 0:

$$\begin{split} \frac{\partial}{\partial \mathbf{B}} \ \mathrm{Tr}[\mathbf{Y^TY - Y^TXBS^{(t+1)} - S^{(1)}}^T \mathbf{B^TX^TY + S^{(t+1)}}^T \mathbf{B^TX^TXBS^{(t+1)}}] &= 0 \\ \Longrightarrow \ \mathbf{0 - X^TYS^{(t+1)}}^T - \mathbf{X^TYS^{(t+1)}}^T + \mathbf{X^TXBS^{(t+1)}}^T \mathbf{S^{(t+1)}}^T + \mathbf{X^TXBS^{(t+1)}}^T \mathbf{S^{(t+1)}}^T \\ &\Longrightarrow \ \mathbf{X^TXBS^{(t+1)}S^{(1)}}^T = \mathbf{X^TYS^{(t+1)}}^T \\ \mathbf{B} &= (\mathbf{X^TX})^{-1}\mathbf{X^TYS^{(t+1)}}^T (\mathbf{S^{(t+1)}S^{(t+1)}}^T)^{-1} \end{split}$$

Therefore 
$$\mathbf{B^{(t+1)}} = (\mathbf{X^TX})^{-1}\mathbf{X^TYS^{(t+1)}}^{\mathbf{T}}(\mathbf{S^{(t+1)}S^{(t+1)}}^{\mathbf{T}})^{-1}$$

We can observe that while computing  $\mathbf{B}^{(1)}$  we required 2 inverse terms to compute so the sub-problem of computing  $\mathbf{B}$  is harder than the sub-problem of  $\mathbf{S}$  which requires only one inverse term to compute.

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**QUESTION** 

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My solution to problem 4 Ridge Regression using Newton's Method

$$\boldsymbol{\omega}_{opt} = \arg\min_{\boldsymbol{\omega}} \frac{1}{2} (\mathbf{y} - \mathbf{X} \boldsymbol{\omega})^{\mathbf{T}} (\mathbf{y} - \mathbf{X} \boldsymbol{\omega}) + \frac{\lambda}{2} \boldsymbol{\omega}^{\mathbf{T}} \boldsymbol{\omega}$$

Considering the loss function:

$$\mathbf{L}(\boldsymbol{\omega}) = \frac{1}{2}(\mathbf{y^Ty} - \mathbf{y^TX}\boldsymbol{\omega} - \boldsymbol{\omega^TX^Ty} + \boldsymbol{\omega^TX^TX}\boldsymbol{\omega}) + \frac{\lambda}{2}\boldsymbol{\omega^T\boldsymbol{\omega}}$$

considering the gradient of loss function:

$$\nabla \mathbf{L}(\boldsymbol{\omega}) = \frac{1}{2}(\mathbf{0} - \mathbf{X^Ty} - \mathbf{X^Ty} + 2\mathbf{X^TX\omega}) + \frac{\lambda}{2}2\boldsymbol{\omega}$$
$$\nabla \mathbf{L}(\boldsymbol{\omega}) = \mathbf{X^TX\omega} - \mathbf{X^Ty} + \lambda\boldsymbol{\omega}$$
$$\nabla \mathbf{L}(\boldsymbol{\omega}) = (\mathbf{X^TX} + \lambda\mathbf{I_D})\boldsymbol{\omega} - \mathbf{X^Ty}$$

considering the hessian of loss function:

$$\nabla^2 \mathbf{L}(\boldsymbol{\omega}) = \mathbf{X}^{\mathbf{T}} \mathbf{X} + \lambda \mathbf{I}_{\mathbf{D}}$$

Now using the newtons method

$$\boldsymbol{\omega}^{(t+1)} = \boldsymbol{\omega}^{(t)} - \mathbf{H}(\boldsymbol{\omega^{(t)}})^{-1}\mathbf{g^{(t)}}$$

substituting the values in newtons formula:

$$\boldsymbol{\omega}^{(t+1)} = \boldsymbol{\omega}^{(t)} - (\mathbf{X}^{\mathbf{T}}\mathbf{X} + \lambda \mathbf{I}_{\mathbf{D}})^{-1} ((\mathbf{X}^{\mathbf{T}}\mathbf{X} + \lambda \mathbf{I}_{\mathbf{D}})\boldsymbol{\omega}^{(t)} - \mathbf{X}^{\mathbf{T}}\mathbf{y})$$
$$\boldsymbol{\omega}^{(t+1)} = (\mathbf{X}^{\mathbf{T}}\mathbf{X} + \lambda \mathbf{I}_{\mathbf{D}})^{-1}\mathbf{X}^{\mathbf{T}}\mathbf{y}$$

As the  $\omega^{t+1}$  is independent of  $\omega$  term. The loss functions gradient and hassian becomes 0 in the next iteration.

So we need only **two iteration** to converge.

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Given a six faced dice rolled N The number of times each face appeared is  $N_1, N_2, ..., N_6$ The probability of each face  $\pi_k$   $k \in (1, 2, 3, 4, 5, 6)$   $\pi_k \in (0, 1)$ 

The likelihood probability mass function for probability vector  $\boldsymbol{\pi} = [\pi_1, \pi_2, ..., \pi_6]$  is Multinolli distribution.

$$P(\mathbf{y}|\pi) = \prod_{n=1}^{N} \prod_{i=1}^{6} \pi_i^{\mathbb{I}[y_n = -i]} = \prod_{i=1}^{6} \pi_i^{N_i}$$

where  $\mathbb{I}[y_n == i]$  is function return 1 if  $y_n == i$  else 0 and  $\sum_{i=1}^6 \pi_i = 1$  Now the prior for the probability vector  $\boldsymbol{\pi}$  is Dirchlet distribution:

$$P(\boldsymbol{\pi}) = \frac{1}{\mathbf{B}(\boldsymbol{\alpha})} \prod_{i=1}^{6} \pi_i^{\alpha_i - 1} \qquad \text{where constant } \mathbf{B}(\boldsymbol{\alpha}) = \frac{\prod_{i=1}^{6} \Gamma(\alpha_i)}{\Gamma(\sum_{i=1}^{6} \alpha_i)}$$

Now for MAP solution:

$$\arg\min_{\boldsymbol{\pi}} \prod_{i=1}^{6} \pi_{i}^{N_{i}} \pi_{i}^{\alpha_{i}-1} = \arg\min_{\boldsymbol{\pi}} \prod_{i=1}^{6} \pi_{i}^{N_{i}+\alpha_{i}-1} \qquad \text{where } \sum_{i=1}^{6} \pi_{i} = 1$$

As it is constrained optimization we use lagranges method:

$$L(\boldsymbol{\pi}, K) = \prod_{i=1}^{6} (N_i + \alpha_i - 1) \log \pi_i + K(\sum_{i=1}^{6} \pi_i - 1)$$

Taking the derivative with respect to each  $\pi_i$  and K, and setting them to zero

$$\pi_i = \frac{N_i + \alpha_i - 1}{K}$$

$$K = N + \sum_{i=1}^{6} \alpha_i - 6$$
 using  $\sum_{i=1}^{6} \pi_i = 1$ 

MAP is given as:

$$\pi_i = \frac{N_i + \alpha_i - 1}{N + \sum_{i=1}^{6} \alpha_i - 6}$$

MAP solution will be better than MLE when there are less number of trails i.e when N is small.

Now calculating the full Bayesian posterior

$$P(\boldsymbol{\pi}|\mathbf{y}) = \frac{P(\boldsymbol{\pi}) * P(\mathbf{y}|\boldsymbol{\pi})}{P(\boldsymbol{\pi}|\mathbf{y})}$$

$$\propto \frac{1}{\mathbf{B}(\boldsymbol{\alpha})} \prod_{i=1}^{6} \pi_i^{\alpha_i - 1} \prod_{i=1}^{6} \pi_i^{N_i} \quad \text{where denominator is constant wrt} \boldsymbol{\pi}$$

$$\propto \prod_{i=1}^{6} \pi_i^{N_i + \alpha_i - 1}$$

$$= \text{Dirichlet}(\boldsymbol{\pi}, N_1 + \alpha_1, ...., N_6 + \alpha_6)$$

As the maximum value of posterior is at mode of Dirichlet distribution we can directly get MAP. i.e

$$\pi_i = \frac{N_i + \alpha_i - 1}{N + \sum_{i=1}^{6} \alpha_i - 6}$$

and we can also get MLE when our prior is uniform i.e when  $\alpha_i=1$ 

$$\pi_i = \frac{N_i}{N}$$