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Large-Scale Learning: Query-driven Machine Learning over Distributed Data

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Abstract

The abstract goes here

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Contents

Chapter 1

Introduction

define aqp [4]

Chapter 2

Related work

The general approach in learning a large multi-dimensional dataset is to investigate the dataset as a whole and estimate the probability density function. G.Cormode et al. in [3] describes the well established techniques used in aggregate query processing. They mention histograms, self tuning histograms, sketches, sampling and wavelets. As C.Anagnostopoulos and P.Triantafillou argue in [2] these techniques assume that they have access to the actual data set, thus can store and preserve the statistical model created. For example to be kept up to date, histograms need to scan all the data. On the other hand Self-tuning histograms execute additional queries to adjust the statistical model accordingly.

As the dataset increases in size, traditional histograms fail to scale well due to the fact that they regularly need to be rebuilt to update the statistical model creating a substantial overhead. It is then noted that the statistical models created by histograms only consider the data distribution without taking into consideration the query pattern of users.[2] Thus, this is not suitable for what we want to achieve, as we are interested in a constructing a model that relies on the query distribution and data distribution. Self-tuning histograms (STH) were proposed to address this by using the cardinality of a query's result to adjust the statistical model. STH still have a fundamental limitation which is the necessity of reading all the dataset because it needs to calculate the probability density function. The use of wavelets, sketches and sampling are also discussed in [2] with the conclusion that they are not viable since they need to access the raw data to create and maintain their structures.

In [2] the query driven approach is discussed in detail and compared to the techniques mentioned above. The query driven approach is very useful in the scenario where one does not have access to the data or it is very costly to access the data. It is able to predict the result of the query without actually running the query.

Chapter 3

Design & Implementation

3.1 Clustering

3.1.1 Nearest Neighbour - Average Data

3.1.2 Offline K-Means

The Algorithm

Batch K-Means is the oldest and most simple clustering method; it is however very efficient. The algorithm, given a finite data set of d-dimensional vectors $X = \{x^t\}_{t=1}^N$ and k *centroids*, or *codebook vectors*, $m_j, j = 1, ..., k$, partitions the data set into k clusters in order to minimize the so called total *reconstruction error*, defined as follows:

$$E(\{m_i\}_{i=1}^k | X) = \sum_t \sum_i b_i^t \tag{3.1}$$

where

$$b_i^t = \begin{cases} 1 & if \parallel x^t - m_i \parallel = min_j \parallel x^t - m_j \parallel \\ 0 & otherwise. \end{cases} \tag{3.2}$$

Therefore, x^t is represented by m_i with an error proportional to the Euclidean distance $\parallel x^t - m_j \parallel$. The procedure starts initializing m_i randomly; at each iteration b_i^t is calculated for all x^t and m_i are updated according to the following rule:

$$m_i = \frac{\sum_t b_i^t x^t}{\sum_t b_i^t}. \tag{3.3}$$

The algorithm terminates if any of the *codebook vectors* m_i hasn't been changed during the update step. Upon termination the function returns the *codebook verctors*[1].

Implementation

The Batch K-Means was implemented in Java. The Cluster class has two objects, an *ArrayList* of *points* representing all the points belonging to the cluster, and a *centroid*, the *codebook vector*. The update function searches for the nearest *codebook vector*.

```
for (int i = 0; i < data.size(); i++) {

        double max = 0;
        int maxIndex = -1;
        for (int j = 0; j < Clusters.size(); j++) {
                double powsum = 0;
                for (int k = 0; k < data.get(0).length; k++) {
                        powsum += Math.pow(data.get(i)[k]
                                        - Clusters.get(j).getCentroid()[k], 2);
                }
                double temp = Math.sqrt(powsum);
                if (maxIndex == -1 || temp <= max) {
                        max = temp;
                        maxIndex = j;
                }
        }
        pointsclusters.set(i, maxIndex + 1);
        Clusters.get(maxIndex).getPoints().add(data.get(i));
}
```

At a later stage the method applies the update rule for each of the *codebook vectors*, counting the number of updated *centroids*.

```
for (int k = 0; k < Clusters.size(); k++) {

        double[] c_d = new double[data.get(0).length];
        for (int j = 0; j < c_d.length; j++) {
                c_d[j] = 0;
        }

        int points = Clusters.get(k).getPoints().size();

        for (int i = 0; i < points; i++) {
                for (int w = 0; w < c_d.length; w++) {
                        c_d[w] += Clusters.get(k).getPoints().get(i)[w];
                }
        }

        if (points > 0) {
                for (int w = 0; w < c_d.length; w++) {
                        c_d[w] /= points;
                }
        }

        double[] conditions = new double[c_d.length];

        for (int w = 0; w < c_d.length; w++) {
                conditions[w] = Math.abs(Clusters.get(k).getCentroid()[w]
                                - c_d[w]);
        }

        int condcounter = 0;
        for(int w=0;w<conditions.length;w++){
                if(conditions[w]<0.001)
                        condcounter++;
        }

        if (condcounter == c_d.length) {
                counter++;
        } else {
                for (int l = 0; l < c_d.length; l++) {
                        Clusters.get(k).getCentroid()[l] = c_d[l];
                }
        }
}
```

The function terminates if the value of the variable counting the number of modified centroids is equal to the number of clusters $counter == Clusters.size()$.

3.1.3 Online K-Means

The Algorithm

The Batch K-Means cannot, or at least not efficiently, deal with huge data sets. Storing a vast amount of data in internal memory can be a serious issue. In order to avoid this problem, Online K-Means does not store input data. Therefore, the algorithm initialize k random *codebook vectors* $m_j, j = 1, ..., k$ from the training set X. For all $x^t \in X$, randomly chosen, the update function computes:

$$i \longleftarrow argmin_j \parallel x^t - m_j \parallel \tag{3.4}$$

$$m_i \longleftarrow m_i + \eta(x^t - m_i) \tag{3.5}$$

until m_i converge [1].

Implementation

The Online K-means was implemented in Java as well. The update method is presented below:

```
public Integer update(float[] point) {
        if (centroids.size() < k) {
                centroids.add(point);
                return centroids.size() - 1;
        } else {
                Integer nearestCentroid = Tools.classify(point, centroids);
                // Move centroid
                this.centroids.set(nearestCentroid, moveCentroid(point, nearestCentroid));

                return nearestCentroid;
        }
}

public float[] moveCentroid(float[] point, int nearestCentroid) {
        float[] update = Tools.subtract(point, this.centroids.get(nearestCentroid));
        update = Tools.multiply(update, alpha);
        return Tools.add(this.centroids.get(nearestCentroid), update);
}
```

The class Tools defines a set of multi dimensional operations like the Euclidean distance, addition, subtraction and multiplication, and finally a method to find the minimum value.

```
public static float distance(float[] p1, float[] p2) {

        float dist = 0;
        for (int i = 0; i < p1.length; i++) {
                dist += (p1[i] - p2[i]) * (p1[i] - p2[i]);
        }
        return (float) Math.sqrt(dist);
}

public static int classify(float[] point, List<float[]> centroids) {
        float minDist = Float.MAX_VALUE;
        int ans = 0;
        for (int i = 0; i < centroids.size(); i++) {
                float tempDist = Tools.distance(point, centroids.get(i));
                if (tempDist < minDist) {
                        minDist = tempDist;
                        ans = i;
                }
        }
        return ans;
}
```

3.1.4 ART

3.1.5 Silhouette

3.2 Query Space Clustering

3.2.1 L interest points

3.2.2 Gaussian distribution

3.3 Prediction

3.3.1 Mapping Query clusters to data clusters

3.3.2 Learning algorithm

3.3.3 Prediction algorithm

Chapter 4

Evaluation

Chapter 5

Conclusion

5.1 Contributions

Bibliography

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