

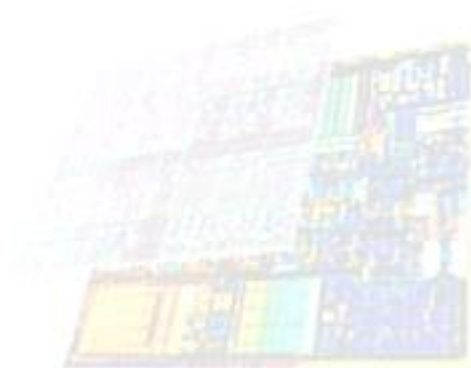
# Administrative Matters

- Course: Graph Theory
- Time/Location: M56-EC016
- Instructor: 李毅郎
- E-mail: [ylli@cs.nctu.edu.tw](mailto:ylli@cs.nctu.edu.tw)
- URL: <https://people.cs.nctu.edu.tw/~ylli/>
- Office: 工三441
- Office Hours: T56 or make an appointment by @
- Teaching Assistants:
  - ✓ 張竣翔 : [lemonade.cs07@nycu.edu.tw](mailto:lemonade.cs07@nycu.edu.tw)      黃晨凱 : [huangkevin88.ee07@nctu.edu.tw](mailto:huangkevin88.ee07@nctu.edu.tw)
  - ✓ 石孟祐 : [yoyochang24.c@nycu.edu.tw](mailto:yoyochang24.c@nycu.edu.tw)      李承翰 : [darrenleeleelee1@gmail.com](mailto:darrenleeleelee1@gmail.com)
  - ✓ 倪子傑 : [nibilly118@gmail.com](mailto:nibilly118@gmail.com)      白育濬 : [a0935796620@gmail.com](mailto:a0935796620@gmail.com)
  - ✓ 耿鈺展 : [kch772018@gmail.com](mailto:kch772018@gmail.com)
- Prerequisites: none
- Textbook: "Graph Theory and Its Applications" by Jonathan L. Gross and Jay Yellen, Second Edition. Publisher: Chapman & Hall/CRC



# Administrative Matters

- Course goal: This course introduces well-known graph models and their applications, and also offers deeper discussions in various well-known graph models and their deduction processes, which are helpful preliminary practices to develop your own solid research model.
- Course contents:
  - ✓ Introduction to Graph Models
  - ✓ Structures and Representation
  - ✓ Trees
  - ✓ Spanning Trees
  - ✓ Connectivity
  - ✓ Optimal Graph Traversals
  - ✓ Planarity and Kuratowski's Theorem
  - ✓ Drawing Graphs and Maps
  - ✓ Graph Colorings
  - ✓ Network Flows and Applications



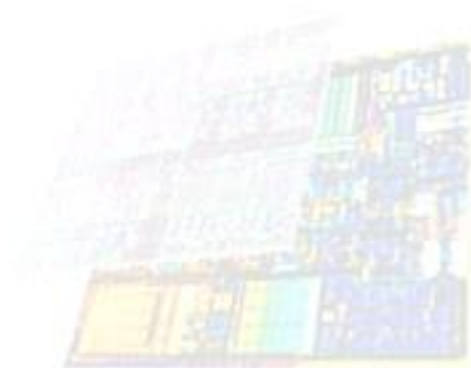
# Administrative Matters

## □ Grading

- ✓ assignments: 35%,
- ✓ Two tests: 65%, (The better one : 35%, the worse one 30%)
- ✓ Class participation: bonus

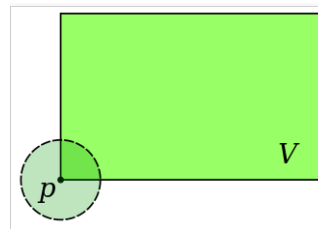
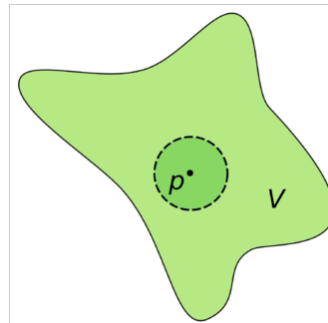
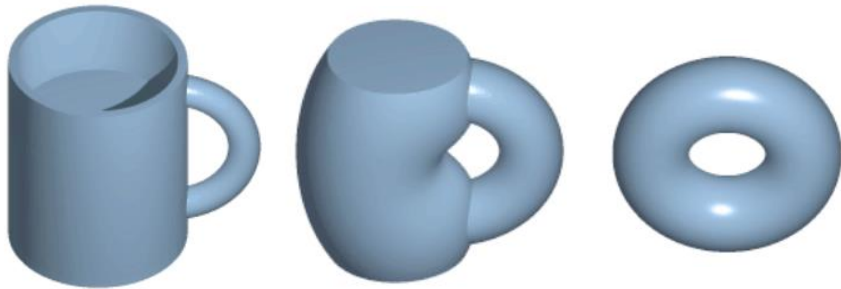
## □ Course Web Site: eCampus

## □ Academic Honesty: *Avoiding cheating at all cost.*



# Preliminary

- ❑ Geometria (Euclidean geometry, Solid geometry, non-Euclidean geometry , Riemannian geometry, Algebraic geometry, Differential geometry, Topology) & Algebra
- ❑ Manifold: Each point of an  $n$ -dimensional manifold has a neighborhood that is homeomorphic (topological isomorphical) to the Euclidean space of dimension  $n$ .
- ❑ 1-D manifold: line and circle. 2-D manifold: surface including plane, sphere and torus.
- ❑ Graph theory can be regarded as 1-D topology.



柏拉圖的形上學將世界切割為兩個不同的區塊：「形式的」智慧世界、以及我們所感覺到的世界。我們所感覺到的世界是從有智慧的形式或理想裡所複製的，但這些複製版本並不完美。那些真正的形式是完美的而且無法改變的，而且只有使用智力加以理解才能實現之，這也表示了人的智力並不包含知覺能力或想像力。



source: wiki



# Preliminary



# Preliminary

- The problem of Seven Bridges of Königsberg solved by Leonhard Euler in 1735

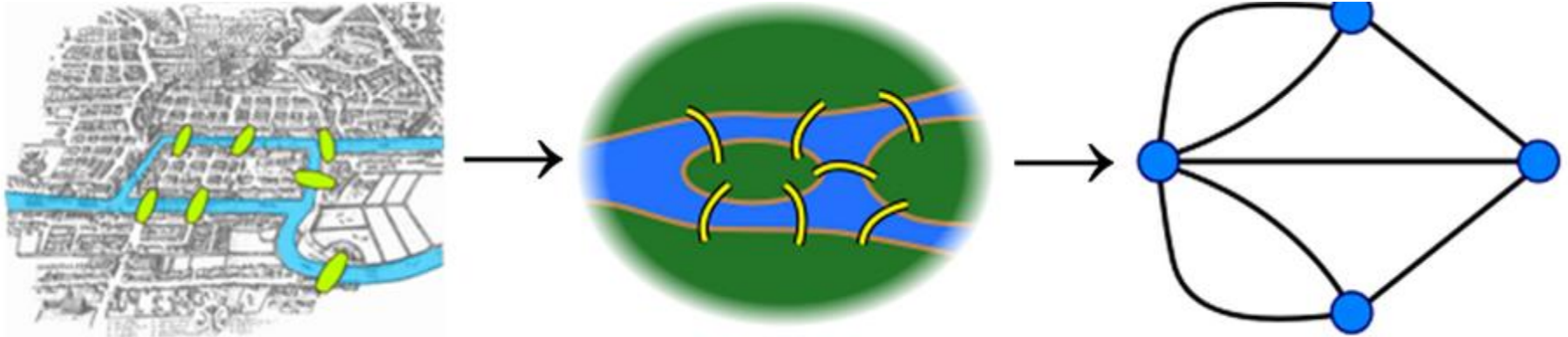
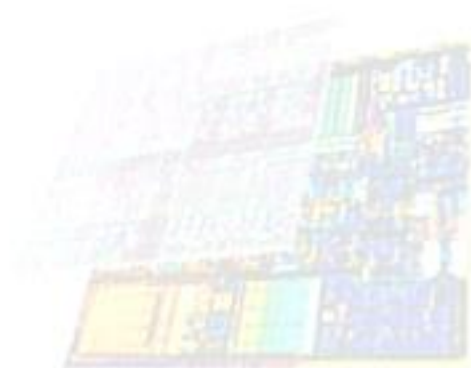


Figure source: wiki







# Chap 1. Introduction to Graph Models



Yih-Lang Li (李毅郎)  
Computer Science Department  
National Chiao Tung University, Taiwan

The sources of most figure images are from the course slides (Graph Theory) of Prof. Gross

# Outline

- Graph Theory Introduction
- Graphs and Digraphs
- Common Families of Graphs
- Graph Modeling Applications
- Walks and Distance
- Paths, Cycles, and Trees
- Vertex and Edge Attributes: More Applications





# 1.1 Graphs and Digraphs

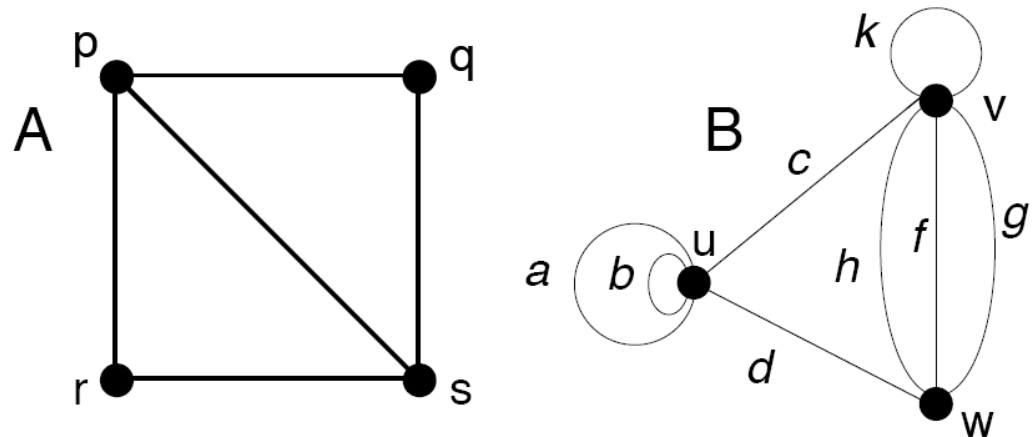
- **DEFINITION:** A **graph**  $G = (V, E)$  is a mathematical structure consisting of two finite sets  $V$  and  $E$ . The elements of  $V$  are called **vertices** (or **nodes**), and the elements of  $E$  are called **edges**. Each edge has a set of one or two vertices associated to it, which are called its **endpoints**.
- **TERMINOLOGY:** An edge is said to **join** its endpoints. A vertex joined by an edge to a vertex  $v$  is said to be a **neighbor** of  $v$ .
- **DEFINITION:** The **(open) neighborhood** of a vertex  $v$  in a graph  $G$ , denoted  $N(v)$ , is the set of all the neighbors of  $v$ . The **closed neighborhood** of  $v$  is given by  $N[v] = N(v) \cup \{v\}$ .

- **DEFINITION:** A **simple graph** has neither self-loops nor multi-edges. A **(general) graph** may have self-loops and/or multi-edges.

$$E_A = \{pq, pr, ps, rs, qs\}$$

$$E_B = \{a, b, c, d, f, g, h, k\}$$

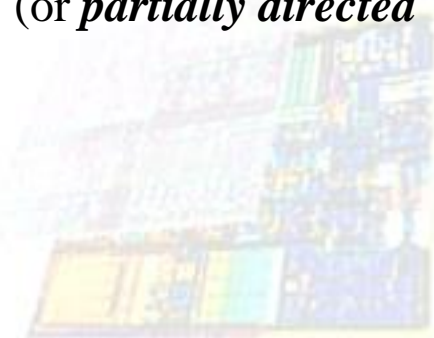
can use vertex to represent edge like  $E_A$ ?  
What's the difference between  $E_A$  and  $E_B$ ?



Line drawings of a graph A and a graph B.

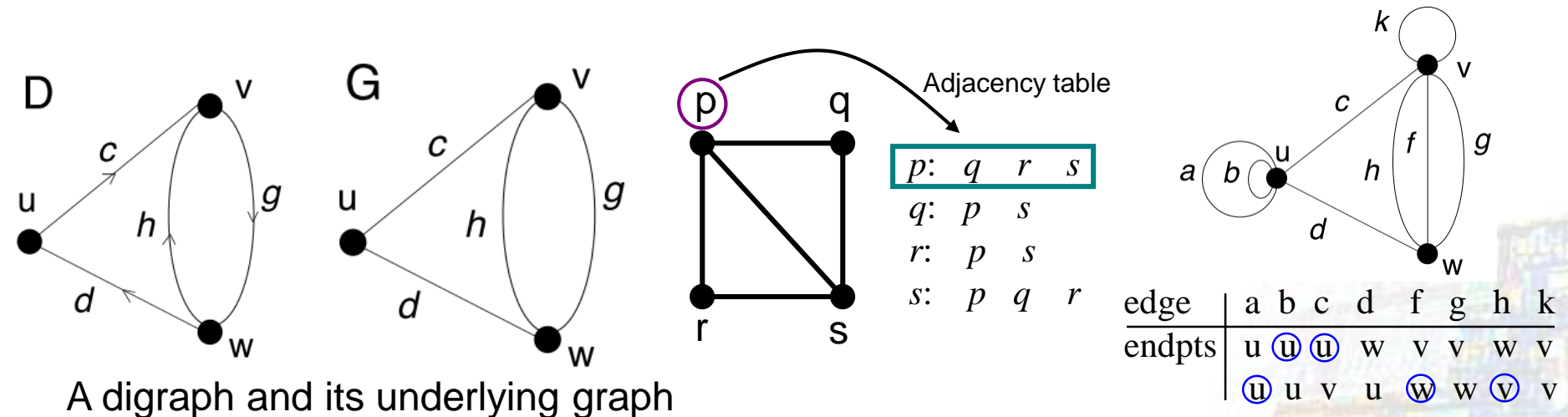
# Simple, General, Null, and Trivial Graphs and Edge Directions

- **DEFINITION:** A *proper edge* is an edge that joins two distinct vertices.
- **DEFINITION:** A *self-loop* is an edge that joins a single endpoint to itself.
- **DEFINITION:** A *multi-edge* is a collection of two or more edges having identical endpoints. The *edge multiplicity* is the number of edges within the multi-edge.
- **DEFINITION:** A *simple graph* has neither self-loops nor multi-edges.
- **DEFINITION:** A *loopless graph* (or *multi-graph*) may have multi-edges but no self-loops.
- **DEFINITION:** A (*general*) *graph* may have self-loops and/or multi-edges.
- **DEFINITION:** A *null graph* is a graph whose vertex- and edge-sets are empty.
- **DEFINITION:** A *trivial graph* is a graph consisting of one vertex and no edges.
- **DEFINITION:** A *directed edge* (or *arc*, from tail to head), *oppositely directed*, *multi-arc*, *arc multiplicity*, *directed graph* (or *digraph*), *simple digraph*, *mixed graph* (or *partially directed graph*)
- **Forward:** along the direction; **backward:** anti the direction.



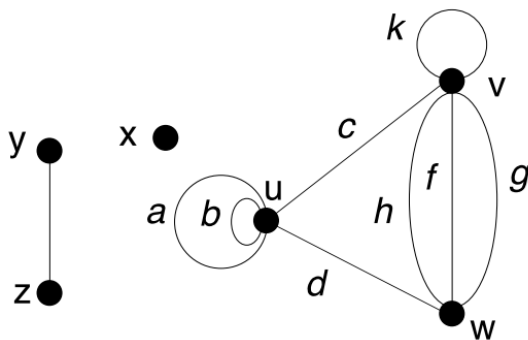
# Formal Specification of Graphs and Digraphs

- DEFINITION:** The *underlying graph* of a directed or mixed graph  $G$  is the graph that results from removing all the designations of head and tail from the directed edges of  $G$  (i.e., deleting all the edge directions).
- DEFINITION:** A *formal specification of a simple graph* is given by an *adjacency table* with a row for each vertex, containing the list of neighbors of that vertex.
- DEFINITION:** A *formal specification of a general graph*  $G = (V, E, \text{endpts})$  consists of a list of its vertices, a list of its edges, and a two-row *incidence table* (specifying the *endpts* function) whose columns are indexed by the edges. The entries in the column corresponding to edge  $e$  are the endpoints of  $e$ .

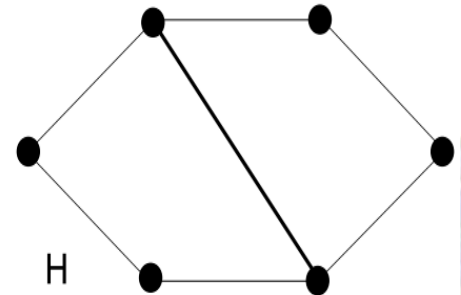
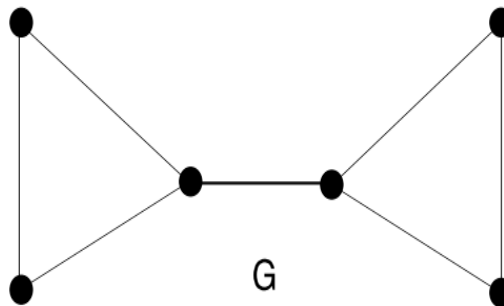


# Degree of a Vertex

- **DEFINITION:** A *formal specification of a general digraph or a mixed graph*  $D = (V, E, \text{endpts}, \text{head}, \text{tail})$  is obtained from the formal specification of the underlying graph by adding the functions  $\text{head} : E_G \rightarrow V_G$  and  $\text{tail} : E_G \rightarrow V_G$ , which designate the *head* vertex and *tail* vertex of each arc.
  - ✓ How to add *head* and *tail* function – ordered-pair, mark head or fixed positioning
- **DEFINITION:** *Adjacent vertices, adjacent edges, incident, degree/valence, d-valent vertex*
- **DEFINITION:** The *degree sequence* of a graph is the sequence formed by arranging the vertex degrees in non-increasing order.
- Two graphs with different structures may have the same degree sequence.



$\langle 6, 6, 4, 1, 1, 0 \rangle$   
 v u w z y x



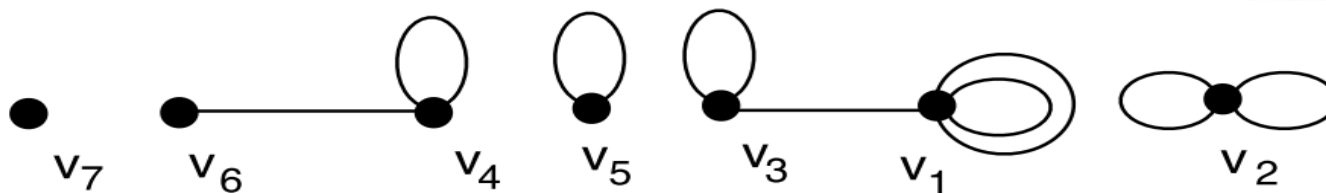
Two graphs with the same degree sequence  
 $\langle 3, 3, 2, 2, 2, 2 \rangle$



# Degree of a Vertex

- **Proposition 1.1.1.** *A non-trivial simple graph  $G$  must have at least one pair of vertices whose degrees are equal.*
  - ✓ **Proof:** pigeonhole principle.
- **Theorem 1.1.2 [Euler's Degree-Sum Theorem].** *The sum of the degrees of the vertices of a graph is twice the number of edges.*
- **Corollary 1.1.3.** *In a graph, there is an even number of vertices having odd degree.*
- **Corollary 1.1.4.** *The degree sequence of a graph is a finite, non-increasing sequence of nonnegative integers whose sum is even.*
- **Question:** For a non-increasing nonnegative sequence of integers, is this sequence the degree sequence of some graph if the sum of all integers is even?
- **Example:** To construct a graph whose degree sequence is  $\langle 5, 4, 3, 3, 2, 1, 0 \rangle$

$v_1 \ v_2 \ v_3 \ v_4 \ v_5 \ v_6 \ v_7$



# Graphic Sequences

- **Theorem 1.1.5.** Suppose that  $\langle d_1, d_2, \dots, d_n \rangle$  is a sequence of nonnegative integers whose sum is even. Then there exists a graph with vertices  $v_1, v_2, \dots, v_n$  such that  $\deg(v_i) = d_i$  for  $i = 1, \dots, n$ .
- **DEFINITION:** A sequence  $\langle d_1, d_2, \dots, d_n \rangle$  is said to be graphic if there is a permutation of it that is the degree sequence of some simple graph. Such a simple graph is said to **realize** the sequence.
- **Theorem 1.1.6.** Let  $\langle d_1, d_2, \dots, d_n \rangle$  be a graphic sequence, with  $d_1 \geq d_2 \geq \dots \geq d_n$ . Then there is a simple graph with vertex-set  $\{v_1, \dots, v_n\}$  satisfying  $\deg(v_i) = d_i$  for  $i = 1, 2, \dots, n$ , **such that**  $v_1$  is adjacent to vertices  $v_2, \dots, v_{d_1+1}$ .

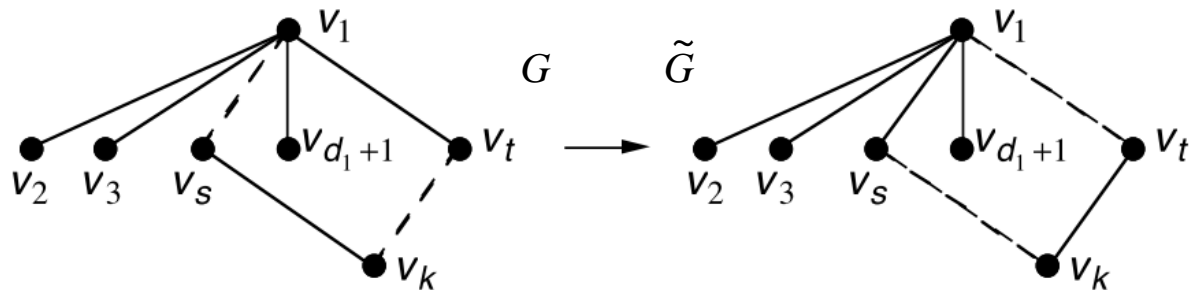
✓ **Proof:**

$r = |N_G(v_1) \cap \{v_2, \dots, v_{d_1+1}\}|$  Select  $G$  such that  $r$  is maximum.

Assume there is a vertex  $v_s$ ,  $2 \leq s \leq d_1+1 < t$ ,  $\deg(v_1) \geq \deg(v_s) \geq \deg(v_{d_1+1}) \geq \deg(v_t)$ ,

In case  $\deg(v_s) > \deg(v_t)$ ,  $\exists v_k$   $G \rightarrow \tilde{G}$ ,  $|N_{\tilde{G}}(v_1) \cap \{v_2, \dots, v_{d_1+1}\}| = r + 1 \rightarrow$  contradiction to the assumption.

In case  $\deg(v_s) = \deg(v_t)$ ,  
swap  $v_t$  with  $v_s$ .



# Graphic Sequences

□ **Corollary 1.1.7 [Havel and Hakimi].** A sequence  $\langle d_1, d_2, \dots, d_n \rangle$  of nonnegative integers such that  $d_1 \geq d_2 \geq \dots \geq d_n$  is graphic if and only if the sequence  $\langle d_2 - 1, \dots, d_{d_1+1} - 1, d_{d_1+2}, \dots, d_n \rangle$  is graphic.

**ALGORITHM: RECURSIVE GRAPHICSEQUENCE**( $\langle d_1, d_2, \dots, d_n \rangle$ )

*Input:* a non-increasing sequence  $\langle d_1, d_2, \dots, d_n \rangle$ .

*Output:* TRUE if the sequence is graphic; FALSE if it is not.

If  $d_1 = 0$  &&  $d_n = 0$

Return TRUE

Else

If  $d_n < 0$

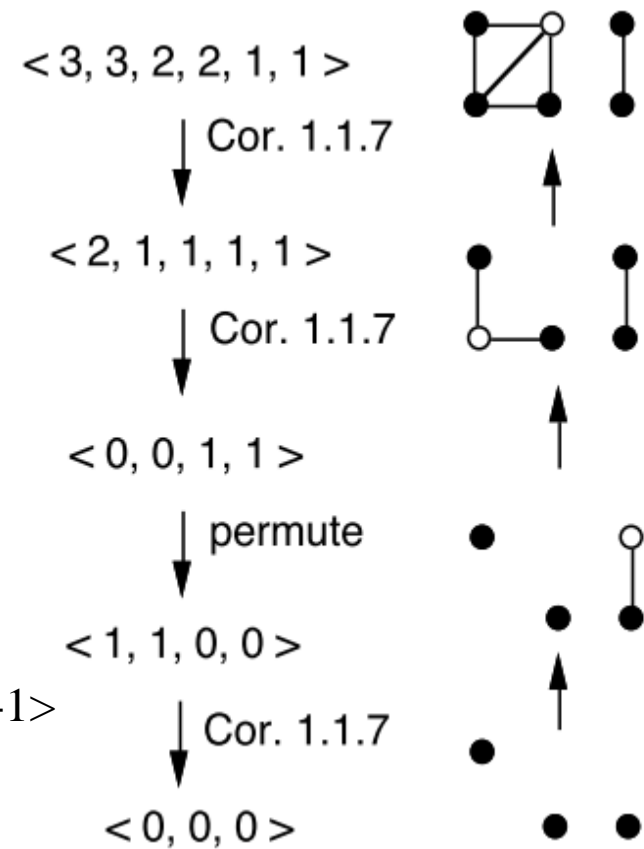
Return FALSE

Else

Let  $\langle a_1, a_2, \dots, a_{n-1} \rangle$  be a non-incr permutation of  $\langle d_2 - 1, \dots, d_{d_1+1} - 1, d_{d_1+2}, \dots, d_n \rangle$ .

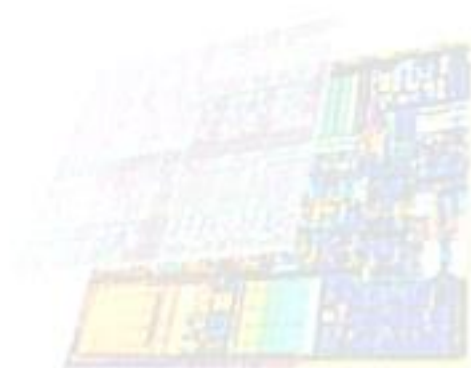
Return GraphicSequence( $\langle a_1, a_2, \dots, a_{n-1} \rangle$ )

□ **Example.**  $\langle 5, 4, 3, 2, 2, 1 \rangle \rightarrow \langle 3, 2, 1, 1, 0 \rangle \rightarrow \langle 1, 0, 0, 0 \rangle \rightarrow \langle 0, 0, -1 \rangle$



# Indegree and Outdegree in a Digraph

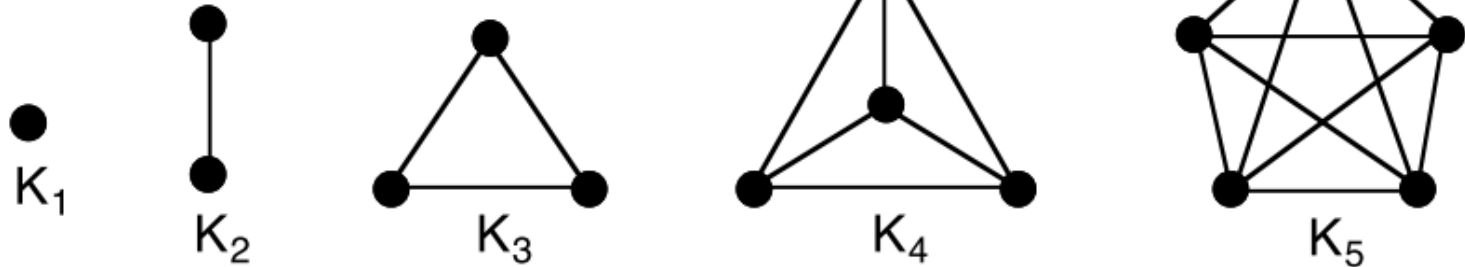
- **DEFINITION:** The *indegree* of a vertex  $v$  in a digraph is the number of arcs directed to  $v$ ; the *outdegree* of vertex  $v$  is the number of arcs directed from  $v$ . Each self-loop at  $v$  counts one toward the indegree of  $v$  and one toward the outdegree.
- **Theorem 1.1.8.** *In a digraph, the sum of the indegrees and the sum of outdegrees both equal the number of edges.*



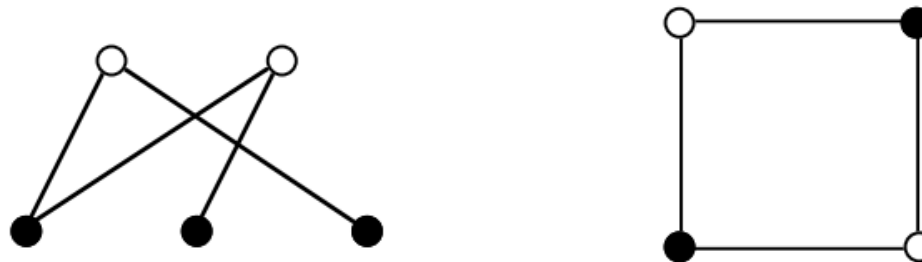


# 1.2 Common Families of Graphs

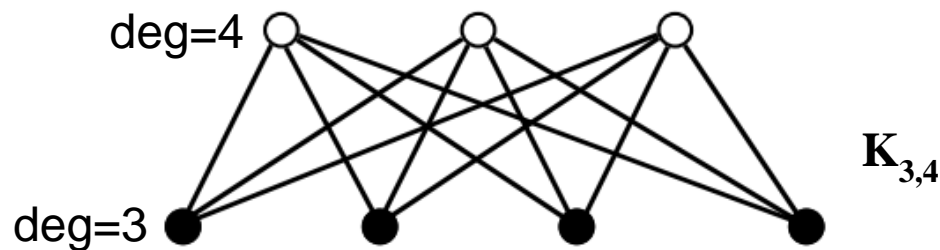
## Complete graphs



## Bipartite graphs

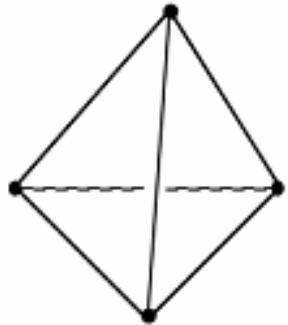


## Complete bipartite graph



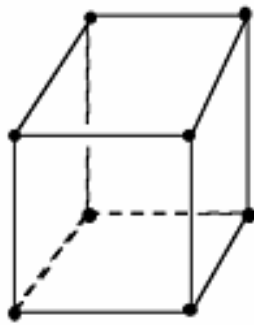
# Regular Graphs

□ **DEFINITION:** A regular graph is a graph whose vertices have common degree  $k$  and is denoted  $k$ -regular graph.



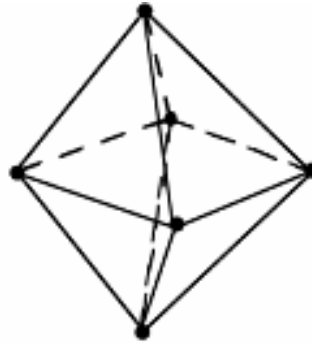
Tetrahedron

(fire)



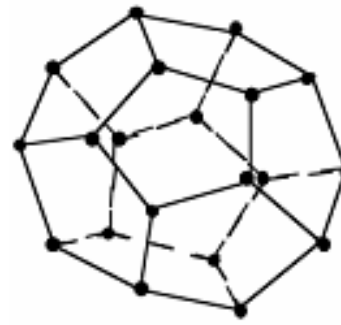
Cube

(earth)



Octahedron

(air)



Dodecahedron

(Ether)



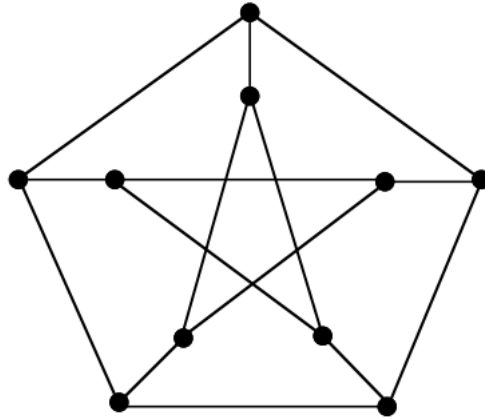
Icosahedron

(water)

□ **Platonic graph:** Only five types of this kind of graphs (in “Timaeus dialogue” & “The elements” ) and each of them consists of regular polygons

- ✓ **Tetrahedron:** 4 regular triangles; **cube:** 6 squares; **Octahedron:** 8 regular triangles; **Dodecahedron:** 12 regular pentagons; **Icosahedron:** 20 regular triangles
- ✓ **Property 1:** The number of polygons adjacent to each vertex is the same.
- ✓ **Property 2:** There exists a sphere such that all vertices are on its surface.
- ✓ **Property 3:** The sum of vertex number and face number equals to the edge number plus 2.

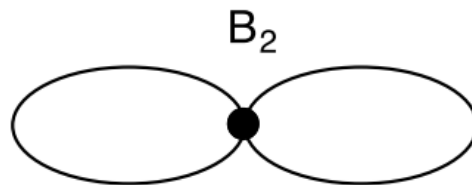
# Regular Graphs



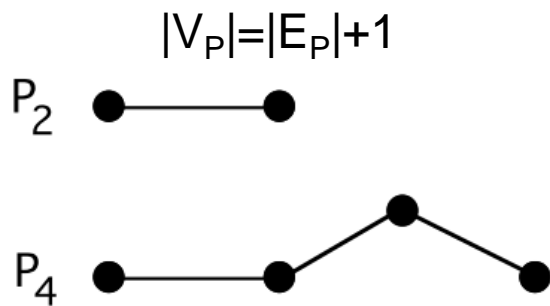
Peterson graph

# Bouquets, Dipoles, Path Graphs, and Cycle Graphs

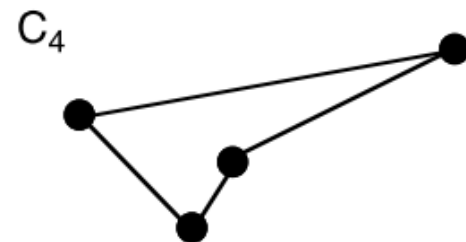
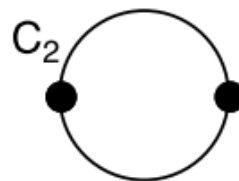
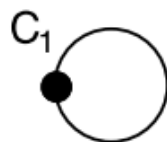
- **DEFINITION:** A graph consisting of a single vertex with  $n$  self-loops is called a *bouquet* and is denoted  $B_n$ .



- **DEFINITION:** A graph consisting of two vertices and  $n$  edges joining them is called a *dipole* and is denoted  $D_n$ .



$$|V_P| = |E_P| + 1$$



$$|V_P| = |E_P|$$

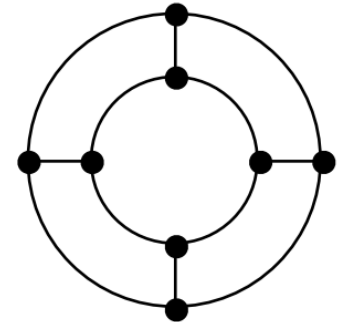
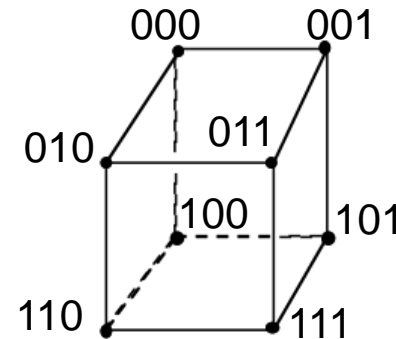
Path graphs  $P_2$  and  $P_4$

Cycle graph  $C_1$ ,  $C_2$ , and  $C_4$



# Hypercubes, Circular Ladders, and Circulant Graphs

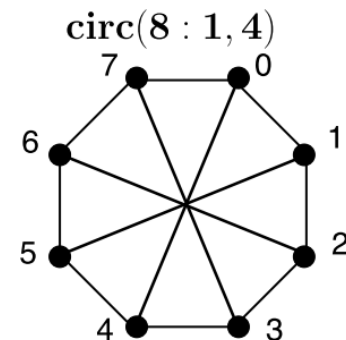
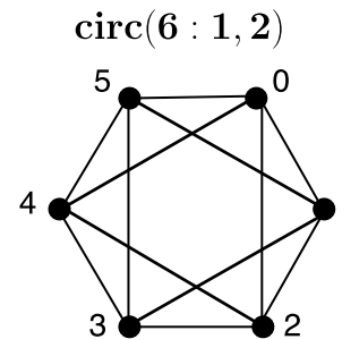
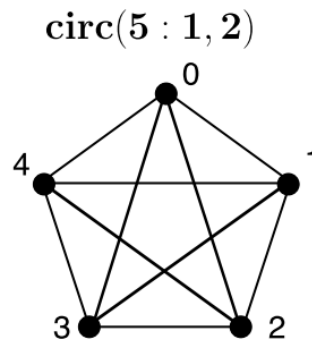
□ Hypercube:  $Q_3$



□ Circular ladder graph:  $CL_4$

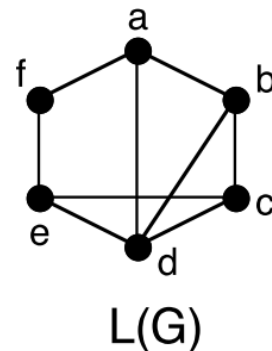
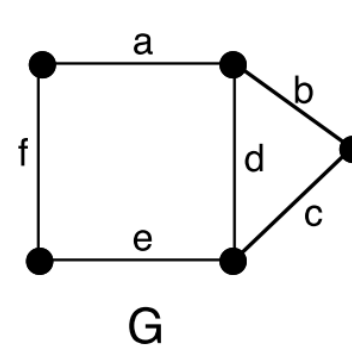
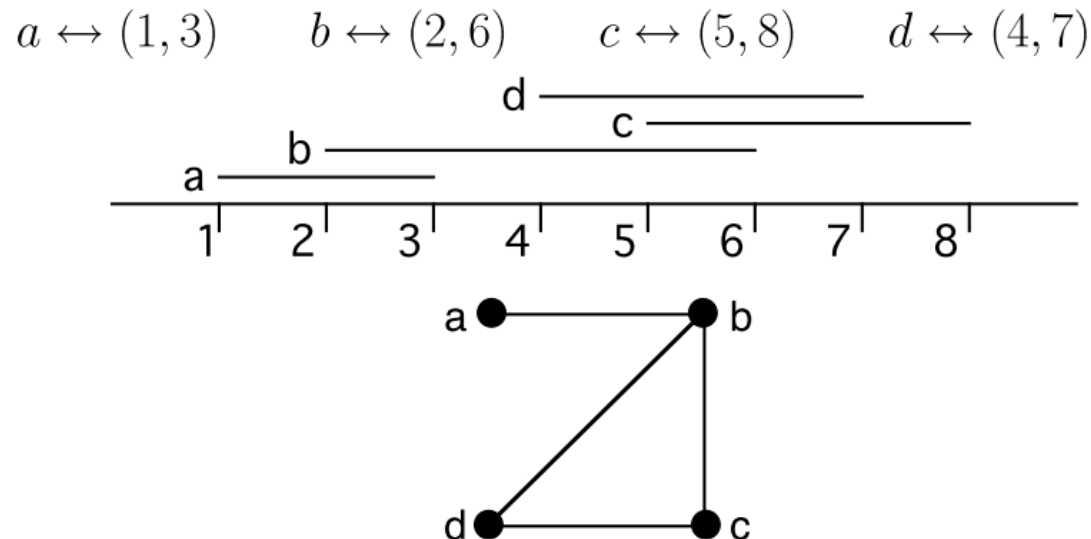
□ **DEFINITION:** To the group of integers  $Z_n = \{0, 1, \dots, n-1\}$  under addition modulo  $n$  and a set  $S \subseteq \{1, 2, \dots, n-1\}$ , the **circulant graph**  $\text{circ}(n : S)$  has a vertex set  $Z_n$ , and two vertices  $i$  and  $j$  are adjacent if and only if there is a number  $s \in S$  such that  $i+s = j \pmod n$  or  $j+s = i \pmod n$ .

✓ The elements of the set  $S$  are called **connections**.



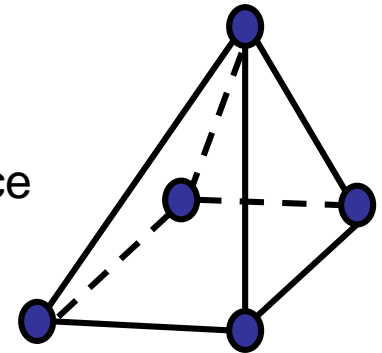
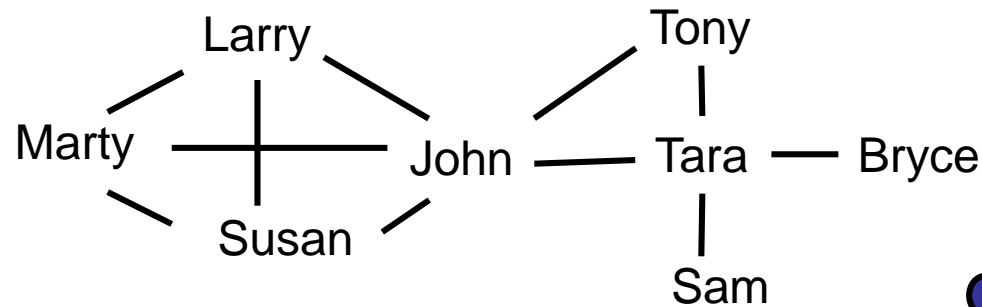
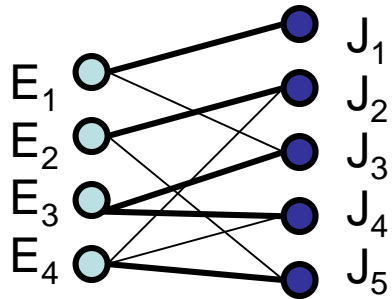
# Intersection, Interval Graphs, and Line Graphs

- DEFINITION:** A simple graph  $G$  with vertex-set  $V_G = \{v_1, v_2, \dots, v_n\}$  is an *intersection graph* if there exists a family of sets  $F = \{S_1, S_2, \dots, S_n\}$  such that vertex  $v_i$  is adjacent to  $v_j$  if and only if  $i \neq j$  and  $S_i \cap S_j \neq \emptyset$ .
- DEFINITION:** A simple graph is an *interval graph* if it is an intersection graph corresponding to a family of intervals on the real line.
- DEFINITION:** The *line graph*  $L(G)$  of a graph  $G$  has a vertex for each edge of  $G$ , and two vertices in  $L(G)$  are adjacent if and only if the corresponding edges in  $G$  have a vertex in common.

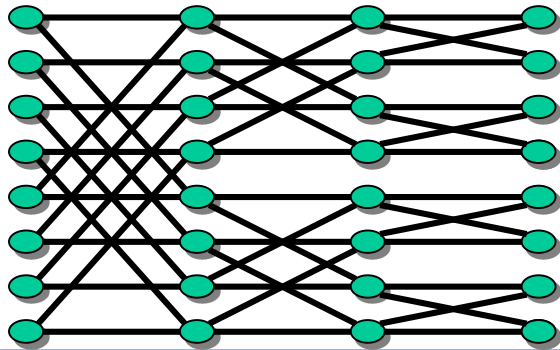


# 1.3 Graph Modeling Applications

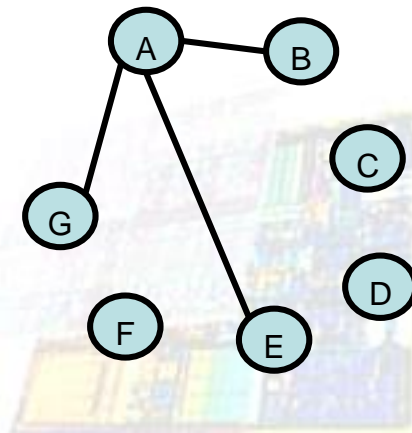
- An optimal assignment of employees to jobs
- An acquaintance network
- Geometric Polyhedra – A non-regular 1-skeleton of a polyhedron



- Butterfly interconnection
- Assigning broadcasting frequencies

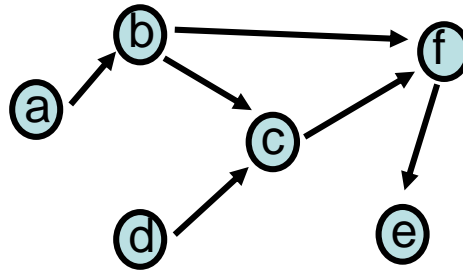


	B	C	D	E	F	G
A	55	110	108	60	150	88
B		87	142	133	98	139
C			77	91	85	93
D				75	114	82
E					107	41
F						123



# 1.3 Graph Modeling Applications

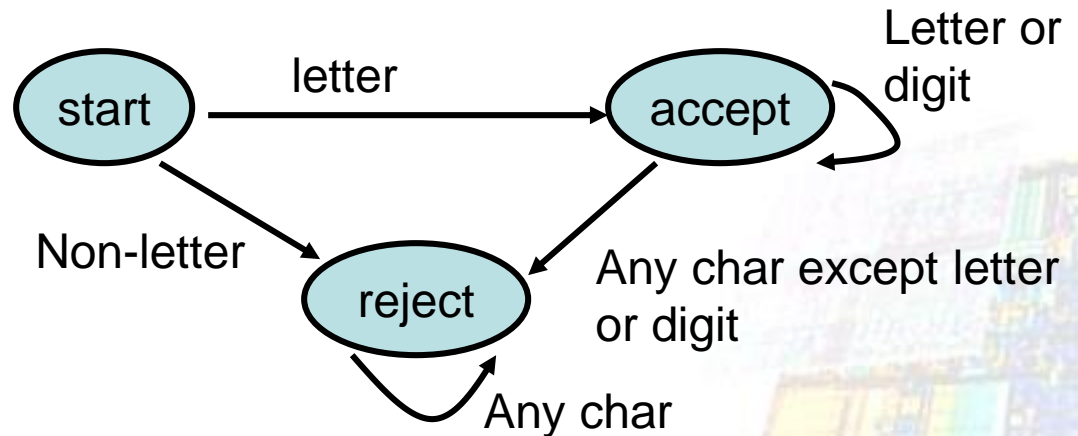
- Activity-scheduling networks



- Flow diagrams for computer programs (auto-tracing & auto-verification)

- Lexical Scanners

✓ Ex. **if** and **ifabc**

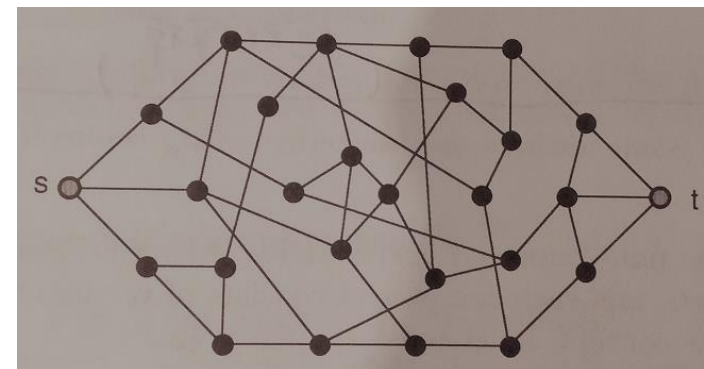
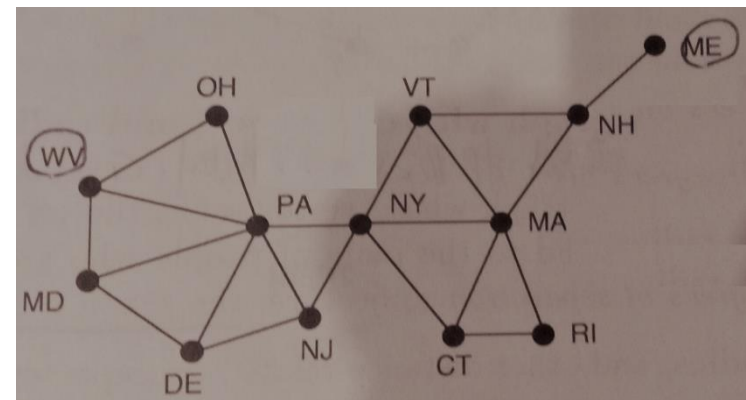
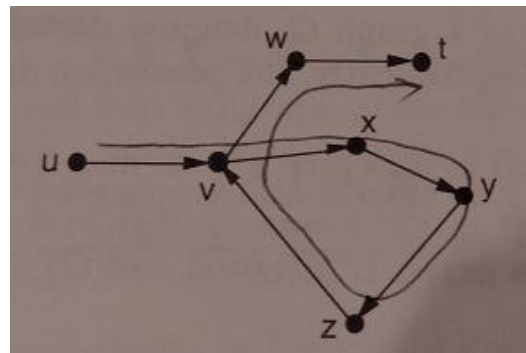
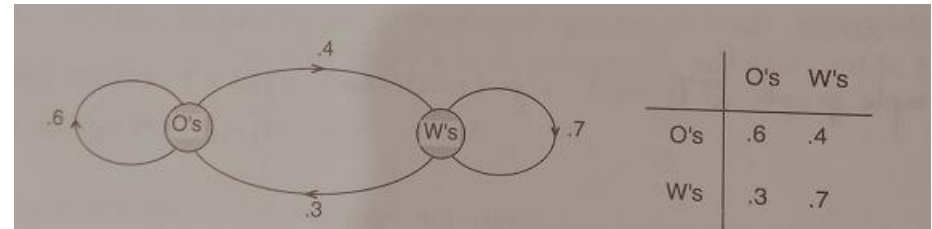
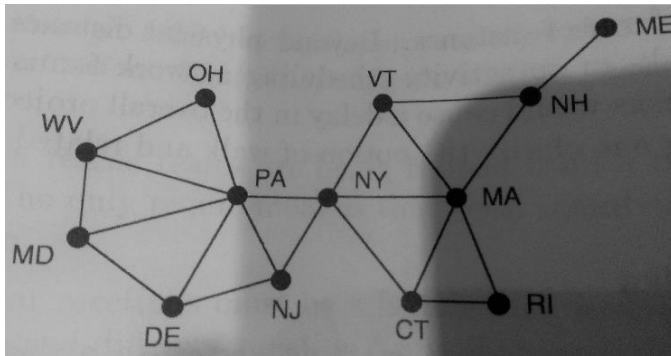




# 1.4 Walks and Distance – Walks and Directed Walks

- **DEFINITION:** In a graph  $G$ , a walk from vertex  $v_0$  to vertex  $v_n$  is an alternating sequence  $W = \langle v_0, e_1, v_1, e_2, \dots, v_{n-1}, e_n, v_n \rangle$  of vertices and edges, such that  $\text{endpts}(e_i) = \{v_{i-1}, v_i\}$ , for  $i = 1, \dots, n$ .
  - ✓ For directed graph,  $W$  is a **directed walk** if each edge  $e_i$  is directed from vertex  $v_{i-1}$  to vertex  $v_i$ . ( $\text{tail}(e_i) = v_{i-1}$  and  $\text{head}(e_i) = v_i$ )
- For a simple graph,  $W = \langle v_0, v_1, \dots, v_n \rangle$
- For a general graph,  $W = \langle v_0, e_1, e_2, \dots, e_n, v_n \rangle$
- **DEFINITION:** The **length** of a walk or directed walk is the number of edge-steps in the walk sequence.
- **DEFINITION:** A **close walk** (or **closed directed walk**) is a nontrivial walk (or directed walk) that begins and ends at the same vertex. An **open walk** (or **open directed walk**) begins and ends at different vertices.
- **DEFINITION:** The **concatenation** of two walks  $W_1 = \langle v_0, e_1, \dots, v_{k-1}, e_k, v_k \rangle$  and  $W_2 = \langle v_k, e_{k+1}, v_{k+1}, e_{k+2}, \dots, v_{n-1}, e_n, v_n \rangle$  such that walk  $W_2$  begins where walk  $W_1$  ends, is the walk  $W_1 \circ W_2 = \langle v_0, e_1, \dots, v_{k-1}, e_k, v_k, e_{k+1}, \dots, v_{n-1}, e_n, v_n \rangle$
- **Sub-walk**

# 1.4 Walks and Distance – Walks and Directed Walks



# Distance, Eccentricity, Diameter, and Radius

□ **DEFINITION:** The *distance*  $d(s, t)$  from a vertex  $s$  to a vertex  $t$  in a graph  $G$  is the length of a shortest  $s$ - $t$  walk if one exists; otherwise,  $d(s, t) = \infty$

✓ *Directed distance*

□ **DEFINITION:** The *eccentricity* of a vertex  $v$  in a graph  $G$ , denoted  $ecc(v)$ , is the distance from  $v$  to a vertex farthest from  $v$ . That is,  $ecc(v) = \max_{x \in V_G} \{d(v, x)\}$

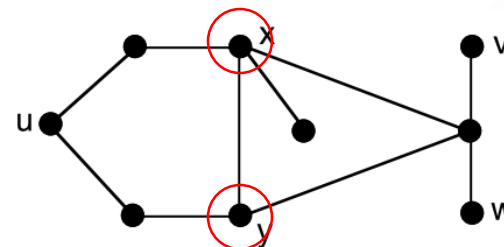
□ **DEFINITION:** The *diameter* of a graph  $G$ , denoted  $diam(G)$ , is the maximum of the vertex eccentricities in  $G$  or, equivalently, the maximum distance between two vertices in  $G$ . That is

$$diam(G) = \max_{x \in V_G} \{ecc(x)\} = \max_{x, y \in V_G} \{d(x, y)\}$$

□ **DEFINITION:** The *radius* of a graph  $G$ , denoted  $rad(G)$ , is the minimum of the vertex eccentricities. That is,  $rad(G) = \min_{x \in V_G} \{ecc(x)\}$

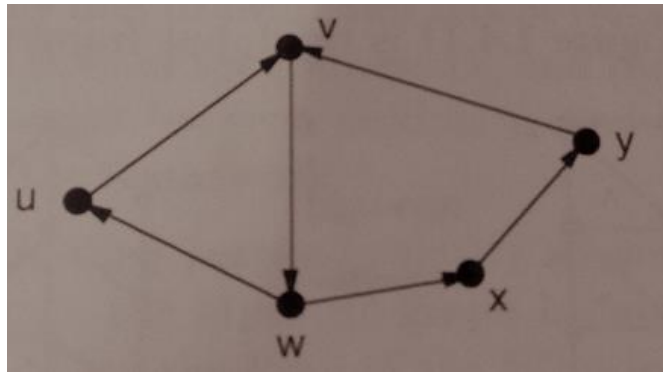
□ **DEFINITION:** A *central vertex*  $v$  of a graph  $G$  is a vertex with minimum eccentricity. Thus,  $ecc(v) = rad(G)$ .

□ **Example.**  $diam(G) = 4$ ,  $rad(G) = 2$



# Connectedness, Strongly Connected Digraph

- DEFINITIONS: *reachable from*; *connected*; *connected* (digraph);
- DEFINITIONS: *mutually reachable*; *strongly connected*
- DEFINITIONS: *strongly orientable*; *strong orientation*



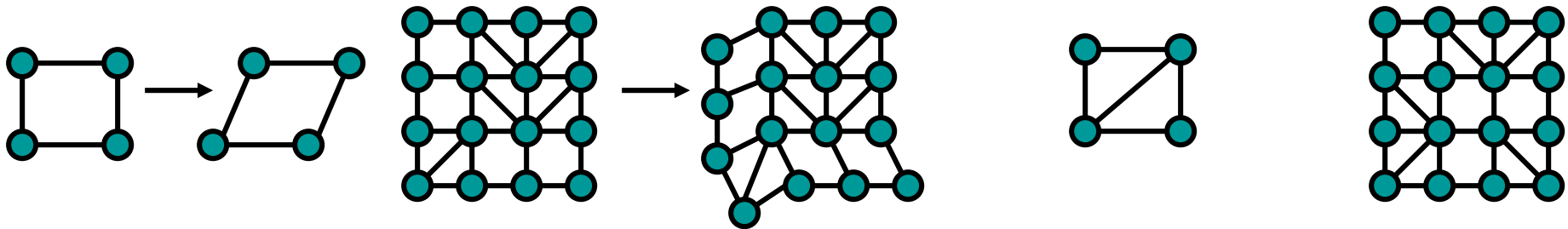
# Application of Connectedness to Rigidity

- *Rigidity of Rectangular Frameworks*: Consider a 2-dimensional framework of steel beams connected by joints that allow each beam to swivel in the plane.

- **DEFINITION**: the framework is said to be **rigid** if none of its beams can swivel.

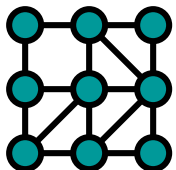
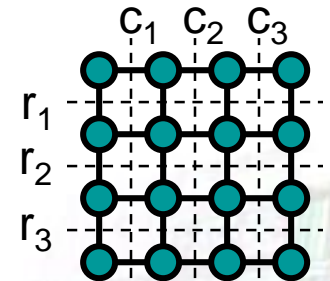
Non-rigid

rigid



- Checking rule: Rigidity can be judged by checking if every rectangle must keep their center lines in perpendicular

- ✓ A diagonal brace in a rectangle at row  $i$  and column  $j \rightarrow r_i \perp c_j$
- ✓  $\perp$  is not completely transitive but can be formed as a sequence
  - $r_i \perp c_j \& c_j \perp r_k \rightarrow r_i \parallel r_k$  and  $r_i \perp c_j \perp r_k$  but not  $r_i \perp r_k$



$$r_1 \perp c_2 \& c_2 \perp r_2 \& c_1 \perp r_2$$

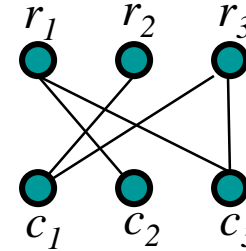
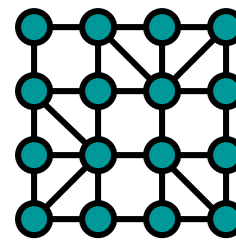
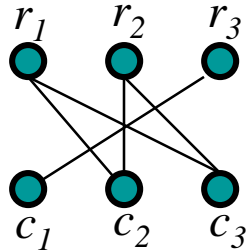
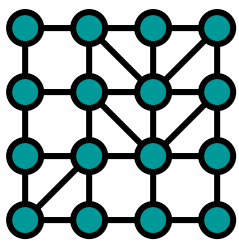
$$r_1 \perp c_2 \perp r_2 \perp c_1 \rightarrow r_1 \perp c_1$$

$$r_1 \perp c_2 \& r_1 \perp c_3 \& r_2 \perp c_2 \& r_2 \perp c_3 \& r_3 \perp c_1$$

$$r_1 \perp c_2 \perp r_2 \perp c_3 \perp r_1 \& r_3 \perp c_1$$

# Application of Connectedness to Rigidity

- ❑ **OBSERVATION:** If every pair row  $i$  and column  $j$  has a related perpendicularity sequence starting at  $r_i$  and ending at  $c_j$  then the framework is rigid.
- ❑ We can build a bipartite graph for perpendicularity sequence by forming a row node set and a column node set and inserting an edge between a row node and a column node if they have perpendicularity relation.



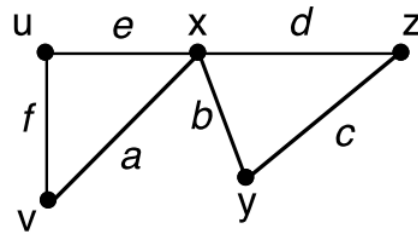
$$r_1 \perp c_2 \& r_1 \perp c_3 \& r_2 \perp c_1 \& r_3 \perp c_1 \& r_3 \perp c_3 \\ c_2 \perp r_1 \perp c_3 \perp r_3 \perp c_1 \perp r_2$$

- ❑ **Theorem 1.4.1.** *A rectangular framework is rigid if only if its associated bipartite graph is connected.*



# 1.5 Paths, Cycles, and Trees

- **DEFINITION:** *trail* (no repeated edges); *path* (no repeated vertices and edges); *trivial*
- **TERMINOLOGY:** no universally agreed-upon terminology for walks, trail, and paths.



$$W = \langle v, a, e, f, a, d, z \rangle$$

$$T = \langle v, a, b, c, d, e, u \rangle$$

- **DEFINITION:** Given a walk  $W = \langle v_0, e_1, v_1, \dots, v_{n-1}, e_n, v_n \rangle$  that contains a nontrivial closed subwalk  $W' = \langle v_k, e_{k+1}, v_{k+1}, \dots, v_{m-1}, e_m, v_k \rangle$ , the **reduction of walk  $W$  by subwalk  $W'$** , denoted  $W - W'$ , is the walk

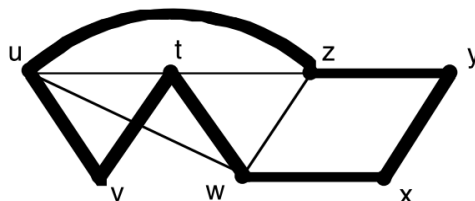
$$W - W' = \langle v_0, e_1, \dots, v_{k-1}, e_k, v_k, e_{m+1}, v_{m+1}, \dots, v_{n-1}, e_n, v_n \rangle$$

Thus,  $W - W'$  is obtained by deleting from  $W$  all of the vertices and edges of  $W'$  except  $v_k$ .

- **DEFINITION:** Given two walks  $A$  and  $B$ , the walk  $B$  is said to be a **reduced walk of  $A$**  if there exists a sequence of walks  $A = W_1, W_2, \dots, W_r = B$  such that for each  $i = 1, \dots, r - 1$ , walk  $W_{i+1}$  is the reduction of  $W_i$  by some closed subwalk of  $W_i$ .

# Deleting Closed Subwalks from Walks and Cycles

- **Lemma 1.5.1.** Every open  $x$ - $y$  walk  $W$  is either an  $x$ - $y$  path or contains a closed subwalk.
- **Theorem 1.5.2.** Let  $W$  be an open  $x$ - $y$  walk. Then either  $W$  is an  $x$ - $y$  path or there is an  $x$ - $y$  path that is a reduced walk of  $W$ .
- **Corollary 1.5.3.** The distance from a vertex  $x$  to a reachable vertex  $y$  is always realizable by an  $x$ - $y$  path.



- **DEFINITION:** *cycle; acyclic graph; hamiltonian cycle; hamiltonian graph*
- **Theorem 1.5.4.** A graph  $G$  is bipartite if and only if it has no cycles of odd length.

**Necessity**  $\Rightarrow$  In a bipartite, a cycle must return to original set

**Sufficiency**  $\Leftarrow$  Assume  $G$  is connected. Get a partition  $(X, Y)$  of  $V$  as follows

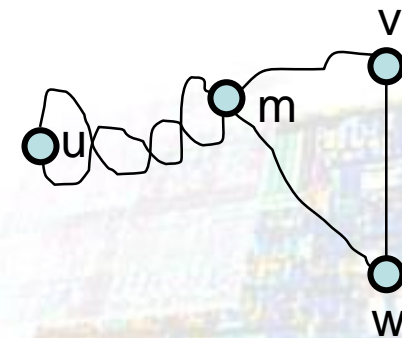
pick any vertex  $u$ ,  $X = \{x \mid d(u, x) \text{ is even}\}$ ;  $Y = \{y \mid d(u, y) \text{ is odd}\}$ ;

**assume  $(X, Y)$  is not a bipartition of  $G \rightarrow e = (v, w)$ ,  $v$  and  $w$  are in  $X$  or  $Y$**

Let  $P_1$  and  $P_2$  be the shortest path from  $u$  to  $v$  and  $w$ . The lengths of  $P_1$  and  $P_2$  are both even or odd. There is at least one common point between  $P_1$  and  $P_2$ , say  $m$ .

$P_1$  and  $P_2$  have the same length from  $u$  to  $m$ .

Cycle  $(m, v, w, m)$  is odd-length.



# Deleting Closed Subwalks from Walks and Cycles

- **Proposition 1.5.5.** Every non-trivial, closed trail  $T$  contains a subwalk that is a cycle.

Let  $T'$  be a minimum length, nontrivial, closed subwalk of  $T \rightarrow$  no proper closed subwalk.

- **Remark.** The assertion of Proposition 1.5.5 is no longer true if  $T$  is merely a closed walk.

- **DEFINITION:** A collection of edge-disjoint cycles,  $C_1, C_2, \dots, C_m$ , is called a *decomposition* of a closed trail  $T$  if each cycle  $C_i$  is either a subwalk or a reduced walk of  $T$  and the edge-sets of the cycles *partition* the edge-set of trail  $T$ .

- **Theorem 1.5.6.** A closed trail can be decomposed into edge-disjoint cycles.

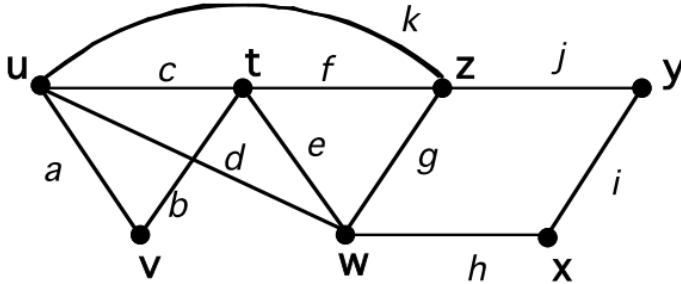
prove by induction:

a closed trail with only one edge is itself a cycle. Assume that the theorem holds for all closed trails with  $m$  or fewer edges.

for the edges  $> m$ , By the proposition 1.5.5, the trail must contain a cycle  $C$ .  $T-C$  can be decomposed into edge-disjoint cycles  $\Rightarrow T$  also can be decomposed into edge-disjoint cycles.

# Cycles and Eulerian Trails

## Edge-disjoint cycles



$$T = \langle u, a, b, c, d, e, f, g, h, i, j, k, u \rangle$$

$$C_1 = \langle z, k, c, f, z \rangle, \langle u, a, b, c, u \rangle$$

$$C_2 = \langle u, a, b, e, d, u \rangle, \langle w, e, f, g, w \rangle$$

$$C_3 = \langle w, h, i, j, g, w \rangle, \langle u, d, h, i, j, k, u \rangle$$

## DEFINITION: *Eulerian trail, eulerian tour, eulerian graph*

## DEFINITION: The *girth* of a graph $G$ with at least one cycle is the length of a shortest cycle in $G$ .

## DEFINITION: A *tree* is a connected graph that has no cycles.

