# Visual Transformers (ViTs)

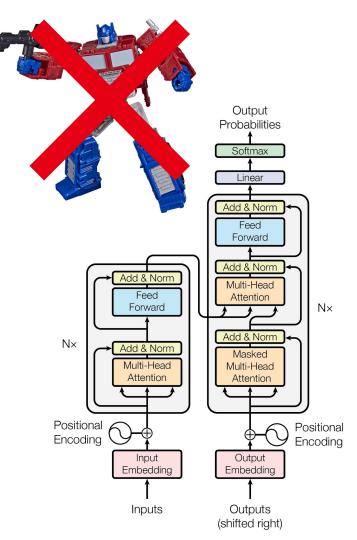
Krzysztof Król

## But what even are "transformers"?

- 1. A deep learning architecture
- 2. Based on the attention mechanism
- 3. Scalable and parallel-izable by default
- 4. Multi-modal (text, image, sound etc.)

#### Variants:

- encoder-only (BERT)
- decoder-only (GPT)
- encoder + decoder (Translation models)



## **History** - "Attention is all you need"

- published in 2017
- mostly google-authored
- unassuming title
- architecture almost unchanged since then

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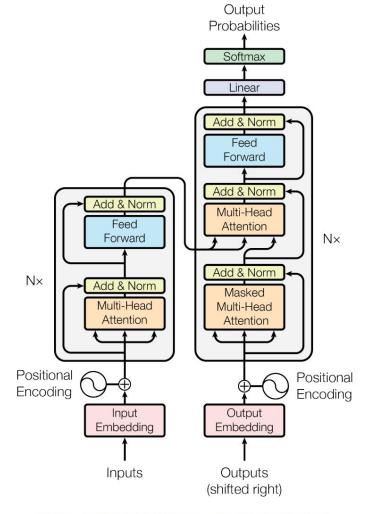


Figure 1: The Transformer - model architecture.

#### **Tokens**

GPT-3.5 & GPT-4

indivisible.

GPT-3 (Legacy)

Many words map to one token, but some don't:

Unicode characters like emojis may be split into

many tokens containing the underlying bytes:

Sequences of characters commonly found next to

each other may be grouped together: 1234567890

Represented as a node in a directional computation graph.

The most fundamental unit of input. They can be:

- Text character, <u>sub-word part</u>, word, sentence
- Image pixel, <u>image patch</u>, row/column of pixels
- Sound single sample, sound patch

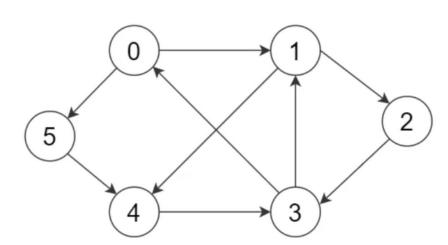
TOKEN IDS

### **Attention**

Mechanism defining how nodes (tokens) "communicate" with each other.

From a node's POV:

- Query (Q) what i'm looking for
- Key (K) what i have
- Value (V) what i will communicate



$$\operatorname{Attention}(Q, K, V) = \operatorname{softmax}(\frac{QK^T}{\sqrt{d_k}})V$$

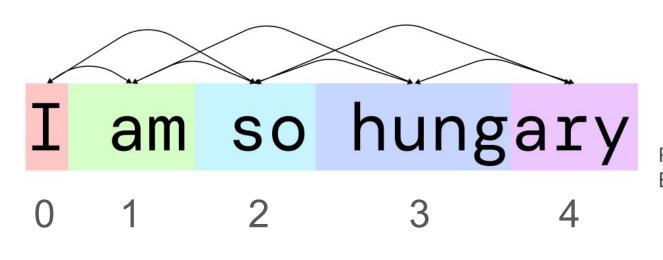
Attention
$$(Q, K, V) = \text{softmax}(\frac{QK^T}{\sqrt{d_k}})V$$

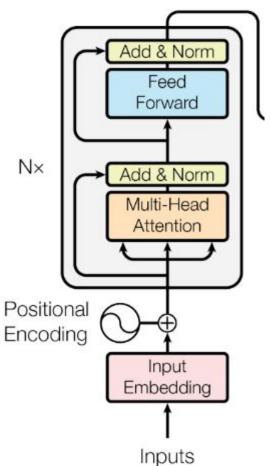
$$\begin{array}{c|c} \mathbf{Q} & \mathbf{K^T} & \mathbf{V} \\ \hline \mathbf{Softmax} \left( \begin{array}{c} & & & & \\ \hline & & & & \\ \hline & & & \\ \end{array} \right) \begin{array}{c} \mathbf{V} \\ \hline \\ \hline \\ \hline \\ \end{array}$$

The self-attention calculation in matrix form

### Encoder

All **nodes** communicate with each other.



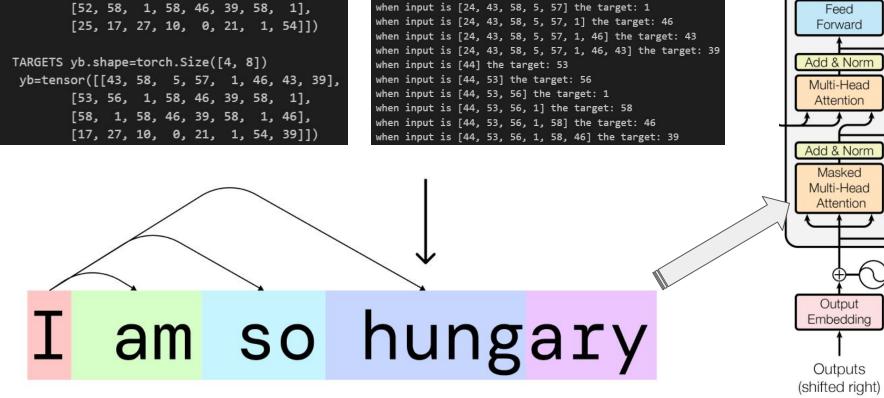


## Decoder

INPUTS xb.shape=torch.Size([4, 8])

xb=tensor([[24, 43, 58, 5, 57, 1, 46, 43],

[44, 53, 56, 1, 58, 46, 39, 58],



when input is [24] the target: 43

when input is [24, 43] the target: 58

when input is [24, 43, 58] the target: 5

when input is [24, 43, 58, 5] the target: 57

Output Probabilities

Softmax

Linear

Add & Norm

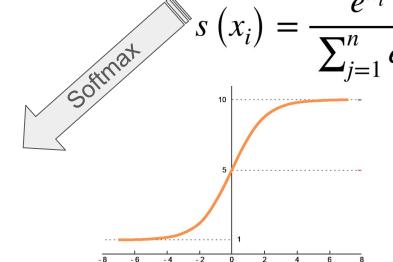
N×

Positional Encoding

## Masked Multi-Head attention

[0.2000, 0.2000, 0.2000, 0.2000, 0.2000, 0.0000, 0.0000, 0.0000], [0.1667, 0.1667, 0.1667, 0.1667, 0.1667, 0.1667, 0.1667, 0.1429, 0.1429, 0.1429, 0.1429, 0.1429, 0.1429, 0.1429, 0.1250, 0.1250, 0.1250, 0.1250, 0.1250, 0.1250, 0.1250, 0.1250])

```
1 weights = torch.zeros((T, T))
     weights = weights.masked_fill(tril == 0, float('-inf'))
     # weights = F.softmax(weights, dim=-1)
tensor([[0., -inf, -inf, -inf, -inf, -inf, -inf, -inf],
       [0., 0., -inf, -inf, -inf, -inf, -inf],
       [0., 0., 0., -inf, -inf, -inf, -inf, -inf],
       [0., 0., 0., 0., -inf, -inf, -inf, -inf],
       [0., 0., 0., 0., 0., -inf, -inf, -inf],
       [0., 0., 0., 0., 0., -inf, -inf],
       [0., 0., 0., 0., 0., 0., -inf],
       [0., 0., 0., 0., 0., 0., 0., 0.]])
```



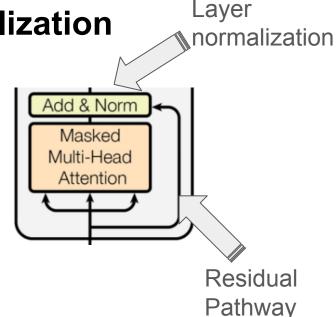
Residual pathways and layer normalization

#### Residual pathways:

- Reduce overfitting in a single step
- stabilizes gradient descent

#### Layer normalization:

- Guarantees mean = 0 and variance = 1
- reduces covariance shift (dependencies between each layer)



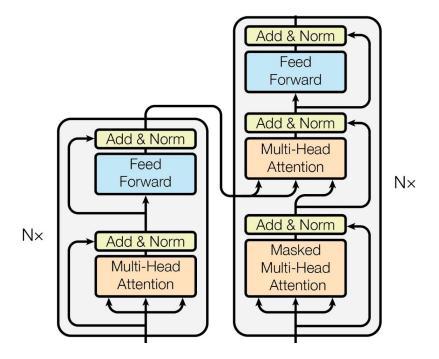
### Feed forward = Old friend: MLP

```
You, 5 days ago | 1 author (You)
class FeedForward(nn.Module):
....""A simple linear layer followed by non-linearity"""
def __init__(self, no_of embedding dims):
super().__init__()
self.net = nn.Sequential(
nn.Linear(no_of_embedding_dims, 4 * no_of_embedding_dims),
nn.ReLU(),
....nn.Linear(4 * no of embedding dims, no of embedding dims),
nn.Dropout(dropout),
)
...def forward(self, x):
   return self.net(x)
```



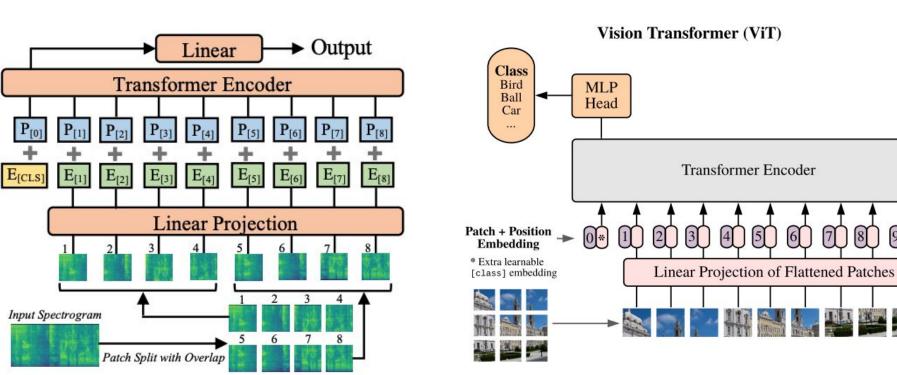
#### How to scale?

Just add more blocks...



## Different input domains

Just patch it, encode it, embed it and throw it in a transformer...



### AN IMAGE IS WORTH 16x16 WORDS: TRANSFORMERS FOR IMAGE RECOGNITION AT SCALE

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#### Vision Transformer (ViT) Class Bird MLP Ball Head Car Transformer Encoder Patch + Position Embedding 0 \* \* Extra learnable Linear Projection of Flattened Patches [class] embedding



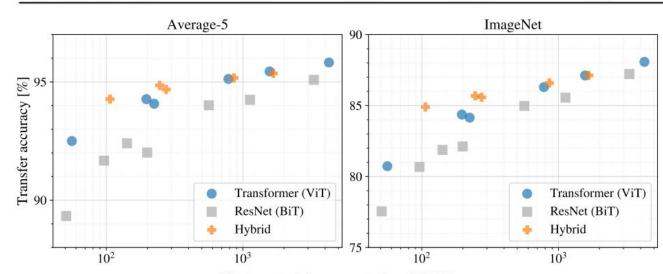
Input

Attention

Figure 6: Representative examples of attention from the output token to the input space. See Appendix D.7 for details.

## Some results:

	Ours-JFT (ViT-H/14)	Ours-JFT (ViT-L/16)	Ours-I21k (ViT-L/16)	BiT-L (ResNet152x4)
ImageNet	$88.55 \pm 0.04$	$87.76 \pm 0.03$	$85.30 \pm 0.02$	$87.54 \pm 0.02$
ImageNet ReaL	$90.72 \pm 0.05$	$90.54 \pm 0.03$	$88.62 \pm 0.05$	90.54
CIFAR-10	$99.50 \pm 0.06$	$99.42 \pm 0.03$	$99.15 \pm 0.03$	$99.37 \pm 0.06$
CIFAR-100	$94.55 \pm 0.04$	$93.90 \pm 0.05$	$93.25 \pm 0.05$	$93.51 \pm 0.08$
Oxford-IIIT Pets	$97.56 \pm 0.03$	$97.32 \pm 0.11$	$94.67 \pm 0.15$	$96.62 \pm 0.23$
Oxford Flowers-102	$99.68 \pm 0.02$	$99.74 \pm 0.00$	$99.61 \pm 0.02$	$99.63 \pm 0.03$
VTAB (19 tasks)	$77.63 \pm 0.23$	$76.28 \pm 0.46$	$72.72 \pm 0.21$	$76.29 \pm 1.70$
TPUv3-core-days	2.5k	0.68k	0.23k	9.9k



Total pre-training compute [exaFLOPs]

## Bonus - Multi-modality

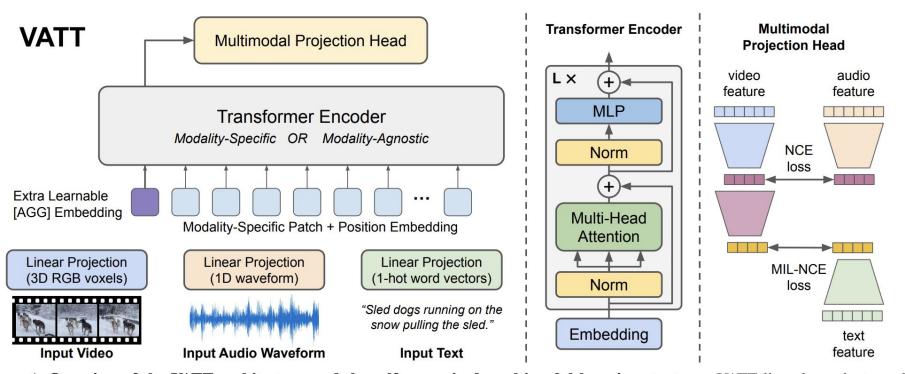


Figure 1. Overview of the VATT architecture and the self-supervised, multimodal learning strategy. VATT linearly projects each modality into a feature vector and feeds it into a Transformer encoder. We define a semantically hierarchical common space to account for the granularity of different modalities and employ the noise contrastive estimation to train the model.