

# Least Squares Problems

## Definition

Consider the possibly overdetermined system of equations

$$Ax = b \tag{1}$$

where  $A \in \mathbb{R}^{n \times m}$  and a vector  $b \in \mathbb{R}^n$ ,  $n \geq m$ . It may not have an exact solution if  $n > m$  or  $A$  is square but singular. The **Least Squares Problem** associated with this system is about finding  $x_0 \in \mathbb{R}^m$  such that

$$\|b - Ax_0\|_2 = \min_{x \in \mathbb{R}^m} \|b - Ax\|_2.$$

## Definition

Consider the possibly overdetermined system of equations

$$Ax = b \quad (1)$$

where  $A \in \mathbb{R}^{n \times m}$  and a vector  $b \in \mathbb{R}^n$ ,  $n \geq m$ . It may not have an exact solution if  $n > m$  or  $A$  is square but singular. The **Least Squares Problem** associated with this system is about finding  $x_0 \in \mathbb{R}^m$  such that

$$\|b - Ax_0\|_2 = \min_{x \in \mathbb{R}^m} \|b - Ax\|_2.$$

**Applications:**

## Definition

Consider the possibly overdetermined system of equations

$$Ax = b \quad (1)$$

where  $A \in \mathbb{R}^{n \times m}$  and a vector  $b \in \mathbb{R}^n$ ,  $n \geq m$ . It may not have an exact solution if  $n > m$  or  $A$  is square but singular. The **Least Squares Problem** associated with this system is about finding  $x_0 \in \mathbb{R}^m$  such that

$$\|b - Ax_0\|_2 = \min_{x \in \mathbb{R}^m} \|b - Ax\|_2.$$

### Applications:

- Polynomial curve fitting.

# Definition

Consider the possibly overdetermined system of equations

$$Ax = b \tag{1}$$

where  $A \in \mathbb{R}^{n \times m}$  and a vector  $b \in \mathbb{R}^n$ ,  $n \geq m$ . It may not have an exact solution if  $n > m$  or  $A$  is square but singular. The **Least Squares Problem** associated with this system is about finding  $x_0 \in \mathbb{R}^m$  such that

$$\|b - Ax_0\|_2 = \min_{x \in \mathbb{R}^m} \|b - Ax\|_2.$$

## Applications:

- ▶ Polynomial curve fitting.
- ▶ Making predictions from existing data.

# Definition

Consider the possibly overdetermined system of equations

$$Ax = b \quad (1)$$

where  $A \in \mathbb{R}^{n \times m}$  and a vector  $b \in \mathbb{R}^n$ ,  $n \geq m$ . It may not have an exact solution if  $n > m$  or  $A$  is square but singular. The **Least Squares Problem** associated with this system is about finding  $x_0 \in \mathbb{R}^m$  such that

$$\|b - Ax_0\|_2 = \min_{x \in \mathbb{R}^m} \|b - Ax\|_2.$$

## Applications:

- ▶ Polynomial curve fitting.
- ▶ Making predictions from existing data.
- ▶ Machine Learning.

# Definition

Consider the possibly overdetermined system of equations

$$Ax = b \quad (1)$$

where  $A \in \mathbb{R}^{n \times m}$  and a vector  $b \in \mathbb{R}^n$ ,  $n \geq m$ . It may not have an exact solution if  $n > m$  or  $A$  is square but singular. The **Least Squares Problem** associated with this system is about finding  $x_0 \in \mathbb{R}^m$  such that

$$\|b - Ax_0\|_2 = \min_{x \in \mathbb{R}^m} \|b - Ax\|_2.$$

## Applications:

- ▶ Polynomial curve fitting.
- ▶ Making predictions from existing data.
- ▶ Machine Learning.

## Direct solution methods:

# Definition

Consider the possibly overdetermined system of equations

$$Ax = b \quad (1)$$

where  $A \in \mathbb{R}^{n \times m}$  and a vector  $b \in \mathbb{R}^n$ ,  $n \geq m$ . It may not have an exact solution if  $n > m$  or  $A$  is square but singular. The **Least Squares Problem** associated with this system is about finding  $x_0 \in \mathbb{R}^m$  such that

$$\|b - Ax_0\|_2 = \min_{x \in \mathbb{R}^m} \|b - Ax\|_2.$$

## Applications:

- ▶ Polynomial curve fitting.
- ▶ Making predictions from existing data.
- ▶ Machine Learning.

## Direct solution methods:

- ▶ Normal Equations Method.



# Definition

Consider the possibly overdetermined system of equations

$$Ax = b \quad (1)$$

where  $A \in \mathbb{R}^{n \times m}$  and a vector  $b \in \mathbb{R}^n$ ,  $n \geq m$ . It may not have an exact solution if  $n > m$  or  $A$  is square but singular. The **Least Squares Problem** associated with this system is about finding  $x_0 \in \mathbb{R}^m$  such that

$$\|b - Ax_0\|_2 = \min_{x \in \mathbb{R}^m} \|b - Ax\|_2.$$

## Applications:

- ▶ Polynomial curve fitting.
- ▶ Making predictions from existing data.
- ▶ Machine Learning.

## Direct solution methods:

- ▶ Normal Equations Method.
- ▶ QR Decomposition Method.

# Definition

Consider the possibly overdetermined system of equations

$$Ax = b \quad (1)$$

where  $A \in \mathbb{R}^{n \times m}$  and a vector  $b \in \mathbb{R}^n$ ,  $n \geq m$ . It may not have an exact solution if  $n > m$  or  $A$  is square but singular. The **Least Squares Problem** associated with this system is about finding  $x_0 \in \mathbb{R}^m$  such that

$$\|b - Ax_0\|_2 = \min_{x \in \mathbb{R}^m} \|b - Ax\|_2.$$

## Applications:

- ▶ Polynomial curve fitting.
- ▶ Making predictions from existing data.
- ▶ Machine Learning.

## Direct solution methods:

- ▶ Normal Equations Method.
- ▶ QR Decomposition Method.
- ▶ Singular Value Decomposition Method.

# Geometry of the Least Squares Problem

As  $A \in \mathbb{R}^{n \times m}$ , the linear map from  $\mathbb{R}^m$  to  $\mathbb{R}^n$  given by  $x \mapsto Ax$ , for all  $x \in \mathbb{R}^m$  has range and null spaces

$$R(A) = \underbrace{\{Ax : x \in \mathbb{R}^m\}}_{\text{also called Col}(A)} \subset \mathbb{R}^n \text{ and } N(A) = \{x \in \mathbb{R}^m : Ax = 0\} \subset \mathbb{R}^m.$$

# Geometry of the Least Squares Problem

As  $A \in \mathbb{R}^{n \times m}$ , the linear map from  $\mathbb{R}^m$  to  $\mathbb{R}^n$  given by  $x \mapsto Ax$ , for all  $x \in \mathbb{R}^m$  has range and null spaces

$$R(A) = \underbrace{\{Ax : x \in \mathbb{R}^m\}}_{\text{also called Col}(A)} \subset \mathbb{R}^n \text{ and } N(A) = \{x \in \mathbb{R}^m : Ax = 0\} \subset \mathbb{R}^m.$$

The LSP is a two stage process involving

1. Find the best approximation to  $b$  from  $R(A)$  i.e., find  $y_0 \in R(A)$  such that  $\|b - y_0\|_2 = \min_{y \in R(A)} \|b - y\|_2$ .
2. Find  $x_0 \in \mathbb{R}^m$  such that  $Ax_0 = y_0$ .

# Geometry of the Least Squares Problem

As  $A \in \mathbb{R}^{n \times m}$ , the linear map from  $\mathbb{R}^m$  to  $\mathbb{R}^n$  given by  $x \mapsto Ax$ , for all  $x \in \mathbb{R}^m$  has range and null spaces

$$R(A) = \underbrace{\{Ax : x \in \mathbb{R}^m\}}_{\text{also called Col}(A)} \subset \mathbb{R}^n \text{ and } N(A) = \{x \in \mathbb{R}^m : Ax = 0\} \subset \mathbb{R}^m.$$

The LSP is a two stage process involving

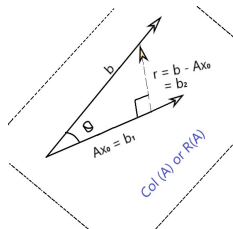
1. Find the best approximation to  $b$  from  $R(A)$  i.e., find  $y_0 \in R(A)$  such that  $\|b - y_0\|_2 = \min_{y \in R(A)} \|b - y\|_2$ .
2. Find  $x_0 \in \mathbb{R}^m$  such that  $Ax_0 = y_0$ .

Since

$$\mathbb{R}^n = R(A) \oplus R(A)^\perp,$$

for  $b \in \mathbb{R}^n$ , there exists unique  $b_1 \in R(A)$ ,  $b_2 \in R(A)^\perp$ , such that  $b = b_1 + b_2$ .

# Geometry of the Least Squares Problem



Therefore for all  $x \in \mathbb{R}^m$ ,  $b - Ax = \underbrace{b_1 - Ax}_{\in R(A)} + \underbrace{b_2}_{\in R(A)^\perp}$  and

$$\begin{aligned} \|b - Ax\|_2^2 &= \langle b_1 - Ax + b_2, b_1 - Ax + b_2 \rangle \\ &= \|b_1 - Ax\|_2^2 + \|b_2\|_2^2 \quad (\text{as } \langle b_1 - Ax, b_2 \rangle = 0 \text{ for all } x \in \mathbb{R}^m) \\ &\geq \|b_2\|_2^2 \\ &= \|\underbrace{b - Ax_0}_{:=r(=b_2)}\|_2^2 \end{aligned}$$

where  $x_0 \in \mathbb{R}^m$  such that  $Ax_0 = b_1$ . Hence,

$$\min_{x \in \mathbb{R}^m} \|b - Ax\|_2^2 \geq \|b - Ax_0\|_2^2 \geq \min_{x \in \mathbb{R}^m} \|b - Ax\|_2^2 \Rightarrow \min_{x \in \mathbb{R}^m} \|b - Ax\|_2 = \|b - Ax_0\|_2.$$

# Geometry of the Least Squares Problem

Hence  $x_0 \in \mathbb{R}^m$  is a solution of the least squares problem and

$$r := b - Ax_0 = b_2 \in R(A)^\perp$$

is the residual vector.

Note that if  $P$  be the orthogonal projection of  $\mathbb{R}^n$  onto  $R(A)$ , then  $Pb = b_1$ . Therefore in summary,

*the orthogonal projection  $b_1$  of  $b$  onto the column space of  $A$  is the nearest vector to  $b$  in the column space of  $A$  with respect to  $\|\cdot\|_2$  and the solution of the LSP associated with the system is a column vector  $x_0$  of scalars which produce the linear combination of the columns of  $A$  to form  $b_1$ .*

# Geometry of the Least Squares Problem

Hence  $x_0 \in \mathbb{R}^m$  is a solution of the least squares problem and

$$r := b - Ax_0 = b_2 \in R(A)^\perp$$

is the residual vector.

Note that if  $P$  be the orthogonal projection of  $\mathbb{R}^n$  onto  $R(A)$ , then  $Pb = b_1$ . Therefore in summary,

*the orthogonal projection  $b_1$  of  $b$  onto the column space of  $A$  is the nearest vector to  $b$  in the column space of  $A$  with respect to  $\|\cdot\|_2$  and the solution of the LSP associated with the system is a column vector  $x_0$  of scalars which produce the linear combination of the columns of  $A$  to form  $b_1$ .*

*Hence the solution of an LSP problem always exists!*



# Geometry of the Least Squares Problem

Hence  $x_0 \in \mathbb{R}^m$  is a solution of the least squares problem and

$$r := b - Ax_0 = b_2 \in R(A)^\perp$$

is the residual vector.

Note that if  $P$  be the orthogonal projection of  $\mathbb{R}^n$  onto  $R(A)$ , then  $Pb = b_1$ . Therefore in summary,

*the orthogonal projection  $b_1$  of  $b$  onto the column space of  $A$  is the nearest vector to  $b$  in the column space of  $A$  with respect to  $\|\cdot\|_2$  and the solution of the LSP associated with the system is a column vector  $x_0$  of scalars which produce the linear combination of the columns of  $A$  to form  $b_1$ .*

*Hence the solution of an LSP problem always exists!*

*How many solutions are there?*

# Geometry of the Least Squares Problem

Hence  $x_0 \in \mathbb{R}^m$  is a solution of the least squares problem and

$$r := b - Ax_0 = b_2 \in R(A)^\perp$$

is the residual vector.

Note that if  $P$  be the orthogonal projection of  $\mathbb{R}^n$  onto  $R(A)$ , then  $Pb = b_1$ . Therefore in summary,

*the orthogonal projection  $b_1$  of  $b$  onto the column space of  $A$  is the nearest vector to  $b$  in the column space of  $A$  with respect to  $\|\cdot\|_2$  and the solution of the LSP associated with the system is a column vector  $x_0$  of scalars which produce the linear combination of the columns of  $A$  to form  $b_1$ .*

*Hence the solution of an LSP problem always exists!*

*How many solutions are there?*

The solution is unique if and only if  $\text{rank } A = m$ .

# Geometry of the Least Squares Problem

Hence  $x_0 \in \mathbb{R}^m$  is a solution of the least squares problem and

$$r := b - Ax_0 = b_2 \in R(A)^\perp$$

is the residual vector.

Note that if  $P$  be the orthogonal projection of  $\mathbb{R}^n$  onto  $R(A)$ , then  $Pb = b_1$ . Therefore in summary,

*the orthogonal projection  $b_1$  of  $b$  onto the column space of  $A$  is the nearest vector to  $b$  in the column space of  $A$  with respect to  $\|\cdot\|_2$  and the solution of the LSP associated with the system is a column vector  $x_0$  of scalars which produce the linear combination of the columns of  $A$  to form  $b_1$ .*

*Hence the solution of an LSP problem always exists!*

*How many solutions are there?*

The solution is unique if and only if  $\text{rank } A = m$ .  
If  $\text{rank } A < m$ , there are infinitely many solutions!

# Geometry of the Least Squares Problem

Hence  $x_0 \in \mathbb{R}^m$  is a solution of the least squares problem and

$$r := b - Ax_0 = b_2 \in R(A)^\perp$$

is the residual vector.

Note that if  $P$  be the orthogonal projection of  $\mathbb{R}^n$  onto  $R(A)$ , then  $Pb = b_1$ . Therefore in summary,

*the orthogonal projection  $b_1$  of  $b$  onto the column space of  $A$  is the nearest vector to  $b$  in the column space of  $A$  with respect to  $\|\cdot\|_2$  and the solution of the LSP associated with the system is a column vector  $x_0$  of scalars which produce the linear combination of the columns of  $A$  to form  $b_1$ .*

*Hence the solution of an LSP problem always exists!*

*How many solutions are there?*

The solution is unique if and only if  $\text{rank } A = m$ .  
If  $\text{rank } A < m$ , there are infinitely many solutions!

**Exercise:** Prove the above statements!

# Normal Equations Method

*How to get  $x_0$ ?*

Since  $R(A)^\perp = N(A^T)$ , where  $N(A^T)$  is the null space of the linear map  $y \mapsto A^T y$  from  $\mathbb{R}^n$  to  $\mathbb{R}^m$ ,  $A^T r = 0$ .

# Normal Equations Method

*How to get  $x_0$ ?*

Since  $R(A)^\perp = N(A^T)$ , where  $N(A^T)$  is the null space of the linear map  $y \mapsto A^T y$  from  $\mathbb{R}^n$  to  $\mathbb{R}^m$ ,  $A^T r = 0$ . Hence  $x_0$  is a solution of

$$A^T A x = A^T b \quad (2)$$

The systems of equations (2) are called the *Normal Equations* of the Least Squares Problem associated with  $Ax = b$ .

# Normal Equations Method

How to get  $x_0$ ?

Since  $R(A)^\perp = N(A^T)$ , where  $N(A^T)$  is the null space of the linear map  $y \mapsto A^T y$  from  $\mathbb{R}^n$  to  $\mathbb{R}^m$ ,  $A^T r = 0$ . Hence  $x_0$  is a solution of

$$A^T A x = A^T b \quad (2)$$

The systems of equations (2) are called the *Normal Equations* of the Least Squares Problem associated with  $Ax = b$ .

**Exercise:** Let  $A \in \mathbb{R}^{n \times m}$  and  $b \in \mathbb{R}^n$ , where  $n \geq m$ . Prove that the following statements are equivalent.

1.  $\text{rank } A = m$ .
2.  $A^T A$  is nonsingular.
3.  $A^T A$  is positive definite.

# Normal Equations Method

How to get  $x_0$ ?

Since  $R(A)^\perp = N(A^T)$ , where  $N(A^T)$  is the null space of the linear map  $y \mapsto A^T y$  from  $\mathbb{R}^n$  to  $\mathbb{R}^m$ ,  $A^T r = 0$ . Hence  $x_0$  is a solution of

$$A^T A x = A^T b \quad (2)$$

The systems of equations (2) are called the *Normal Equations* of the Least Squares Problem associated with  $Ax = b$ .

**Exercise:** Let  $A \in \mathbb{R}^{n \times m}$  and  $b \in \mathbb{R}^n$ , where  $n \geq m$ . Prove that the following statements are equivalent.

1.  $\text{rank } A = m$ .
2.  $A^T A$  is nonsingular.
3.  $A^T A$  is positive definite.

Pseudocode for solving the Least Squares Problem via Normal Equations when  $\text{rank } A = m$ :

1. Form the Normal Equations. ( $2nm^2 + O(nm)$  flops)
2. Solve them via the Cholesky Method. ( $m^3/3 + O(m^2)$  flops)
3. Compute two norm squared of the residual vector. ( $2nm + 3n$  flops)



# Normal Equations Method

Since  $\kappa_2(A^T A) = (\kappa_2(A))^2$ , the Normal Equations can be very ill conditioned even if  $A$  is mildly ill conditioned.

# Normal Equations Method

Since  $\kappa_2(A^T A) = (\kappa_2(A))^2$ , the Normal Equations can be very ill conditioned even if  $A$  is mildly ill conditioned.

The computation of  $A^T A$  is the most expensive step in the process and is also very prone to rounding error.

For example, for the full rank matrix

$$A = \begin{bmatrix} 1 & 1 \\ \epsilon & 0 \\ 0 & \epsilon \end{bmatrix}$$

where  $\epsilon^2 < u$ ,  $\text{fl}(A^T A) = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$  is singular!

Therefore the method may not perform well even for mildly ill conditioned matrices.

# QR Decomposition Method

**Case 1:**  $A$  is full rank, i.e.,  $\text{rank } A = m$ .

Let  $A = Q \begin{bmatrix} R_1 \\ 0 \end{bmatrix}$  be a QR decomposition of  $A$  and  $Q_1$  be the isometry formed by the first  $m$  columns of  $Q$ .

# QR Decomposition Method

**Case 1:**  $A$  is full rank, i.e.,  $\text{rank } A = m$ .

Let  $A = Q \begin{bmatrix} R_1 \\ 0 \end{bmatrix}$  be a QR decomposition of  $A$  and  $Q_1$  be the isometry formed by the first  $m$  columns of  $Q$ .

Then  $Q_1 Q_1^T$  is the orthogonal projection onto  $R(A)$  or  $\text{Col}(A)$ .  
Hence,  $b_1 = Q_1 Q_1^T b$  and the solution  $x_0$  of the LSP associated with  $Ax = b$  satisfies

$$\begin{aligned} Ax_0 &= Q_1 Q_1^T b \\ \Rightarrow Q \begin{bmatrix} R_1 \\ 0 \end{bmatrix} x_0 &= Q[e_1 \cdots e_m][e_1 \cdots e_m]^T \underbrace{Q^T b}_{:=c} \\ \Rightarrow \begin{bmatrix} R_1 \\ 0 \end{bmatrix} x_0 &= \begin{bmatrix} I_m & 0 \\ 0 & 0 \end{bmatrix}_{n \times n} c \\ \Rightarrow R_1 x_0 &= c_1 \end{aligned}$$

where  $c_1$  is the vector of first  $m$  rows of  $c$ .

# QR Decomposition Method

**Case 1:**  $A$  is full rank, i.e.,  $\text{rank } A = m$ .

Let  $A = Q \begin{bmatrix} R_1 \\ 0 \end{bmatrix}$  be a QR decomposition of  $A$  and  $Q_1$  be the isometry formed by the first  $m$  columns of  $Q$ .

Then  $Q_1 Q_1^T$  is the orthogonal projection onto  $R(A)$  or  $\text{Col}(A)$ .  
Hence,  $b_1 = Q_1 Q_1^T b$  and the solution  $x_0$  of the LSP associated with  $Ax = b$  satisfies

$$\begin{aligned} Ax_0 &= Q_1 Q_1^T b \\ \Rightarrow Q \begin{bmatrix} R_1 \\ 0 \end{bmatrix} x_0 &= Q[e_1 \cdots e_m][e_1 \cdots e_m]^T \underbrace{Q^T b}_{:=c} \\ \Rightarrow \begin{bmatrix} R_1 \\ 0 \end{bmatrix} x_0 &= \begin{bmatrix} I_m & 0 \\ 0 & 0 \end{bmatrix}_{n \times n} c \\ \Rightarrow R_1 x_0 &= c_1 \end{aligned}$$

where  $c_1$  is the vector of first  $m$  rows of  $c$ .

# QR Decomposition Method

**Case 2:**  $\text{rank } A = r < m$ .

# QR Decomposition Method

**Case 2:**  $\text{rank } A = r < m$ .

**Exercise:** Let  $AP = Q \begin{bmatrix} R_1 & R_2 \\ 0 & 0 \end{bmatrix}$  be a rank revealing QR

decomposition of  $A$  where  $R_1 \in \mathbb{R}^{r \times r}$ ,  $R_2 \in \mathbb{R}^{r \times m-r}$ ,  $R_1$  being upper triangular and nonsingular. Let  $Q_1 = [q_1 \cdots q_r]$  be the isometry formed by the first  $r$  columns of  $Q$ . Then prove that

$\text{Col}(A)(= R(A)) = \text{span} \{APe_1, \dots, APe_r\} = \text{span} \{q_1, \dots, q_r\} = \text{Col}(Q_1)$ .

# QR Decomposition Method

**Case 2:**  $\text{rank } A = r < m$ .

**Exercise:** Let  $AP = Q \begin{bmatrix} R_1 & R_2 \\ 0 & 0 \end{bmatrix}$  be a rank revealing QR

decomposition of  $A$  where  $R_1 \in \mathbb{R}^{r \times r}$ ,  $R_2 \in \mathbb{R}^{r \times m-r}$ ,  $R_1$  being upper triangular and nonsingular. Let  $Q_1 = [q_1 \cdots q_r]$  be the isometry formed by the first  $r$  columns of  $Q$ . Then prove that

$$\text{Col}(A) (= R(A)) = \text{span} \{APe_1, \dots, APe_r\} = \text{span} \{q_1, \dots, q_r\} = \text{Col}(Q_1).$$

Therefore,  $Q_1 Q_1^T$  is the orthogonal projection onto  $\text{Col}(A)$  and any solution  $x_0$  of the LSP associated with  $Ax = b$  satisfies

$$\begin{aligned} Ax_0 = Q_1 Q_1^T b &\Rightarrow Q \begin{bmatrix} R_1 & R_2 \\ 0 & 0 \end{bmatrix} \underbrace{P^T x_0}_{:=y} = Q[e_1 \cdots e_r][e_1 \cdots e_r]^T \underbrace{Q^T b}_{:=c} \\ &\Rightarrow \begin{bmatrix} R_1 & R_2 \\ 0 & 0 \end{bmatrix}_{n \times m} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}_{m \times 1} = \begin{bmatrix} I_r & 0 \\ 0 & 0 \end{bmatrix}_{n \times n} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}_{n \times 1} \end{aligned}$$

$c_1, y_1$  being the vectors of first  $r$  rows of  $c$  and  $y$  respectively and  $c_2, y_2$  the vector formed by the last  $m - r$  rows of  $y$  and last  $n - r$  rows of  $c$  respectively



# QR Decomposition Method

Then,  $R_1 y_1 + R_2 y_2 = c_1 \Rightarrow R_1 y_1 = c_1 - R_2 y_2$ .

# QR Decomposition Method

Then,  $R_1 y_1 + R_2 y_2 = c_1 \Rightarrow R_1 y_1 = c_1 - R_2 y_2$ .

Choose  $y_2$  arbitrarily and  $y_1$  as the solution of the above  $r \times r$  upper triangular system.

# QR Decomposition Method

Then,  $R_1 y_1 + R_2 y_2 = c_1 \Rightarrow R_1 y_1 = c_1 - R_2 y_2$ .

Choose  $y_2$  arbitrarily and  $y_1$  as the solution of the above  $r \times r$  upper triangular system.

For ease of computation choose  $y_2 = 0$ . Then one solution  $x_0 \in \mathbb{R}^m$  satisfying

$$\|b - Ax_0\|_2^2 = \min_{x \in \mathbb{R}^m} \|b - Ax\|_2^2$$

is given by

$$x_0 = P \begin{bmatrix} y_1 \\ 0 \end{bmatrix}$$

where  $R_1 y_1 = c_1$ .

# QR Decomposition Method

Then,  $R_1 y_1 + R_2 y_2 = c_1 \Rightarrow R_1 y_1 = c_1 - R_2 y_2$ .

Choose  $y_2$  arbitrarily and  $y_1$  as the solution of the above  $r \times r$  upper triangular system.

For ease of computation choose  $y_2 = 0$ . Then one solution  $x_0 \in \mathbb{R}^m$  satisfying

$$\|b - Ax_0\|_2^2 = \min_{x \in \mathbb{R}^m} \|b - Ax\|_2^2$$

is given by

$$x_0 = P \begin{bmatrix} y_1 \\ 0 \end{bmatrix}$$

where  $R_1 y_1 = c_1$ .

**Exercise:** If  $r = b - Ax_0$  prove that  $\|r\|_2 = \|c_2\|_2$ .

# QR Decomposition Method

**Pseudocode for solving the LSP associated with  $Ax = b$  via QR decomposition method:**

---

1. Find  $R = \begin{bmatrix} R_1 & R_2 \\ 0 & 0 \end{bmatrix}$  of a rank revealing QR decomposition of  $A$  and suppose  $Q_1, \dots, Q_r$  are the reflectors and  $P_1, \dots, P_r$  are the permutations required in the process. Here  $r \leq m$ .  
( costs  $2nm^2 - \frac{2}{3}m^3 + O(nm) + O(m^2)$  flops if  $r = m$ .)

# QR Decomposition Method

**Pseudocode for solving the LSP associated with  $Ax = b$  via QR decomposition method:**

---

1. Find  $R = \begin{bmatrix} R_1 & R_2 \\ 0 & 0 \end{bmatrix}$  of a rank revealing QR decomposition of  $A$  and suppose  $Q_1, \dots, Q_r$  are the reflectors and  $P_1, \dots, P_r$  are the permutations required in the process. Here  $r \leq m$ .  
( costs  $2nm^2 - \frac{2}{3}m^3 + O(nm) + O(m^2)$  flops if  $r = m$ .)
2. Compute  $c = Q_r \cdots Q_1 b$  and extract vectors  $c_1, c_2$  from its first entries.  
(costs  $O(nm)$  flops if  $r = m$ .)

# QR Decomposition Method

**Pseudocode for solving the LSP associated with  $Ax = b$  via QR decomposition method:**

---

1. Find  $R = \begin{bmatrix} R_1 & R_2 \\ 0 & 0 \end{bmatrix}$  of a rank revealing QR decomposition of  $A$  and suppose  $Q_1, \dots, Q_r$  are the reflectors and  $P_1, \dots, P_r$  are the permutations required in the process. Here  $r \leq m$ .  
(costs  $2nm^2 - \frac{2}{3}m^3 + O(nm) + O(m^2)$  flops if  $r = m$ .)
2. Compute  $c = Q_r \cdots Q_1 b$  and extract vectors  $c_1, c_2$  from its first entries.  
(costs  $O(nm)$  flops if  $r = m$ .)
3. Find  $\|r\|_2^2 = \|c_2\|_2^2$ .  
(costs  $O(nm)$  flops if  $r = m$ .)

# QR Decomposition Method

**Pseudocode for solving the LSP associated with  $Ax = b$  via QR decomposition method:**

---

1. Find  $R = \begin{bmatrix} R_1 & R_2 \\ 0 & 0 \end{bmatrix}$  of a rank revealing QR decomposition of  $A$  and suppose  $Q_1, \dots, Q_r$  are the reflectors and  $P_1, \dots, P_r$  are the permutations required in the process. Here  $r \leq m$ .  
(costs  $2nm^2 - \frac{2}{3}m^3 + O(nm) + O(m^2)$  flops if  $r = m$ .)
2. Compute  $c = Q_r \cdots Q_1 b$  and extract vectors  $c_1, c_2$  from its first entries.  
(costs  $O(nm)$  flops if  $r = m$ .)
3. Find  $\|r\|_2^2 = \|c_2\|_2^2$ .  
(costs  $O(nm)$  flops if  $r = m$ .)
4. Solve  $R_1 y = c_1$ .  
(costs  $O(m^2)$  flops if  $r = m$ .)



# QR Decomposition Method

**Pseudocode for solving the LSP associated with  $Ax = b$  via QR decomposition method:**

1. Find  $R = \begin{bmatrix} R_1 & R_2 \\ 0 & 0 \end{bmatrix}$  of a rank revealing QR decomposition of  $A$  and suppose  $Q_1, \dots, Q_r$  are the reflectors and  $P_1, \dots, P_r$  are the permutations required in the process. Here  $r \leq m$ .  
(costs  $2nm^2 - \frac{2}{3}m^3 + O(nm) + O(m^2)$  flops if  $r = m$ .)
2. Compute  $c = Q_r \cdots Q_1 b$  and extract vectors  $c_1, c_2$  from its first entries.  
(costs  $O(nm)$  flops if  $r = m$ .)
3. Find  $\|r\|_2^2 = \|c_2\|_2^2$ .  
(costs  $O(nm)$  flops if  $r = m$ .)
4. Solve  $R_1 y = c_1$ .  
(costs  $O(m^2)$  flops if  $r = m$ .)
5. Set  $x_0 = P_1 \cdots P_r \begin{bmatrix} y \\ 0 \end{bmatrix}_{m \times 1}$ .  
(Here the zeroes are necessary only if  $r < m$ .)