

✓ nmi | spring 2024

lecture 18 : finite difference methods

✓ 7.2 finite difference methods

finite difference methods (FDM) replace derivatives with simpler, discrete approximations.

let $y(t)$ be a function with at least four continuous derivatives.

$$y'(t) = \frac{y(t+h) - y(t-h)}{2h} - \frac{h^2}{3!} y'''(c)$$
$$y''(t) = \frac{y(t+h) - 2y(t) + y(t-h)}{h^2} - \frac{h^2}{2 \cdot 3!} y^{(iv)}(c).$$

oc both first and second derivatives have error proportional to h^2 .

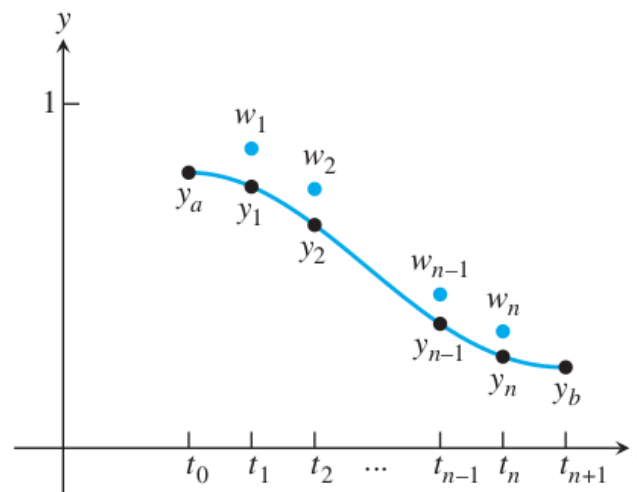


Figure 7.6 The Finite Difference Method for BVPs. Approximations $w_i, i = 1, \dots, n$ for the correct values y_i at discrete points t_i are calculated by solving a linear system of equations.

if linear BVP, then solve with gauss elimination or iterative, else an algebraic system of nonlinear equations.

✓ 7.2.1 linear BVP

✓ example 08

example 08 revisits example 07 using finite differences.

$$\text{example 08} \quad \begin{cases} y'' = 4y \\ y(0) = 1 \\ y(1) = 3. \end{cases}$$

consider the discrete form of differential equation $y'' = 4y$ using the centered-difference form for the second derivative. ie,

$$\frac{w_{i+1} - 2w_i + w_{i-1}}{h^2} - 4w_i = 0$$

⇓

$$w_{i+1} + (-4h^2 - 2)w_i + w_{i-1} = 0.$$

for $n = 3$ points between interval end points, then step-size $h = \frac{1}{n+1} = \frac{1}{3+1} = \frac{1}{4}$. including boundary conditions gives three equations in three unknowns:

$$\begin{aligned} 1 + (-4h^2 - 2)w_1 + w_2 &= 0 & y(0) &= 1 \\ w_1 + (-4h^2 - 2)w_2 + w_3 &= 0 \\ w_2 + (-4h^2 - 2)w_3 + 3 &= 0 & y(1) &= 3. \end{aligned}$$

$$\Downarrow \quad h = \frac{1}{4}$$

$$\begin{bmatrix} -\frac{9}{4} & 1 & 0 \\ 1 & -\frac{9}{4} & 1 \\ 0 & 1 & -\frac{9}{4} \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ -3 \end{bmatrix}.$$

⇓ by gaussian elimination,

$$w = [1.0249, 1.3061, 1.9138]^T.$$

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➤ example 08, part 2: error

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✓ usw

for any fixed t and step-size h , the FDM approximation $w_h(t)$ is order two in h and can be extrapolated with a simple formula.

✓ 7.2.2 nonlinear BVP

FDM applied to nonlinear DEQ results in a system of nonlinear algebra for multivariate newtons method (ch 2).

✓ example 09

example 09 looks fresh. solve nonlinear BVP

$$\text{example 09} \quad \begin{cases} y'' = y - y^2 \\ y(0) = 1 \\ y(1) = 4. \end{cases}$$

the discretized form at t_i

$$\frac{w_{i+1} - 2w_i + w_{i-1}}{h^2} - w_i + w_i^2 = 0$$

⇓

$$w_{i-1} - (2 + h^2)w_i + h^2w_i^2 + w_{i+1} = 0.$$

for $2 \leq i \leq n - 1$ and the boundary conditions:

$$\begin{aligned} y_a - (2 + h^2)w_1 + h^2w_1^2 + w_2 &= 0 \\ w_{n-1} - (2 + h^2)w_n + h^2w_n^2 + y_b &= 0. \end{aligned}$$

↓ solve $F(w) = 0$ with newtons multivariate,

$$w^{k+1} = w^k - DF(w^k)^{-1} F w^k$$

↓

$$DF(w^k) \Delta w = -F(w^k), \quad \Delta w = w^{k+1} - w^k$$

↓

$$F \begin{bmatrix} w_1 \\ w_2 \\ \vdots \\ w_{n-1} \\ w_n \end{bmatrix} = \begin{bmatrix} y_a - (2 + h^2)w_1 + h^2w_1^2 + w_2 \\ w_1 - (2 + h^2)w_2 + h^2w_2^2 + w_3 \\ \vdots \\ w_{n-2} - (2 + h^2)w_{n-1} + h^2w_{n-1}^2 + w_n \\ w_{n-1} - (2 + h^2)w_n + h^2w_n^2 + y_b \end{bmatrix}$$

where $y_a = 1, y_b = 4$. the jacobian $DF(w)$ of F is

$$\begin{bmatrix} 2h^2w_1 - (2 + h^2) & 1 & 0 & \cdots & 0 \\ 1 & 2h^2w_2 - (2 + h^2) & \ddots & \ddots & \vdots \\ 0 & 1 & \ddots & 1 & 0 \\ \vdots & \ddots & \ddots & 2h^2w_{n-1} - (2 + h^2) & 1 \\ 0 & \cdots & 0 & 1 & 2h^2w_n - (2 + h^2) \end{bmatrix}$$

the i th row is the partial of the i th component of F with respect to each w_j .

➤ code, matlab

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➤ code, python

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➤ example 10

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