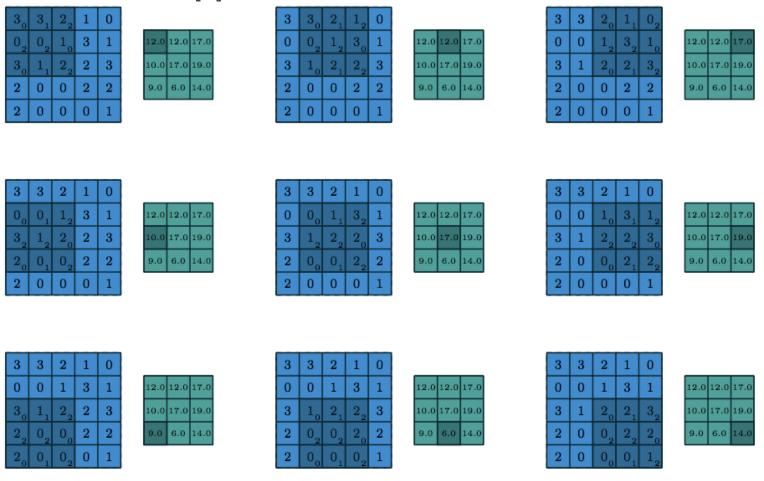
LIPSCHITZ CONSTRAINTS IN WASSERSTEIN GANS

Kyle Sargent

Department of Computer Science, Harvard University

Lipschitz Constant of a Convolution: Approximations and Bounds

For our purposes, convolution refers to the convolving of a 2-dimensional square kernel over a 2-dimensional input pane. In a general convolution, the kernel discretely steps over the input pane; at each step, the dot product between the current area of the input pane and the kernel is computed and added to the output. The figure below, due to Dumoulin and Visin [3], is an excellent visualization of this process.



In fact, convolution of an $n \times n$ input pane by a $k \times k$ kernel can be thought of as a linear transformation by a matrix. For example, let K be a 2x2 kernel

$$K = \begin{bmatrix} k_1 & k_2 \\ k_3 & k_4 \end{bmatrix}$$

And consider a 3x3 input pane p

$$P = \begin{bmatrix} p_1 & p_2 & p_3 \\ p_4 & p_5 & p_6 \\ p_7 & p_8 & p_9 \end{bmatrix}$$

Convolution of P by K would yield a 2x2 output pane, without padding. But we could also think of this as a map $C_K: \mathbb{R}^{3\times 3} \to \mathbb{R}^{2\times 2} \simeq T_K: \mathbb{R}^9 \to \mathbb{R}^4$. The matrix for this transformation would be given by the so-called "Toeplitz" matrix

$$T_K = \begin{bmatrix} k_1 & k_2 & 0 & k_3 & k_4 & 0 & 0 & 0 & 0 \\ 0 & k_1 & k_2 & 0 & k_3 & k_4 & 0 & 0 & 0 \\ 0 & 0 & k_1 & k_2 & 0 & k_3 & k_4 & 0 & 0 \\ 0 & 0 & 0 & k_1 & k_2 & 0 & k_3 & k_4 & 0 \end{bmatrix}$$

Thus convolution is a linear map, so its Lipschitz constant is just its spectral norm. We consider two methods for approximating the spectral norm of a convolution.

Method 1: Let T_K be the block-Toeplitz matrix of a general convolution, and R_K be the reshaped kernel matrix from above. Then

$$\sigma(T_K) \le \sqrt{n}\sigma(R_k)$$

where n is some constant (consult Tsuzuku, Sato, and Sugiyama [6] for details) and R_k is the reshaped matrix of kernels, and the spectral norm σ of it is computed via power iteration.

Method 2 (Toeplitz Normalization): For a given convolution kernel, the transpose of the implicit Toeplitz matrix is given by convolution via the original kernel, rotated 180 degrees. We can thus perform a power iteration of the form

(1)
$$v_i \leftarrow \frac{C_{\tilde{k}}^T(u_{i-1})}{\|C_{\tilde{k}}^T(u_{i-1})\|_2}$$

(2) $u_i \leftarrow \frac{C_{\tilde{k}}^T(v_i)}{\|C_{\tilde{k}}(v_i)\|_2}$

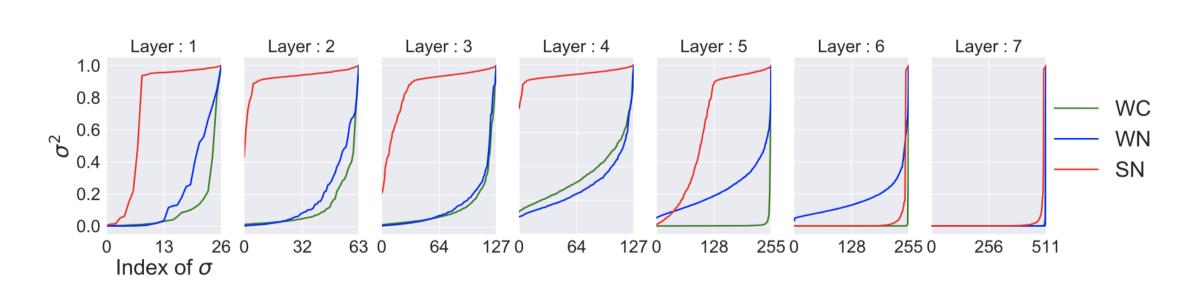
(2)
$$u_i \leftarrow \frac{C_k^T(v_i)}{\|C_k(v_i)\|_2}$$

Mode Collapse and Weight Spectra

Some methods for enforcing a Lipschitz constraint can be too restrictive. Consider the following normalizations

- 1. Weight clipping (WC) to a fixed interval [-c, c] as in Arjovsky, Chintala, and Bottou [1]
- 2. The weight normalization (WN) of Salimans and Kingma [5], setting the l_2 norm of the row of each weight matrix to 1
- 3. Spectral normalization (SN)

We make the following observation: all three normalizations are sufficient to enforce Lipschitz continuity of the discriminator. But not all normalizations which enforce Lipschitz continuity are created equally; some introduce undesirable side effects such as spectral collapse. The following figure is due to Miyato et al. [4]:



Spectral Gradient Clipping

Brock, Donahue, and Simonyan [2] experimented with spectral clamping: setting $\sigma_0 = \min(\sigma_0, r)$ σ_1) where r > 1 is some fixed ratio. Spectral gradient clipping follows essentially the same principle as spectral clipping, just applied to weight gradients.

$$(1) \ \sigma_0 \leftarrow u_0^T W' v_0$$

(2)
$$v_1 \leftarrow \frac{(W' - \sigma_0 u v^T) u_1}{\|(W' - \sigma_0 u v^T) u_1\|_2}$$

(3)
$$u_1 \leftarrow \frac{(W' - \sigma_0 u v^T)^T v_1}{\|(W' - \sigma_0 u v^T)^T v_1\|_2}$$

$$(4) \ \sigma_1 \leftarrow u_1^T (W' - \sigma_0 u v^T) v_1$$

After each backward pass, we simply clamp the gradients so that σ_0 is at most $r \cdot \sigma_1$, where r is some fixed hyperparameter greater than 1.

$$W' \leftarrow W' - \min(0, \sigma_0 - r \cdot \sigma_1) u_0 v_0^T$$

Results: Toeplitz-Normalized Discriminator

We identify a trade-off between model capacity and K-Lipschitz continuity of the discriminator.

Results (Toeplitz-normalized Discriminator)		
k	Inception	
	Score	
1	2.62	
2	7.34	
4	5.77	
8	3.05	

Results: Spectral Gradient Clipping

The values of r which collapsed training were vastly different depending on whether we applied clipping in the generator or discriminator. In early training, we found the discriminator to regularly update the gradients of its weights with extremely low rank updates — with σ_0/σ_1 on the order of 30. Later, σ_0/σ_1 stabilized to around 3 for most updates. Thus, for small values of r, spectral clipping in the discriminator proved catastrophic. By contrast, the generator is considerably more amenable to spectral clamping.

Results (Spectral gradient clamping with ratio r in Generator)		
r	Inception	
	Score	
1.05	3.782	
1.5	7.82	
2	7.94	

Results (Spectral gradient clamping with ratio r in Discriminator)		
r	Inception Score	
	Score	
4	3.84	
15	7.92	
30	7.95	

Acknowledgements

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