

Learning to Detect Every Thing in an Open World

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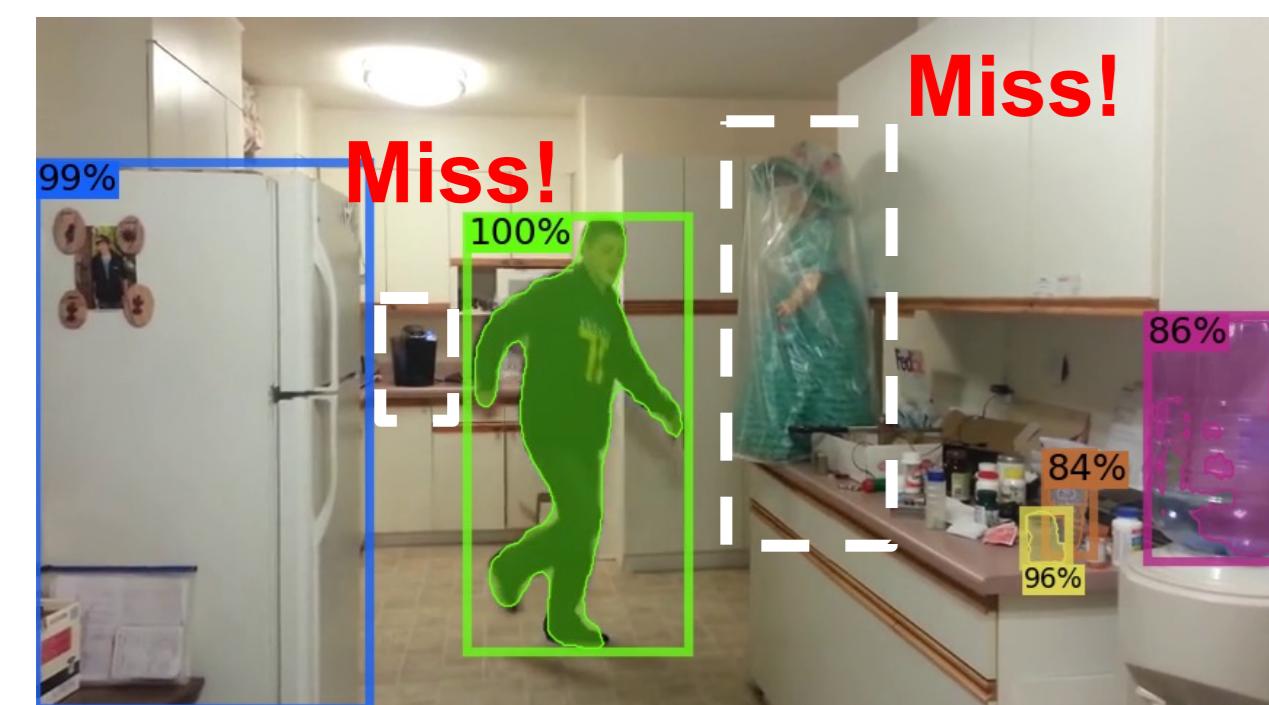
1: Boston University, 2: MIT-IBM Watson AI Lab, 3: University of California Berkeley

Introduction

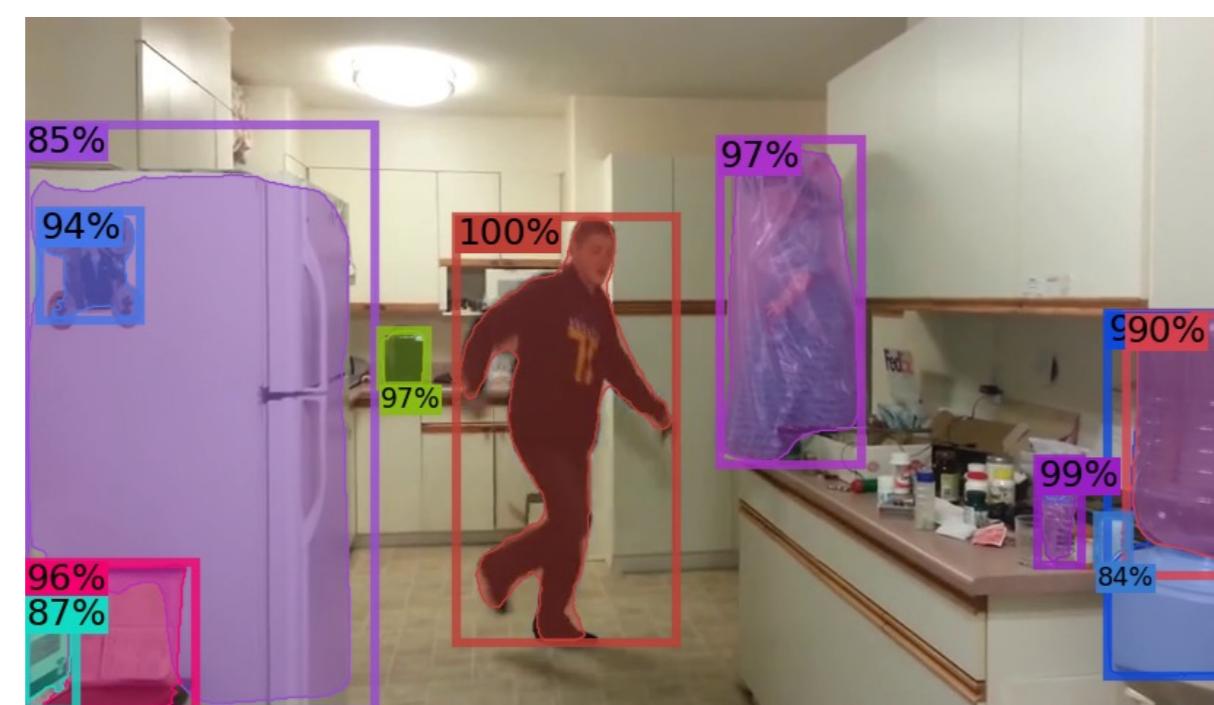
Open-world Instance Segmentation

- Detect and segment novel objects as “object”
- Novel = categories not covered by dataset

Mask RCNN (trained on COCO)

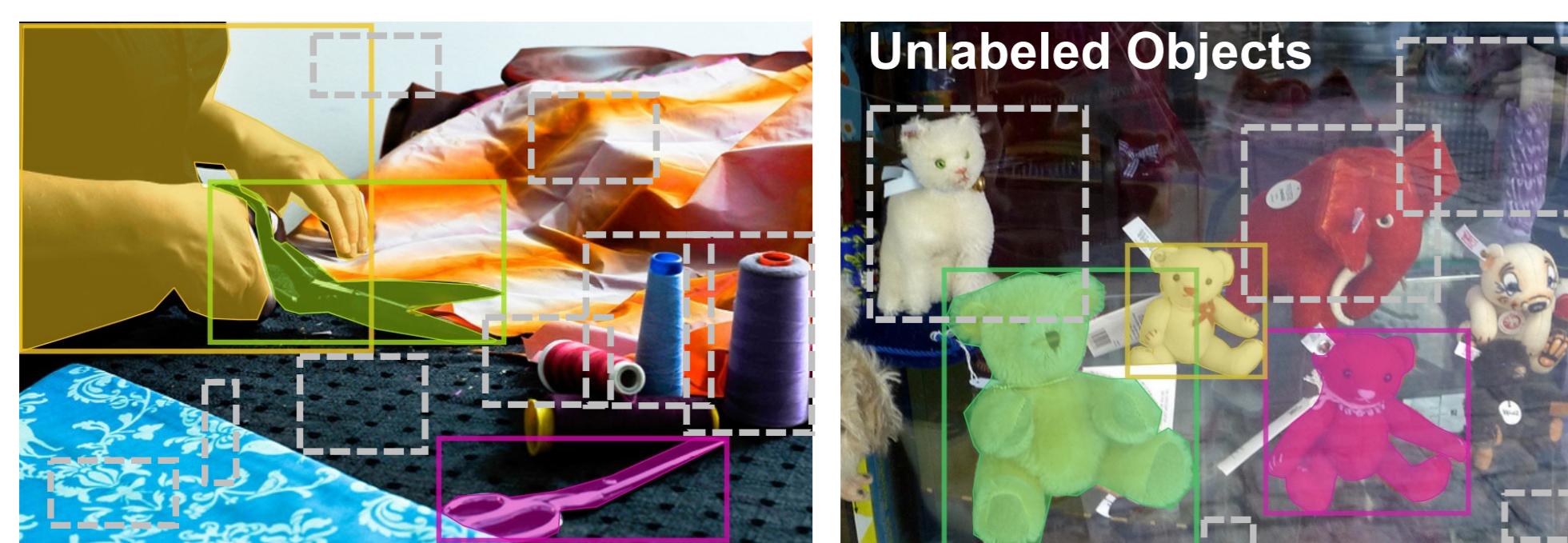


Ours (trained on COCO)



Issues

- Dataset does not cover all categories of objects
⇒ Many unlabeled objects in images
- Regard the unlabeled objects as background when training detector
⇒ Objectness of novel objects is suppressed.



Proposed Approach

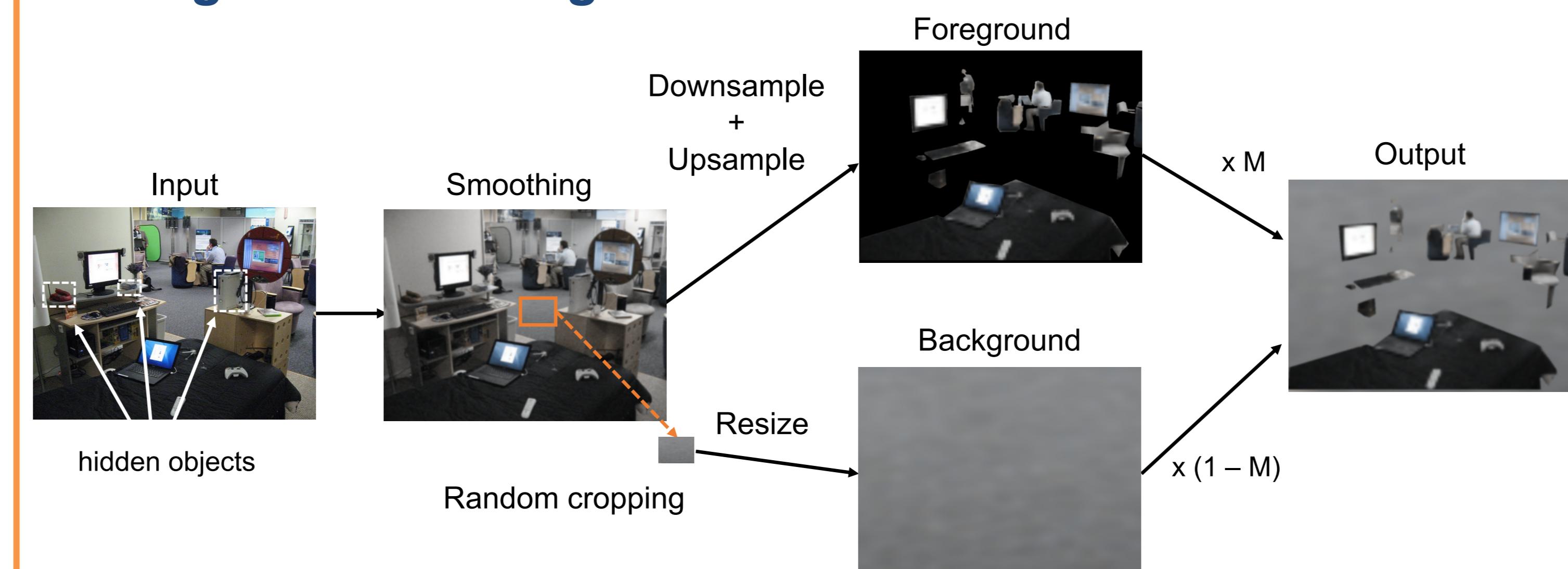
- We do not want to suppress unlabeled objects as background.
⇒ **Background Erasing: Erase unlabeled objects**
- Need to solve domain-gap between synthesized and real data
⇒ **Decoupled Training: Solve the domain-gap**

Summary

- A simple framework for open-world instance segmentation.
- This method is effective in one-stage and two-stage detectors.
- Applicable to diverse datasets, e.g., COCO, UVO, Mapillary
- 12.8 points improvement on VOC to Non-VOC evaluation.

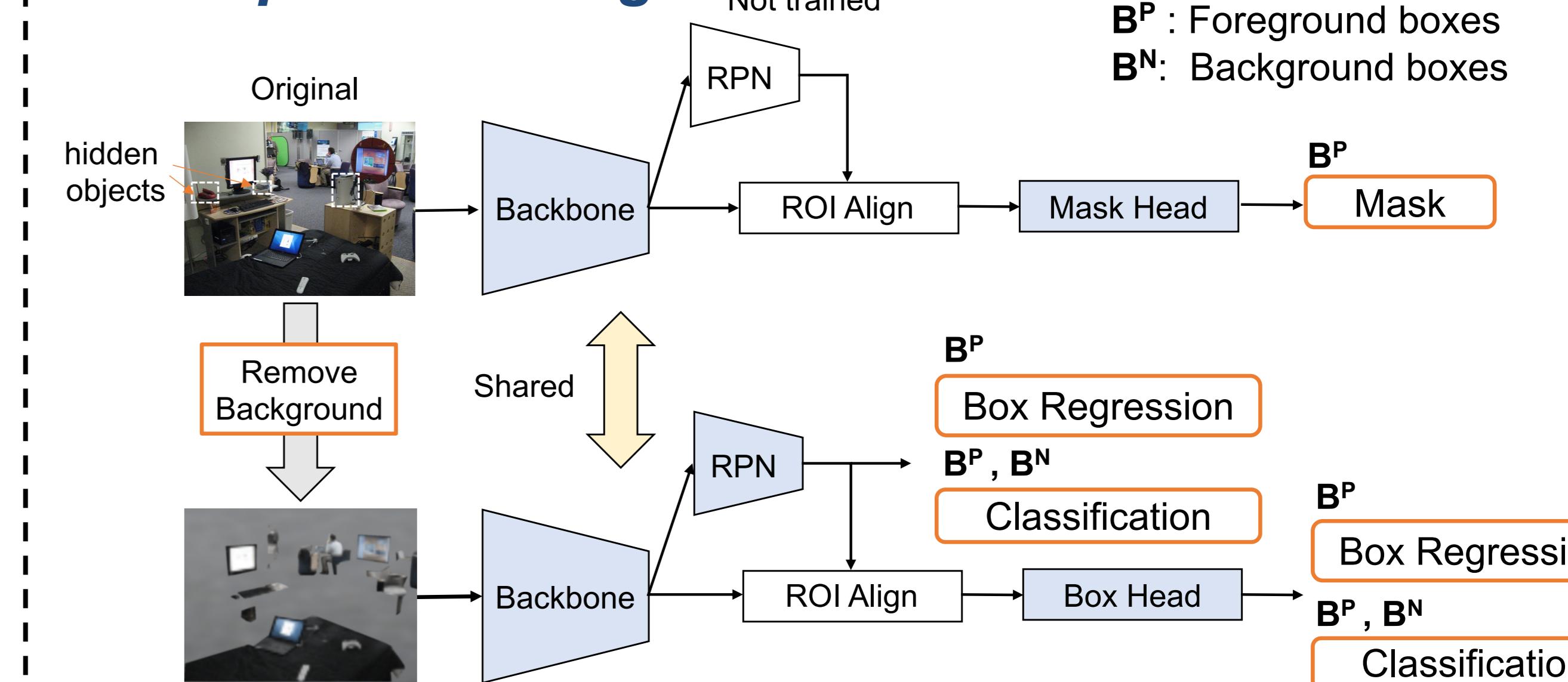
Method

Background Erasing



- Copy-paste foreground object on background canvas.

Decoupled Training



- Detection loss on synthesized images.
- Segmentation loss on real images.

Results

Cross-Category Evaluation on COCO

Method	Non-VOC						All			
	AP	Box	AR ₁₀	AR ₁₀₀	Mask	AP	AR ₁₀	AR ₁₀₀	Mask	AP
Mask RCNN	1.5	8.8	10.9	0.7	7.2	9.1	19.3	23.1	16.7	19.9
Mask RCNN ^P	3.4	8.7	10.7	2.2	7.2	8.9	19.1	23.0	16.5	19.8
Mask RCNN ^S	1.1	13.2	18.0	0.6	11.3	15.8	21.7	27.4	19.2	24.4
LDET	5.0	18.2	30.8	4.7	16.3	27.4	24.4	36.8	22.4	33.1

Cross-Dataset Evaluation on COCO to UVO

Method	Train	Box					Mask				
		AP	AR	AR _{small}	AR _{med}	AR _{large}	AP	AR	AR _{small}	AR _{med}	AR _{large}
Mask RCNN	VOC	19.8	30.0	10.7	21.3	43.0	15.5	23.9	9.2	18.5	32.8
Mask RCNN ^P	(COCO)	19.2	30.1	10.6	21.3	43.3	15.4	24.1	9.4	18.4	33.2
Mask RCNN ^S		19.7	32.0	10.0	23.3	46.0	14.1	25.9	9.5	20.2	35.4
LDET		22.4	43.7	24.7	39.9	52.9	18.4	36.0	22.1	34.8	41.4
Mask RCNN	COCO	25.3	42.3	22.2	38.3	52.0	20.6	35.9	19.6	33.9	42.6
Mask RCNN ^P		24.4	41.9	22.3	37.8	51.5	20.1	35.4	19.7	33.6	41.8
Mask RCNN ^S		23.4	40.5	17.6	34.9	52.3	18.0	34.7	16.6	31.5	42.8
LDET		25.8	47.5	29.1	44.8	55.6	21.9	40.7	26.8	40.0	45.7

Evaluation on One-stage detector

Detector	Method	AR ₁₀	AR ₅₀	AR ₁₀₀
RetinaNet	Plain	9.9	15.7	17.8
	LDET	15.3	26.7	31.0
TensorMask	Plain	10.6	17.6	19.7
	LDET	16.3	26.8	31.1

Objectness

