EE2023 TUTORIAL 1 (SOLUTIONS)

Solution to Q.1

Write z in polar form:

$$z = x + jy = |z| \exp(j \angle z).$$

Since adding integer multiples of 2π to $\angle z$ does not affect the value of z, we may also express z as

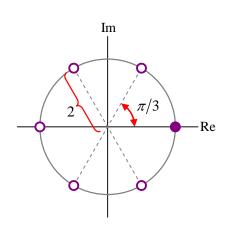
$$z = |z| \exp(j(\angle z + 2k\pi))$$

where k is an integer. This leads to

$$\sqrt[N]{z} = |z|^{1/N} \exp\left(j\left(\frac{\angle z}{N} + \frac{2k\pi}{N}\right)\right); \quad k = 0, 1, \dots, N-1,$$

which yields the N distinct values of $\sqrt[N]{z}$.

$$\begin{cases} z = 64 \rightarrow \begin{cases} |z| = 64 \\ \angle z = 0 \end{cases} \\ \sqrt[6]{64} = |z|^{1/N} \exp\left(j\left(\frac{\angle z}{N} + \frac{2k\pi}{N}\right)\right) \Big|_{z=64, N=6} \\ = 2\exp\left(j\left(\frac{k\pi}{3}\right)\right); \quad k = 0, 1, \dots, 5 \end{cases} \\ = \begin{cases} (2), \ 2\exp\left(j\left(\frac{\pi}{3}\right)\right); \ 2\exp\left(j\left(\frac{2\pi}{3}\right)\right); \\ (-2), \ 2\exp\left(j\left(\frac{4\pi}{3}\right)\right); \ 2\exp\left(j\left(\frac{5\pi}{3}\right)\right) \end{cases} \end{cases}$$

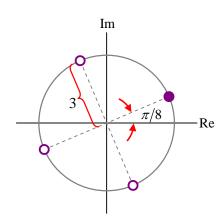


$$z = j81 \rightarrow \begin{cases} |z| = 81 \\ \angle z = \frac{\pi}{2} \end{cases}$$

$$\sqrt[4]{j81} = |z|^{1/N} \exp\left(j\left(\frac{\angle z}{N} + \frac{2k\pi}{N}\right)\right)\Big|_{z=81, N=4}$$

$$= 3\exp\left(j\left(\frac{\pi}{8} + \frac{k\pi}{2}\right)\right); \quad k = 0, 1, \dots, 3$$

$$= \begin{cases} 3\exp\left(j\left(\frac{\pi}{8}\right)\right), \quad 3\exp\left(j\left(\frac{5\pi}{8}\right)\right), \\ 3\exp\left(j\left(\frac{9\pi}{8}\right)\right), \quad 3\exp\left(j\left(\frac{13\pi}{8}\right)\right) \end{cases}$$



(a) $p(t) = 2 - 2\text{rect}\left(\frac{t - 0.75}{3.5}\right)$

(b) By inspection, x(t) is not periodic.

 $2\sin(\pi t)$ p(t)-1 x(t) $-1 \quad 0 \quad 1 \quad 2.5 \quad \rightarrow t$

Notice the π rad (or 180°) phase jumps in x(t) occurring at the zero crossings of p(t)-1.

(c)

$$x^{2}(t) = 4\sin^{2}(\pi t) \underbrace{(p(t)-1)^{2}}_{1}$$

$$= 4\sin^{2}(\pi t)$$

$$= 2(1-\cos(2\pi t))$$

$$x^{2}(t)$$

$$x^{2}(t)$$

$$x^{2}(t)$$

$$x^{2}(t)$$

$$x^{2}(t)$$

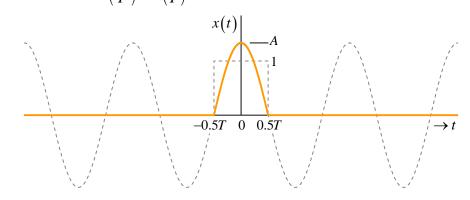
Note that $x^2(t)$ is periodic with a period of T = 1.

Total energy:
$$\begin{cases} E = \int_{-\infty}^{\infty} x^2(t) dt = \sum_{n=-\infty}^{\infty} \underbrace{\int_{nT}^{(n+1)T} x^2(t) dt}_{\text{fover one period thus independent of } n} = \underbrace{\left(\underbrace{\int_{0}^{T} x^2(t) dt}_{\text{finite}}\right) \underbrace{\sum_{n=-\infty}^{\infty} 1}_{\infty} = \infty}_{\infty}$$

Average Power:
$$\begin{cases} P = \frac{1}{T} \int_{-T/2}^{T/2} x^2(t) dt = \int_{-0.5}^{0.5} 2(1 - \cos(2\pi t)) dt = 2 \\ x^2(t) \text{ is periodic. } \\ P \text{ can be obtained} \\ \text{by averaging over} \\ \text{one period.} \end{cases}$$

Conclusion: x(t) is an aperiodic power signal.

Half-cosine pulse: $x(t) = A\cos\left(\frac{\pi t}{T}\right)\operatorname{rect}\left(\frac{t}{T}\right)$

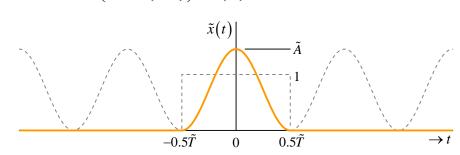


$$x^{2}(t) = \frac{A^{2}}{2} \left[1 + \cos\left(\frac{2\pi t}{T}\right) \right] \operatorname{rect}\left(\frac{t}{T}\right)$$

Energy:
$$E = \frac{A^2}{2} \int_{-0.5T}^{0.5T} 1 + \cos\left(\frac{2\pi t}{T}\right) dt = \frac{1}{2} A^2 T$$

$$\int_{\text{over one period } =0}^{\text{over one}} dt = \frac{1}{2} A^2 T$$

Raised-cosine pulse: $\tilde{x}(t) = \frac{\tilde{A}}{2} \left(1 + \cos \left(\frac{2\pi t}{\tilde{T}} \right) \right) \operatorname{rect} \left(\frac{t}{\tilde{T}} \right)$



$$\tilde{x}^{2}\left(t\right) = \frac{\tilde{A}^{2}}{4} \left[\frac{3}{2} + 2\cos\left(\frac{2\pi t}{\tilde{T}}\right) + \frac{1}{2}\cos\left(\frac{4\pi t}{\tilde{T}}\right)\right] \operatorname{rect}\left(\frac{t}{\tilde{T}}\right)$$

Energy:
$$\tilde{E} = \frac{\tilde{A}^2}{4} \int_{-0.5\tilde{T}}^{0.5\tilde{T}} \frac{3}{2} + 2 \underbrace{\cos\left(\frac{2\pi t}{\tilde{T}}\right)}_{\text{over one period } = 0} + \frac{1}{2} \underbrace{\cos\left(\frac{4\pi t}{\tilde{T}}\right)}_{\text{over two periods } = 0} dt = \frac{3}{8} \tilde{A}^2 \tilde{T}$$

Both x(t) and $\tilde{x}(t)$ will have the same energy if $A^2T=\frac{3}{4}\tilde{A}^2\tilde{T}$.

(a) Let m, n and k be positive integers. Based on the definition of a periodic signal, we have

$$x_1(t) = x_1(t+T_1) = x_1(t+mT_1)$$

 $x_2(t) = x_2(t+T_2) = x_2(t+nT_2)$

Hence,

$$x_0(t) = x_1(t) + x_2(t) = x_1(t + mT_1) + x_2(t + nT_2).$$

If $mT_1 = nT_2 = kT_0$, then

$$x_0(t) = x_1(t + kT_0) + x_2(t + kT_0) = x_0(t + kT_0)$$

which shows that $x_0(t)$ is periodic with a period of T_0 and a fundamental frequency of $f_0 = \frac{1}{T_0}$. Under this condition, (i.e. $mT_1 = nT_2 = kT_0$),

$$\frac{1}{T_1} = m \frac{1}{kT_0}$$
 implying that
$$\begin{cases} \cdots \cdots \frac{1}{kT_0} \text{ are common factors of } \left\{ \frac{1}{T_1}, \frac{1}{T_2} \right\} \cdots \\ \text{and} \\ \frac{1}{T_0} \text{ is the highest common factor (HCF) of } \left\{ \frac{1}{T_1}, \frac{1}{T_2} \right\} \end{cases}$$
 or
$$f_0 \text{ is the highest common factor (HCF) of } \left\{ f_1, f_2 \right\}$$

Conclusion: For $x_0(t)$ to be periodic, $\{f_1, f_2\}$ must have a HCF. In turn, this HCF is the fundamental frequency of $x_0(t)$

(b) i.
$$x(t) = \cos(3.2t) + \sin(1.6t) + \exp(j2.8t)$$
 ...
$$\begin{cases} \cos(3.2t) & \text{has a frequency of } 3.2 \ rad/s \\ \sin(1.6t) & \text{has a frequency of } 1.6 \ rad/s \\ \exp(j2.8t) & \text{has a frequency of } 2.8 \ rad/s \end{cases}$$

Highest common factor (HCF) of $\{3.2, 1.6, 2.8\}$ exists and is equal to 0.4. Thus, x(t) is periodic and has a fundamental frequency of 0.4 rad/s (or $0.2/\pi Hz$) and a fundamental period of $5\pi s$.

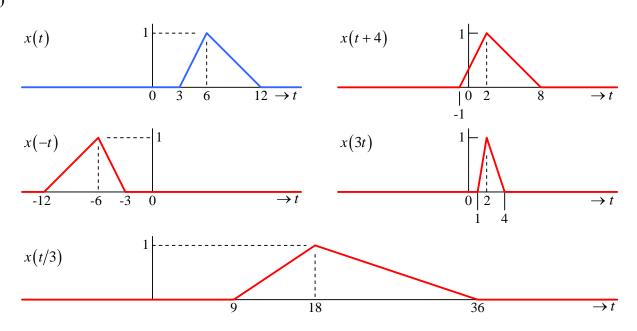
REMARKS: Although x(t) is periodic with a fundamental frequency of 0.4 rad/s, it does not contain the fundamental frequency component itself.

(b) ii.
$$x(t) = \cos(4t) + \sin(\pi t)$$
 ... $\begin{cases} \cos(4t) \text{ has a frequency of } 4 \text{ } rad/s \\ \sin(\pi t) \text{ has a frequency of } \pi \text{ } rad/s \end{cases}$

Highest common factor (HCF) of $\{4, \pi\}$ does not exist. Thus, x(t) is not periodic.

REMARKS: Summing sinusoids does not necessarily lead to a periodic signal unless the frequencies of the sinusoids are harmonics of a common fundamental frequency.

(a)



(b) We observe that y(t) is a time-scaled, -reversed and –shifted version of x(t).

For problems of this nature, we should start with time-scaling first since it involves linear warping of the time axis. If we were to start with time-shifting and/or time-reversal, we may have to redo them after time-scaling. However, this sequence of operation need not be followed if we are sketching the signal from the mathematical expression.

Comparing x(t) and y(t), we note that y(t) involves time-scaling (or contraction) of x(t) by a factor of 3.

 $x(t) \qquad \qquad 1 \qquad \qquad 1$

Time-scaling of x(t): $\tilde{y}(t) = x(3t)$

 $\begin{array}{c|c}
\tilde{y}(t) & 1 \\
\hline
0 \mid 2 & \rightarrow t
\end{array}$

Time-reversal of $\tilde{y}(t)$: $\tilde{\tilde{y}}(t) = \tilde{y}(-t) = x(-3t)$

 $\tilde{\tilde{y}}(t) \qquad \begin{array}{c} -1 \\ \hline -2 & 0 \\ \end{array} \longrightarrow t$

Time shifting of $\tilde{\tilde{y}}(t)$: $\begin{cases} y(t) = \tilde{\tilde{y}}(t+4) \\ = x(-3(t+4)) \end{cases}$

 $y(t) \qquad | 1 \qquad | 1$

 $\therefore y(t) = x(-3(t+4))$

Let

$$\delta(t) = \lim_{\Delta \to 0} x(t)$$
 where $x(t) = \frac{1}{\Delta} \operatorname{rect}\left(\frac{t}{\Delta}\right)$.

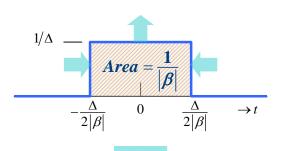
Here, we have implicitly assumed that $\Delta > 0$.

Due to symmetry, we have $\delta(\beta t) = \delta(|\beta|t)$.

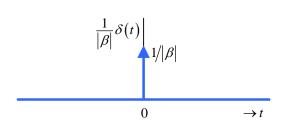
$$\begin{split} \delta(\beta t) &= \delta(|\beta|t) \\ &= \lim_{\Delta \to 0} x(|\beta|t) = \lim_{\Delta \to 0} \frac{1}{\Delta} \operatorname{rect}\left(\frac{t}{\Delta/|\beta|}\right) \end{split}$$

$$\mathrm{But} \quad \begin{pmatrix} \lim_{\Delta \to 0} \frac{1}{\Delta} \mathrm{rect} \bigg(\frac{t}{\Delta / |\beta|} \bigg) = \begin{cases} \infty; & t = 0 \\ 0; & t \neq 0 \end{cases} \\ \lim_{\Delta \to 0} \int_{-\infty}^{\infty} \frac{1}{\Delta} \mathrm{rect} \bigg(\frac{t}{\Delta / |\beta|} \bigg) dt = \frac{1}{|\beta|} \end{pmatrix}.$$

Hence,
$$\delta(\beta t) = \lim_{\Delta \to 0} \frac{1}{\Delta} \operatorname{rect}\left(\frac{t}{\Delta/|\beta|}\right) = \frac{1}{|\beta|} \delta(t)$$
.



 $\Delta \rightarrow 0$



Domain-scaling of $\delta(\cdot)$ is often encountered in transforming a spectrum containing $\delta(\cdot)$ between cyclic-frequency (f) and radian frequency (ω) domain:

$$\left[\delta(\omega) = \delta(2\pi f) = \frac{1}{2\pi}\delta(f)\right] \text{ or } \left[\delta(f) = \delta\left(\frac{\omega}{2\pi}\right) = 2\pi\delta(\omega)\right].$$