

Physics-informed Machine Learning for Uncertainty Quantification in Land Models

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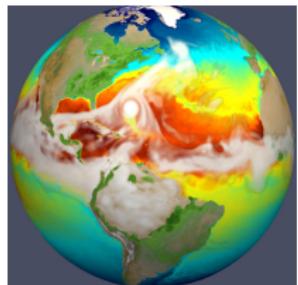
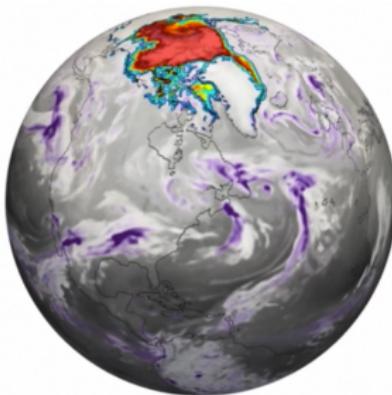
Outline

- Motivation
 - Energy Exascale Earth System Model (E3SM): Land component
- Need for Surrogate Models
 - Polynomial Chaos Surrogate
 - Karhunen-Loève expansions for field quantities
 - Neural Network Surrogates
 - Multilayer Perceptron (MLP)
 - Long short term memory (LSTM)
 - **Physics-based LSTM**
- Global Sensitivity Analysis (GSA)
- Preliminary Results

E3SM Model Overview

Energy Exascale Earth System Model (E3SM) is a coupled earth model

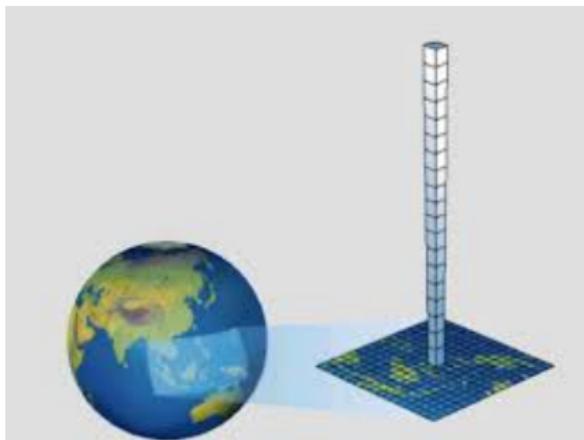
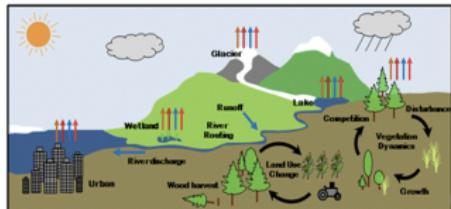
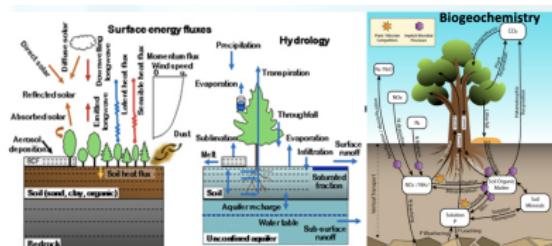
- US Department of Energy (DOE) sponsored Earth system model <https://e3sm.org>
- Ocean, Atmosphere, Sea ice and **Land** Components
- Computationally expensive to run the coupled mode (including ocean and atmosphere)
- Can only do a few global simulations of coupled E3SM models → hard to get training data



E3SM Land Model (ELM) Overview

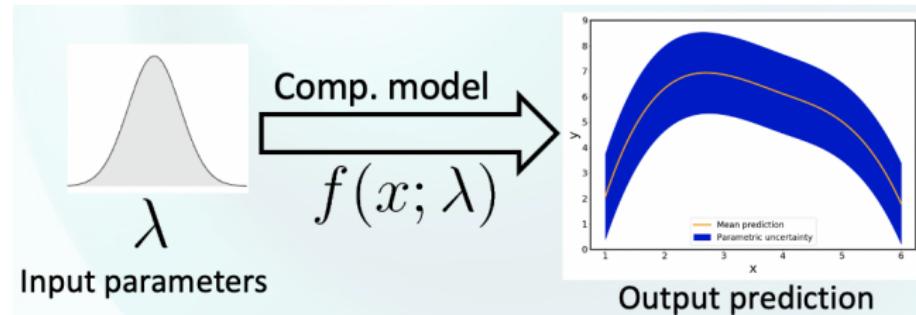
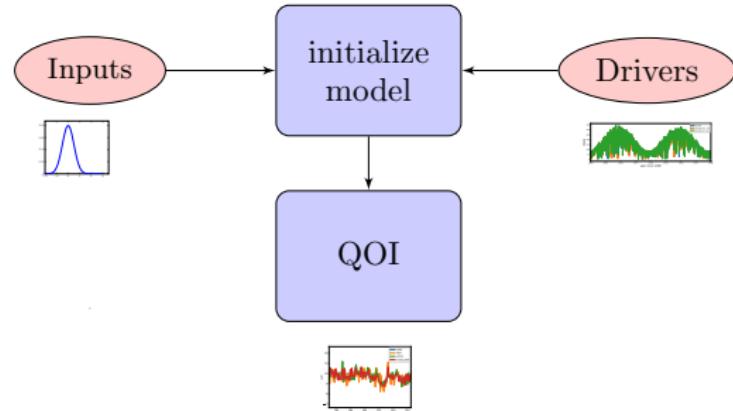
Land model incorporates a set of biogeophysical processes:

- Cheapest component, can run in single column mode
- Simplified python model available (sELM)
- Can evaluate model many times for various input parameters



ELM Produces Time Series given Input Parameters and Forcing Drivers

- $\mathcal{O}(10) - \mathcal{O}(100)$ uncertain inputs
- Daily Forcings/Drivers
 - ① Min/Max Temperature
 - ② Day of Year
 - ③ Solar radiation
 - ④ Water Availability



Time evolution of a nominal simulation

Surrogates are necessary for **expensive** computational models

- ... otherwise called supervised ML, metamodel, emulator, proxy, response surface.

$$f(x; \lambda) \approx f_s(x; \lambda)$$

- Surrogates are required for ensemble-intensive studies, such as
 - parameter estimation
 - uncertainty propagation
 - global sensitivity analysis
 - optimal experimental design

This talk

Investigating surrogate construction approaches for
ELM to enable all of the above

Polynomial chaos (PC) surrogate for black-box $f(\lambda)$

- Represent QOIs as orthogonal expansion of random variables

$$f(\lambda) \approx f_c(\lambda(\xi)) = \sum_{\alpha \in \mathcal{I}} c_\alpha \Psi_\alpha(\xi)$$

- Germ: $\xi = (\xi_1, \xi_2, \dots, \xi_d)$, e.g. uniform: $\lambda(\xi)$ is a linear scaling
- Multi-index $\alpha = \{\alpha_1, \dots, \alpha_d\}$
- Orthogonal polynomials wrt $p(\xi)$, $\Psi_\alpha(\xi) = \prod_{i=1}^d \psi_{\alpha_i}(\xi_i)$
- Typical construction approach: regression to find PC modes c_α

Advantages of PC

- moment estimation, uncertainty propagation, global sensitivity

Expensive model challenge

- Use Bayesian regression, helps to quantify lack of simulation data

High-d challenge $d \gg 1$

- Number of terms in expansion of order p and dimension d :

$$|\mathcal{I}| = \frac{(d+p)!}{d!p!}$$

- Use sparse regression
- We employ Bayesian compressed sensing (BCS): iterative algorithm for Bayesian sparse learning [Babacan, 2010; Sargsyan, 2014; Ricciuto, 2018]

'Free' Global Sensitivity Analysis with PC

$$f(\boldsymbol{\lambda}(\boldsymbol{\xi})) \simeq \sum_{\alpha \in \mathcal{I}} c_\alpha \Psi_\alpha(\boldsymbol{\xi})$$

- Main effect sensitivity indices

$$S_i = \frac{Var[\mathbb{E}(f(\boldsymbol{\lambda}|\lambda_i)]}{Var[f(\boldsymbol{\lambda})]} = \frac{\sum_{\alpha \in \mathcal{I}_i} c_\alpha^2 \|\Psi_\alpha\|^2}{\sum_{\alpha \in \mathcal{I} \setminus \{0\}} c_\alpha^2 \|\Psi_\alpha\|^2}$$

- \mathcal{I}_i is the set of bases with only ξ_i involved
- S_i is the uncertainty contribution that is due to i -th parameter only
- Total effect sensitivity indices

$$T_i = 1 - \frac{Var[\mathbb{E}(f(\boldsymbol{\lambda}|\lambda_{-i})]}{Var[f(\boldsymbol{\lambda})]} = \frac{\sum_{\alpha \in \mathcal{I}_i^T} c_\alpha^2 \|\Psi_\alpha\|^2}{\sum_{\alpha \in \mathcal{I} \setminus \{0\}} c_\alpha^2 \|\Psi_\alpha\|^2}$$

- \mathcal{I}_i^T is the set of bases with ξ_i involved, including all its interactions.
- T_i is the total uncertainty contribution due to i -th parameter

[Sudret, 2008; Crestaux, 2009; Sargsyan, 2017]

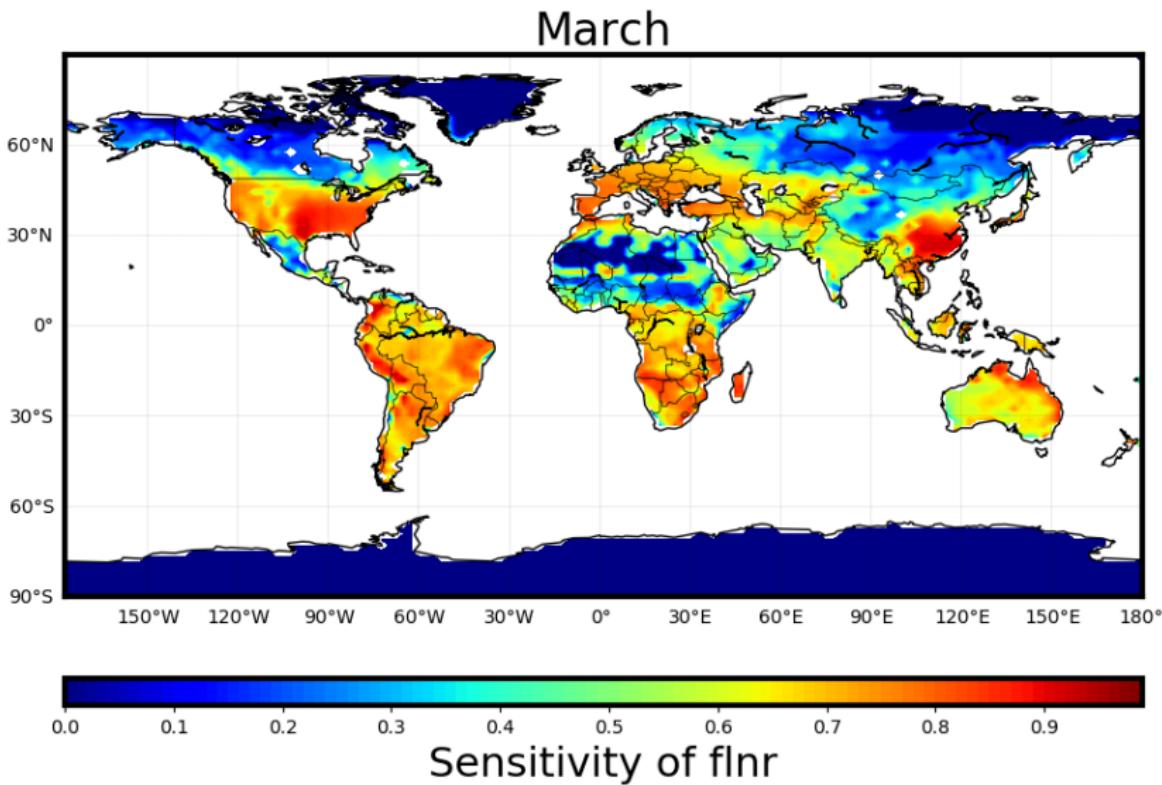
Spatio-temporal surrogate model via Karhunen-Loève expansions

- 3183 active land cells over 180 months is $> 500,000$ outputs
- Karhunen-Loève expansions help reduce dimensionality due to strong spatio-temporal correlations (think of Principal Component Analysis in stochastic space)

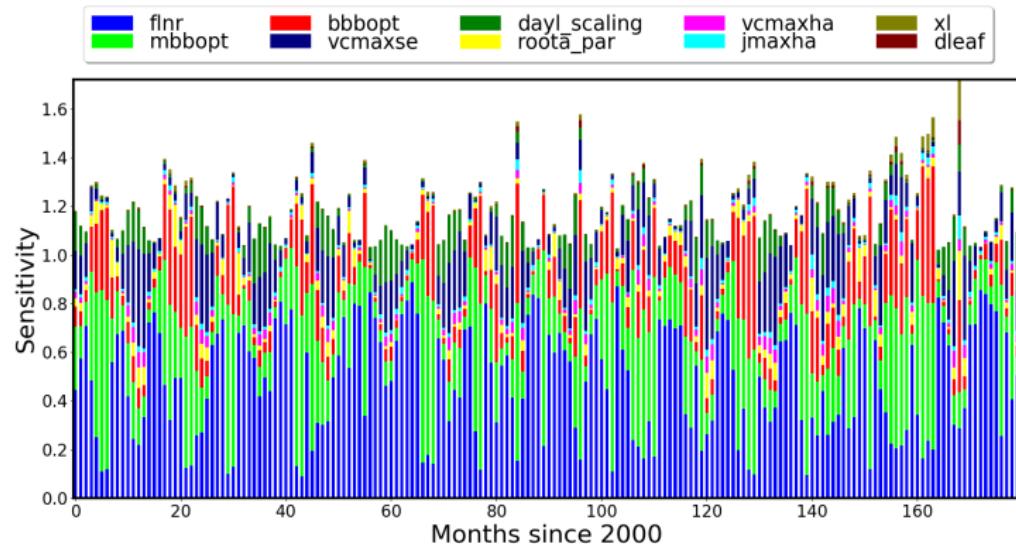
$$f(x; \lambda) = \bar{f}(x; \lambda) + \sum_{j=0}^J f_j(\lambda) \sqrt{\mu_j} \phi_j(x)$$

- Instead of 500,000 surrogates, we build about $J = 2,000$ surrogates, one for each eigen-component $f_j(\lambda)$
- End result: a single PC surrogate with x -dependent coefficients (i.e. resolving space and time), with about 5% relative error compared to true ELM
- Surrogate ELM is extremely cheap to evaluate and is being used online to calibrate the parameters

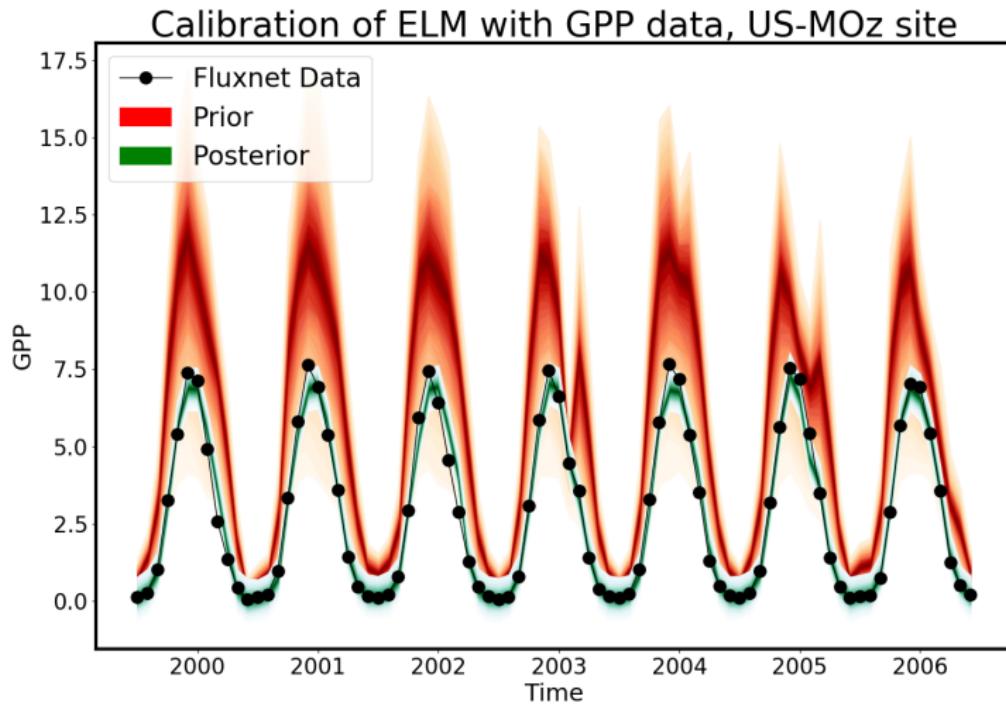
Representative results: spatially resolved GSA



Representative results: time-resolved GSA

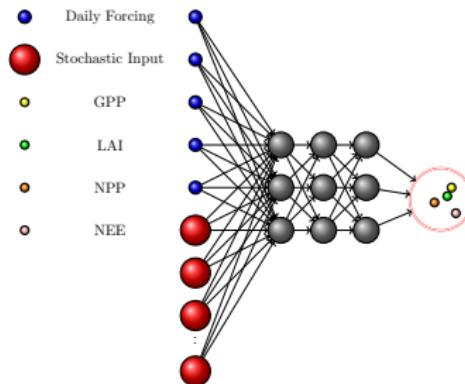


Representative results: Bayesian inference and prediction with surrogate



Transitioning from UQ technologies to ML

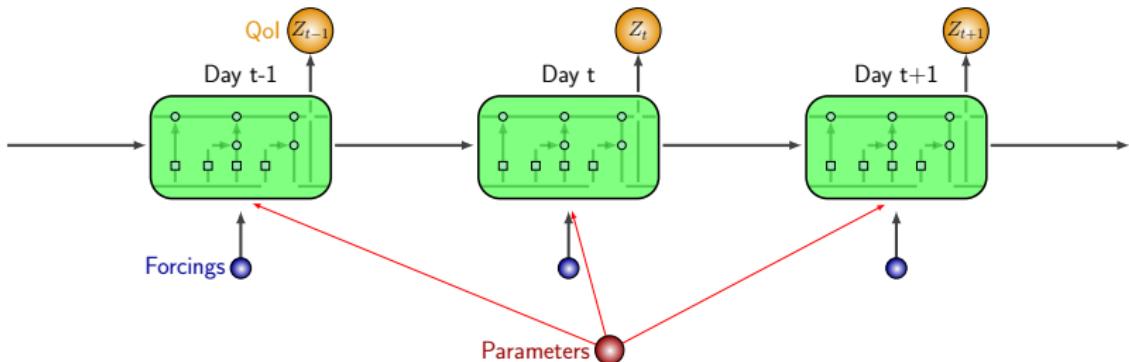
- Polynomial chaos requires smooth QoIs
- Exploring transient behavior and daily dynamics requires more accurate surrogates
- Benign MLP, feed-forward network did not do too well



- Does not account for temporal aspect of model
- Cannot propagate information of QoIs day to day (or month to month)

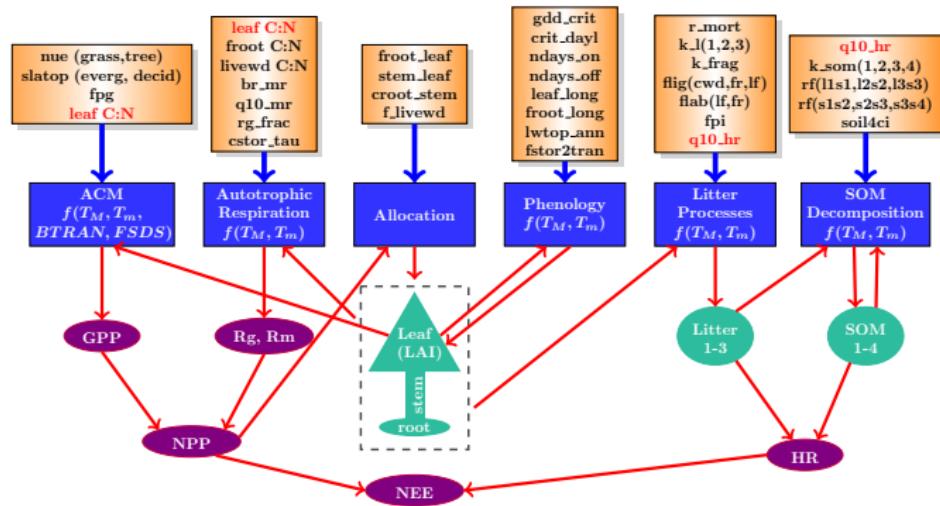
Long short term memory (LSTM) accounts for temporal evolution

- Vanilla LSTM Recurrent NN architecture
- One network per QoI
- Much better than PC, better than MLP

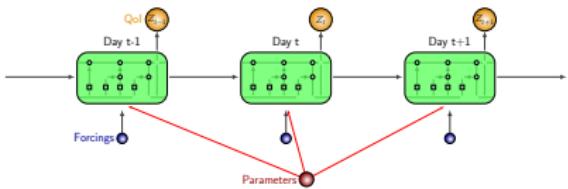


Graph Structure of ELM Land Model

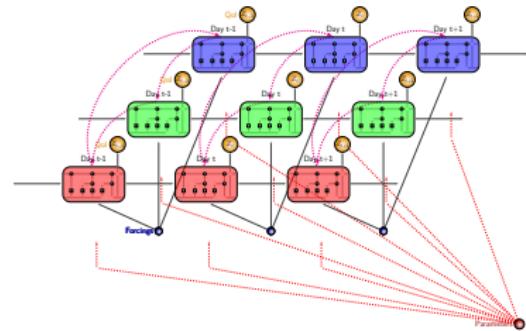
Looking under the hood helps build physics-informed architecture



Physics-driven architecture incorporates known connections into LSTM

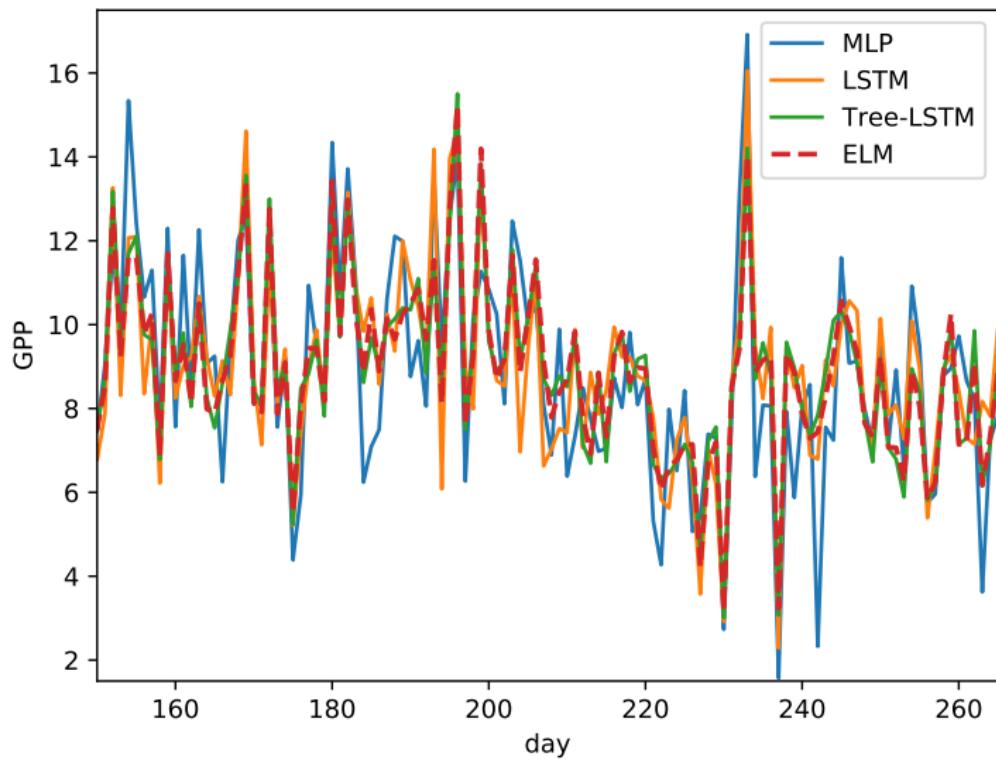


Vanilla LSTM

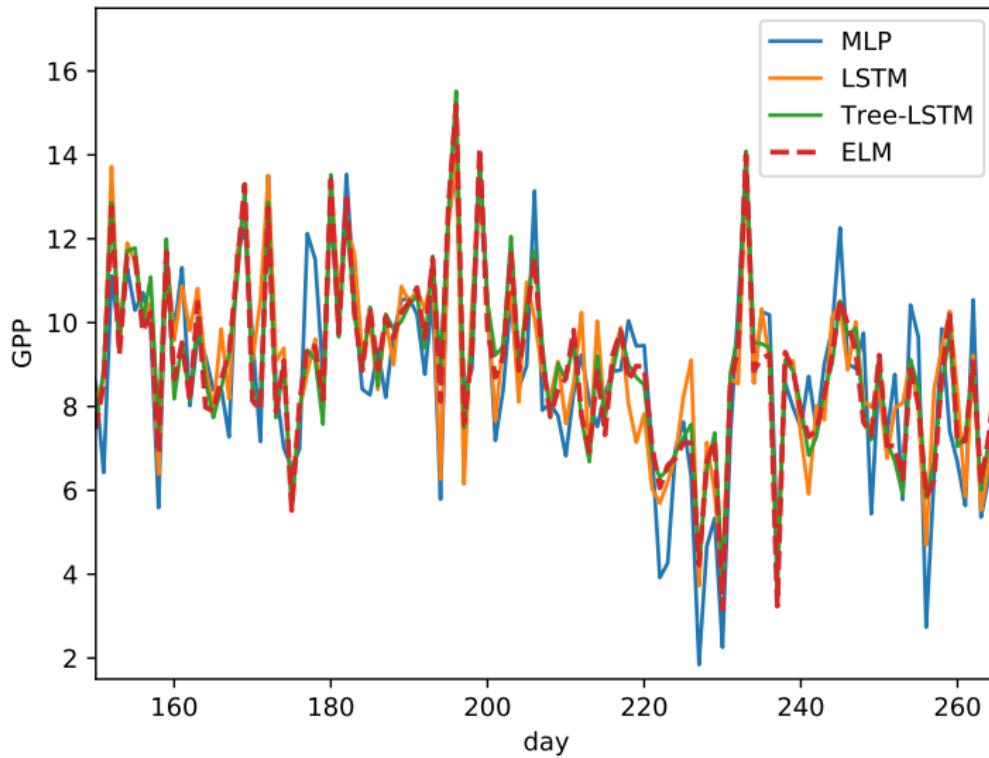


Physics-informed LSTM

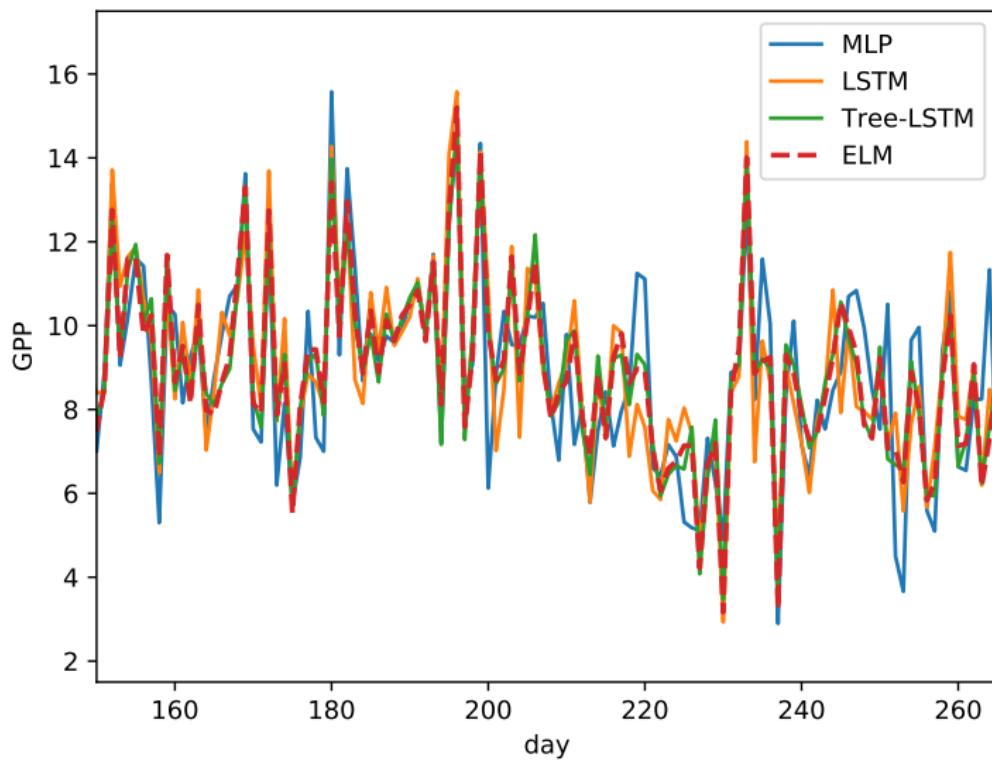
NN fits to ELM



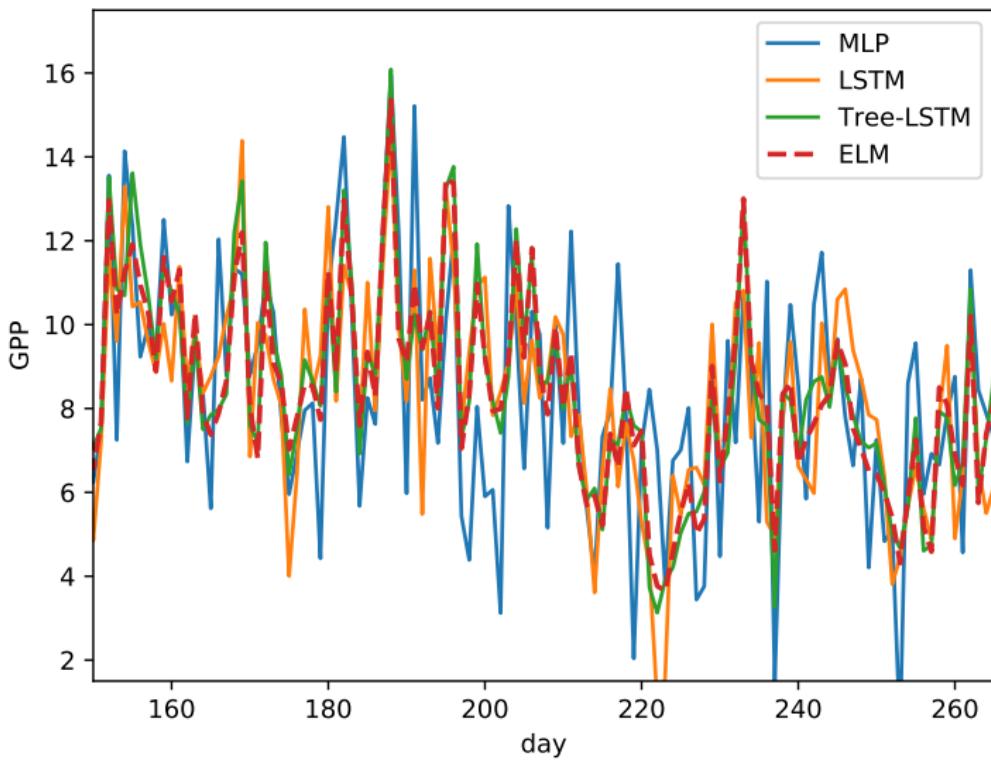
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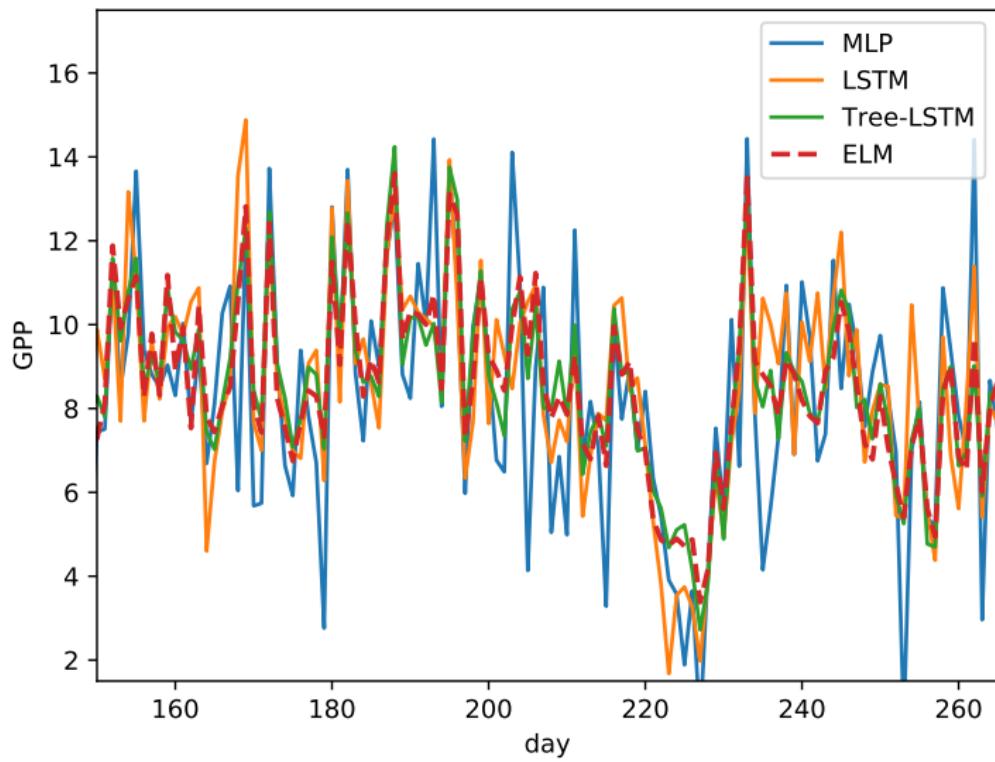
NN fits to ELM



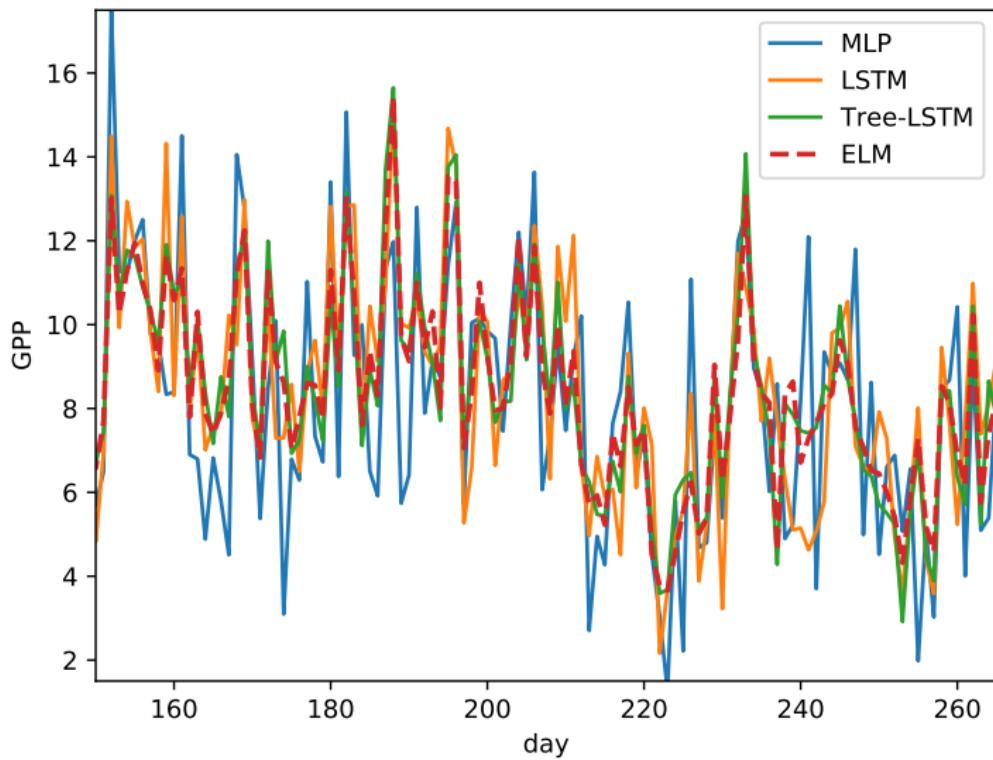
NN fits to ELM



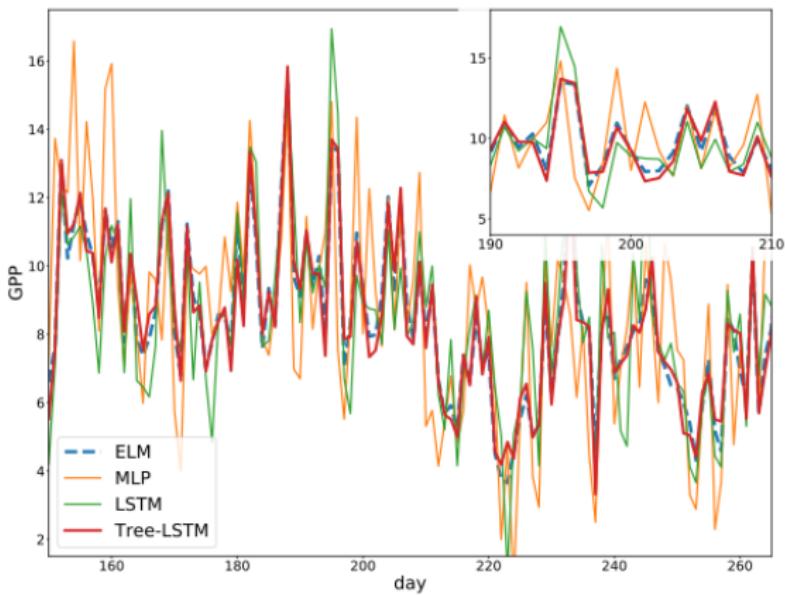
NN fits to ELM



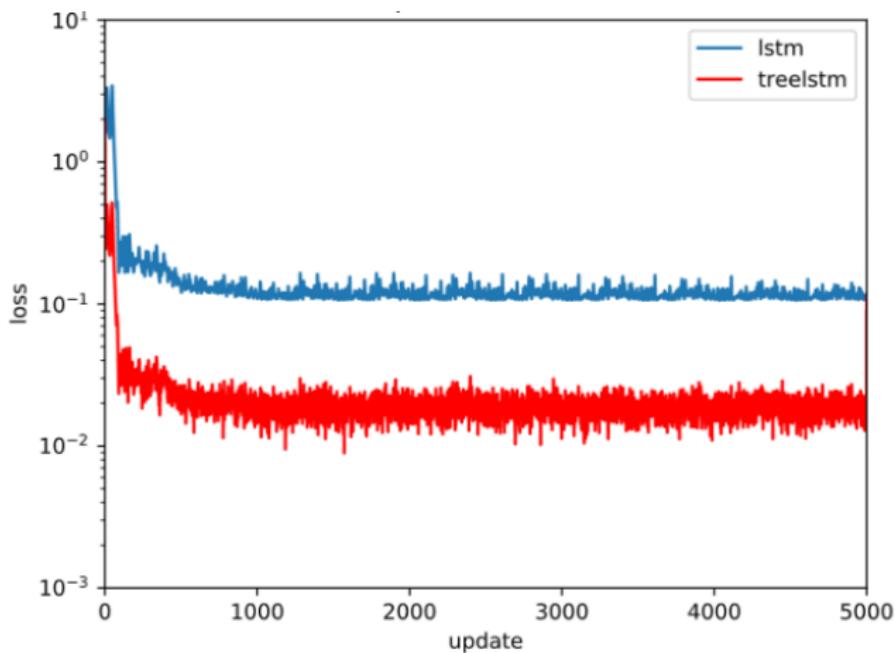
NN fits to ELM



NN fits to ELM



NN fits to ELM



- Mean estimate: $E[f(\boldsymbol{\lambda})] \approx \frac{1}{N} \sum_{n=1}^N f(\boldsymbol{\lambda}^{(n)})$
- Variance estimate: $Var[f(\boldsymbol{\lambda})] \approx \frac{1}{N} \sum_{n=1}^N f(\boldsymbol{\lambda}^{(n)})^2 - E[f(\boldsymbol{\lambda})]^2$
- Main sensitivity:

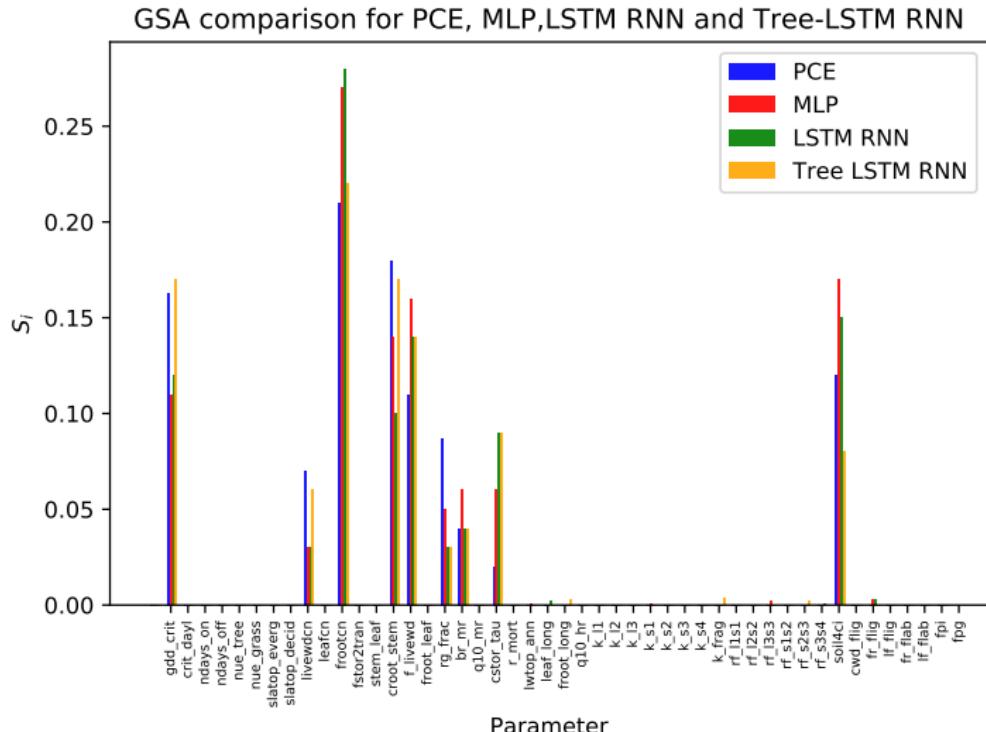
$$S_i = \frac{Var[\mathbb{E}(f(\boldsymbol{\lambda}|\lambda_i)]}{Var[f(\boldsymbol{\lambda})]} \approx \frac{1}{Var[f(\boldsymbol{\lambda})]} \left(\frac{1}{N} \sum_{n=1}^N f(\boldsymbol{\lambda}^{(n)}) f(\boldsymbol{\lambda}'^{(n)}_{-i} \cup \boldsymbol{\lambda}_i^{(n)}) - E[f(\boldsymbol{\lambda})] \right)$$

where $\boldsymbol{\lambda}'^{(n)}_{-i} \cup \boldsymbol{\lambda}_i^{(n)}$ is a single-column swap sample given two sampling schemes $\boldsymbol{\lambda}^{(n)}$ and $\boldsymbol{\lambda}'^{(n)}$

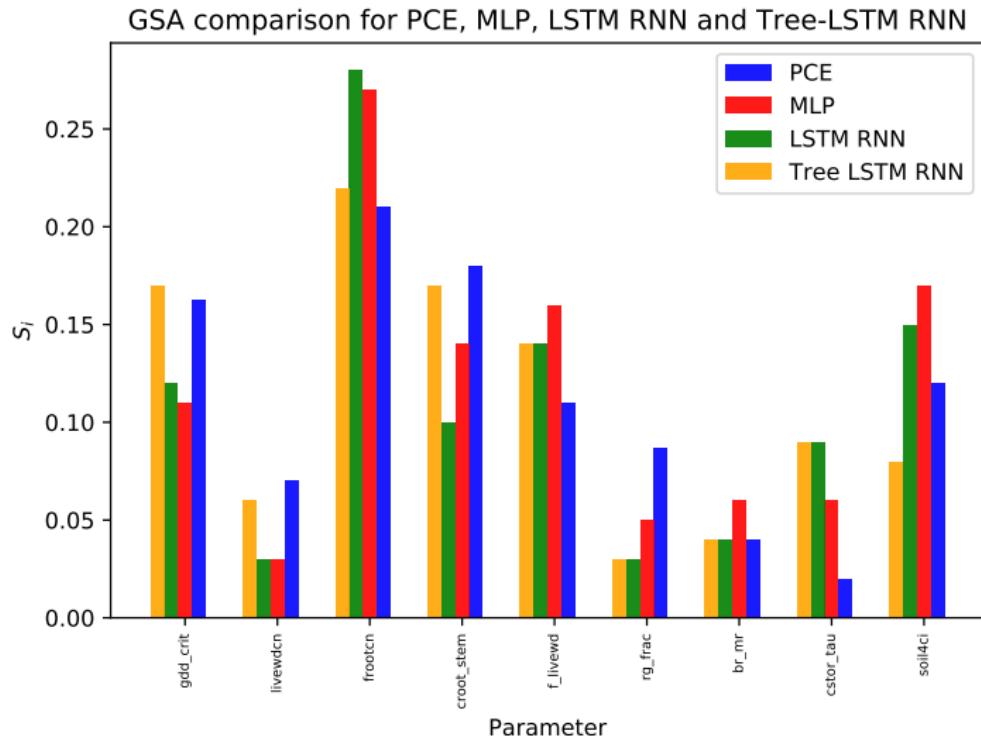
- ... similar estimators for total sensitivity
- Inherits all the challenges of Monte-Carlo

[Jansen, 1999; Sobol, 2001; Saltelli, 2002]

Global Sensitivity Analysis Comparison



Global Sensitivity Analysis Comparison



Overview

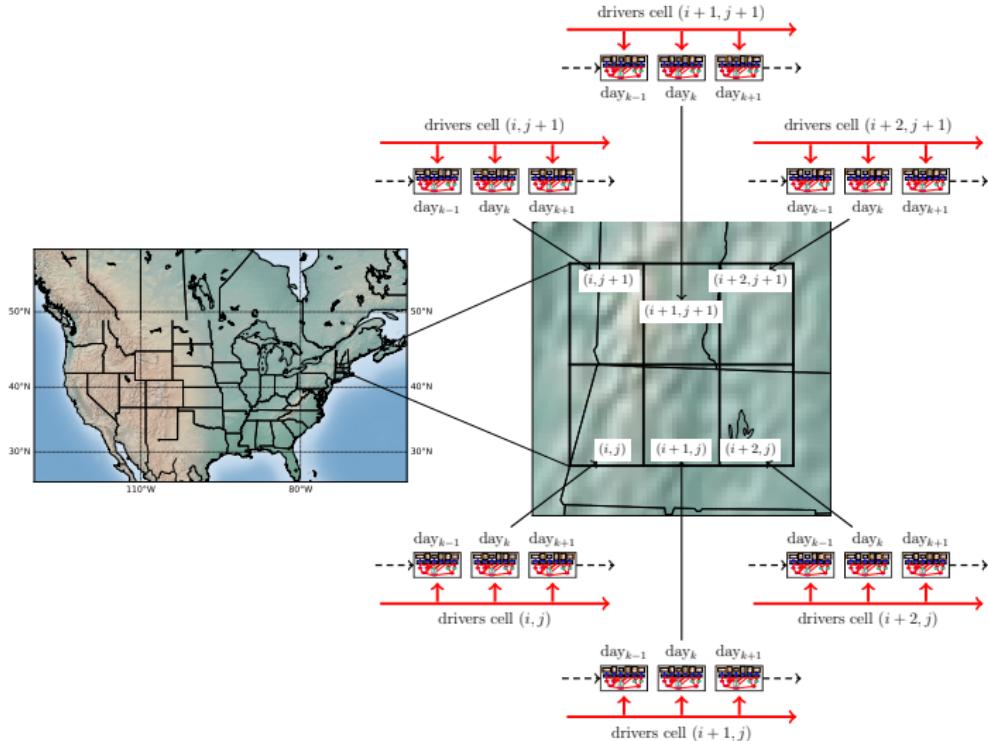
- Key UQ step, surrogate construction == supervised ML
- Dimensionality reduction via Karhunen-Loève expansions (aka autoencoder)
- Physics-based LSTM architecture outperforms traditional NN methods (MLP) and traditional UQ methods (PCEs)
- Qualitatively similar sensitivity results compared to PCE

Current:

- Employing the reduced-dimensional spatio-temporal surrogate for calibration and optimal experimental design

Additional Material

ELM Simulation Details



Tree RNN more accurate than PCE and traditional ML methods

- Computed Mean RMS for each Surrogate

Method	Train (Daily/Month)	Val (Daily/Month)
PCE	(N/A)/35%	(N/A)/46%
MLP	19/14%	32/20%
LSTM	14/10%	21/16%
Tree-LSTM	6/2%	9/5%

- Tree-LSTM outperforms PCE, MLP and LSTM-RNN

Global Sensitivity Analysis

- $Y = f(X_1, X_2, X_3, \dots, X_N)$
- Total Variance decomposition (normalized)

$$Var(Y) = E[Var(Y|X)] + Var(E[Y|X])$$

- If X_i are independent: $V(Y) = \sum_{i=1}^N V_i + \sum_{1 \leq i \leq j \leq N} V_{ij} + \dots + V_{1,\dots,p}$
- Use Sobol indices → QOI's variance to be decomposed based on variances of inputs

Sobol Indices

$$S_i = \frac{Var_{X_i}(E(Y|X_i))}{Var(Y)} \quad \text{First Sobol Indices}$$

$$S_{ij} = \frac{Var_{ij}}{Var(Y)} \quad \text{Second Order Sobol Indices}$$

Method

- PCE allows for analytical computation of S_i
- ML needs Monte Carlo Integration to compute S_i

Summary of Case Study

Training Details

- Generate samples from sELM model: 30 years (1980-2009)
- Each training set (time history) has 10,950 data points (daily)
- Simulation at University of Michigan Biological Station site
- 500 training samples, 500 validation samples

NN Details

- Train on daily Qols
- 500 Epochs of SGD
- 2 layers, 150 neurons
- L_2 loss, dropout regularization

MLP

- No time dynamics
- No physics

LSTM

- Time dynamics
- No physics

Tree-LSTM

- Time dynamics
- Physics

PC Details

- Hard to train on daily averages (noisy)
- Train on monthly averages
- Use Bayesian compressive sensing to compute coefficients
- Build surrogate for each average month, i.e. 30×12 surrogates