

# *Model Error Estimation and Uncertainty Quantification of Machine Learning Interatomic Potentials*

*Khachik Sargsyan,  
Logan Williams, Habib N. Najm*

Sandia National Laboratories, Livermore, CA

Error control in first-principles modelling  
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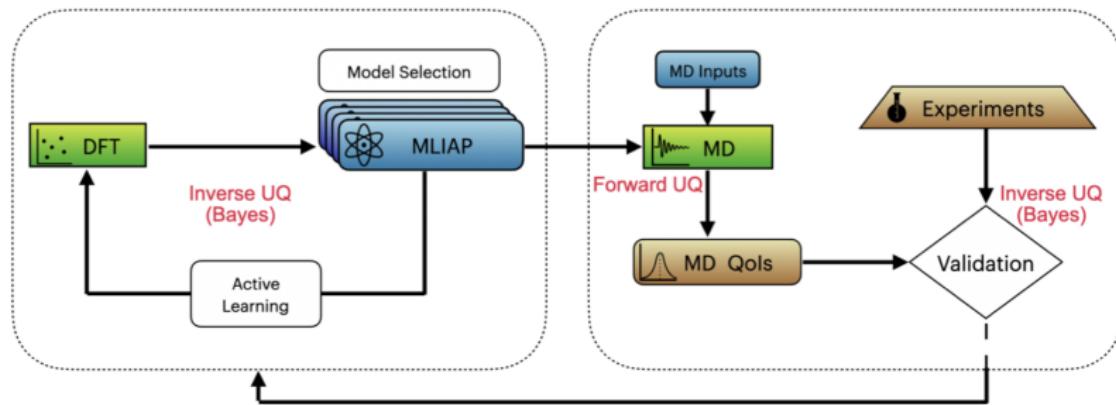
# Acknowledgements

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- DOE, Office of Science,
  - Fusion Energy Sciences (FES)
  - Advanced Scientific Computing Research (ASCR)

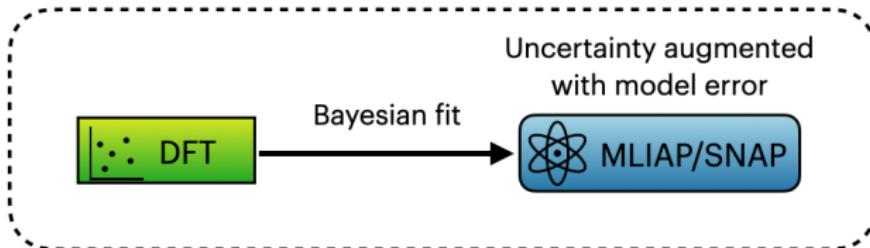


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# Outline

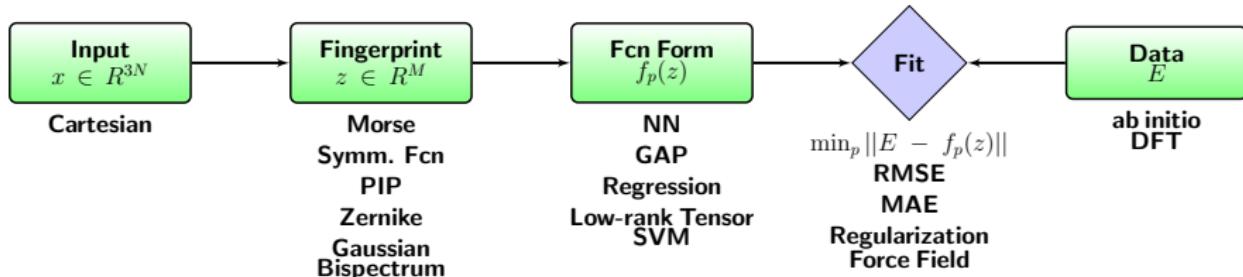


# Outline

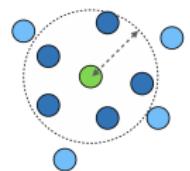


- UQ for machine learning interatomic potentials (MLIAP)
  - ... for uncertainty propagation
  - ... for active learning
  - ... for model selection
- Bayesian approach
  - More focus on linear regression models:  
Spectral Neighbor Analysis Potential (SNAP)
  - Importance of noise model, embedded model error construction
  - Relation to variational inference

# ML Interatomic Potentials (MLIAP): supervised ML



- Partition the interatomic interaction energy into individual contributions of the atoms  $E_{\text{total}} = \sum_{i=1}^N E_i$
- Assume flexible functional forms of each such contribution
  - Function of positions of the neighboring atoms
  - $O(100)$  parameters
- Require the energy, forces and/or stresses predicted by a MLIAP to be close to those obtained by a quantum mechanical model on some atomic configurations (a.k.a. training set)

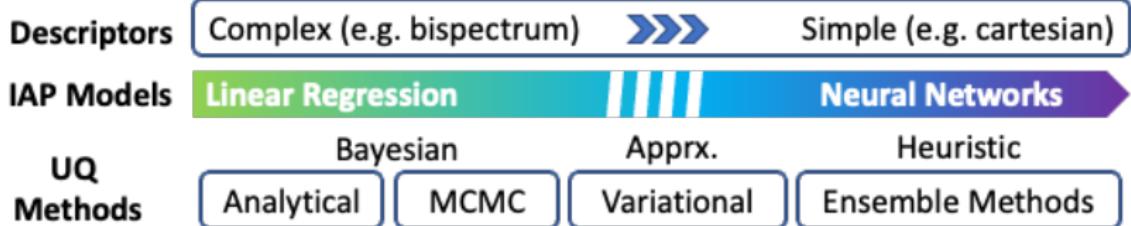


# MLIAP - desired features

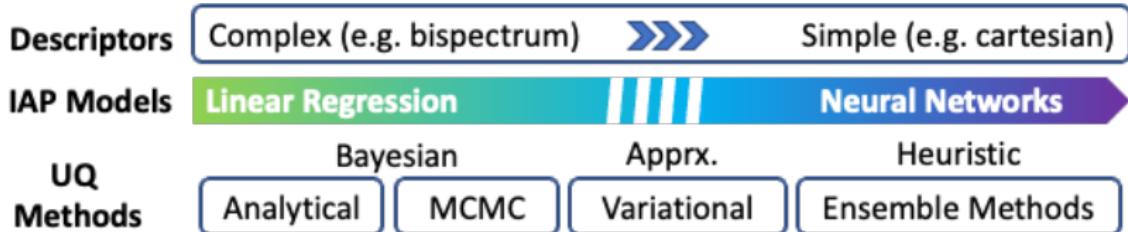
- Good input descriptors
- Accurate, fast-to-evaluate, analytic derivatives
- High-dimensional, flexible functional form
- Transferable/generalizable to unseen atomic configurations
- Account for physics:
  - invariant with respect to translation, rotation, and reflection of the space, and also permutation of chemically equivalent atoms
- Locality (depend on surrounding atoms only within a finite cut-off radius), but remain smooth with respect to atoms entering and leaving the local neighborhood
- **Equipped with uncertainty estimate**
  - for active learning, for MD propagation, ...

# Enabling parametric fits with uncertainties

$$y \approx f_c(x)$$



# Focus on SNAP (Left end of the figure)



- [Thompson et al., 2015] “Spectral neighbor analysis method for automated generation of quantum-accurate interatomic potentials”, *J Comp Phys*, 2015.

$$f(q) = \sum_{k=0}^K c_k B_k(q)$$

- Linear expansion in parameters  $c$ .
- Bayesian inference: both MCMC and analytical posterior PDFs are feasible

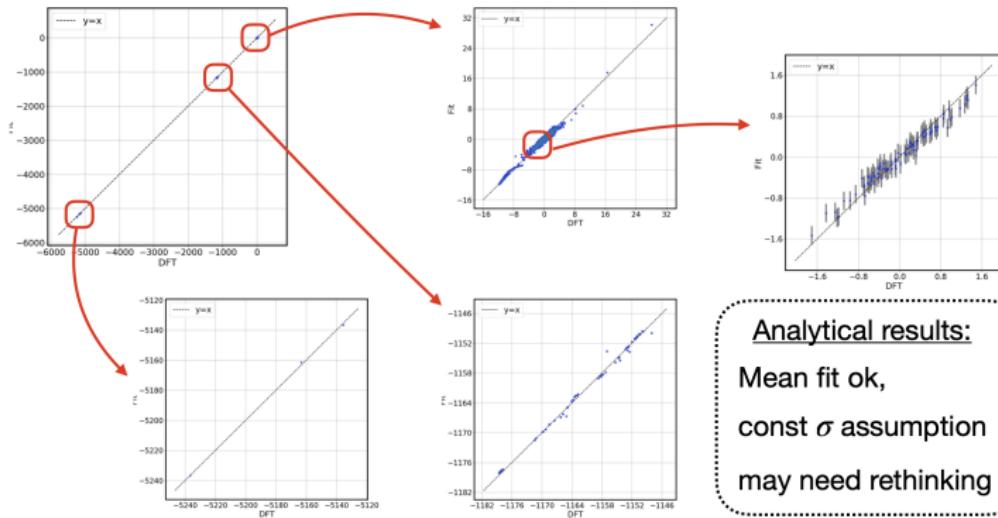
# (Bayesian) Parameter Inference

- Given a model  $f(x, c)$  and data  $y_i = y(x_i)$ , calibrate parameters  $c$ .
  - Linear model  $f(x, c) = Bc$  with coefficients  $c$
  - NN model  $f(x, c) = NN_c(x)$  with weights/biases  $c$
- Bayesian least-squares fit:  
$$p(c|y) \propto p(y|c)p(c) \propto \prod_{i=1}^N \exp\left(-\frac{(f(x_i, c) - y_i)^2}{2\sigma^2}\right)$$
- ... corresponding data model  $y_i = f(x_i, c) + \sigma \underbrace{\epsilon_i}_{\mathcal{N}(0,1)}$
- Exact answer for linear models:  $c \sim \mathcal{N}\left((B^T B)^{-1} B^T y, \sigma^2 (B^T B)^{-1}\right)$

# SNAP uncertainty with Tantalum data set

$$f(q) = \sum_{k=0}^K c_k B_k(q)$$

- Employed FitSNAP <https://github.com/FitSNAP/FitSNAP>



Analytical results:  
Mean fit ok,  
const  $\sigma$  assumption  
may need rethinking

- Assumptions baked in likelihood form are crucial!
- i.i.d. gaussian noise with constant  $\sigma$  is not well founded.

# Elephant in the room: model is assumed to be \*the\* correct model behind data

$$y_i = \underbrace{f(x_i, c)}_{\text{Model}} + \underbrace{\sigma_i \epsilon_i}_{\text{Data err.}} \quad \text{Truth} \quad \text{Model} \neq \text{Truth}$$

- One gets biased estimates of parameters  $c$  (crucial if the model is physical, and/or  $c$  is propagated through other models)
- More data leads to overconfident predictions (we become more and more certain about the wrong values of the data)
- More evident when there is no (observational/experimental) data error: e.g. DFT is data, and MLIAP is model

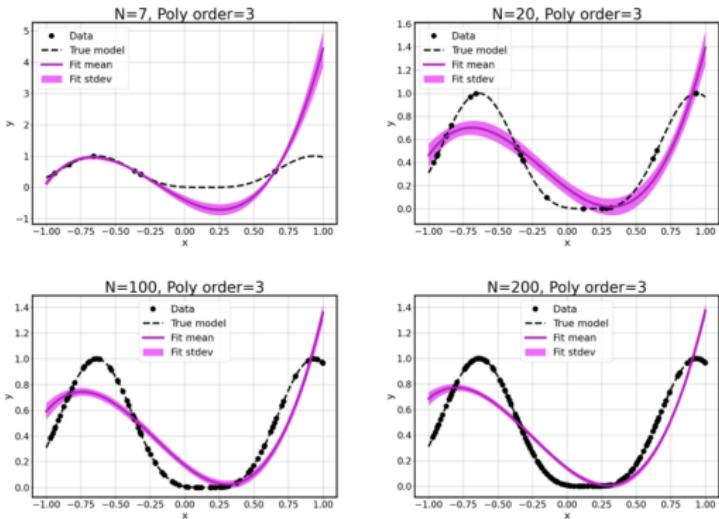
# Posterior pushed-forward uncertainty does not capture true discrepancy

Synthetic data  
 $y(x) = \sin^4(2x - 0.3)$

Cubic fit

$$y_i \approx \sum_{k=0}^3 c_k B_k(x)$$

**More data leads to overconfident prediction**



# Capturing model error in data model (a.k.a. likelihood)

## External correction (Kennedy-O'Hagan):

$$y_i = f(x_i, c) + \delta(x_i) + \sigma_i \epsilon_i$$

- Kennedy, O'Hagan, "Bayesian Calibration of Computer Models".  
*J Royal Stat Soc: Series B (Stat Meth)*, 63: 425-464, 2001.
- 

## Internal correction (embedded model error):

$$y_i = f(x_i, c + \delta(x_i)) + \sigma_i \epsilon_i$$

- Allows meaningful usage of calibrated model
- ‘Leftover’ noise term even with no data error
- Respects physics (not too relevant in our context)

- Sargsyan, Najm, Ghanem, "On the Statistical Calibration of Physical Models".  
*Int. J. Chem. Kinet.*, 47: 246-276, 2015.
  - Sargsyan, Huan, Najm, "Embedded Model Error Representation for Bayesian Model Calibration".  
*Int. J. Uncert. Quantif.*, 9(4): 365-394, 2019.
- 

- Typically requires uncertainty propagation in the likelihood computation
- For linear regression, we can take some shortcuts (see next)

# Embedded Model Error for Linear Regression Models

Conventional (i.i.d. error term):

$$y_i \approx \sum_{k=0}^P c_k B_k(x_i) + \sigma_i \epsilon_i$$

Embed uncertainty in all or selected coefficients:

$$y_i \approx \sum_{k=0}^P (c_k + d_k \xi_k) B_k(x_i) = \overbrace{\sum_{k=0}^P c_k B_k(x_i)}^{\text{Model}} + \overbrace{\sum_{k=0}^P d_k B_k(x_i) \xi_k}^{\text{Model Error}}$$

Note:

No formal distinction between internal and external corrections:  
but the error is now model-informed.

Conventional:

$$y_i \approx \sum_{k=0}^P c_k B_k(x_i) + \sigma_i \epsilon_i \quad p(c|y) \propto \prod_{i=1}^N \exp \left( -\frac{(\sum_{k=0}^P c_k B_k(x_i) - y_i)^2}{2\sigma_i^2} \right)$$

---

Embedded:

$$y_i \approx \sum_{k=0}^P (c_k + d_k \xi_k) B_k(x_i) = \underbrace{\sum_{k=0}^P c_k B_k(x_i)}_{\text{Model}} + \underbrace{\sum_{k=0}^P d_k B_k(x_i) \xi_k}_{\text{Model Error}}$$

$$p(c, d|y) \propto \underbrace{p(y|c, d)}_{\text{Likelihood}} \underbrace{p(c, d)}_{\text{Prior}}$$

Note:

Both likelihood and prior selection are challenging.

## Embedded Model Error: Two Approximate Likelihood Options

$$y_i \approx \sum_{k=0}^P (c_k + d_k \xi_k) B_k(x_i) = \sum_{k=0}^P c_k B_k(x_i) + \sum_{k=0}^P d_k B_k(x_i) \xi_k$$

---

Option 1: IID

$$p(c, d|y) \propto \prod_{i=1}^N \exp \left( -\frac{(\sum_{k=0}^P c_k B_k(x_i) - y_i)^2}{2 \sum_{k=0}^K d_k^2 B_k(x_i)^2} \right)$$

---

Option 2: ABC

$$p(c, d|y) \propto \prod_{i=1}^N \exp \left( -\frac{(\sum_{k=0}^P c_k B_k(x_i) - y_i)^2 + (\sqrt{\sum_{k=0}^P d_k^2 B_k^2(x_i)} - \alpha |\sum_{k=0}^P c_k B_k(x_i) - y_i|)^2}{2\epsilon^2} \right)$$

Note:

Does not have to be MCMC: simply optimize the posterior for  $(c, d)$

# Pushed forward predictive uncertainty captures the true discrepancy from the data

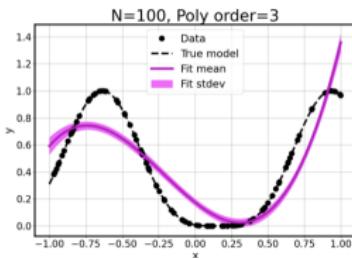
Synthetic data

$$y(x) = \sin^4(2x - 0.3)$$

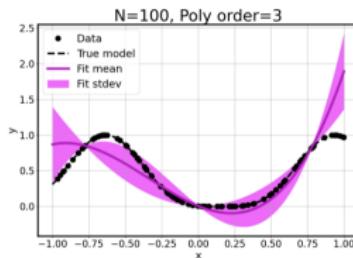
Cubic fit

$$y_i \approx \sum_{k=0}^3 c_k B_k(x)$$

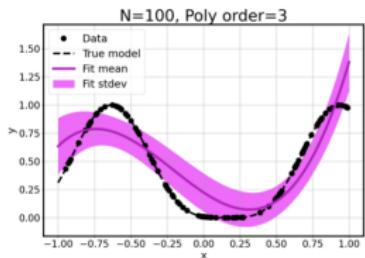
Classical case



Model error, IID likelihood

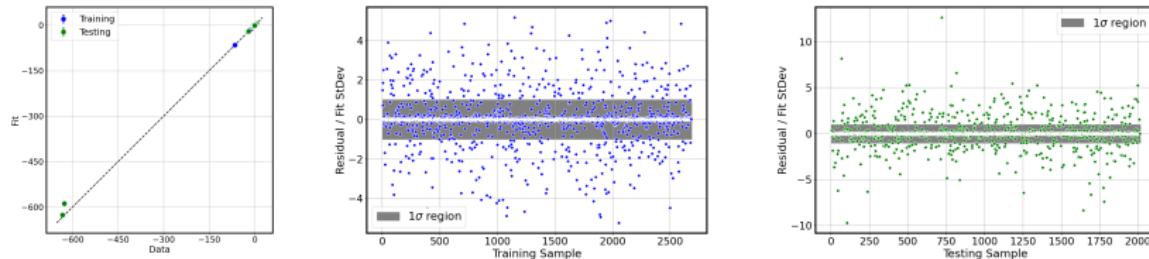


Model error, ABC likelihood

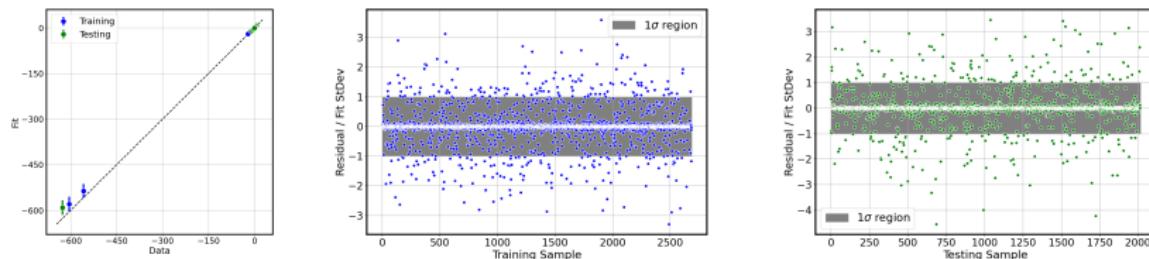


# Uncertainty validation: W-ZrC Dataset

## Uncertainty without model error

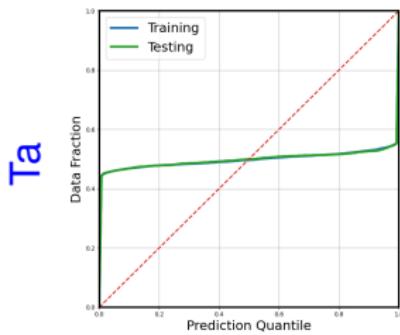


## Uncertainty with model error

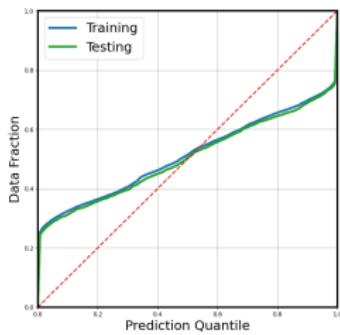


# Uncertainty validation: two examples

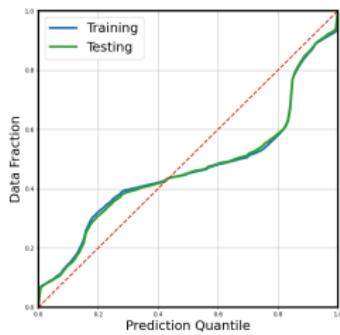
Conventional



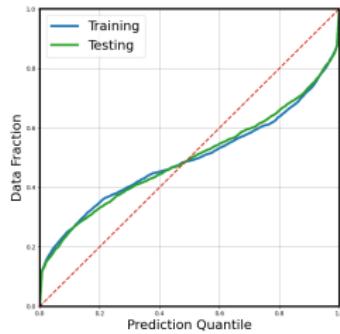
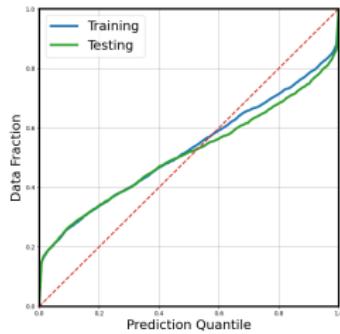
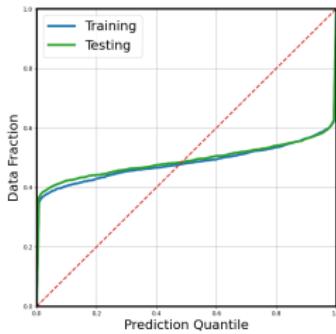
Embedded, IID Lik.



Embedded, ABC Lik.



W-ZrC



# Model Error Wrapup: several challenges and choices

- Embedding type, e.g. additive/multiplicative

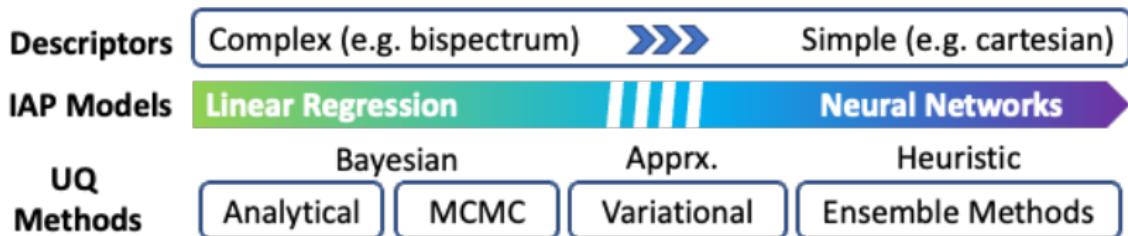
$$y_i \approx \sum_{k=0}^P (c_k + d_k \xi_k) B_k(x_i)$$

or

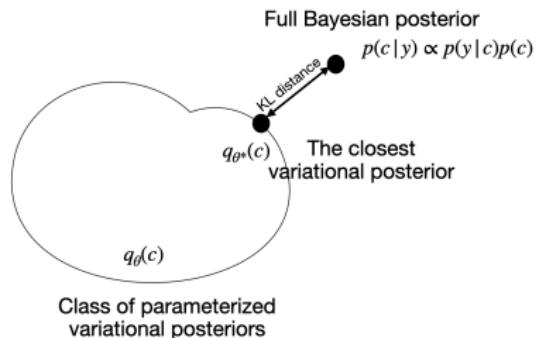
$$y_i \approx \sum_{k=0}^P (c_k + c_k d_k \xi_k) B_k(x_i)$$

- Degenerate (Gaussian) likelihoods: resort to approximate Bayesian computation (ABC) or independent (IID) assumptions
- Difficult posterior PDFs for MCMC, choice of priors for embedding parameters
- Which coefficients to embed the model error in?
- Connect predictive uncertainty and the residual error with an extrapolation metric
- Weighting between energies, forces and stresses

# Variational inference is a compromise between Bayesian and Empirical approaches



# Variational inference in a nutshell



$$KL(p_1||p_2) = \int \ln \left( \frac{p_1(x)}{p_2(x)} \right) p_1(x) dx$$

- e.g. Mean-Field Variational Inference (MFVI): ansatz  $c \sim \mathcal{N}(\mu, \text{diag}(\nu))$  and find best  $(\mu, \nu)$ , i.e.
- minimize Kullback-Leibler distance to the full Bayesian posterior,  
 $\operatorname{argmin}_{(\mu, \nu)} KL(\mathcal{N}(\mu, \text{diag}(\nu)) || \mathcal{N}(\mu_0, \Sigma)),$
- replaces sampling (MCMC) problem with an optimization problem.

# Note the connection between variational inference and embedded model error

- Variational methods:  $c \sim N(\mu, \Sigma)$  and optimize  $\mu, \Sigma$ .
  - In NN context, this is largely called Bayesian Neural Networks
  - Minimize Kullback-Leibler distance via Stoch. Gradient Descent
- Embedded model error:  $c \sim N(\mu, \Sigma)$  and optimize  $\mu, \Sigma$ .
  - Minimize Gaussian approximation of output predictions (IID), or
  - Minimize statistics/moment matching criterion (ABC)

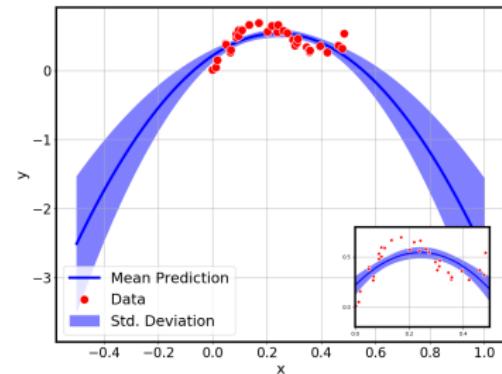
Next:

Overparameterized linear regression (mimicking NN) challenges mean-field variational inference outside training support.

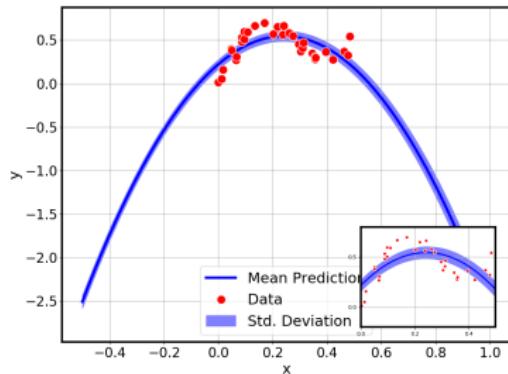
# Polynomial fit: Extrapolation scenario

Order=2

Full Bayesian Posterior  
 $\mathcal{N}(\mu, \Sigma)$



Variational Posterior  
 $\mathcal{N}(\mu, 1/\text{diag}(\Sigma^{-1}))$

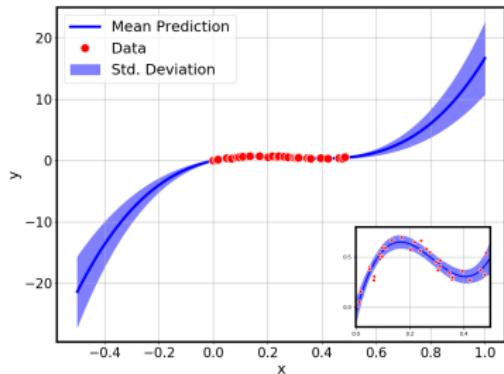


Variational posterior predictions heavily underestimate both interpolative and extrapolative errors, in the overparameterized regimes.

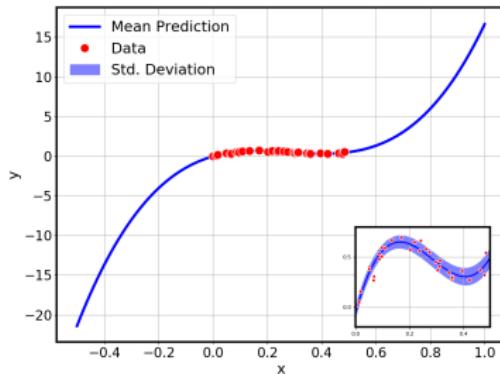
# Polynomial fit: Extrapolation scenario

Order=3

Full Bayesian Posterior  
 $\mathcal{N}(\mu, \Sigma)$



Variational Posterior  
 $\mathcal{N}(\mu, 1/\text{diag}(\Sigma^{-1}))$

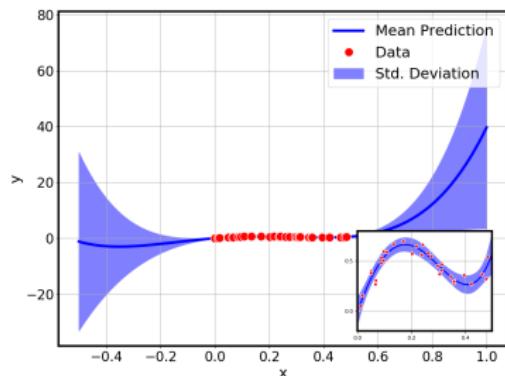


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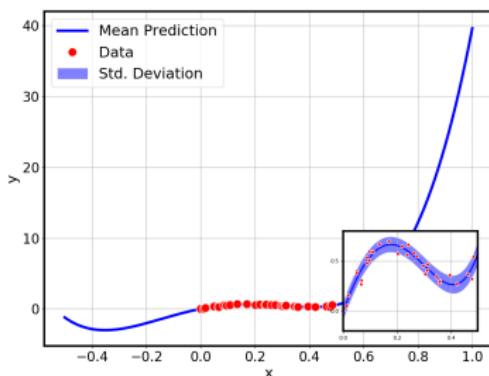
# Polynomial fit: Extrapolation scenario

Order=4

Full Bayesian Posterior  
 $\mathcal{N}(\mu, \Sigma)$



Variational Posterior  
 $\mathcal{N}(\mu, 1/\text{diag}(\Sigma^{-1}))$

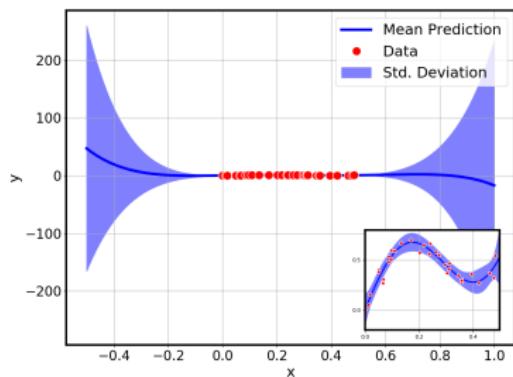


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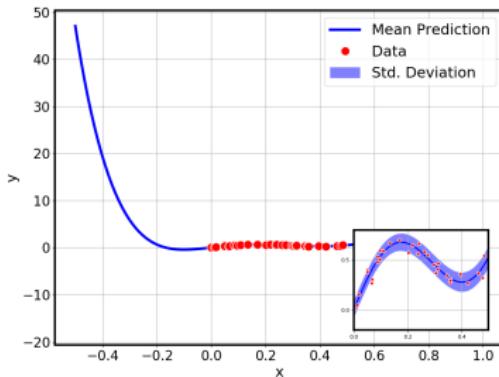
# Polynomial fit: Extrapolation scenario

Order=5

Full Bayesian Posterior  
 $\mathcal{N}(\mu, \Sigma)$



Variational Posterior  
 $\mathcal{N}(\mu, 1/\text{diag}(\Sigma^{-1}))$

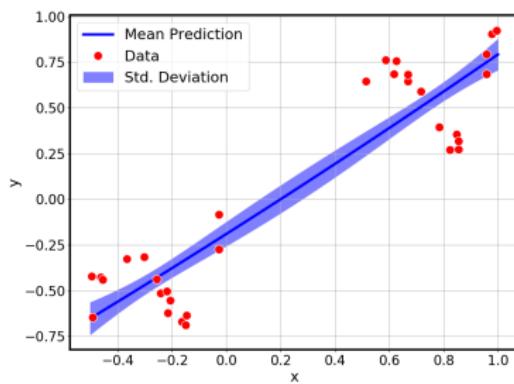


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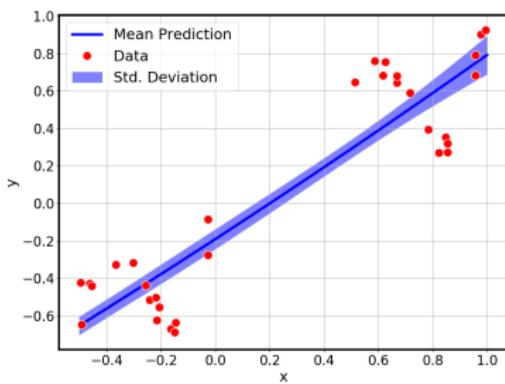
# Polynomial fit: Interpolation scenario

Order=2

Full Bayesian Posterior  
 $\mathcal{N}(\mu, \Sigma)$



Variational Posterior  
 $\mathcal{N}(\mu, 1/\text{diag}(\Sigma^{-1}))$

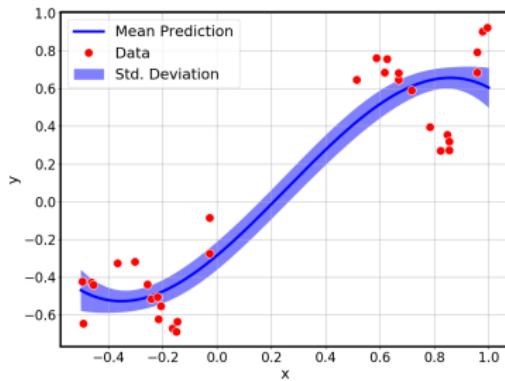


Variational posterior predictions heavily underestimate both interpolative and extrapolative errors, in the overparameterized regimes.

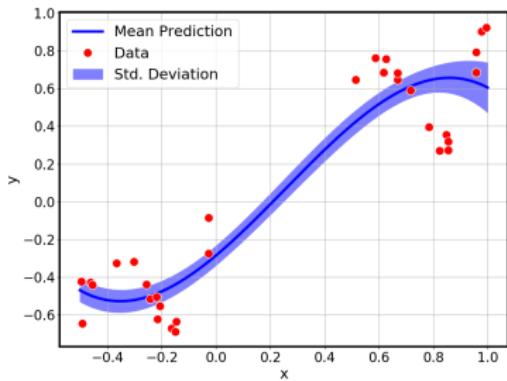
# Polynomial fit: Interpolation scenario

Order=3

Full Bayesian Posterior  
 $\mathcal{N}(\mu, \Sigma)$



Variational Posterior  
 $\mathcal{N}(\mu, 1/\text{diag}(\Sigma^{-1}))$

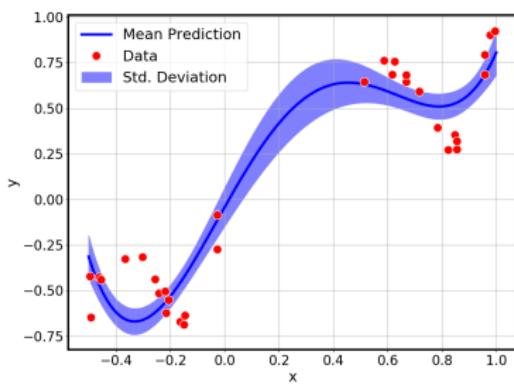


Variational posterior predictions heavily underestimate both interpolative and extrapolative errors, in the overparameterized regimes.

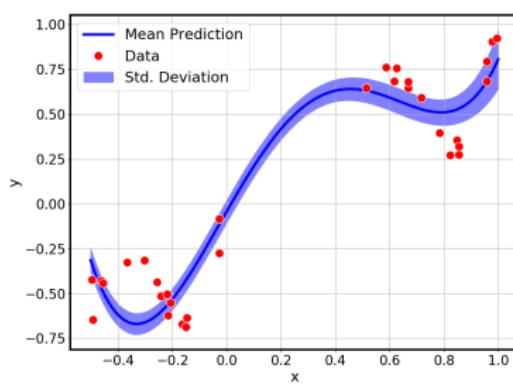
# Polynomial fit: Interpolation scenario

Order=4

Full Bayesian Posterior  
 $\mathcal{N}(\mu, \Sigma)$



Variational Posterior  
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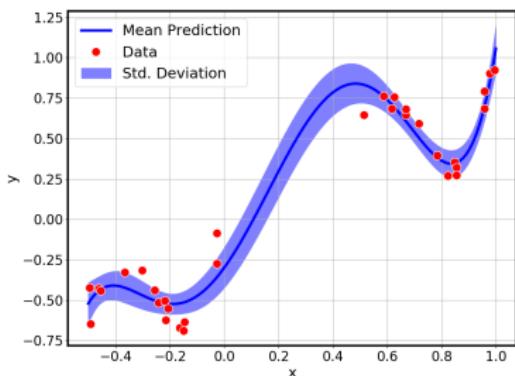


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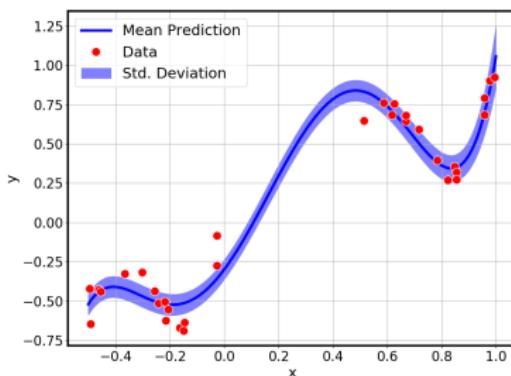
# Polynomial fit: Interpolation scenario

Order=5

Full Bayesian Posterior  
 $\mathcal{N}(\mu, \Sigma)$



Variational Posterior  
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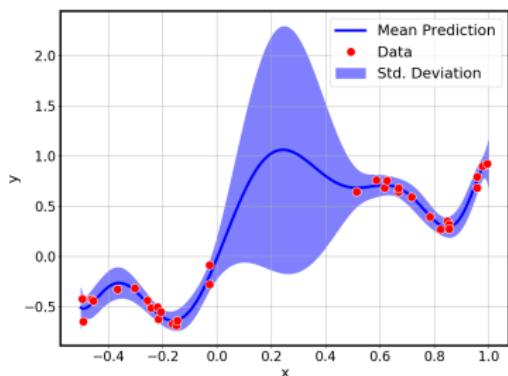


Variational posterior predictions heavily underestimate both interpolative and extrapolative errors, in the overparameterized regimes.

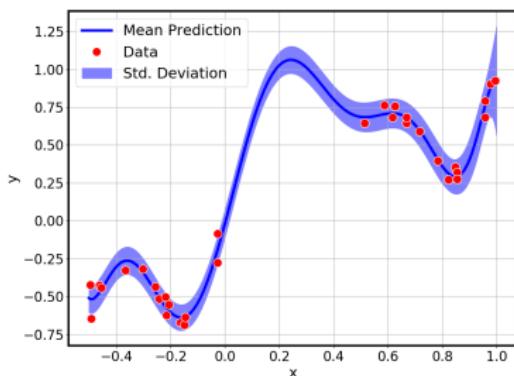
# Polynomial fit: Interpolation scenario

Order=10

Full Bayesian Posterior  
 $\mathcal{N}(\mu, \Sigma)$



Variational Posterior  
 $\mathcal{N}(\mu, 1/\text{diag}(\Sigma^{-1}))$

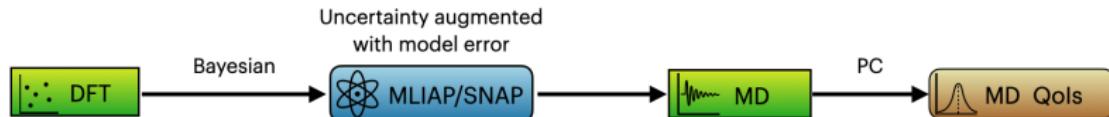


Variational posterior predictions heavily underestimate both interpolative and extrapolative errors, in the overparameterized regimes.

- Bayesian fit of parameterized MLIAPs
  - Noise assumptions are crucial
- Embedded model error
  - Statistical correction *inside* the model: joint inference of model parameters and the correction
  - Leads to model-driven noise model
  - Meaningful model-error uncertainty capturing the true residual
  - A few shortcuts in linear regression models
  - Choices to make: priors, approximate likelihoods, MCMC sampler, where to embed...
- Variational inference
  - Approximate alternative to MCMC for nonlinear, complex models
  - Underestimates the uncertainty for overparameterized models: dangerous when extrapolating!
  - Mechanically similar to embedded model error, except the optimization objective/method (and, potentially, the interpretation!)

# Additional Material

# Uncertainty Propagation through MD



- PC intro setup; SNAP coefficients form a first order Gauss-Hermite Polynomial Chaos (PC)

$$E \approx \sum_{k=0}^P \underbrace{(c_k + d_k \xi_k)}_{\tilde{c}} B_k(x)$$

- Sample SNAP coefficients
- Evaluate MD Qols
- Build PC for MD Qols, possibly multilevel/multifidelity
- Evaluate PDF/statistics of Qols
- Challenges: high-d input, noisy MD simulations

# Uncertainty-enabling wrappers over PyTorch modules

Deterministic

`torch.nn.module`

Probabilistic

`wrapper(torch.nn.module)`

Option 1: ensemble NN

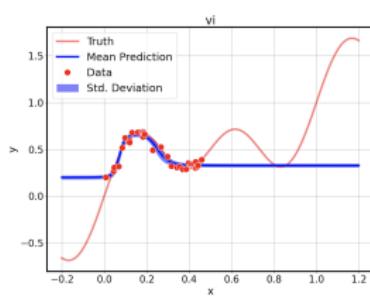
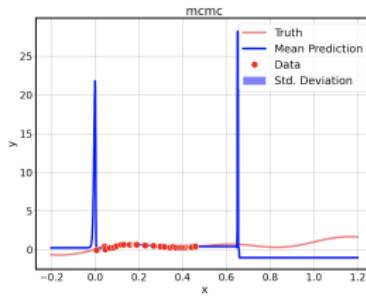
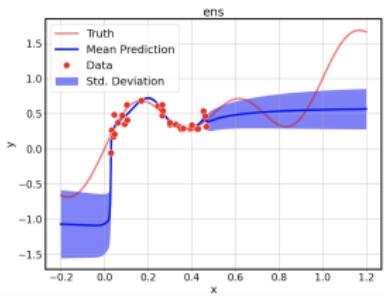
```
nn_ens = EnsRegr(torch.nn.module, nens=111)  
  
class EnsRegr():  
    def __init__(self, nnmodule, nens=1, verbose=False):  
        self.nnmodule = nnmodule  
        self.verbose = verbose  
        self.nens = nens
```

Option 2: NN learning with MCMC

```
nn_mcmc = MCMCRegr(torch.nn.module)  
  
class MCMCRegr():  
    def __init__(self, nnmodule, verbose=True):  
        self.nnmodule = nnmodule  
        self.verbose = verbose
```

Option 3: NN learning with VI

```
nn_vi = VIRegr(torch.nn.module)  
  
class VIRegr():  
    def __init__(self, nnmodule, verbose=False):  
        self.bnmod = BNet(nnmodule)  
        self.verbose = verbose
```



- MCMC struggles with complex NNs; VI underestimates; Ensembles do well

# Uncertainty-enabling wrappers over PyTorch modules

Deterministic

`torch.nn.module`

Probabilistic

`wrapper(torch.nn.module)`

Option 1: ensemble NN

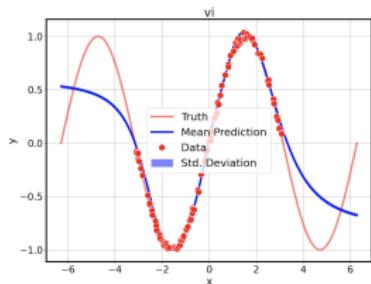
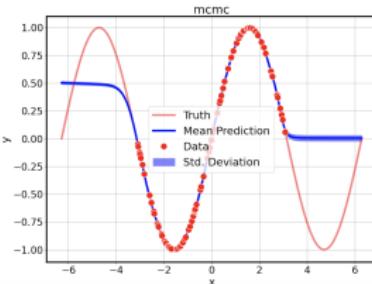
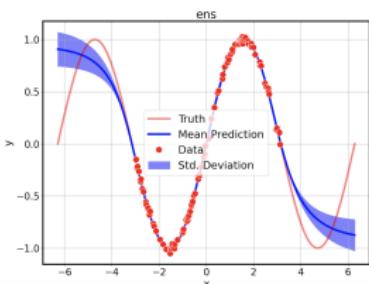
```
nn_ens = EnsRegr(torch.nn.module, nens=111)  
  
class EnsRegr():  
    def __init__(self, nnmodule, nens=1, verbose=False):  
        self.nnmodule = nnmodule  
        self.verbose = verbose  
        self.nens = nens
```

Option 2: NN learning with MCMC

```
nn_mcmc = MCMCRegr(torch.nn.module)  
  
class MCMCRegr():  
    def __init__(self, nnmodule, verbose=True):  
        self.nnmodule = nnmodule  
        self.verbose = verbose
```

Option 3: NN learning with VI

```
nn_vi = VIRegr(torch.nn.module)  
  
class VIRegr():  
    def __init__(self, nnmodule, verbose=False):  
        self.bnmod = BNet(nnmodule)  
        self.verbose = verbose
```



- MCMC struggles with complex NNs; VI underestimates; Ensembles do well

# Literature

## Model error embedding

- [Sargsyan et al., 2019] “Embedded model error representation for Bayesian model calibration”, *Int. J. Uncertain. Quantif.*, 9(4), 2019.
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## MLIAPs

- [Thompson et al., 2015] “Spectral neighbor analysis method for automated generation of quantum-accurate interatomic potentials”, *J Comp Phys*, 2015.
  - [J. Behler, 2014] “Representing potential energy surfaces by high-dimensional neural network potentials”, *J. Phys.: Condens. Matter*, 26, 2014.
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## Active learning

- [B. Settles, 2009] “Active learning literature survey”, *Comp Sci Tech Report 1648*, University of Wisconsin-Madison, 2009.
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## Active learning for MLIAPs

- [E. Podryabinkin, A. Shapeev, 2017] “Active learning of linearly parametrized interatomic potentials”, *Comp Mat Sci*, 140, 2017.
- [J. Vandermause et al., 2020] “On-the-fly active learning of interpretable Bayesian force fields for atomistic rare events”, *npj Computational Materials*, 6, 2020.