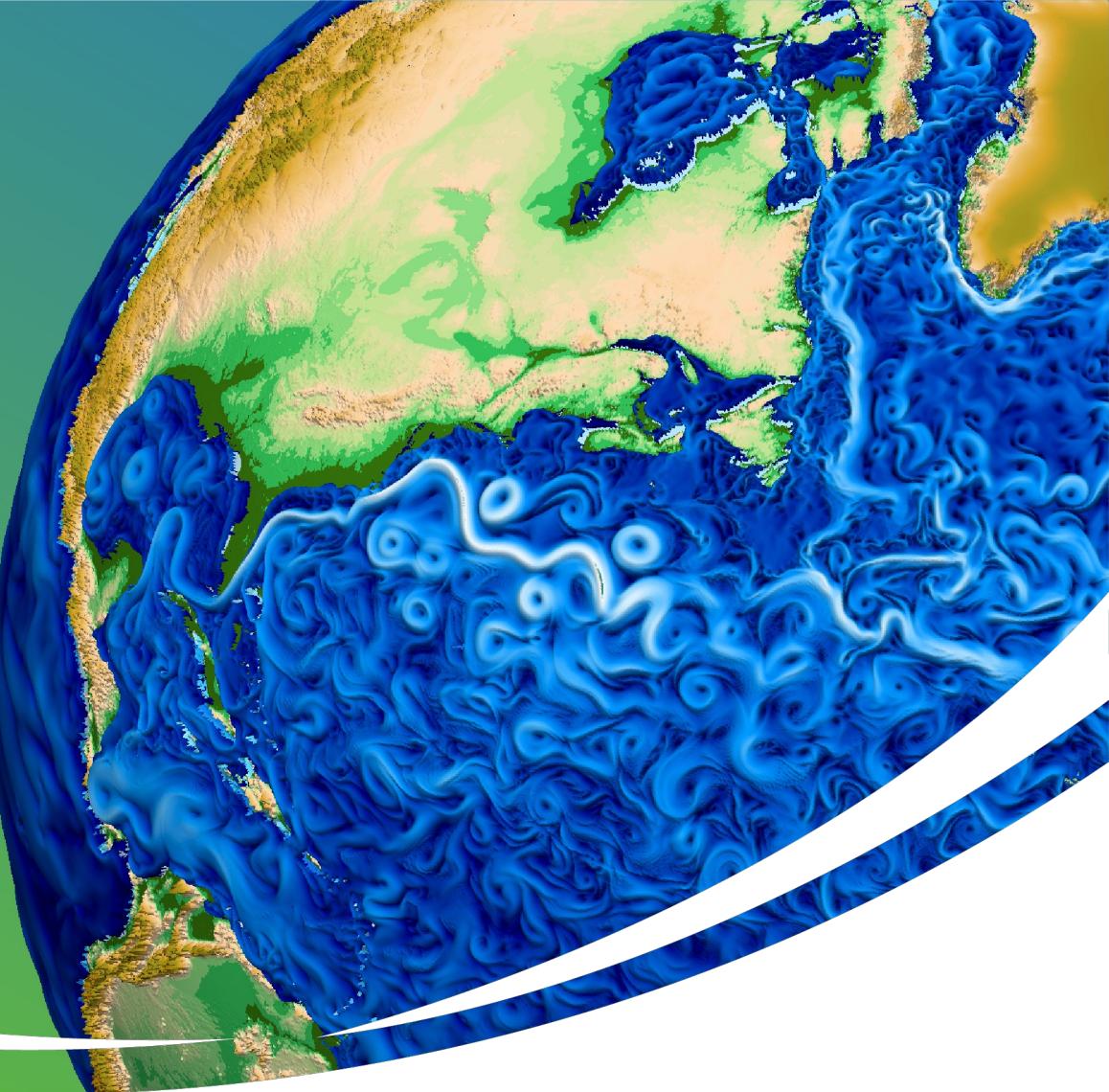


# Reduced-Dimensional Neural Network Surrogate Construction and Calibration of the E3SM Land Model

Khachik Sargsyan (SNL), Daniel Ricciuto (ORNL)



Sandia  
National  
Laboratories

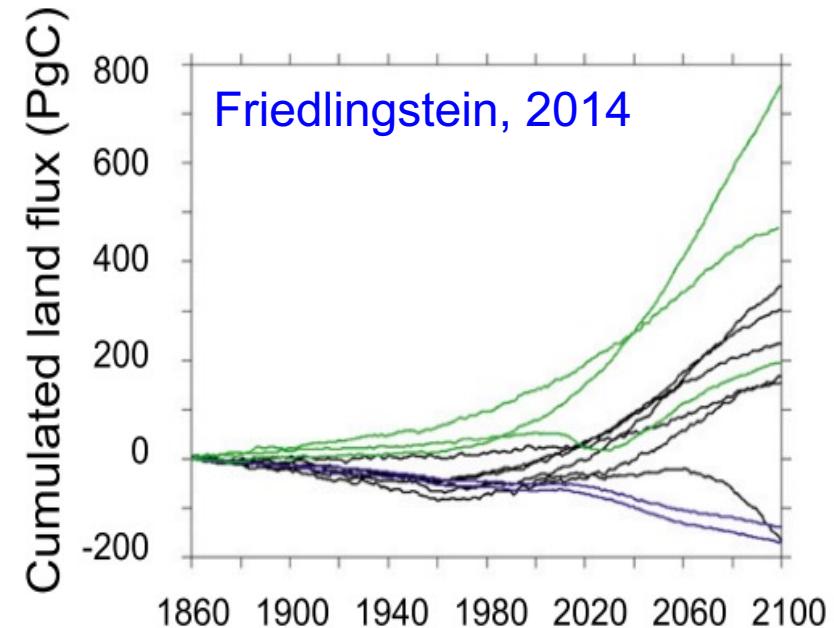


CLM/PPE Webinar  
Feb 15, 2024

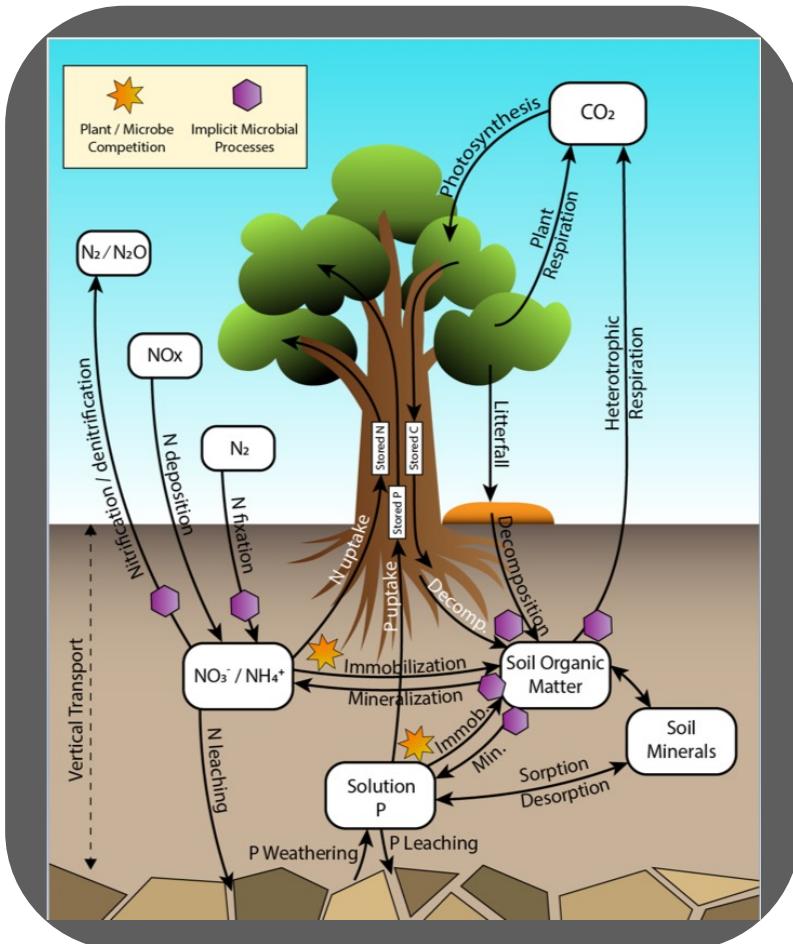


# Motivation and Overview

- Land-surface model parametric uncertainty remains large
- High model expense → Need for **model surrogates** for sample-intensive studies,  
such as ...
  - Global sensitivity analysis (forward UQ)
  - Model calibration (inverse UQ)
- Major **challenges**
  - Expensive model evaluation, small ensembles
  - High dimensional (spatio-temporal) outputs
- Reduced-dimensional, inexpensive surrogate construction via Karhunen-Loève expansions and Neural Networks (KLNN)
- Surrogate enables global sensitivity analysis and Bayesian model calibration



# E3SM Land Model (ELM): focus on carbon and energy cycle

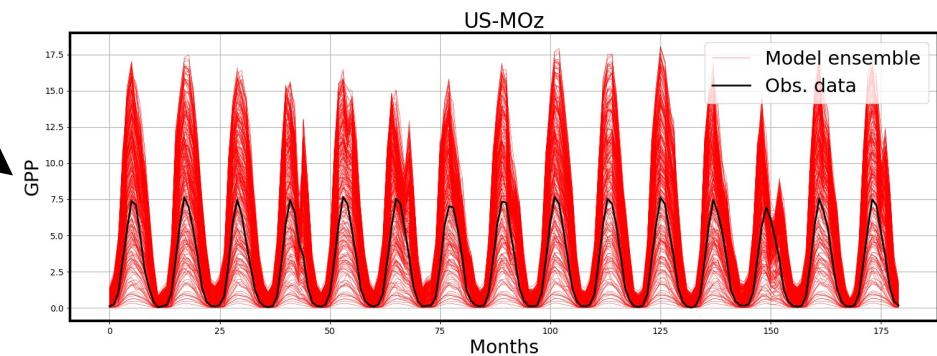
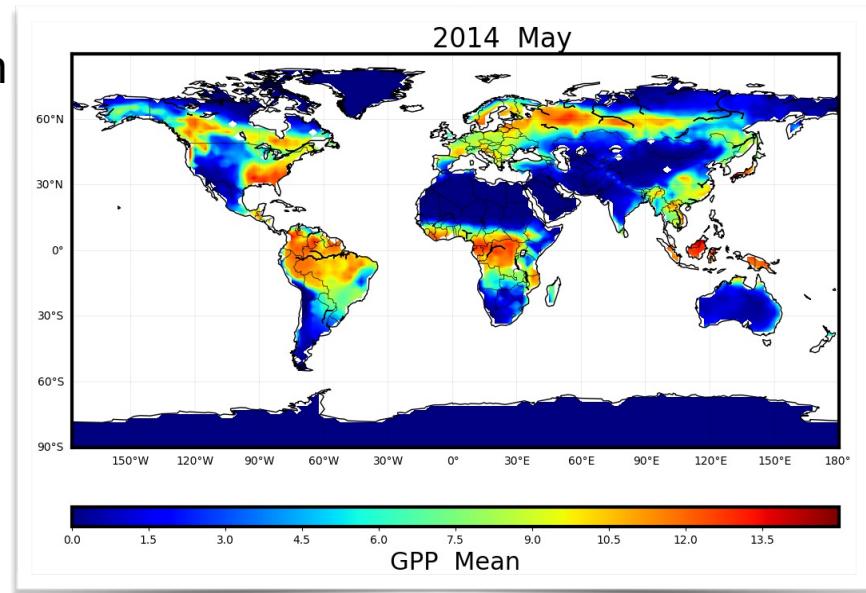


Satellite Phenology version  
used for this study  
(close to CLM4.5)

Quantity of Interest:  
Gross primary productivity  
(GPP)...

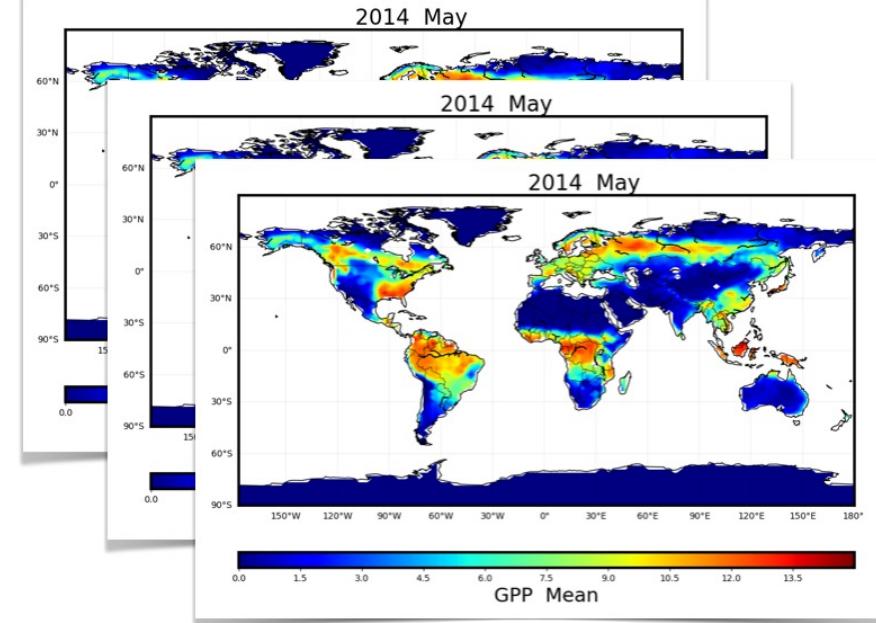
... resolved in space, ...

... and in time.



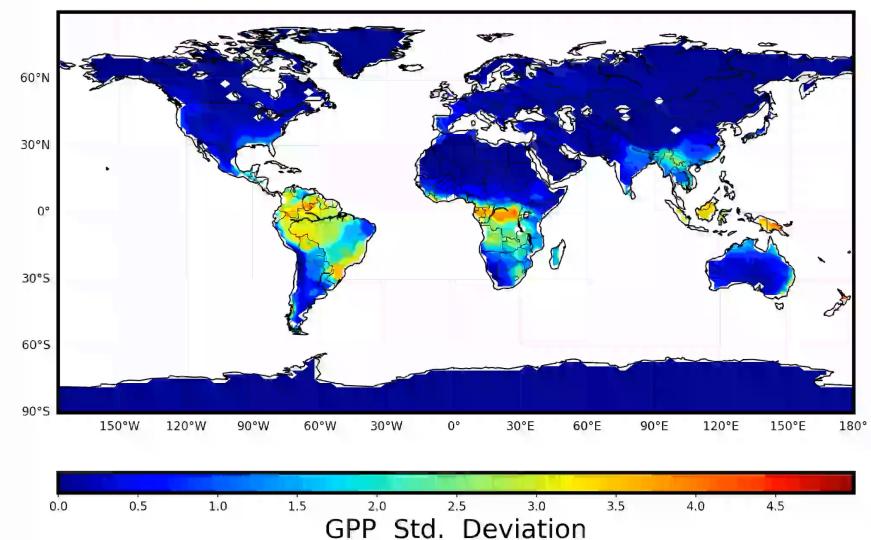
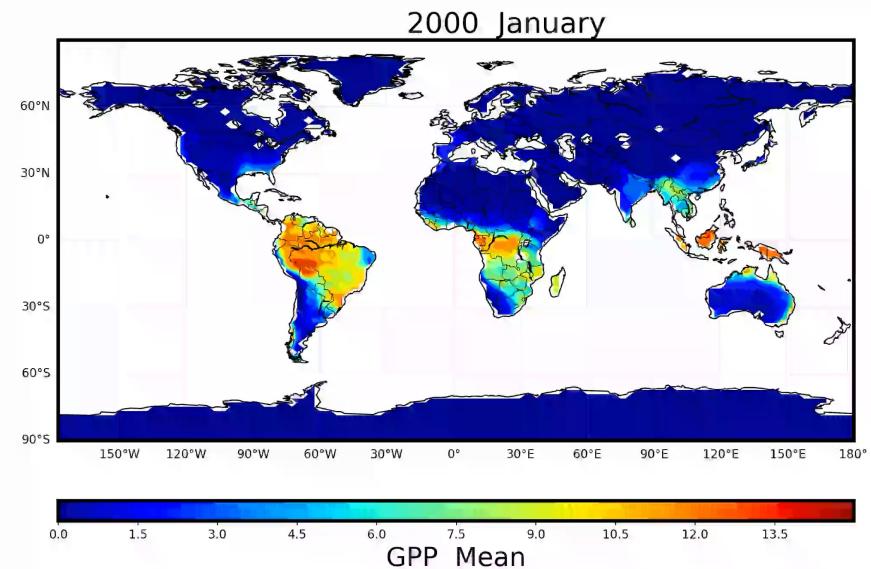
## Model Ensemble (275 samples)

1.9x2.5 resolution, satellite phenology



## Perturbed Parameters

Parameter	Description	Min	Max
flnr	Fraction of leaf in RuBisCO	0	0.25
mbbopt	Stomatal slope (Ball-Berry)	2	13
bbbopt	Stomatal intercept (Ball-Berry)	1000	40000
roota_par	Rooting depth distribution	1	10
vcmaxha	Activation energy for Vcmax	50000	90000
vcmaxse	Entropy for Vcmax	640	700
jmaxha	Activation energy for jmax	50000	90000
dayl_scaling	Day length factor	0	2.5
dleaf	Characteristic leaf dimension	0.01	0.1
xl	Leaf/stem orientation index	-0.6	0.8





# Forward UQ

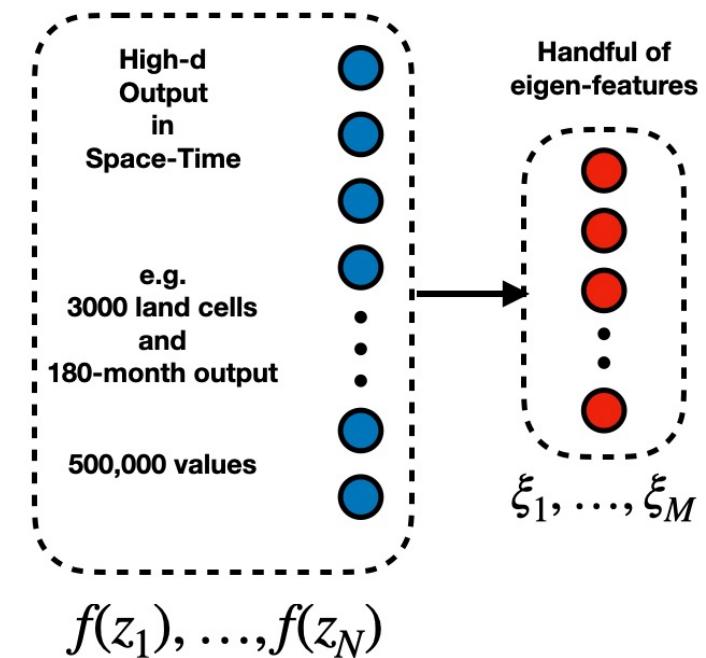
a.k.a. surrogate construction, global sensitivity analysis,  
uncertainty propagation

# Dimensionality Reduction via Karhunen-Loève Expansion

$$f(\lambda; z) \approx \bar{f}(z) + \sum_{m=1}^M \xi_m(\lambda) \sqrt{\mu_m} \phi_m(z)$$

Uncertain parameters      "Certain" conditions

- Spatio-temporal model output  $f(\lambda; z)$ , where  $z = (x, y, t)$
- Output field has large dimensionally  $N = N_x \times N_y \times N_t$
- Eigenpairs  $(\mu_m, \phi_m(z))$  are found via eigen-solve
- Analysis reduces to  $M \ll N$  eigenfeatures  $\xi_1, \dots, \xi_M$
- Under the hood: this is essentially an SVD



# KL is essentially a Singular Value Decomposition

KL

$$f(\lambda^k; zi) - \bar{f}(zi) \approx \sum_{m=1}^M \xi_m(\lambda^k) \sqrt{\mu_m} \phi_m(zi)$$

$$F_{ki} = \sum_{m=1}^M U_{km} \Sigma_{mm} V_{im}$$

SVD

$$F = U \Sigma V^T$$

Karhunen-Loëve expansion

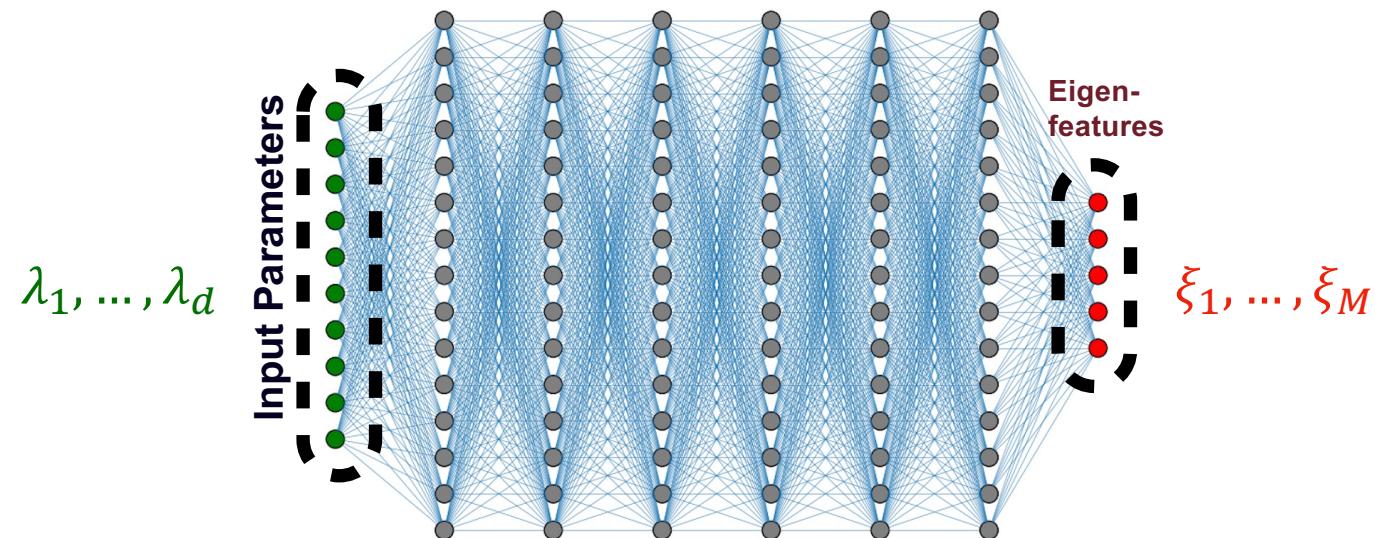
- is centralized (first subtract the mean)
- often comes with the continuous form
- has random variable interpretation for the latent features (aka left singular vectors)  $\xi_m$



# KL+NN = reduced dimensional spatio-temporal surrogate

The goal is to construct a surrogate with respect to uncertain parameters  $\lambda$ , such that  
 $f(\lambda; z_i) \approx f_s(\lambda; z_i)$  for all conditions  $z_i$ .

Instead of building surrogate for each individual  $z_i$  for  $i = 1, \dots, N$ ,  
we construct neural network (NN) surrogate for  $\xi_1, \dots, \xi_M$  where  $M \ll N$ .



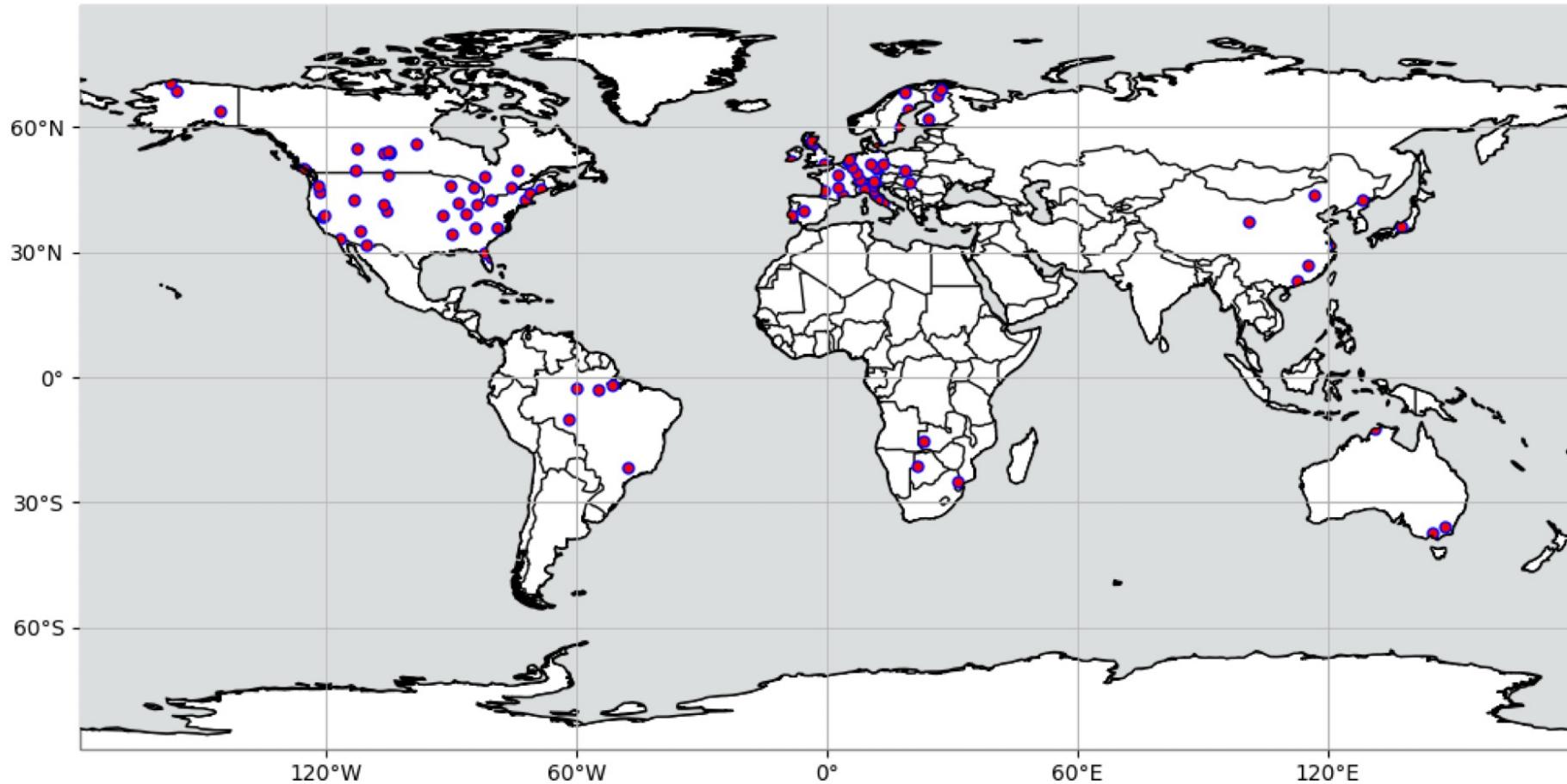
$$f(\lambda; z) \approx \bar{f}(z) + \sum_{m=1}^M \xi_m(\lambda) \sqrt{\mu_m} \phi_m(z)$$

$\uparrow$

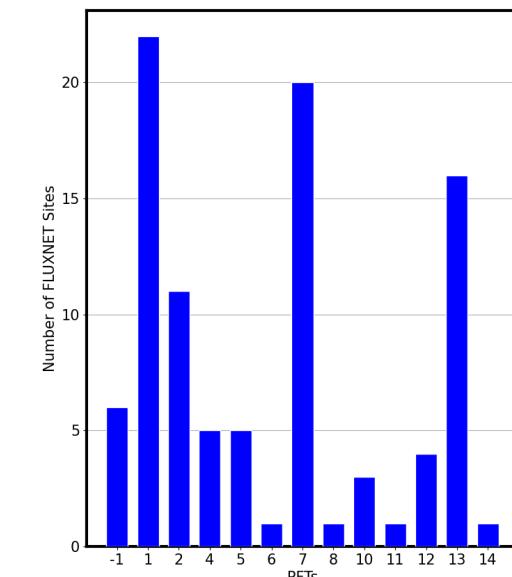
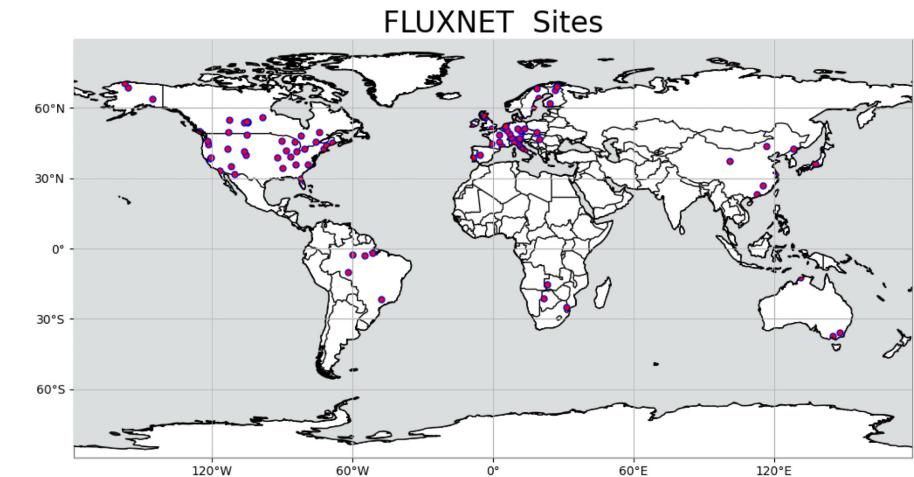
$\xi_m^{NN}(\lambda)$



## Methodological evaluation at 96 FLUXNET sites



ID	PFT Name	Count
1	Boreal evergreen needleleaf tree	22
2	Temperate evergreen needleleaf tree	11
3	Boreal deciduous needleleaf tree	0
4	Tropical evergreen broadleaf tree	5
5	Temperate evergreen broadleaf tree	5
6	Tropical deciduous broadleaf tree	1
7	Temperate deciduous broadleaf tree	20
8	Boreal deciduous broadleaf tree	1
9	Broadleaf evergreen shrub	0
10	Temperate deciduous broadleaf shrub	3
11	Boreal deciduous broadleaf shrub	1
12	C3 arctic grass	4
13	C3 non-arctic grass	16
14	C4 grass	1
-1	Mixed	6



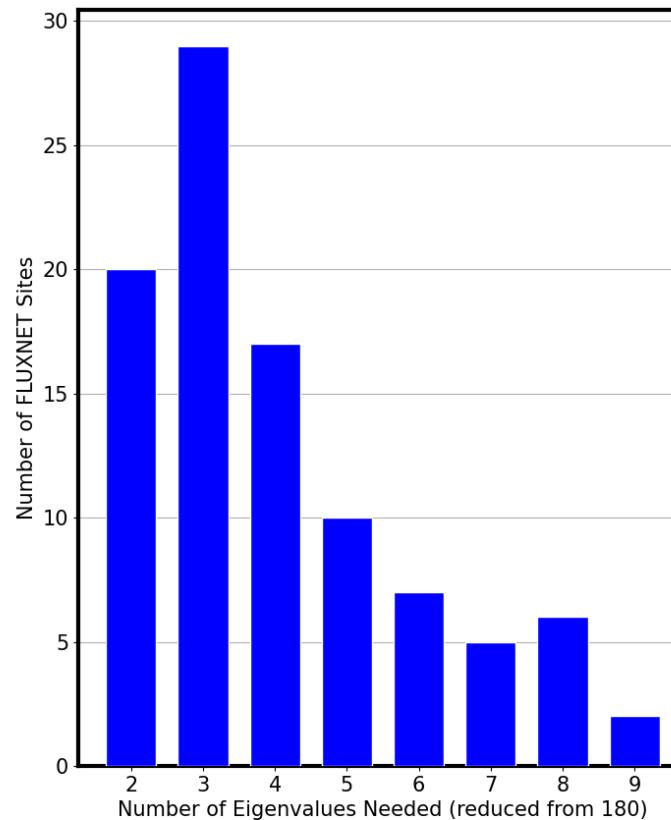


# Several case studies

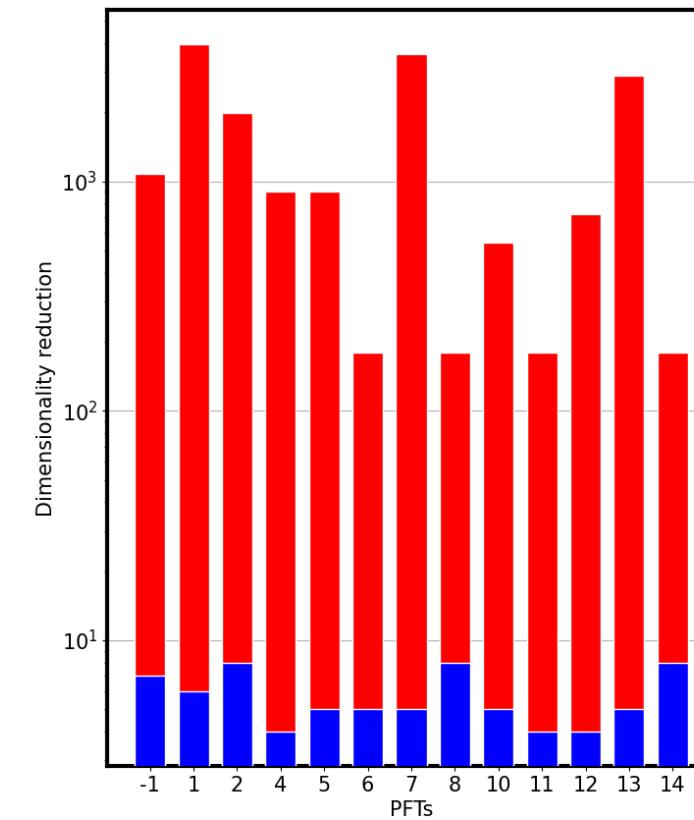
Space \ Time	$N_t = 180$ Months (full 15 years)	$N_t = 12$ Months (average out interannual)	$N_t = 4$ Seasons (average out within seasons)	$N_t = 1$ (global time-average)
FLUXNET sites $N_x = 96$ (or group by PFTs)	F180	F12	F4	F1
Global 144x96 $N_x \cong 4000$ <b>vegetated cells</b> (or regional zoom)	G180	G12	G4	G1

# Dimensionality reduction via KL

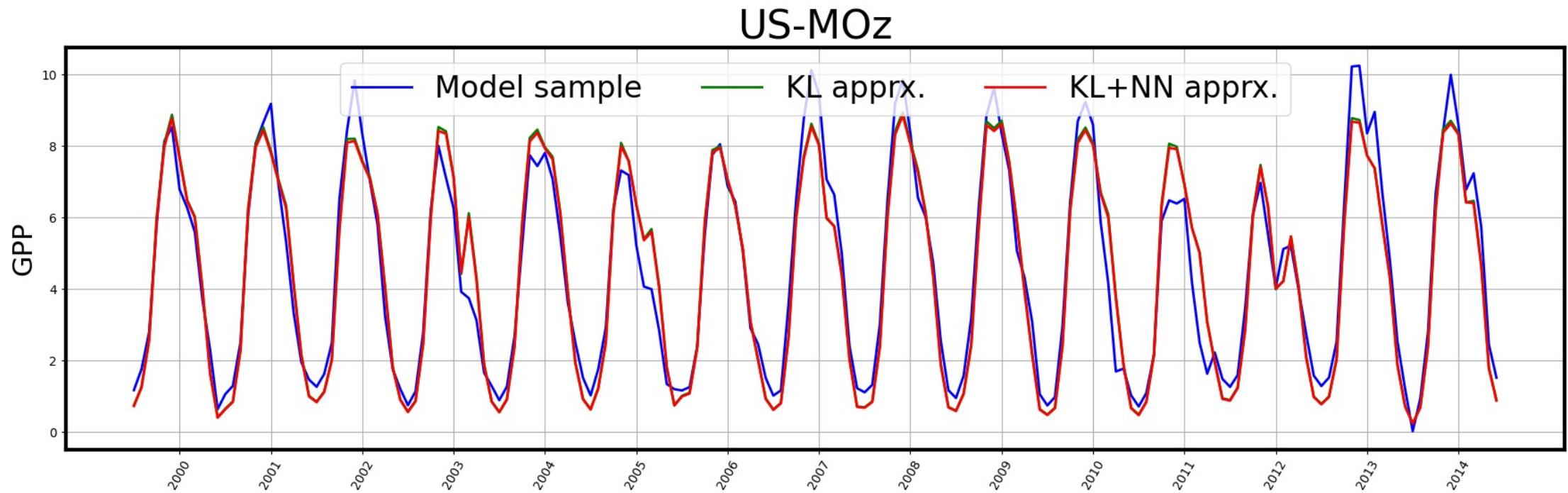
Per-site dimensionality reduction



Per-PFT dimensionality reduction

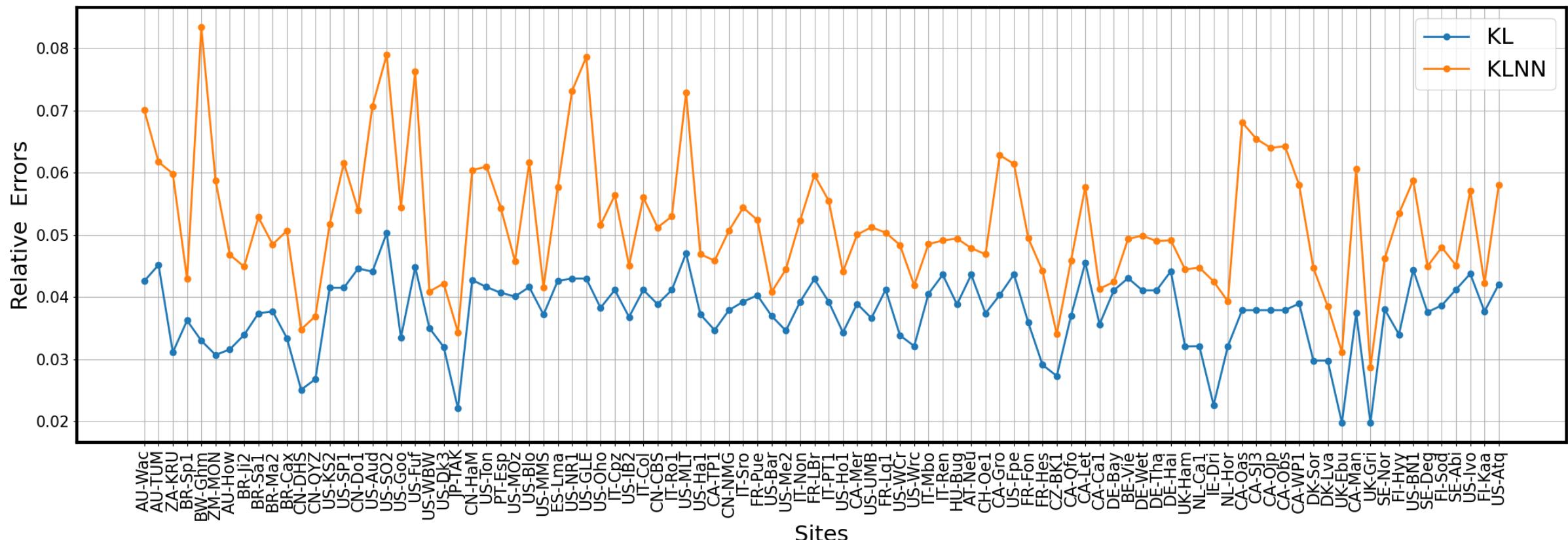


# KL+NN a single training sample approximation

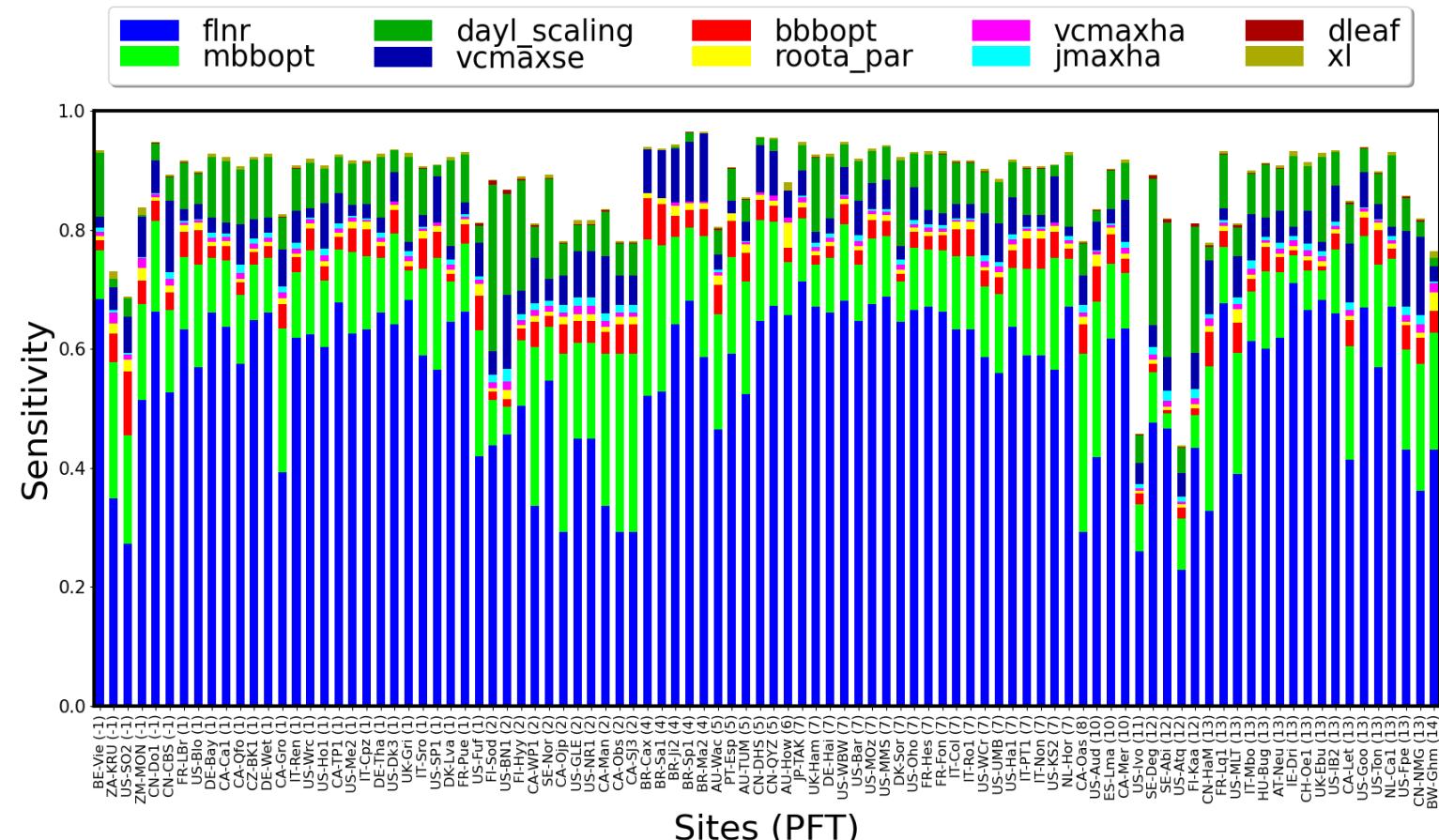


# KL+NN surrogate performance

Instead of  $96 \times 180 = 17280$  surrogates, we build  
a single NN surrogate in the reduced, 8-dimensional latent space

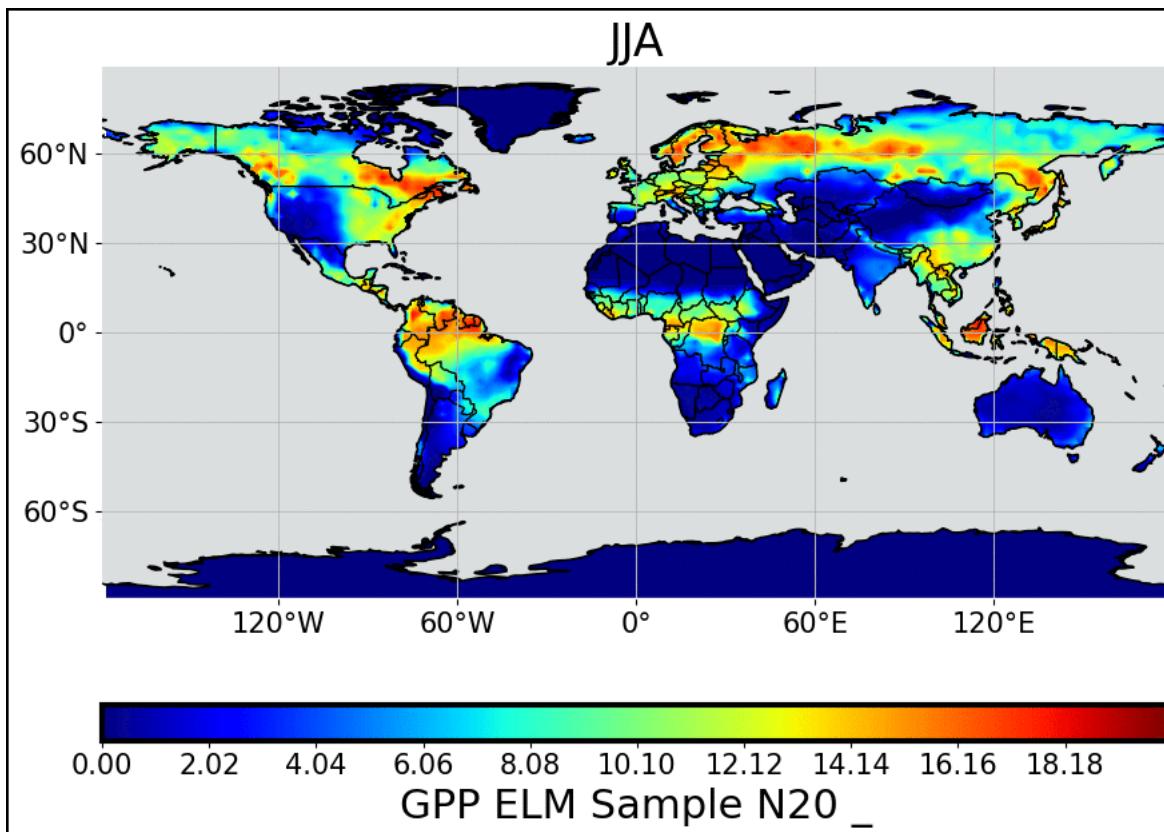


# Sensitivity at 96 FLUXNET sites: RuBisCO leaf fraction is the most impactful parameter

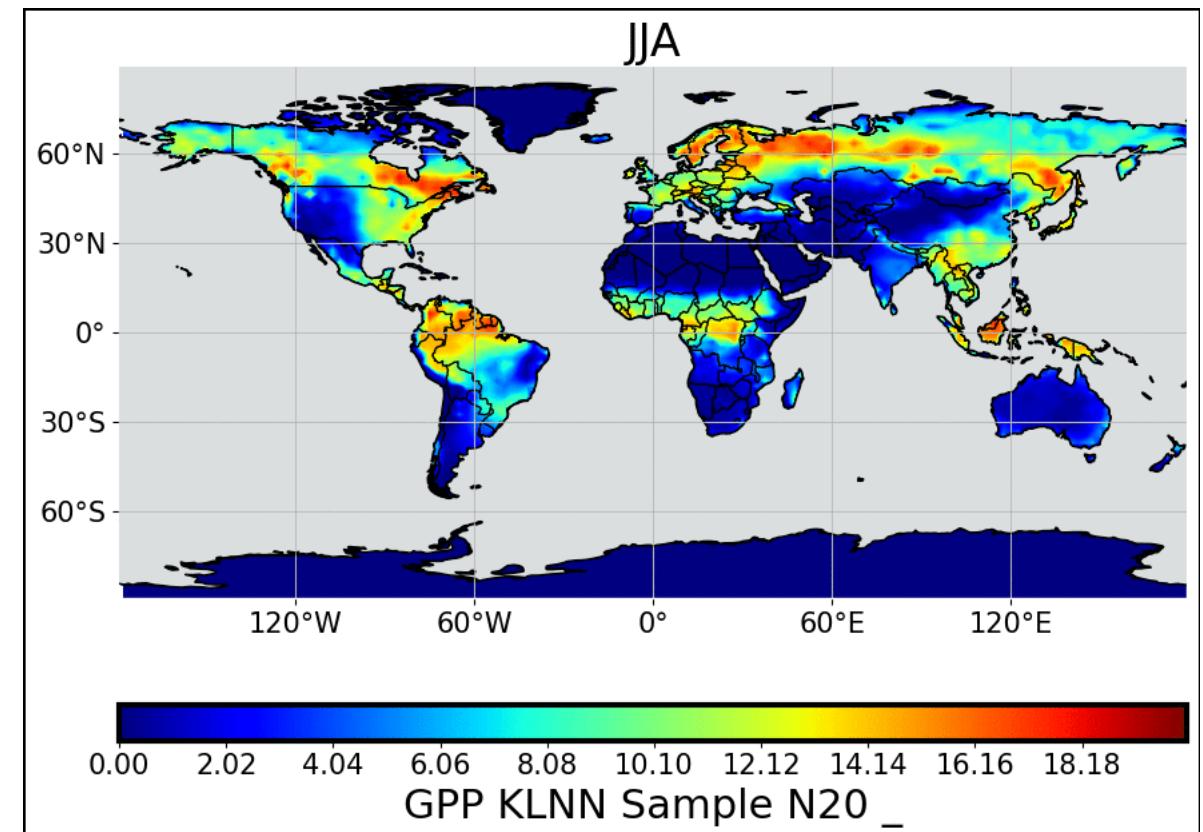


Dimensionality reduction from 4000 cells x 4 seasons = **16000** to **11-dimensional latent space**

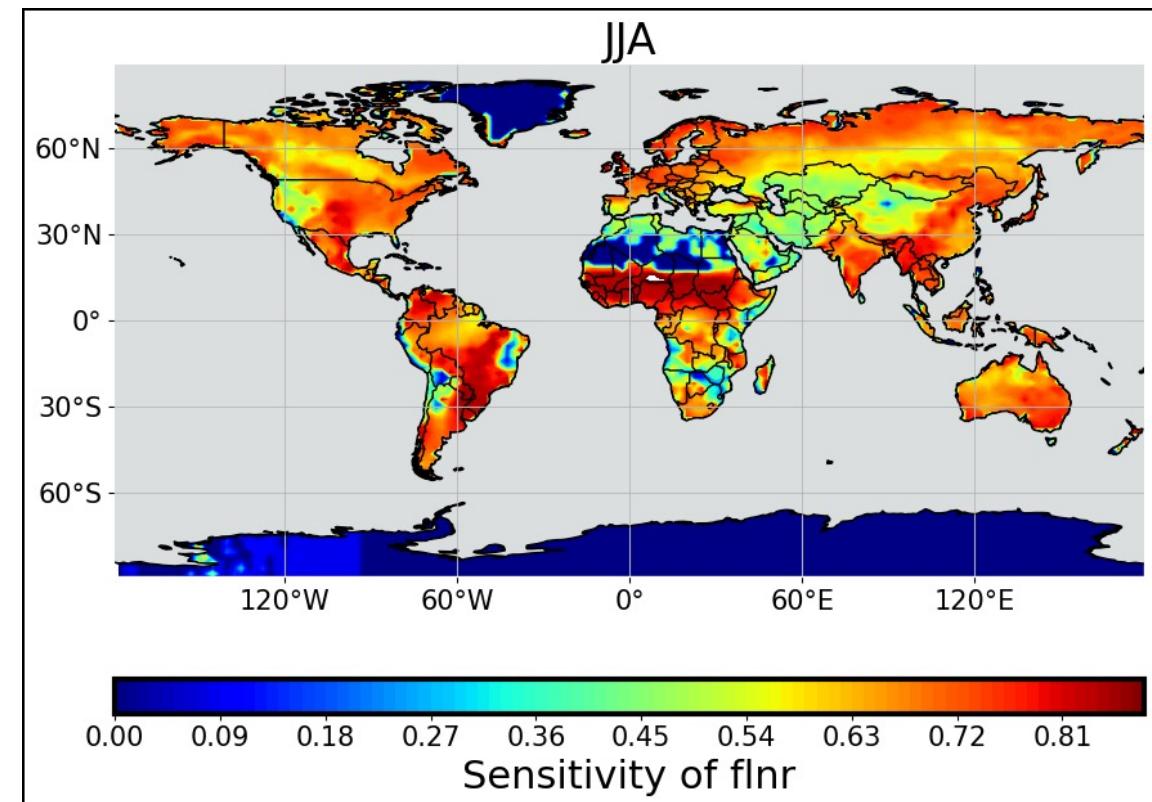
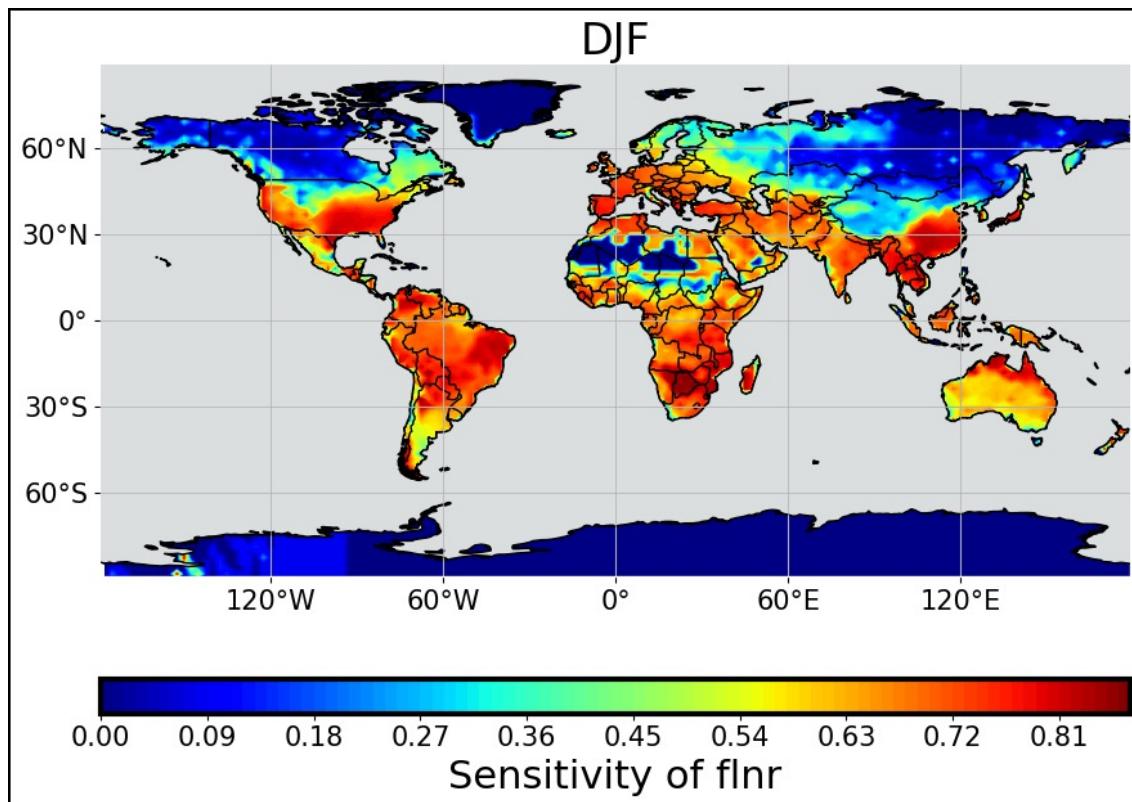
## ELM Model Samples



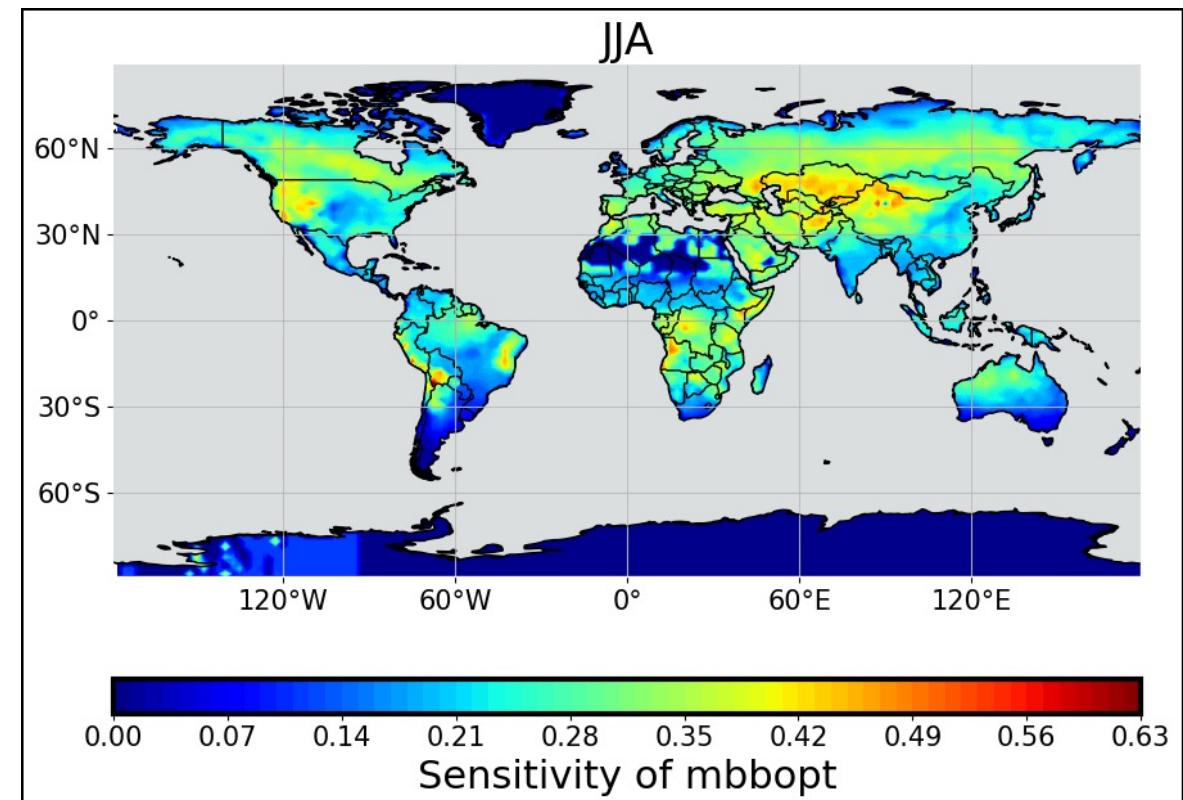
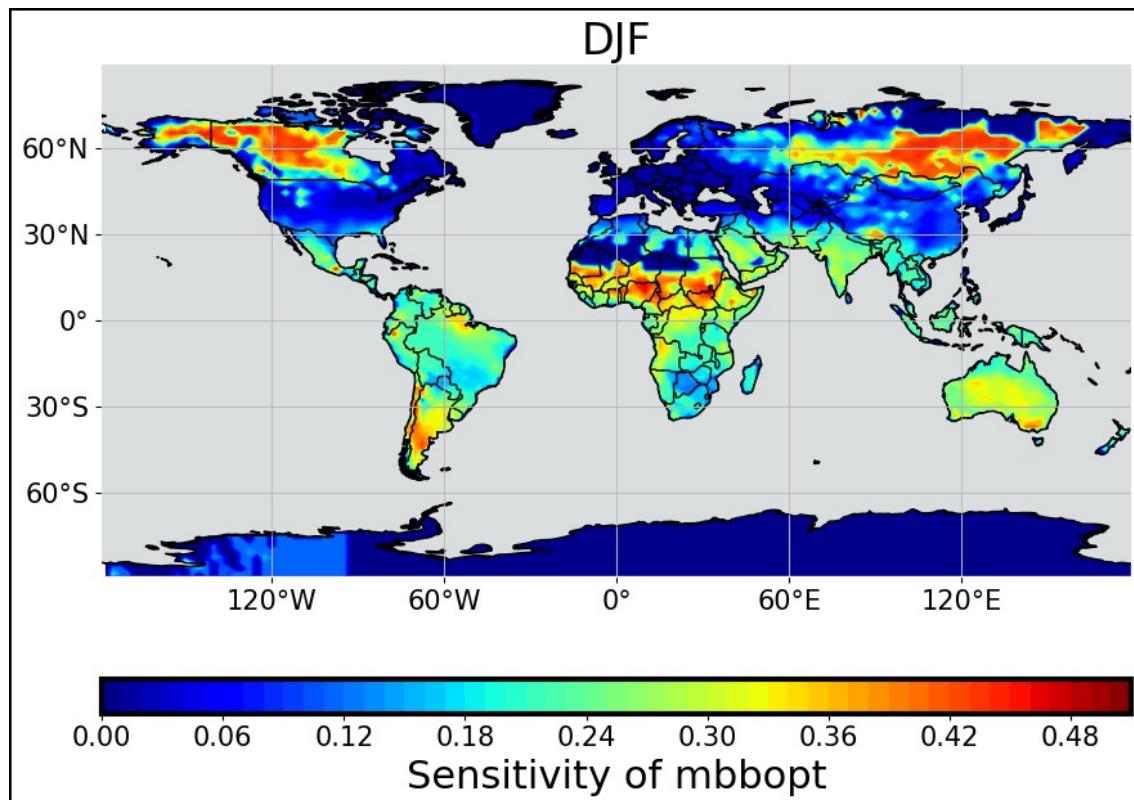
## KLNN Surrogate Samples



# fLNR sensitivity across the globe



# mbbopt sensitivity across the globe





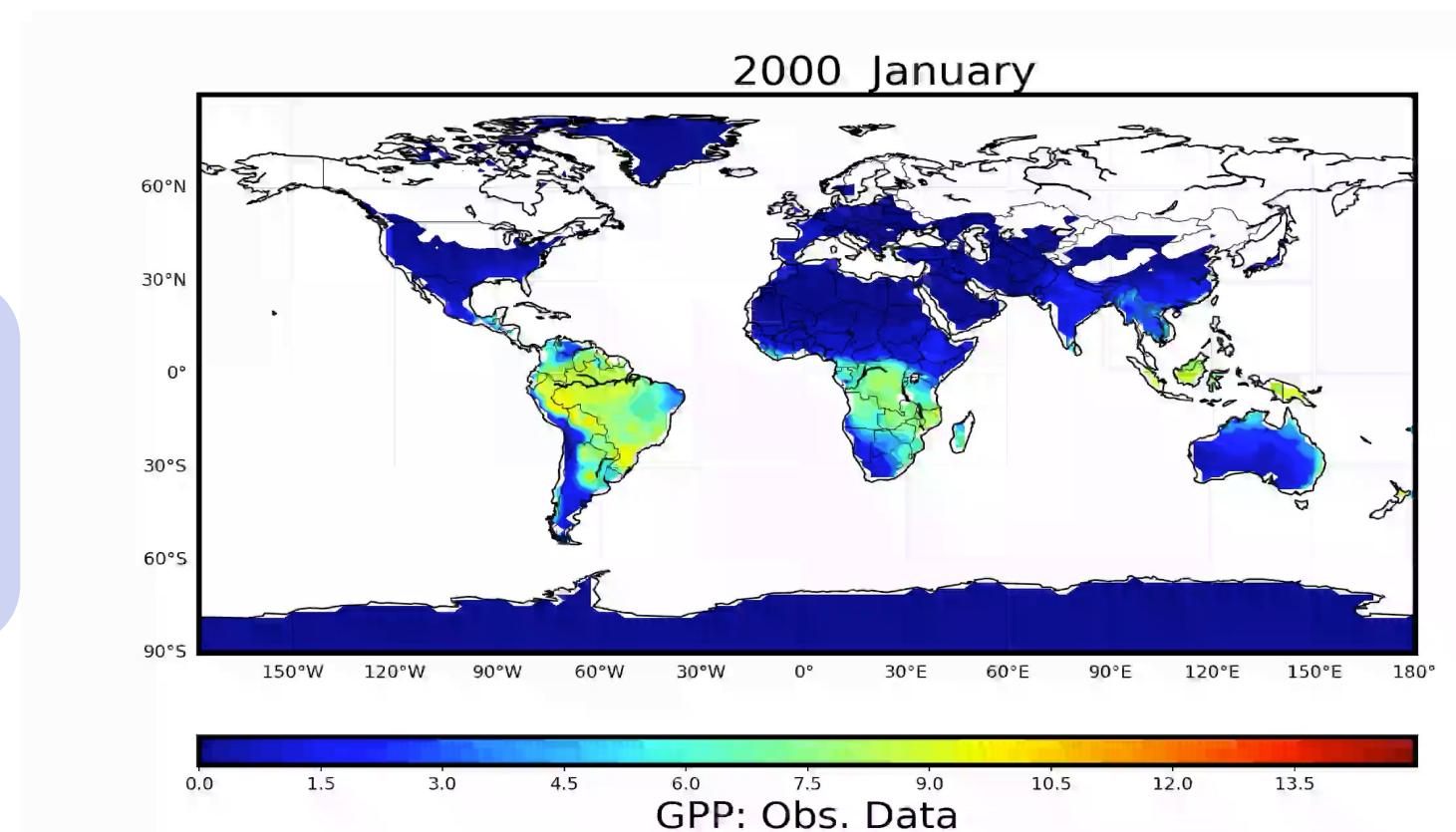
# Inverse UQ

a.k.a. calibration or parameter estimation

# Reference Data

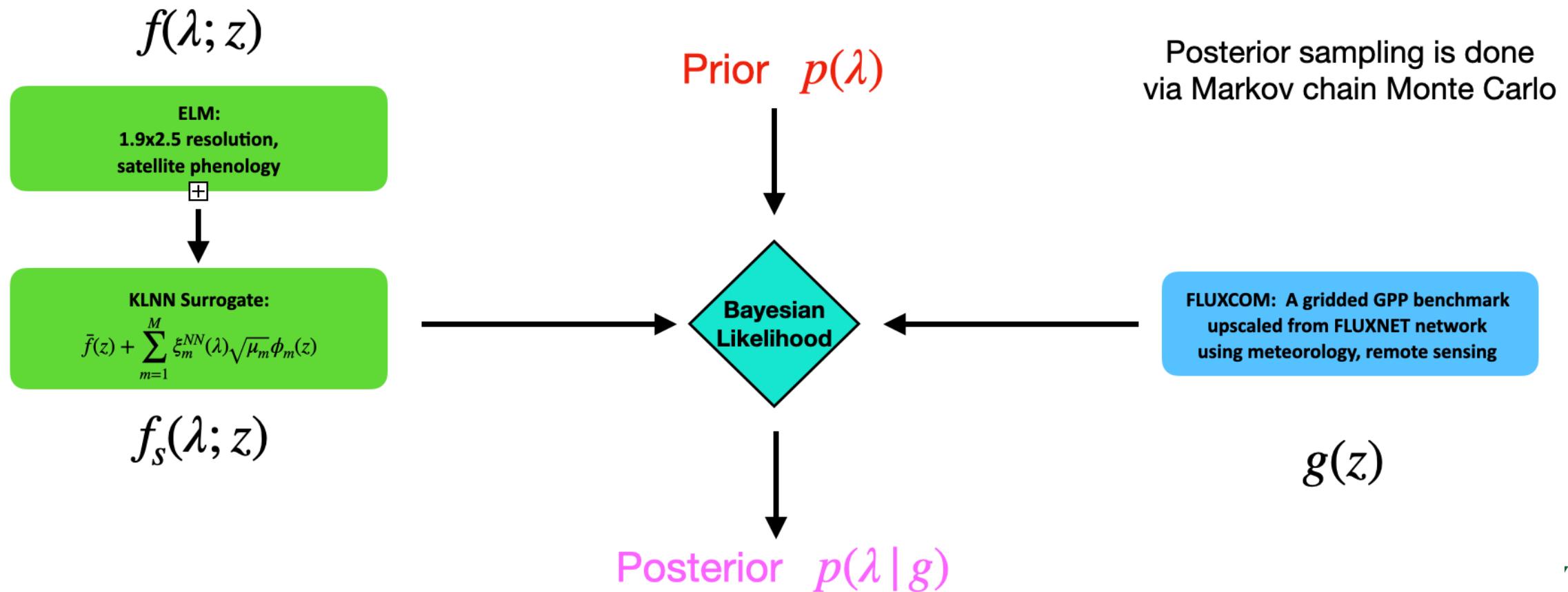
FLUXCOM: A gridded GPP benchmark upscaled from FLUXNET network using meteorology, remote sensing

<https://www.fluxcom.org/>



Bayes' formula

$$p(\lambda | g) \propto p(g | \lambda) p(\lambda)$$



# Bayesian Likelihood is constructed in the reduced space

Bayes' formula

$$p(\lambda|g) \propto p(g|\lambda)p(\lambda)$$

KLNN surrogate:

$$f(\lambda; z) \approx \bar{f}(z) + \sum_{m=1}^M \xi_m^{NN}(\lambda) \sqrt{\mu_m} \phi_m(z)$$

Project observed data to the KL eigenspace:

$$g(z) \approx \bar{f}(z) + \sum_{m=1}^M \eta_m \sqrt{\mu_m} \phi_m(z)$$

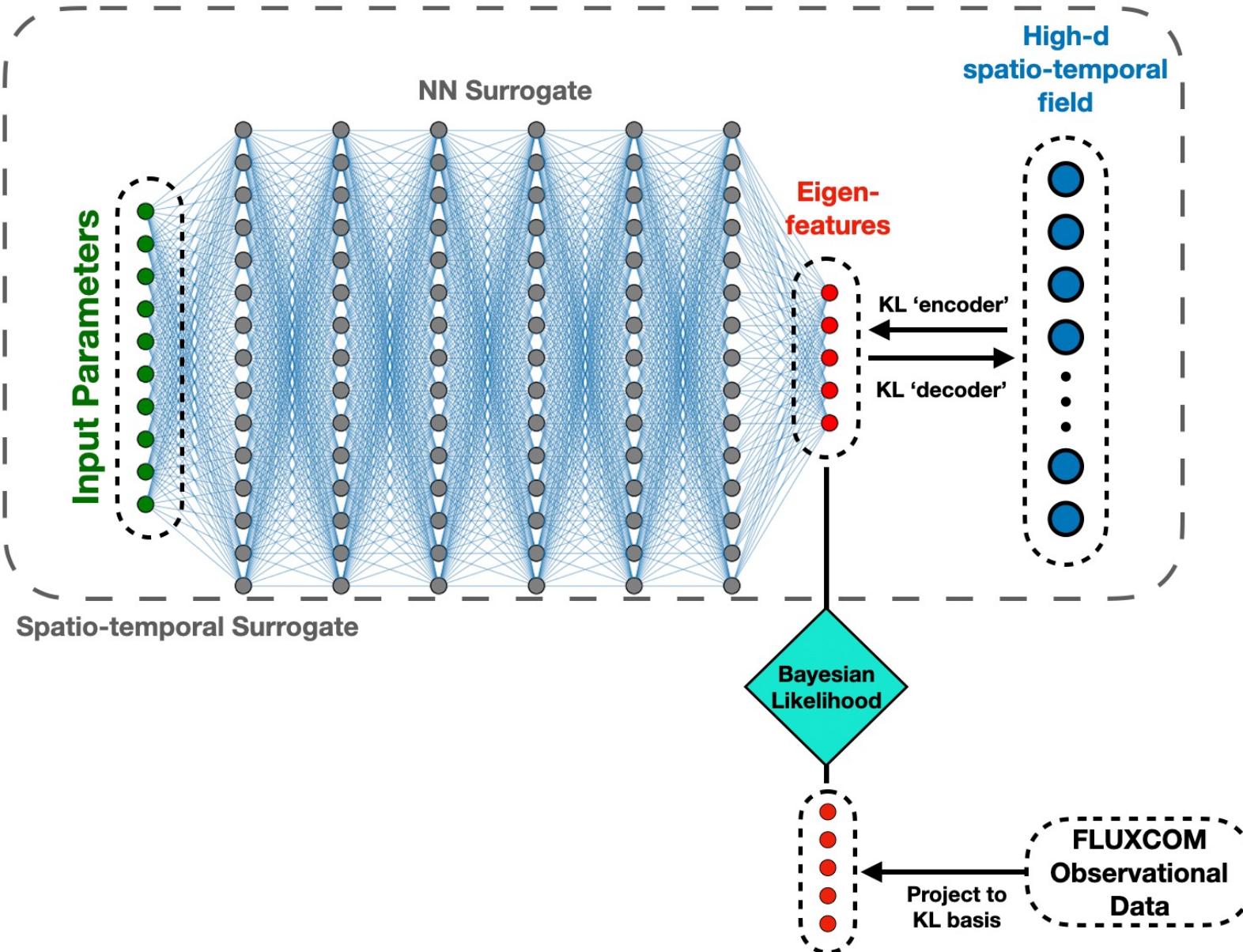
**Pointwise likelihood (naïve) :**

$$L_g(\lambda) \equiv p(g|\lambda) \propto \exp\left(-\sum_{i=1}^N \frac{(g(z_i) - f(\lambda; z_i))^2}{2\sigma_i^2}\right)$$

**Reduced likelihood :**

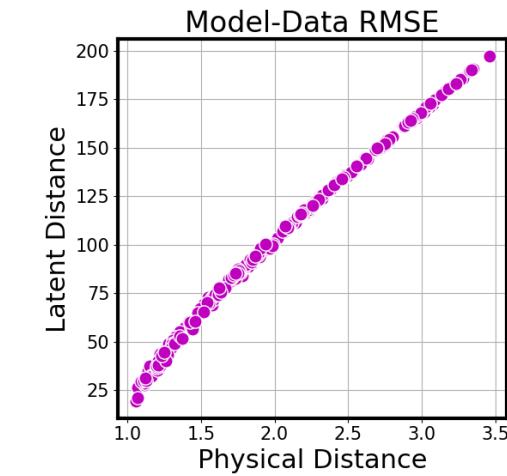
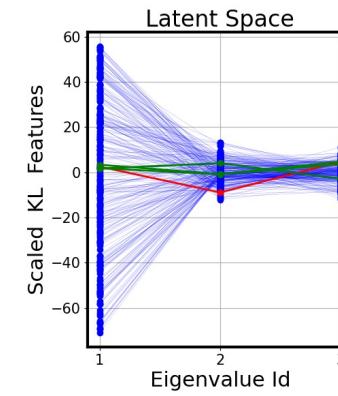
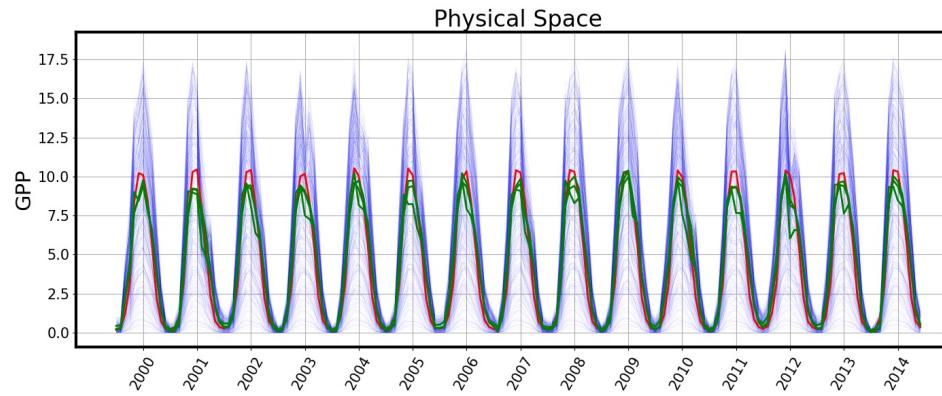
$$L_g(\lambda) \equiv p(g|\lambda) \propto \exp\left(-\sum_{m=1}^M \frac{(\eta_m - \xi_m^{NN}(\lambda))^2}{2\sigma^2}\right)$$

Eigenfeatures  $\xi_m$ 's are uncorrelated, zero-mean, unit variance, hence iid gaussian likelihood is a much better assumption in the reduced space.

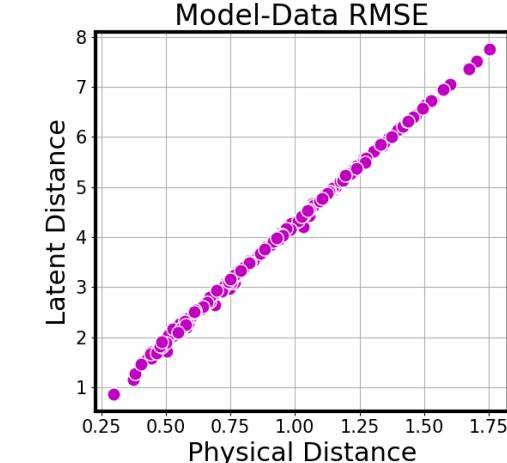
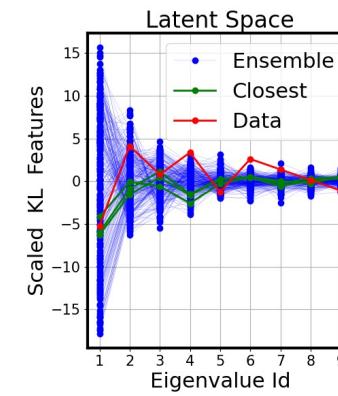
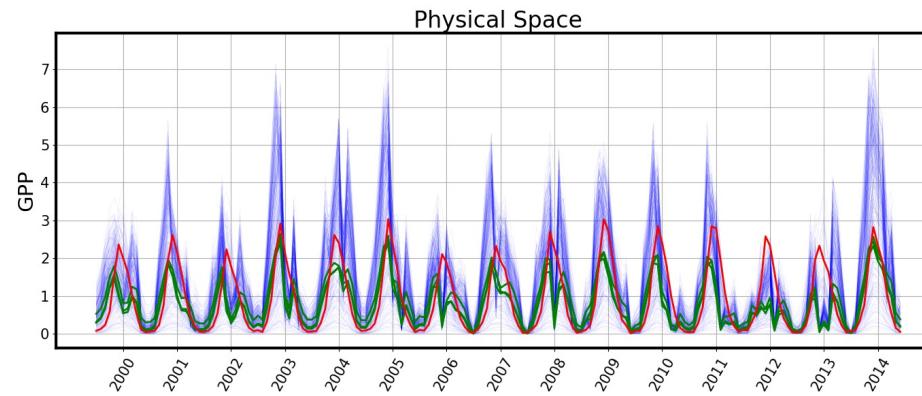


Surrogate-enabled calibration workflow incorporates both forward and inverse UQ tasks

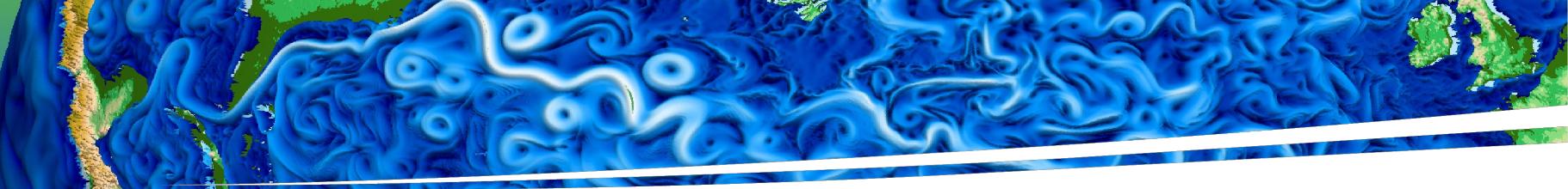
# Latent space distance is well-correlated with the physical distance between model and data



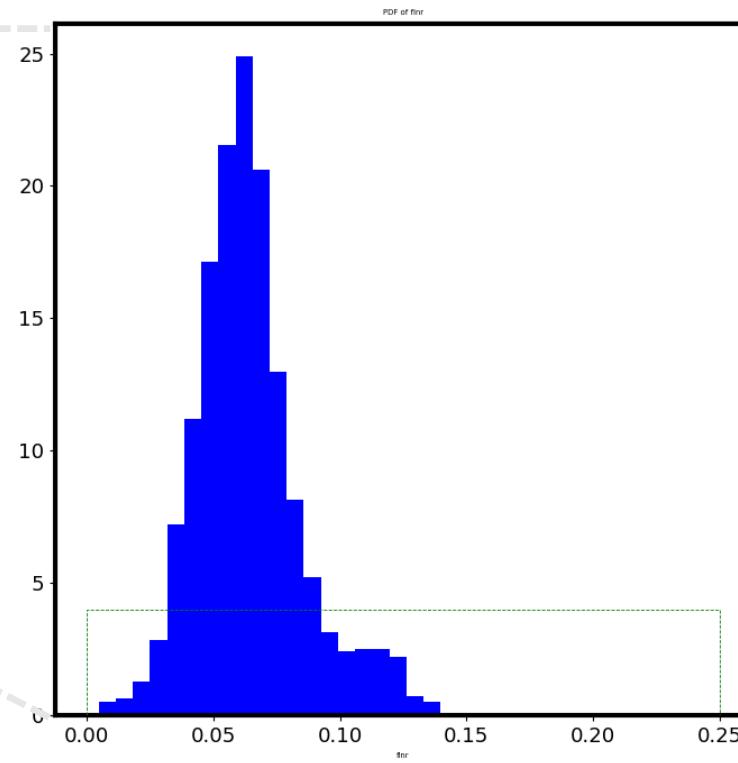
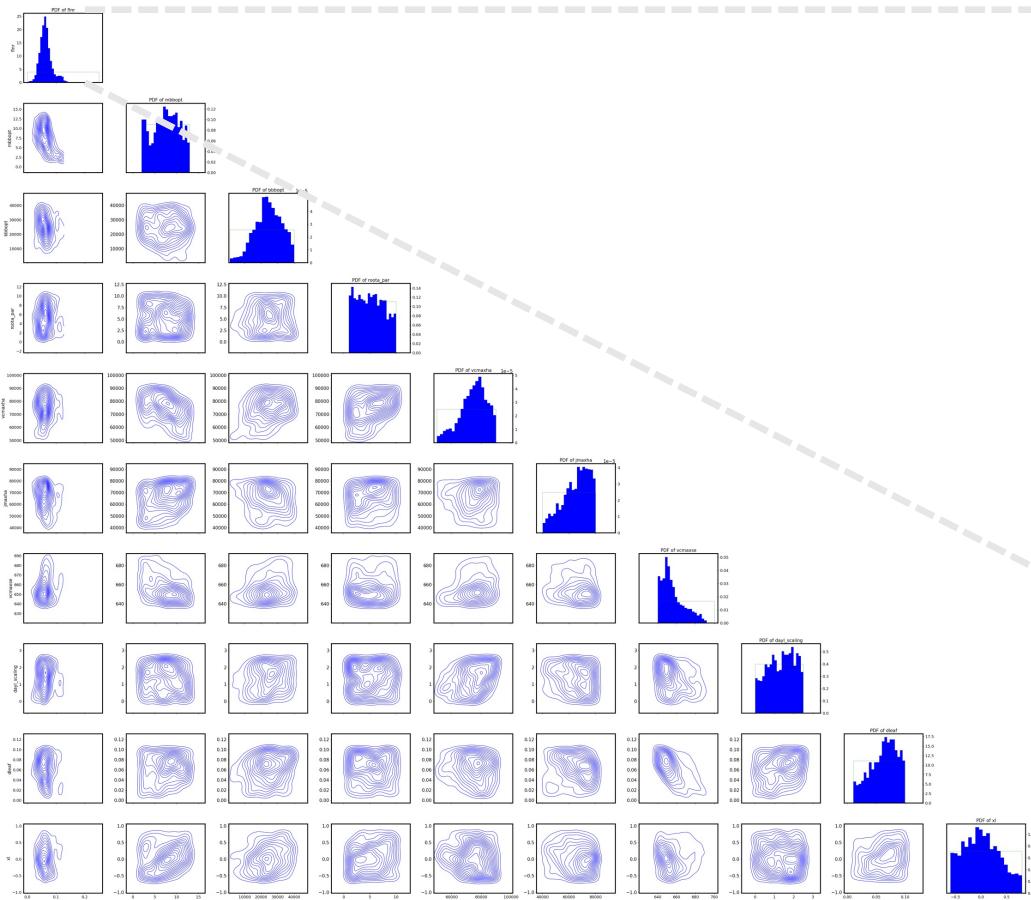
US-Ha1



US-GLE

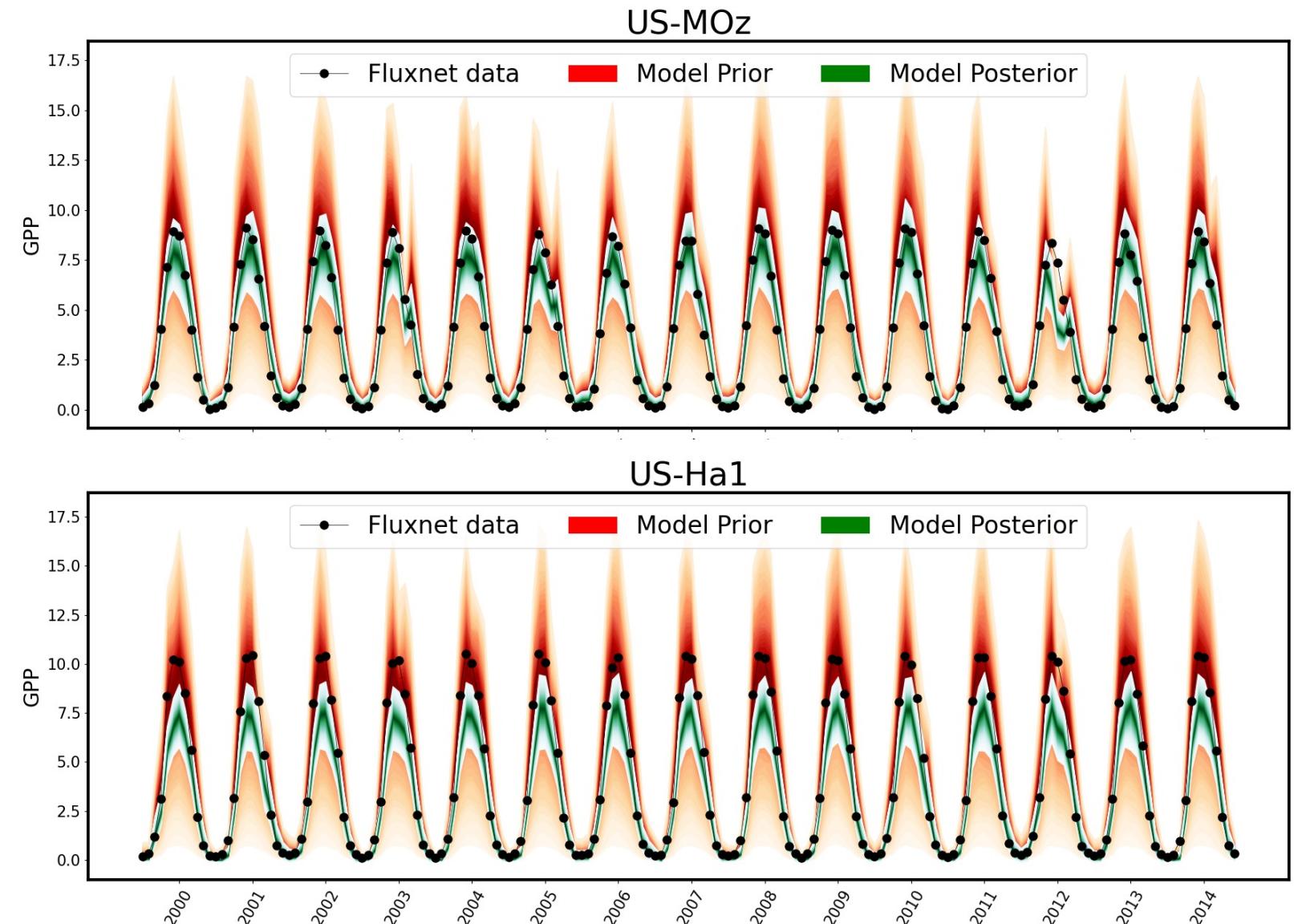


# Bayesian MCMC calibration enabled by KLNN surrogate



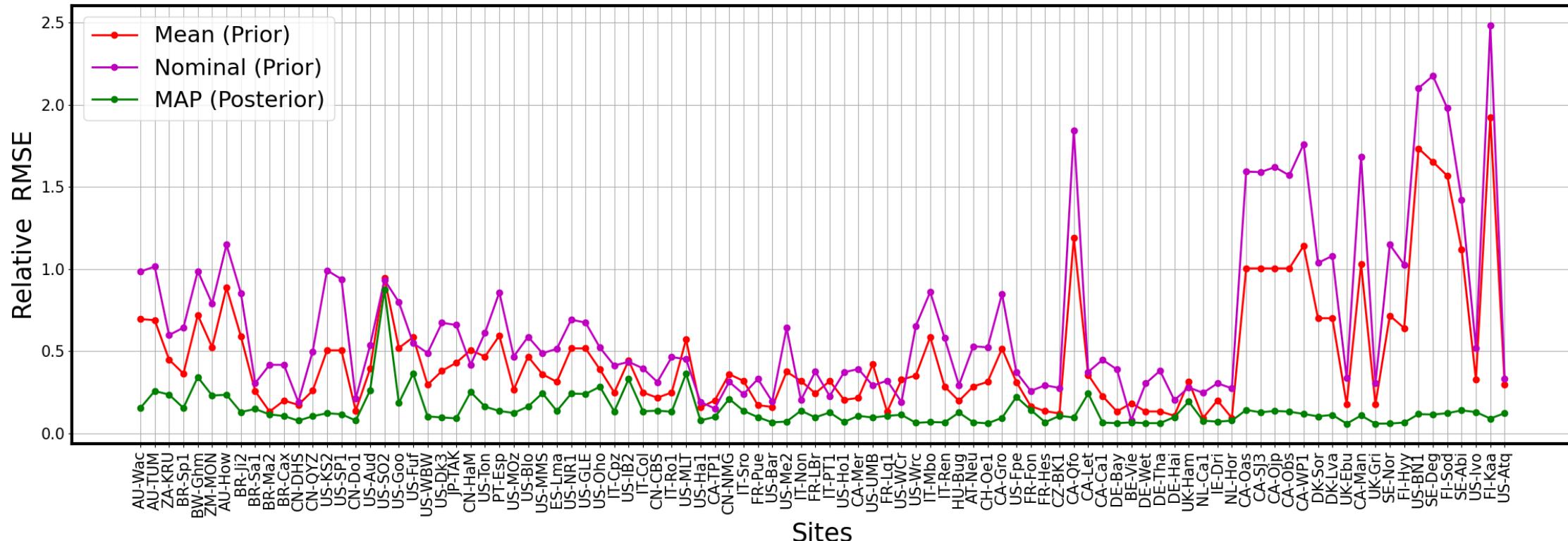
RuBisCO leaf fraction (**fLNR**) is the most constrained parameter

Time evolution  
of GPP at select  
FLUXNET sites



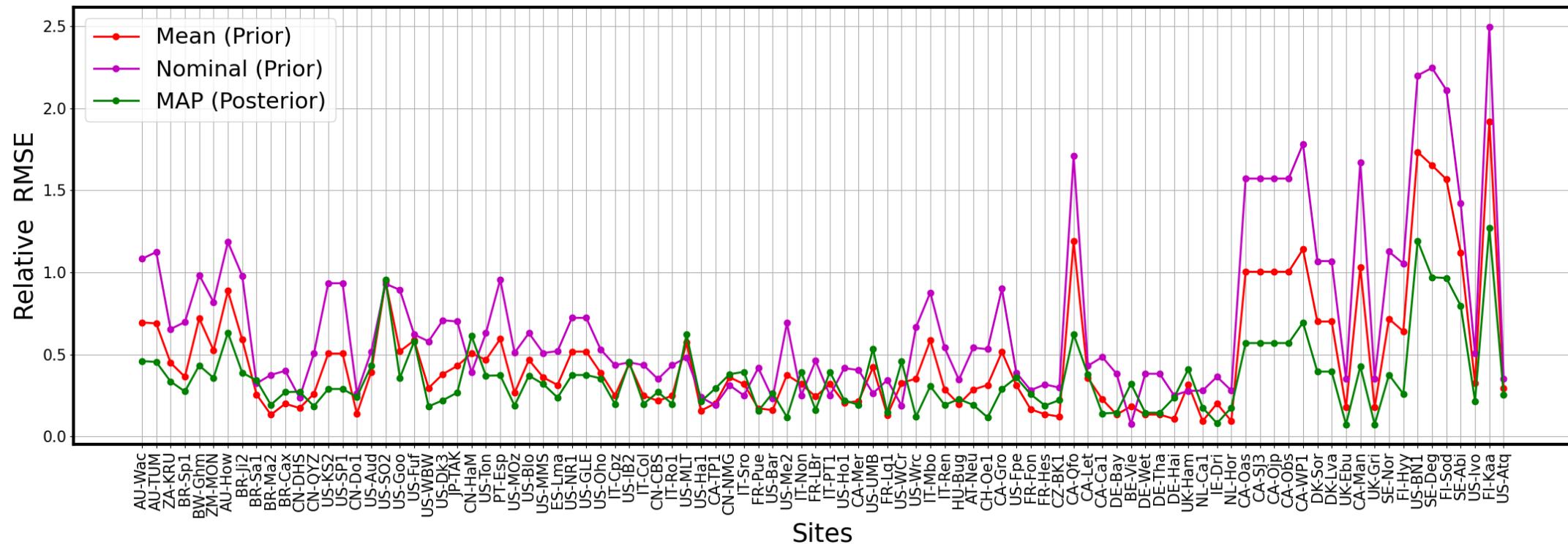
# Calibration brings model prediction closer to reference data

## Site-specific parameters



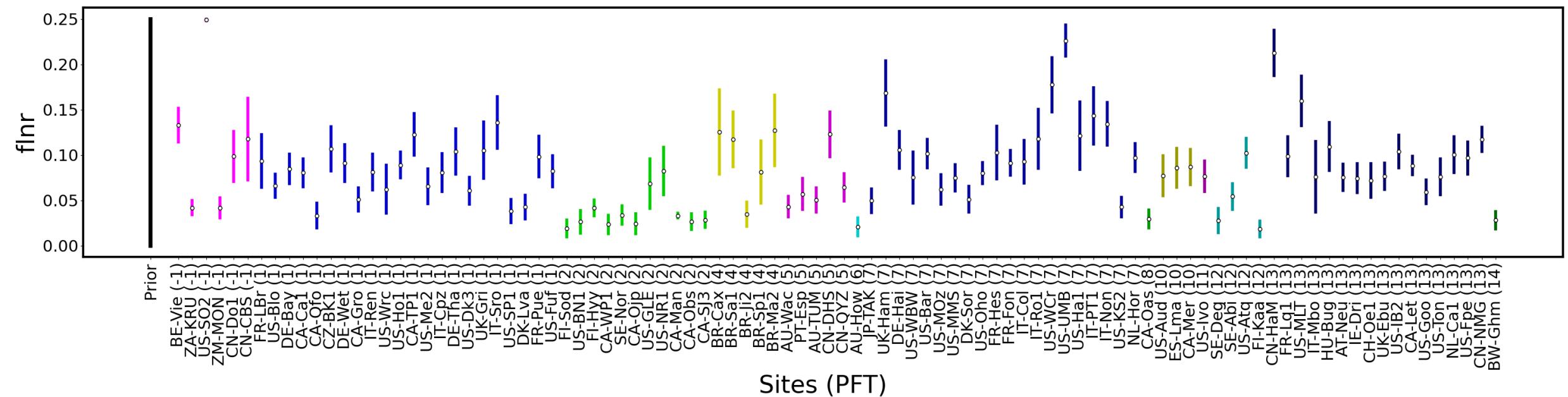
# Calibration brings model prediction closer to reference data

## Common parameters for all sites



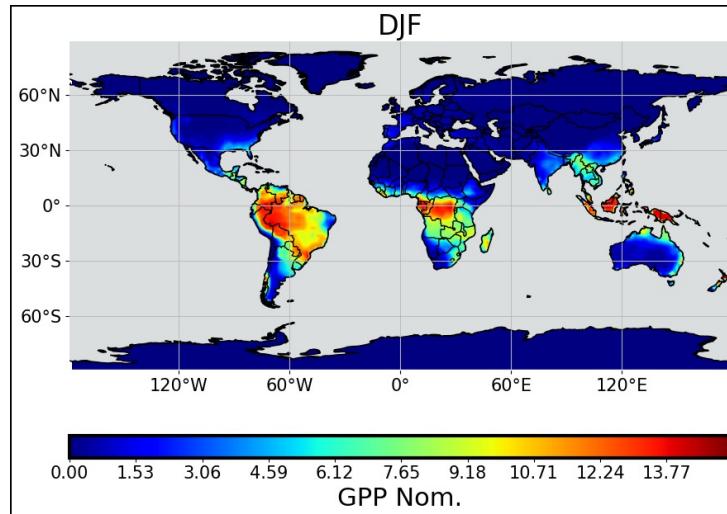
# Local (site-specific) fLNR posterior PDFs

Grouped by PFTs

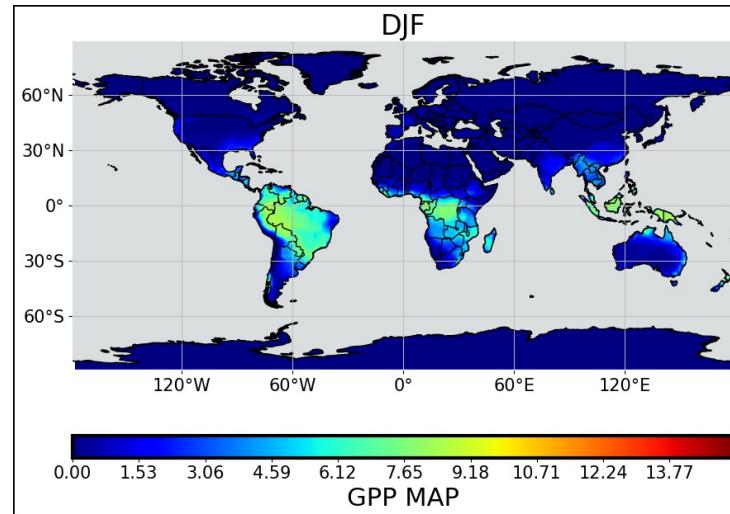




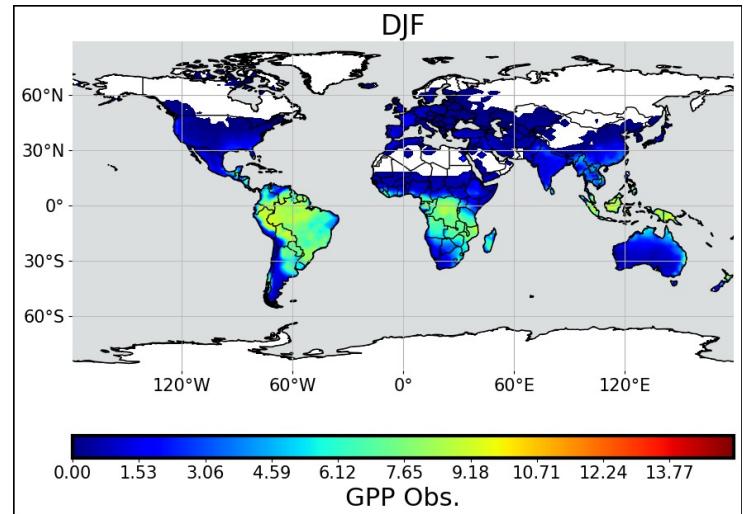
Nominal parameter (prior)



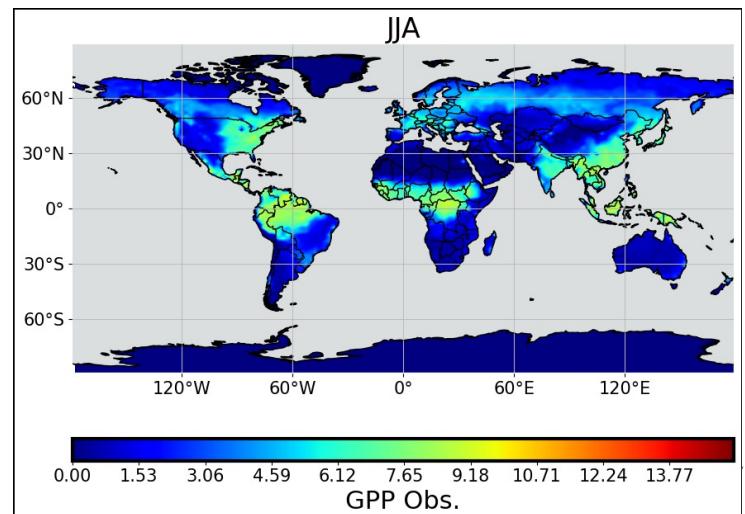
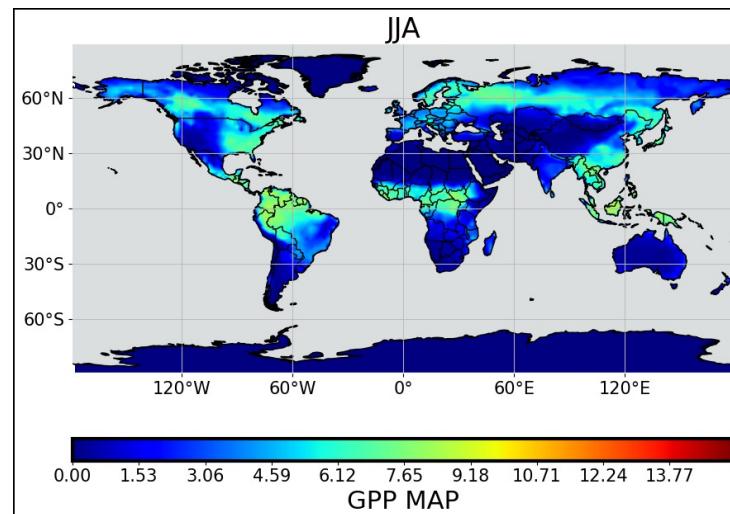
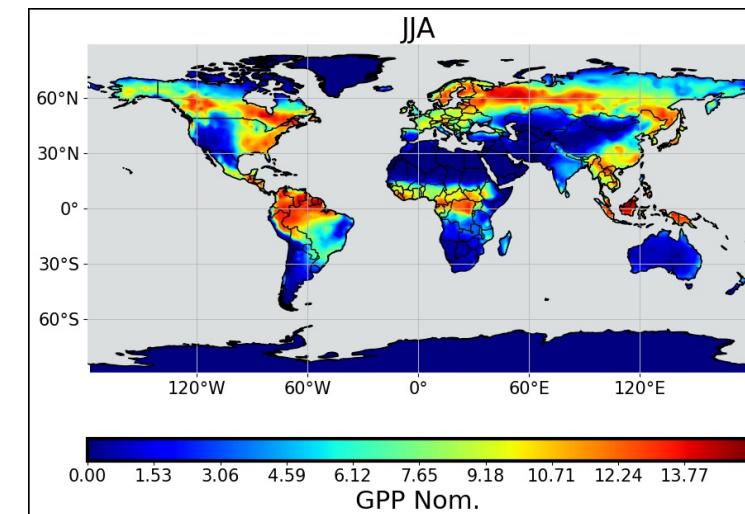
Max a posteriori (MAP)



Reference data



Winter

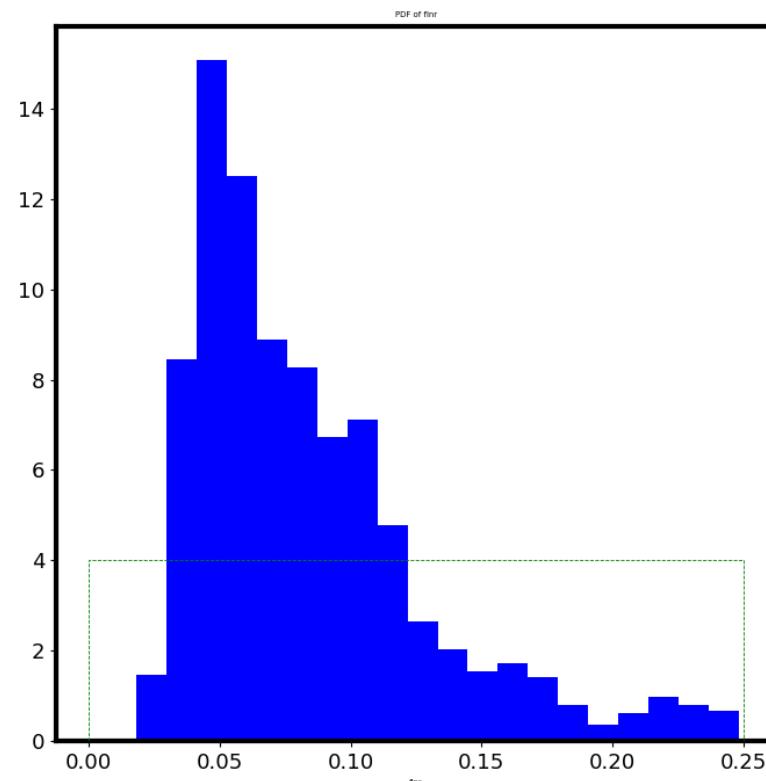


Summer

# Two calibration regimes

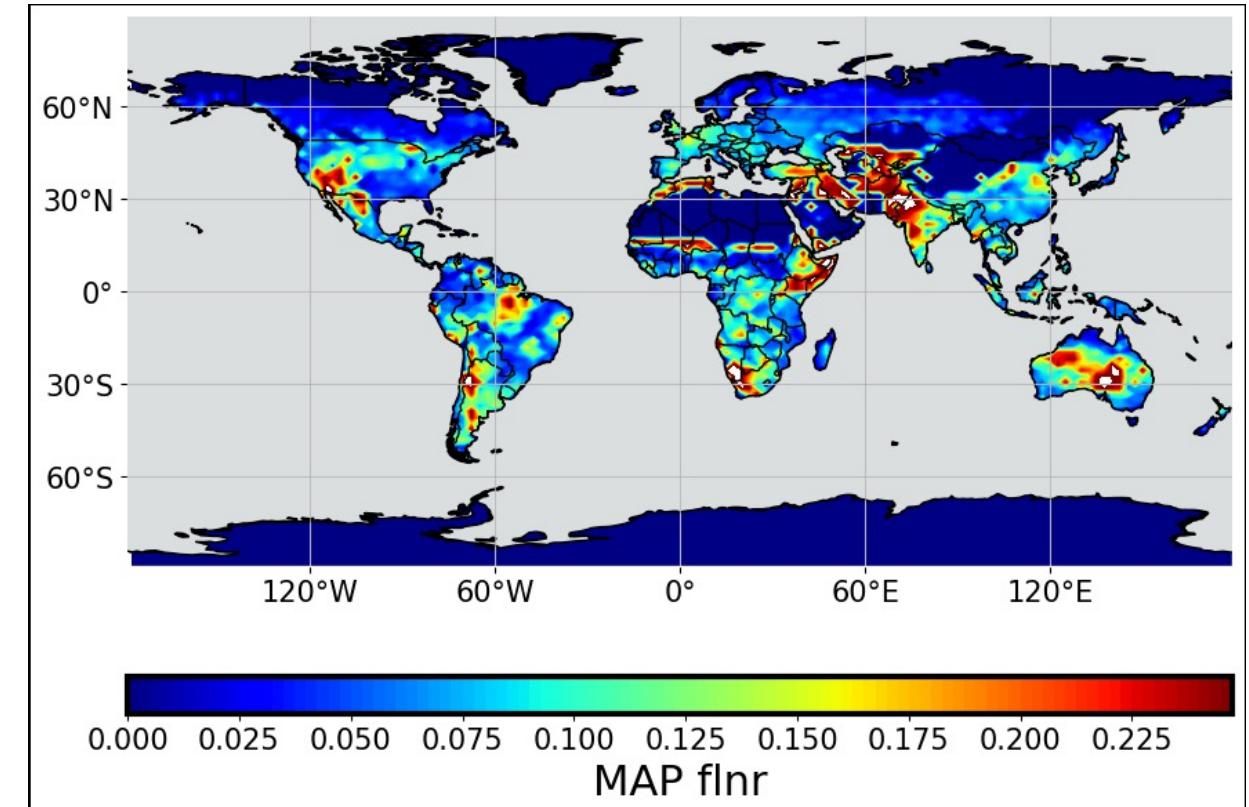
One global surrogate

Fixed global fLNR parameter

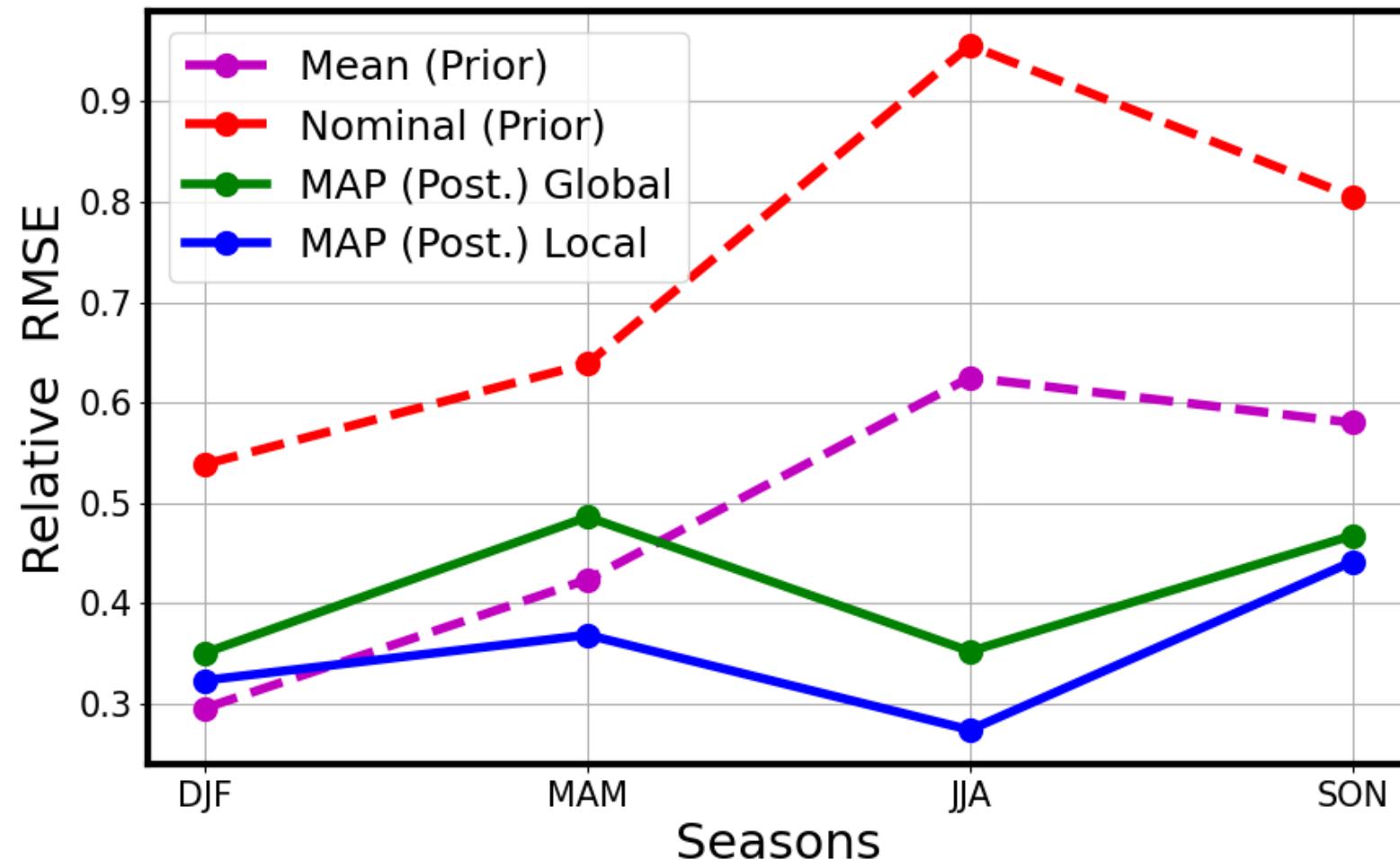


One surrogate per grid cell

Local fLNR parameter

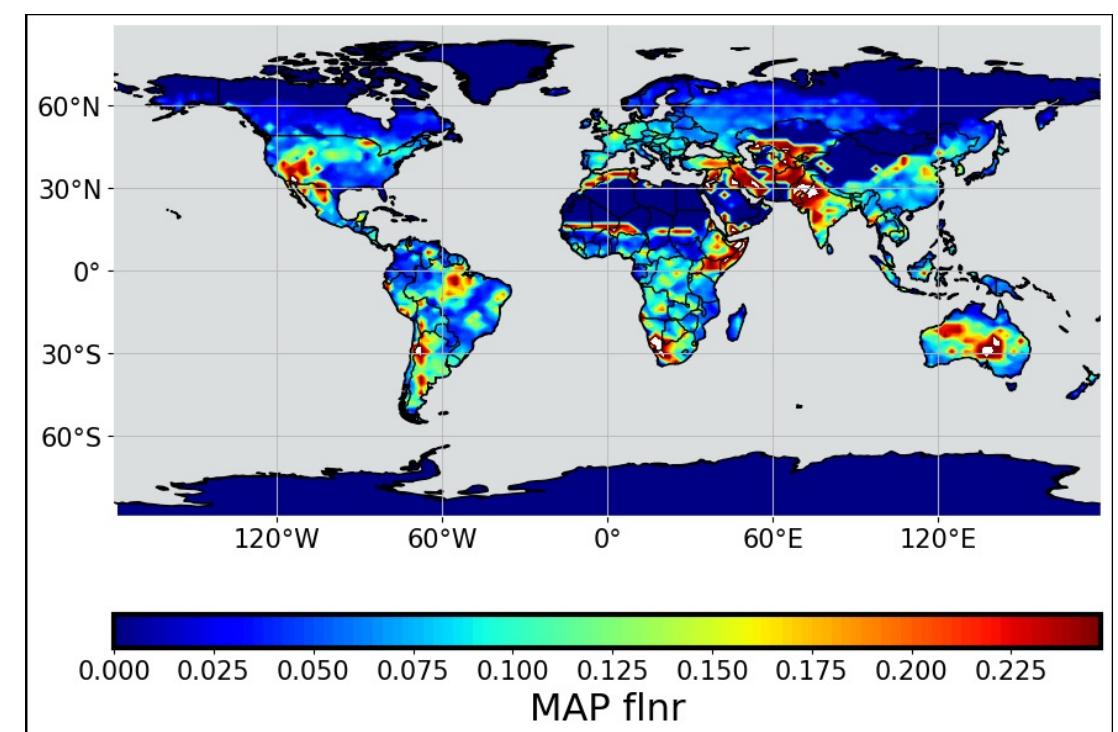
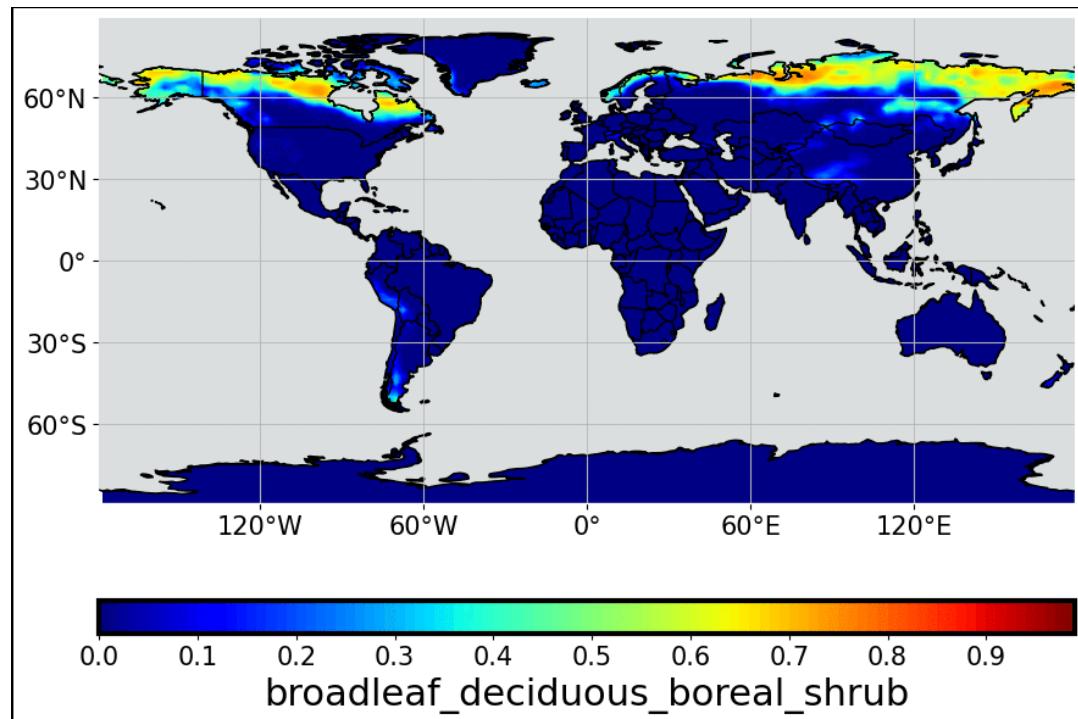


# Localized calibration works slightly better

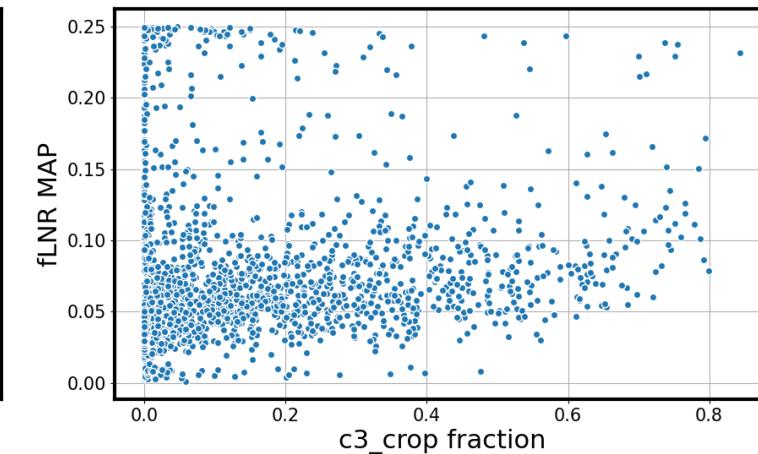
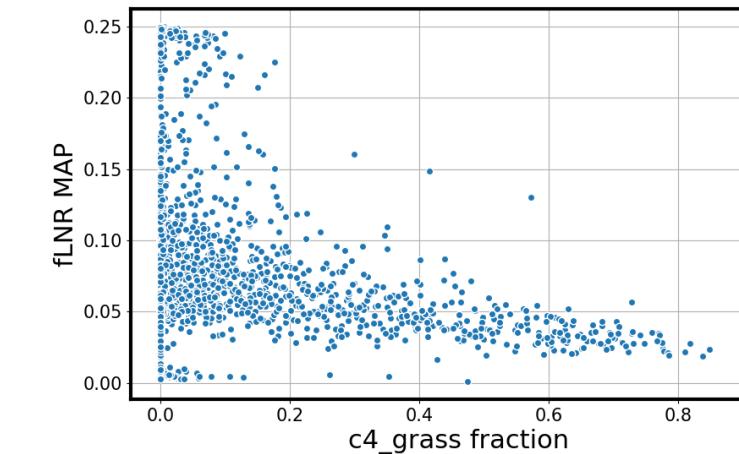
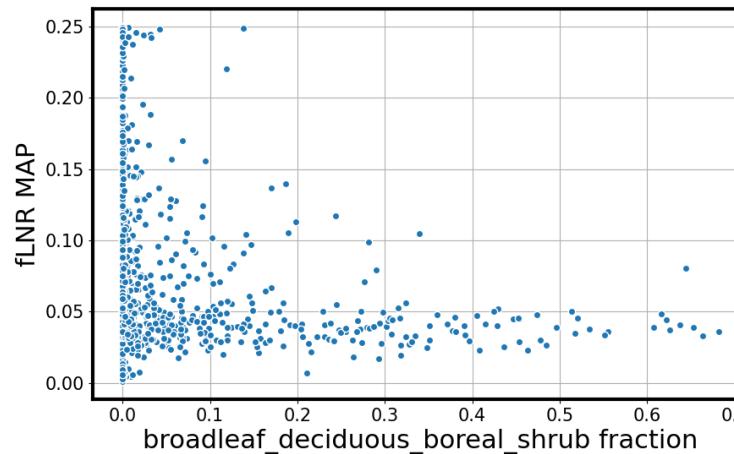
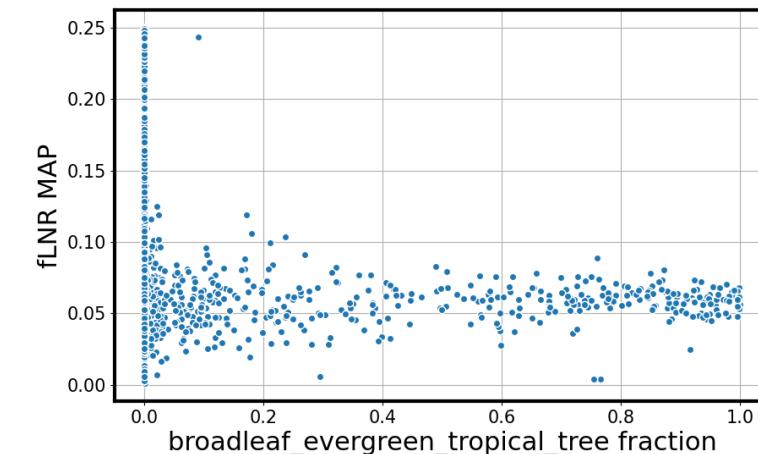
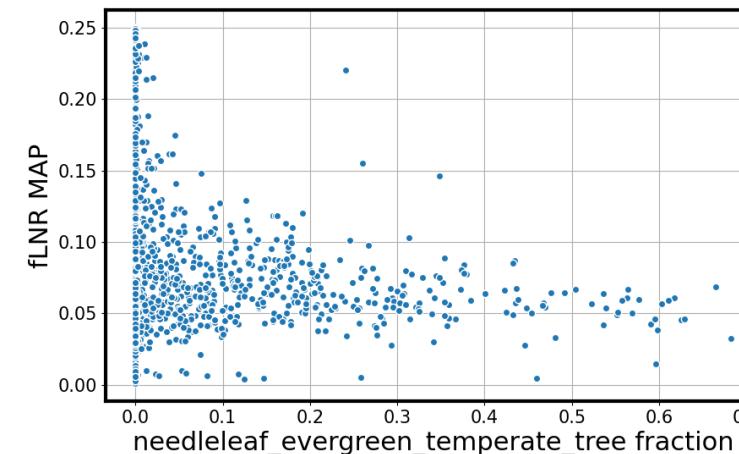
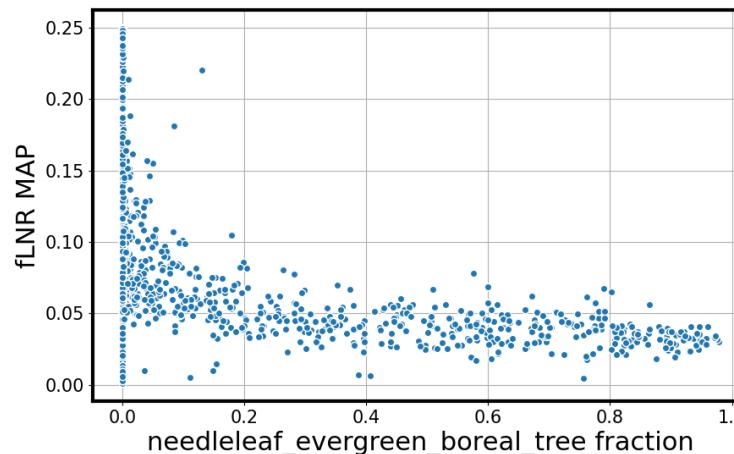


# Correlate PFT fractions globally with best fLNR values

PFT Fractions for all PFTs



# Correlate PFT fractions globally with best fLNR values





## Summary

---

- Karhunen-Loève (KL) decomposition reduces the spatio-temporal output dimensionality, taking advantage of correlations over space and time.
  - Neural network (NN) surrogate in the reduced eigenspace leads to a spatio-temporal KLNN surrogate that is a small fraction of ELM cost.
  - KLNN surrogate enables sampling based global sensitivity analysis and Bayesian calibration performed in the eigenspace.
- 

### Ongoing work:

- *Potential PFT-dependent reparameterization to improve model's ability to match reference data.*
- *Calibration with embedded model discrepancy to avoid overfitting.*



# Additional Material

# KL truncation relies on variance retention

$$f(\lambda; z) \approx \bar{f}(z) + \sum_{m=1}^M \xi_m(\lambda) \sqrt{\mu_m} \phi_m(z)$$

$$Var[f(z)] = \sum_{m=1}^M \mu_m \phi_m^2(z)$$

$$Var[f] = \sum_{m=1}^M \mu_m$$

$$M = \operatorname{argmin}_{M'} \frac{\sum_{m=1}^{M'} \mu_m}{\sum_{m=1}^{\infty} \mu_m} > 0.99$$

# Polynomial Chaos intro

- Our traditional tool for uncertainty representation and propagation
- Random variables represented as polynomial expansion of standard random variables,

such as gaussian or uniform

$$\xi = \sum_{k=1}^K c_k \psi_k(\eta)$$

- Convenient for uncertainty propagation

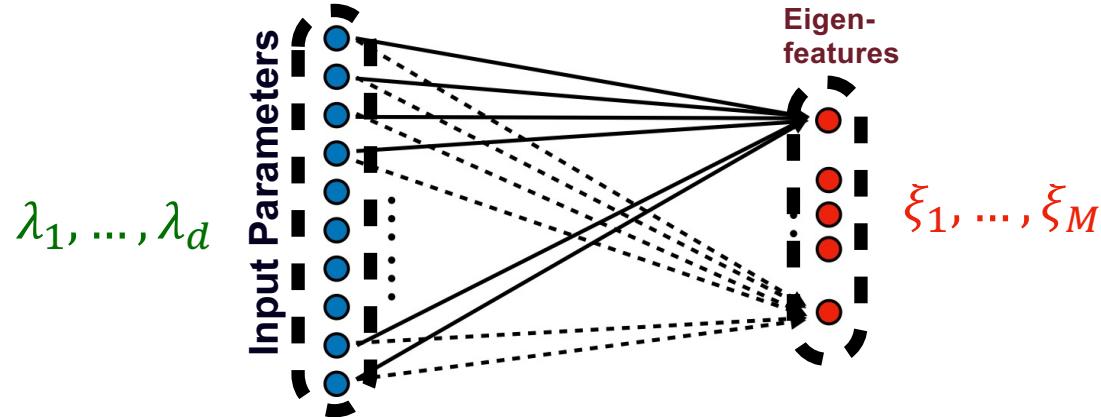
$$f(\xi) = \sum_{k=0}^K f_k \psi_k(\eta)$$

- Moment estimation
- Global Sensitivity Analysis (a.k.a. Sobol indices or variance-based decomposition)

# KL+PC = reduced dimensional spatio-temporal surrogate

The goal is to construct a surrogate with respect to uncertain parameters  $\lambda$ , such that  
 $f(\lambda; z_i) \approx f_s(\lambda; z_i)$  for all conditions  $z_i$ .

Instead of building surrogate for each individual  $z_i$  for  $i = 1, \dots, N$ ,  
we construct polynomial chaos (PC) surrogate for  $\xi_1, \dots, \xi_M$  where  $M \ll N$ .



$$f(\lambda; z) \approx \bar{f}(z) + \sum_{m=1}^M \xi_m(\lambda) \sqrt{\mu_m} \phi_m(z)$$

$\uparrow$

$\xi_m^{PC}(\lambda)$

# PC vs NN comparison

Polynomial Chaos

Simple regression,  
easy to train

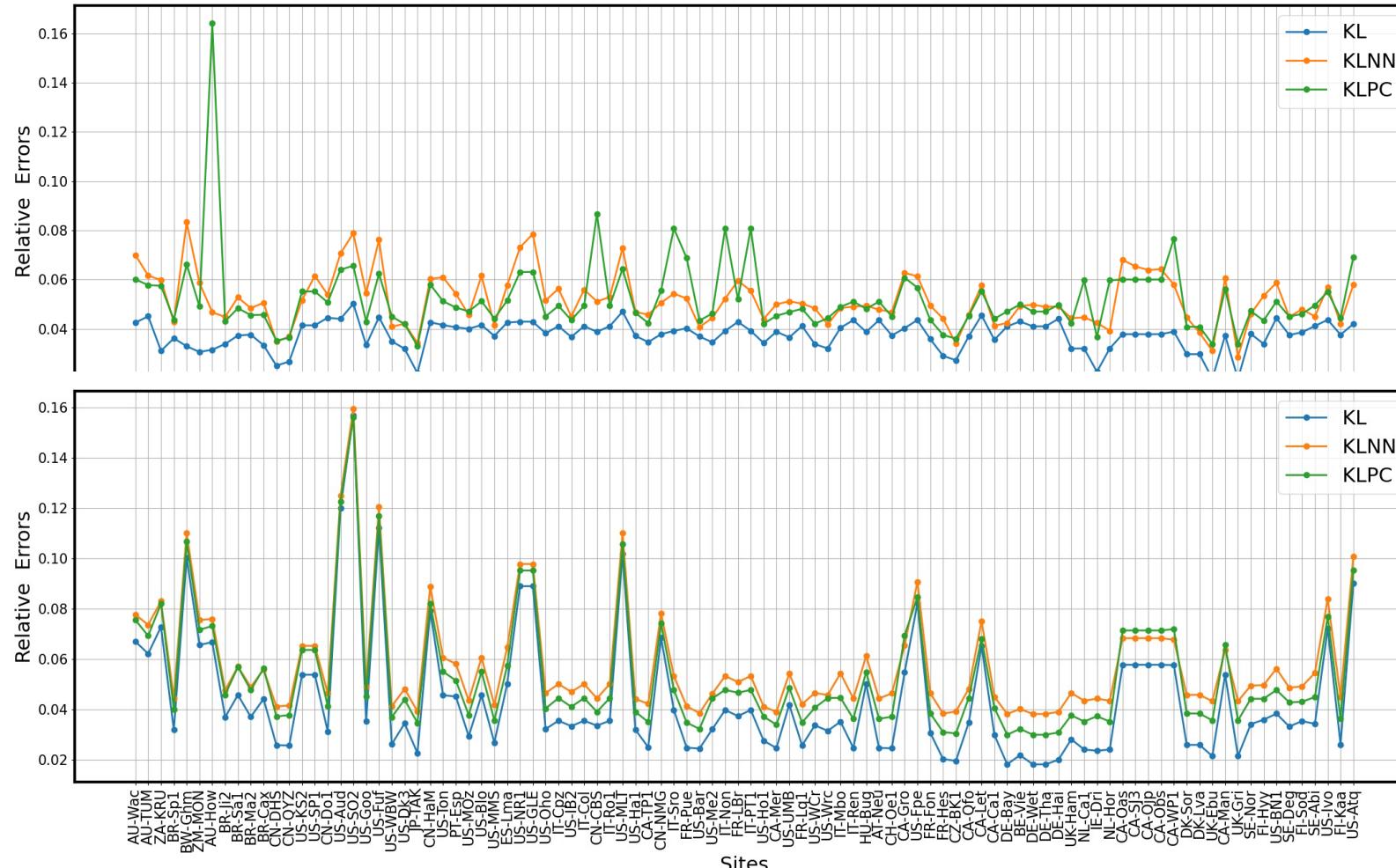
GSA and variance decomposition,  
More interpretable

Neural Network

More flexible,  
highly customizable

Multiple outputs at once,  
More accurate (in theory)

# PC vs NN comparison



96 temporal surrogates  
with each 180 outputs

Single spatio-temporal  
surrogate  
with 96x180 outputs

# Bayesian Likelihood in the reduced space TBD

KLNN surrogate:

$$f(\lambda; z) \approx \bar{f}(z) + \sum_{m=1}^M \xi_m^{NN}(\lambda) \sqrt{\mu_m} \phi_m(z)$$

Project observed data to the KL eigenspace:

$$g(z) \approx \bar{f}(z) + \sum_{m=1}^M \eta_m \sqrt{\mu_m} \phi_m(z)$$

**Pointwise likelihood (old) :**

$$L_g(\lambda) \equiv p(g|\lambda) \propto \exp\left(-\sum_{i=1}^N \frac{(g(z_i) - f(\lambda; z_i))^2}{2\sigma_i^2}\right)$$

**Data model (old) :**

$$g(z_i) = f(\lambda; z_i) + \sigma_i \epsilon_i$$

i.i.d. Normal

$$L_g(\lambda) \equiv p(g|\lambda) \propto \exp\left(-\sum_{m=1}^M \frac{(\eta_m - \xi_m^{NN}(\lambda))^2}{2\sigma^2}\right)$$

**Data model (new) :**

$$\eta_m = \xi_m^{NN}(\lambda) + \tilde{\sigma} \epsilon_m$$

$\downarrow$

$$g(z_i) = f(\lambda; z_i) + \sum_{m=1}^M \tilde{\epsilon}_m \sqrt{\mu_m} \phi_m(z_i)$$

MVN (physics-based)