

Bagian 1

$$z = \frac{1}{a^3} (xy^3 + x^3y) = \frac{r^4}{a^3} (\cos\varphi \cdot \sin^3\varphi + \cos^3\varphi \cdot \sin\varphi) =$$

$$x = r \cos\varphi$$

$$y = r \sin\varphi$$

$$= \frac{r^4}{a^3} \cos\varphi \sin\varphi = \frac{r^4}{2a^3} \sin 2\varphi$$

$$g_{ij} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$g_{11} = \left(\frac{\partial x}{\partial r} \right)^2 + \left(\frac{\partial y}{\partial r} \right)^2 + \left(\frac{\partial z}{\partial r} \right)^2 =$$

$$= \cos^2\varphi + \sin^2\varphi + \left(2 \frac{r^3}{a^3} \sin 2\varphi \right)^2 =$$

$$= 1 + \left(2 \frac{r^3}{a^3} \sin 2\varphi \right)^2 = 1 + \frac{4r^6}{a^6} \sin^2 2\varphi$$

$$g_{12} = g_{21} = \frac{\partial x}{\partial r} \cdot \frac{\partial x}{\partial \varphi} + \frac{\partial y}{\partial r} \cdot \frac{\partial y}{\partial \varphi} + \frac{\partial z}{\partial r} \cdot \frac{\partial z}{\partial \varphi} =$$

$$= -\cos\varphi \cdot r \sin\varphi + r \sin\varphi \cos\varphi + \frac{2r^3}{a^3} \sin 2\varphi \cdot \frac{r}{a^3} \cos 2\varphi =$$

$$= \frac{r^4}{a^3} \cos 2\varphi = \frac{r^7}{a^6} \sin 4\varphi$$

$$g_{22} = \left(\frac{\partial x}{\partial \varphi} \right)^2 + \left(\frac{\partial y}{\partial \varphi} \right)^2 + \left(\frac{\partial z}{\partial \varphi} \right)^2 =$$

$$= r^2 \sin^2\varphi + r^2 \cos^2\varphi + \frac{r^8}{a^6} \cos^2 2\varphi$$

$$g_{ij} = \begin{pmatrix} 1 + \frac{4r^6}{a^6} \sin^2 2\varphi & \frac{r^7}{a^6} \sin 4\varphi \\ \frac{r^7}{a^6} \sin 4\varphi & r^2 + \frac{r^8}{a^6} \cos^2 2\varphi \end{pmatrix}$$

Bagian 5.

$$V = \det \begin{pmatrix} A \\ B \\ C \end{pmatrix}$$

$$V_1 = \det \begin{pmatrix} A \\ B \\ C \end{pmatrix}$$

$$g_{ki} A^i = A_k$$

$$V = g V_1$$

$$\frac{V}{V_1} = \frac{g}{g_1}$$

no c-by

$$c_{ij} = c_{ji}$$

$$c_{ij} \neq a_{ij}$$

$$c_{11} = g_1$$

$$(T.k \ A)$$

$$= \begin{vmatrix} A & A \\ B & B \\ C & C \end{vmatrix}$$

$$\bar{A}_k \bar{B}^k = \frac{\partial x_i}{\partial \bar{x}_k} \frac{\partial \bar{x}^k}{\partial x_i} A^i B_i$$

$$\bar{A}_k = \frac{\partial x_i}{\partial \bar{x}_k} A^i$$

$$\bar{B}^k = \frac{\partial \bar{x}^k}{\partial x_j} B^j$$

$$\bar{A}_k \bar{B}^k = \underbrace{\frac{\partial x_i}{\partial \bar{x}_k} \frac{\partial \bar{x}^k}{\partial x_j}}_{\delta_i^j} A^i B^j = S$$

При переходе в новые координаты
 S не меняется $\Rightarrow S$ -скаляр

Задача 3

$$R_{ijkl} \Gamma^{kl}$$

$$R_{ijkl} = \frac{\partial x^m}{\partial \bar{x}^i} \frac{\partial x^p}{\partial \bar{x}^j} \frac{\partial x^l}{\partial \bar{x}^k} \frac{\partial x^p}{\partial \bar{x}^l} \cdot R_{mp\ell b}$$

$$\Gamma^{kl} = \frac{\partial \bar{x}^k}{\partial x^i} \cdot \frac{\partial \bar{x}^l}{\partial x^j} \Gamma^{\alpha\beta}$$

$$R_{ijkl} \Gamma^{kl} = \frac{\partial x^m}{\partial \bar{x}^i} \frac{\partial x^p}{\partial \bar{x}^j} \left(\frac{\partial x^a}{\partial \bar{x}^k} \frac{\partial \bar{x}^k}{\partial x^b} \right) \times \frac{\partial x^p}{\partial \bar{x}^i} \cdot \frac{\partial \bar{x}^i}{\partial x^a} R_{mp\ell b} \cdot \Gamma^{\alpha\beta} =$$

$$= \frac{\partial x^m}{\partial \bar{x}^i} \frac{\partial x^p}{\partial \bar{x}^j} R_{mp\ell b} \Gamma^{\alpha\beta}$$

Закон преобразования ковариантного тензора 2-го ранга.

Задача 4.

$$A_i A^i = \frac{\partial x^i}{\partial \bar{x}^k} \frac{\partial \bar{x}^k}{\partial x^j} A_i A^j = \delta^j_i = \delta^j_i$$

не меняется

$$A_i = \frac{\partial x^k}{\partial \bar{x}^i} A_k$$

$$A^i = \frac{\partial x^i}{\partial \bar{x}^p} A^p$$

$$A_i A^i = \frac{\partial x^k}{\partial \bar{x}^i} \frac{\partial x^i}{\partial \bar{x}^p} A_k A^p = \delta^p_k A_k A^p = S$$

не меняется при переходе

$$A_k = A^k$$

и [c]

$$P_{ik} = \frac{\partial A_i}{\partial x^k}$$

$$\frac{\partial \bar{A}_i}{\partial \bar{x}^k} = \frac{\partial}{\partial x^l} (\bar{A}_i) = \frac{\partial}{\partial x^l} \left(\frac{\partial x^j}{\partial x^i} A_j \right) =$$

$$= \frac{\partial A_j}{\partial x^k} \frac{\partial x^j}{\partial x^l} + A_j \frac{\partial^2 x^j}{\partial x^l \partial x^i} - \text{кв}$$

$$A_i = \frac{\partial x^j}{\partial \bar{x}^i} A_j \quad \text{тензорный закон.}$$

Закон преобразования не тензорный!

$$\bar{T}_{kl} = \frac{\partial x^i}{\partial \bar{x}^k} \frac{\partial x^j}{\partial \bar{x}^l} T_{ij}$$

$$3. \quad P_{ik} = \frac{\partial A_i}{\partial x^k} = \frac{\partial A_\alpha}{\partial x^k} = \frac{\partial A_\alpha}{\partial x^\beta} \frac{\partial x^\beta}{\partial \bar{x}^k} \frac{\partial x^\alpha}{\partial \bar{x}^i} +$$

$$+ A_\alpha \frac{\partial^2 x^\alpha}{\partial x^i \partial \bar{x}^k} - \frac{\partial A_\alpha}{\partial x^\beta} \frac{\partial x^\beta}{\partial \bar{x}^i} \frac{\partial x^\alpha}{\partial \bar{x}^k} -$$

$$- A_\alpha \frac{\partial^2 x^\alpha}{\partial \bar{x}^k \partial \bar{x}^i} \quad (\text{коротко дифференциро-} \\ \text{вание не важно}) \quad \Rightarrow$$

Поменили местами индексы

$$\alpha \text{ и } \beta$$

$$\Rightarrow \frac{\partial A_\alpha}{\partial x^\beta} \frac{\partial x^\beta}{\partial \bar{x}^k} \frac{\partial x^\alpha}{\partial \bar{x}^i} - \frac{\partial A_\beta}{\partial x^\alpha} \frac{\partial x^\alpha}{\partial \bar{x}^k} \frac{\partial x^\beta}{\partial \bar{x}^i} =$$

$$= \left(\frac{\partial A_\alpha}{\partial x^\beta} - \frac{\partial A_\beta}{\partial x^\alpha} \right) \left(\frac{\partial x^\beta}{\partial \bar{x}^k} \frac{\partial x^\alpha}{\partial \bar{x}^i} \right)$$

$$\bar{T}_{kl} = \frac{\partial x^i}{\partial \bar{x}^k} \frac{\partial x^j}{\partial \bar{x}^l} T_{ij} \quad \text{тензорный} \\ \text{закон} \\ \text{преобразования}$$

Задание 5.

$$V = \det \begin{pmatrix} A_1 & A_2 & A_3 \\ B_1 & B_2 & B_3 \\ C_1 & C_2 & C_3 \end{pmatrix}$$

$$V_1 = \det \begin{pmatrix} A^1 & A^2 & A^3 \\ B^1 & B^2 & B^3 \\ C^1 & C^2 & C^3 \end{pmatrix}$$

$$g_{ki} A^i = A_k$$

$$V = g V_1$$

$$\cancel{V} = \cancel{V} \cancel{g} = \begin{pmatrix} g_{1k} A^k & g_{2k} A^k & g_{3k} A^k \\ g_{1k} B^k & g_{2k} B^k & g_{3k} B^k \\ g_{1k} C^k & g_{2k} C^k & g_{3k} C^k \end{pmatrix} =$$

$$\begin{aligned} &= \left| \begin{array}{l} \text{no c-by} \\ C_{ij} = a_{ij} b_{ji} \\ C_{ij} = a_{i1} b_{j1} + a_{i2} b_{j2} + a_{i3} b_{j3} \\ C_{11} = \underbrace{g_{1k} A_k}_{A_k, k=1,2,3} + \underbrace{g_{2k} B_k}_{A_k, k=1,2,3} + \underbrace{g_{3k} C_k}_{A_k, k=1,2,3} \end{array} \right| = \end{aligned}$$

$$= \left(\text{т.к. } A_k = g_{ki} A^i \right) =$$

$$= \begin{vmatrix} A_1 & A_2 & A_3 \\ B_1 & B_2 & B_3 \\ C_1 & C_2 & C_3 \end{vmatrix}$$

к стабильности
зависит от наличия
существенными не
эксперименте. Тем
благодаря этому они
составляет ~ 10-14
разрешение достигает
сегодняшний день су
Действительно,
мов в магнитном по
рефсона) [2, 3] и м

$$\Gamma_{jk} = \frac{\delta A_i}{\delta X_k}$$

1. n.

$$VV_1 = \det \begin{pmatrix} A^i A_i & A^i B_i & A^i C_i \\ B^i A_i & B^i B_i & B^i C_i \\ C^i A_i & C^i B_i & C^i C_i \end{pmatrix} =$$

$$= \begin{vmatrix} c_{ij} = a_{ij} b_{ji} \\ c_{11} = A_1 A^1 + A_2 A^2 + A_3 A^3 \end{vmatrix} =$$

$$= \begin{vmatrix} A^1 & A^2 & A^3 \\ B^1 & B^2 & B^3 \\ C^1 & C^2 & C^3 \end{vmatrix} \cdot \begin{vmatrix} A_1 & A_2 & A_3 \\ B_1 & B_2 & B_3 \\ C_1 & C_2 & C_3 \end{vmatrix}$$