



A
PROJECT
REPORT
ON
BOYER MOORE'S VOTING ALGORITHM
Submitted in partial fulfillment of the requirement for the IV semester
of
**BACHELOR OF
TECHNOLOGY**
IN
DESIGN AND ANALYSIS OF ALGORITHM

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**18CSC204J- Design and Analysis
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Record Work**

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DESIGN AND ANALYSIS OF ALGORITHMS in SRM INSTITUTE OF SCIENCE
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Examiner-2

CERTIFICATE

This is to certify that the project entitled “**Boyer Moore’s Voting Algorithm**” carried out by **KUMAR SHASHWAT** under my supervision at Department of Computing and Technology, SRM Institute of Technology, Kattankulathur, Chennai.

The work is original, as it has not been submitted earlier either in part or full for any purpose before.

Dr. C. Muralidharan
(Asst. Professor)

DECLARATION

I, hereby declare that the work presented in this dissertation entitled “**Boyer Moore’s Voting Algorithm**” has been done by me and my team, and this dissertation embodies my own work.

Approved By:
Dr. C. Muralidharan

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Contribution Table

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NIPURN BHAAL	RA2011003011272	Idea for the project.
KUMAR SHASHWAT	RA2011003011262	Implementation of Code
AYUSH PODDAR	RA2011003011279	Preparation of ppt
KUMAR SHASHWAT, NIPURN BHAAL & AYUSH PODDAR	RA2011003011262 , RA2011003011272 & RA2011003011279	Preparation of report and analysis of code

Visualizing Boyer Moore's Voting Algorithm

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Abstract:

The Boyer–Moore majority vote algorithm is an algorithm for finding the majority of a sequence of elements using linear time and constant space. The Boyer-Moore voting algorithm is one of the popular optimal algorithms which is used to find the majority element among the given elements that have more than $N/2$ occurrences. This works perfectly fine for finding the majority element which takes 2 traversals over the given elements, which works in $O(N)$ time complexity and $O(1)$ space complexity.

Keywords:

Greedy Algorithm, Space Complexity Optimization.

Introduction:

- We have taken this algorithm instead of Divide and Conquer as our approach because it helps us to reduce auxiliary recursion calls as in traditional Divide and Conquer method.
- Among all the algorithmic approaches, the simplest and straightforward approach is the Greedy method. In this approach, the decision is taken on the basis of current available information without worrying about the effect of the current decision in future.

Introduction – Problem Statement

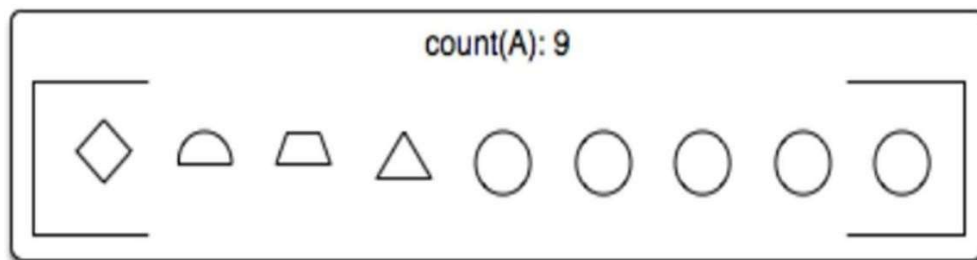
In a general Presidency election, there are N candidates who can cast a vote either for themselves or any other member. Only two persons designated as President and Vice President have to be elected. President gets the maximum votes followed by the vice president.

Find all candidates that get votes more than $\lfloor n/3 \rfloor$ times.

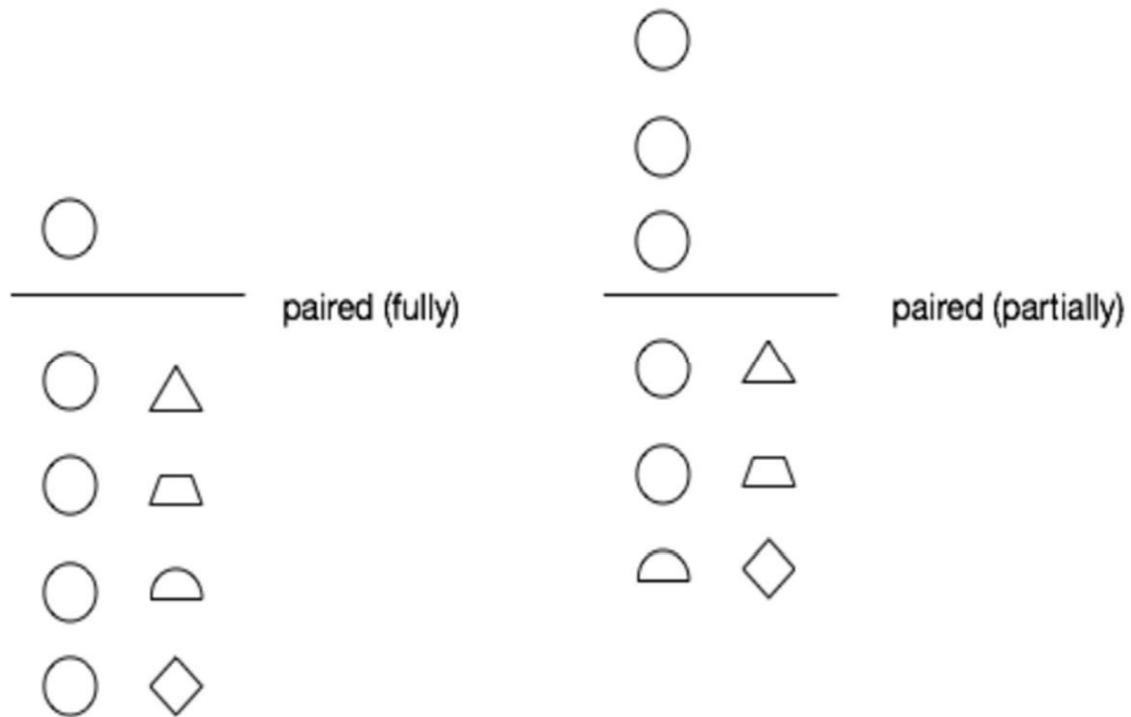
Solve this using a space complexity of $O(1)$.

Problem Explanation

Suppose there are nine elements in array A , and the round one is the majority.



No matter in what order we select element from the array, we can only get two results.

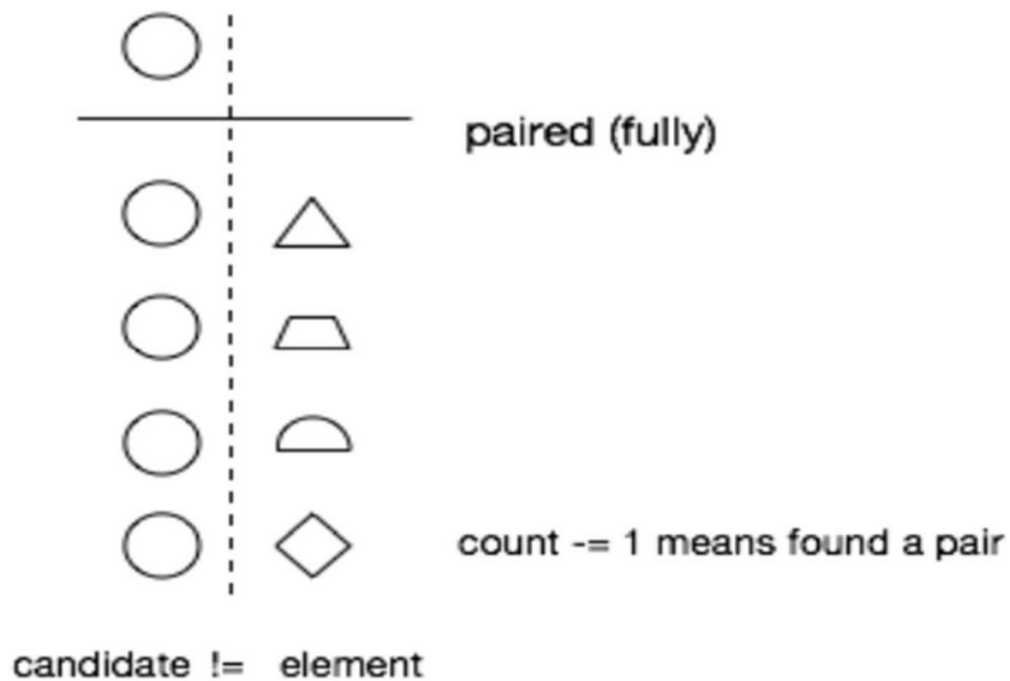


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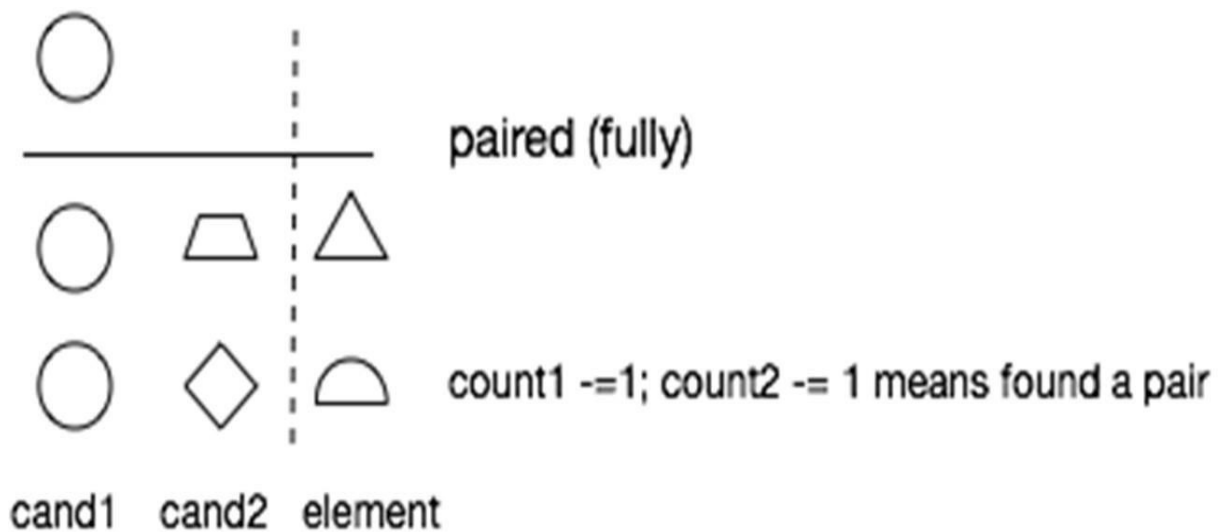
Compared to fully pairing, it is a little wasting of the partially pairing as there are some round ones are not paired (definitely it would be left). So, under the condition that the majority element exists, we could only think about the **fully pairing situation**. (It's useful when dealing with $n/3$ situation)

We can consider either column as the candidate, and it's intuitive for me to get understand that the code means found a pair.

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So here comes the $n/3$ problem, we would only think about the fully pairing situation. If the overone third majority exists, it should be left after pairing.



Q/A Related to Problem Statement

Why would we use three elements as a pair?

- ✓ Because it makes sure that in fully pairing the count of majority element equals $n/3$.

Why we have implemented Greedy Approach?

- ✓ Among all the algorithmic approaches, the simplest and straightforward approach is the Greedy method. In this approach, the decision is taken on the basis of current available information without worrying about the effect of the current decision in future.
- ✓ Greedy algorithms build a solution part by part, choosing the next part in such a way, that it gives an immediate benefit. This approach never reconsiders the choices taken previously. This approach is mainly used to solve optimization problems. Greedy method is easy to implement and quite efficient in most of the cases. Hence, we can say that Greedy algorithm is an algorithmic paradigm based on heuristic that follows local optimal choice at each step with the hope of finding global optimal solution.
- ✓ In many problems, it does not produce an optimal solution though it gives an approximate (near optimal) solution in a reasonable time.

Explanation of Algorithm with Example

If $N=15$, then

$$\text{Frequency (ME)} = N/3 = 5$$

In this case, we realize that we can have 3 cases.

Case 1: 0 people winning: Everyone gets unique votes or some get 2 etc.

Case 2: Person winning: President who gets vote like 6 and rest all get less than 6.

For example: 1 1 1 1 1 1 2 2 3 3 4 4 5 5 6

President: 1 with 6 votes

Case 3: 2 people winning: Vice President both get equal to 6 or one of them gets more than 6.

For Example: 1 1 1 1 1 1 1 2 2 2 2 2 2 8 8

President: 1 with 7 votes

Vice President: 2 with 6 votes

Rest: 2 votes

Visualizing Boyer Moore's Voting Algorithm with OneStatement

What will President and Vice President say?

- President will say that “I won with a difference of 5”.
- Vice President will say that “I won with a difference of 4”

Till this point I want you to realise that Vote of Majority Element is only affected by Minority elements. By people who are not winning.

Hence in this case we have to maintain two independent counters keeping track of **ME1** and **ME2**.

The only thing to note here is that when you reach a Minority element, that minority element will affect both President and Vice President's vote.

That's why when we hit a minority element, we reduce count for both the Majority Elements as it is affecting winning difference of both the winning Candidates

Understanding through the help of Example

Example

Index: 0 1 2 3 4 5 6 7 8 9 0 1 2 3 4

Given Array: 1 2 3 1 1 1 7 7 1 1 7 5 7 7 7

cnt1: 1

cnt2: 1

Count 1 is for ME1->

Initialized to 0

Count 2 is for ME2->

Initialized by 0

At i=0: We get First Candidate

At i: 1: This is not equal to our first candidate so new counter initialized by 1

Index: 0 1 2 3 4 5 6 7 8 9 0 1 2 3
4

Given Array: 1 2 3 1 1 1 7 7 1 1
 7 5 7 7 7

cnt1: .1 0

cnt2:1 0

At i=2: This vote is a loss for both the candidates BUT not in the long run. That's what we are trying to do. We want our counters to be greater than 1 for that candidate to win.

Index: 0 1 2 3 4 5 6 7 8 9 0 1 2 3
 4

Given Array: 1 2 3 1 1 1 7 7 1 1
 7 5 7 7 7

cnt1: 1....0 1 2 3... 4 5....4

cnt2:1.0.....1 2...3 2 3 4 5

Make sure to update new ME1 and ME2 when counters == 0.

Make sure to check whether these really are Majority Elements because this algorithm will give you ME1 and ME2 in any case.

Source Code

```

VotingAlgorithm.cpp > majorityElement(vector<int>&)
5      {
6          int n = arr.size(); int cnt1 = 0;
7          int cnt2 = 0; int me1 = -1; int me2 = -1;
8
9          // Find candidates
10         for (auto element : arr)
11         {
12             if (element == me1)
13             {
14                 ++cnt1;
15             }
16             else if (element == me2)
17             {
18                 ++cnt2;
19             }
20             else if (cnt1 == 0)
21             {
22                 me1 = element;
23                 ++cnt1;
24             }
25             else if (cnt2 == 0)
26             {
27                 me2 = element;
28                 ++cnt2;
29             }
30             else
31             {
32                 --cnt1;
33                 --cnt2;
34             }
35         }
36     }
```

```
35     }
36
37     int validFreq = floor(n / 3);
38
39     vector<int> result = {};
40     int vc1 = 0, vc2 = 0;
41
42     for (int i = 0; i < n; i++)
43     {
44         if (arr[i] == me1)
45             ++vc1;
46         else if (arr[i] == me2)
47             ++vc2;
48     }
49     if (vc1 > validFreq)
50         result.push_back(me1);
51     if (vc2 > validFreq)
52         result.push_back(me2);
53     return result;
54 }
```

Time Complexity

Time Complexity will remain **$O(n)$**

Space Complexity

Space complexity will be **$O(1)$**

Conclusion

Problem could be solved using Divide and conquer, but greedy helps us to reduce auxiliary recursion calls as in traditional Divide and Conquer method.

The amount of memory that the algorithm needs is the space for one element and one counter. In the random access model of computing usually used for the analysis of algorithms, each of these values can be stored in a machine word and the total space needed is $O(1)$. If an array index is needed to keep track of the algorithm's position in the input sequence, it doesn't change the overall constant space bound. The algorithm's bit complexity (the space it would need, for instance, on a Turing machine) is higher, the sum of the binary logarithms of the input length and the size of the universe from which the elements are drawn. Both the random access model and bit complexity analyses only count the working storage of the algorithm, and not the storage for the input sequence itself.

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