

ECEN 5803
Mastering Embedded System Architecture
(Fall-2023)

PROJECT-1 : MODULE 1
TO C OR NOT TO C

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Que 1] Starting with the results from Lab_Exercise_1 in the Homework 2-Practical, create another Keil project, call it M1String and replace the string copy and string capitalization assembly language functions with C functions written by you or your partner. Compile and run this project. Compare the memory usage between the assembly language function project and the C function project – which uses less memory?

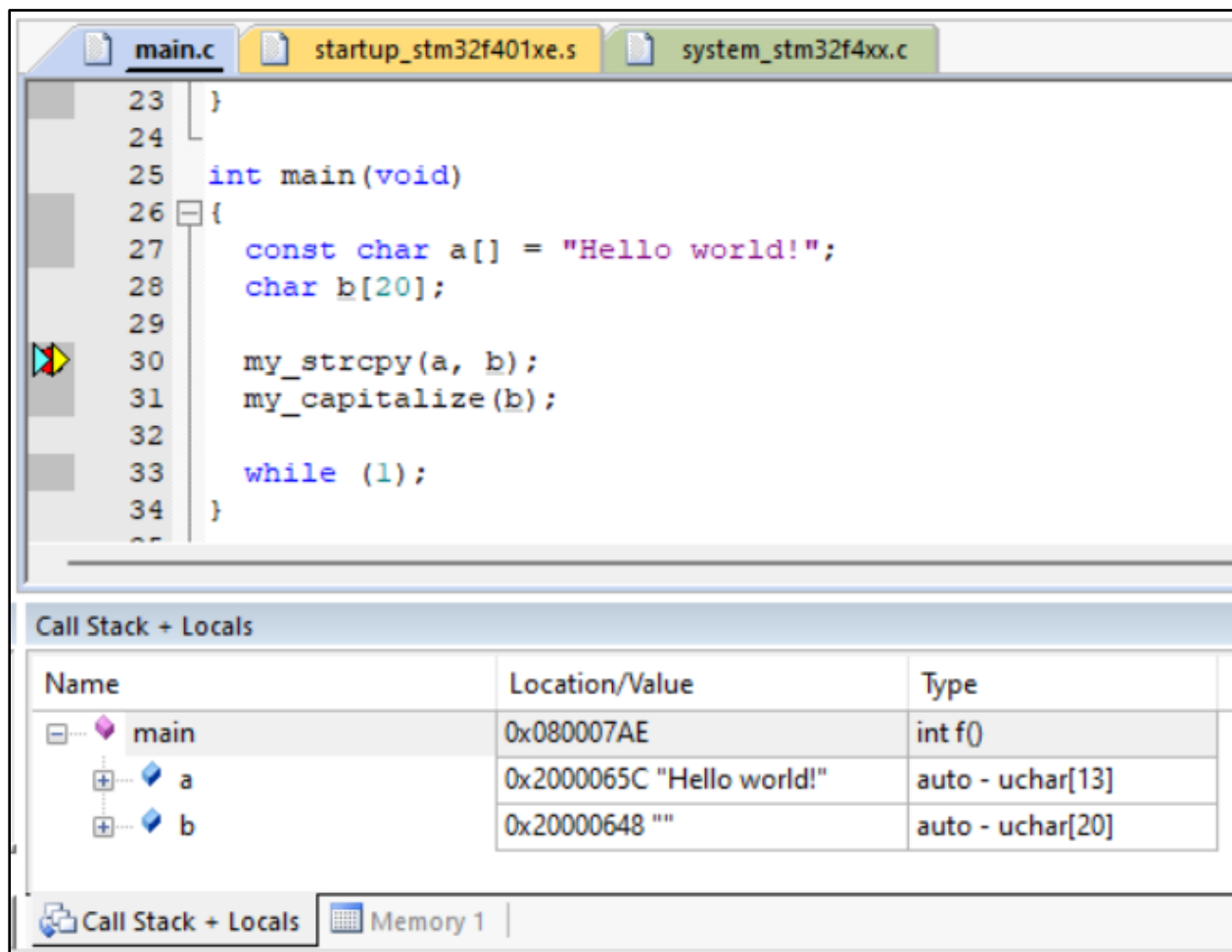
Ans:

C code write, compile and run:

Note: please find the attached M1String project also the code is updated in the Appendix(end of this document)

Code output:

string copy:



The screenshot shows the Keil IDE with the following components:

- Code Editor:** Displays the `main.c` file with the following code:

```
23 }
24
25 int main(void)
26 {
27     const char a[] = "Hello world!";
28     char b[20];
29
30     my_strcpy(a, b);
31     my_capitalize(b);
32
33     while (1);
34 }
```
- Call Stack + Locals:** A window showing the current state of the program's call stack and local variables.

Name	Location/Value	Type
main	0x080007AE	int f()
a	0x2000065C "Hello world!"	auto - uchar[13]
b	0x20000648 ""	auto - uchar[20]
- Bottom Bar:** Shows tabs for "Call Stack + Locals" and "Memory 1".

string before copy

The screenshot shows a debugger interface with three tabs at the top: `main.c`, `startup_stm32f401xe.s`, and `system_stm32f4xx.c`. The `main.c` tab is active, displaying the following C code:

```

23 }
24
25 int main(void)
26 {
27     const char a[] = "Hello world!";
28     char b[20];
29
30     my_strcpy(a, b);
31     my_capitalize(b);
32
33     while (1);
34 }

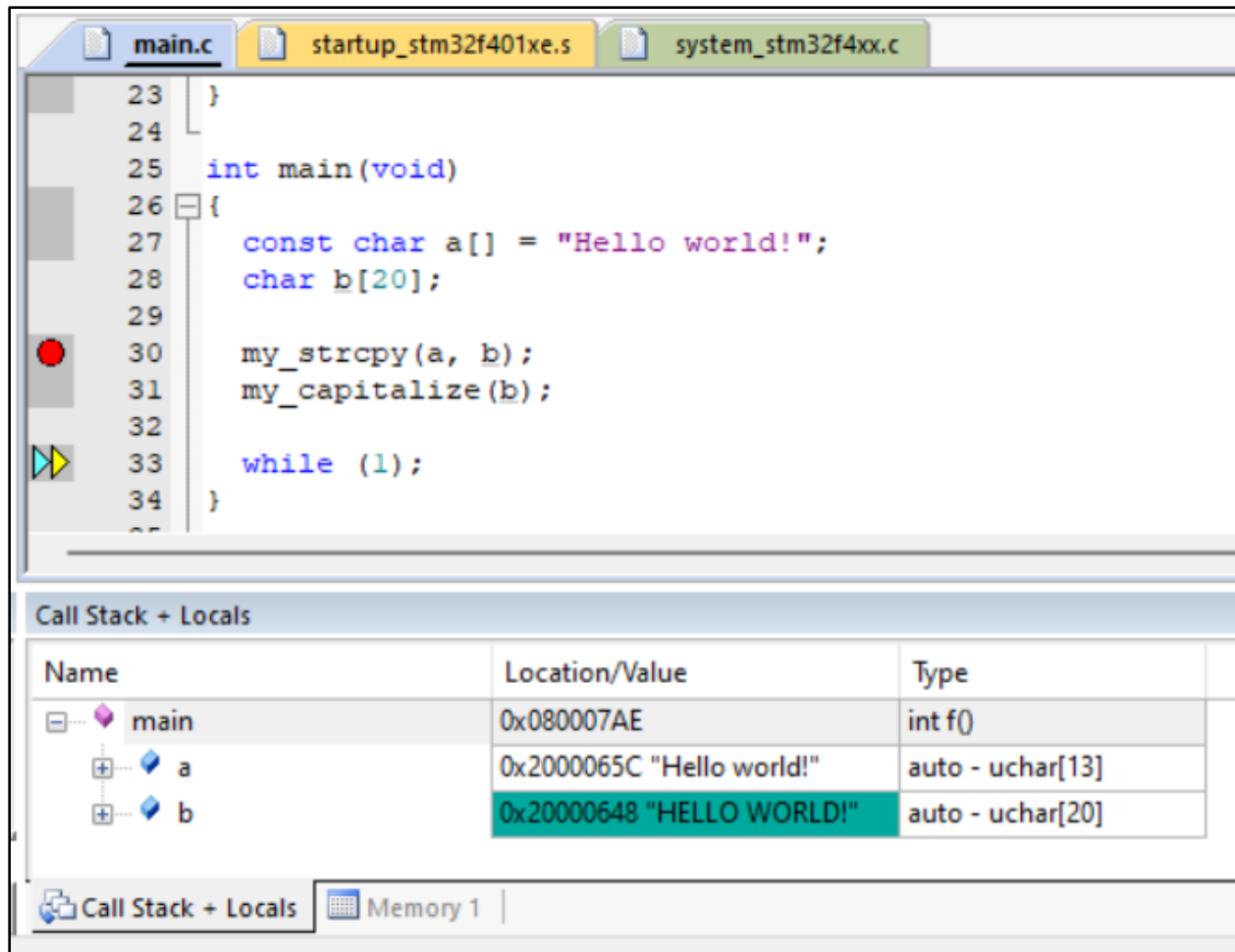
```

Below the code editor is the **Call Stack + Locals** window. It contains a table with the following data:

Name	Location/Value	Type
main	0x080007AE	int f()
a	0x2000065C "Hello world!"	auto - uchar[13]
b	0x20000648 "Hello world!"	auto - uchar[20]

At the bottom of the debugger window, there are two tabs: **Call Stack + Locals** (selected) and **Memory 1**.

string after copy



Memory usage comparison between the assembly language function project and the C function project:

Assembly language Code Memory Usage:

```

Build Output
compiling timer.c...
compiling i2c.c...
compiling main.c...
compiling stm32f4xx_adc.c...
compiling adc.c...
compiling comparator.c...
compiling stm32f4xx_gpio.c...
compiling gpio.c...
compiling stm32f4xx_rcc.c...
compiling stm32f4xx_i2c.c...
compiling uart.c...
assembling startup_stm32f401xe.s...
compiling system_stm32f4xx.c...
linking...
Program Size: Code=1696 RO-data=420 RW-data=0 ZI-data=1656
".\Objects\MlString.axf" - 0 Error(s), 0 Warning(s).
Build Time Elapsed: 00:00:01

```

1.1 Keil project asm build output

=====						
Code (inc. data)	RO Data	RW Data	ZI Data	Debug		
1696	42	420	0	1656	32411	Grand Totals
1696	42	420	0	1656	32411	ELF Image Totals
1696	42	420	0	0	0	ROM Totals
=====						
Total RO Size (Code + RO Data)			2116 (2.07kB)		
Total RW Size (RW Data + ZI Data)			1656 (1.62kB)		
Total ROM Size (Code + RO Data + RW Data)			2116 (2.07kB)		
=====						

1.2 asm code .map file

Assembly code uses 1696 bytes of code memory with optimization set to -O0 as shown below.

C language Code Memory Usage:

```

Build Output
Rebuild started: Project: M1String
*** Using Compiler 'V6.19', folder: 'C:\Keil_v5\ARM\ARMCLANG\Bin'
Rebuild target 'Target 1'
compiling stm32f4xx_i2c.c...
compiling stm32f4xx_adc.c...
compiling stm32f4xx_usart.c...
compiling i2c.c...
compiling main.c...
compiling stm32f4xx_gpio.c...
compiling comparator.c...
compiling stm32f4xx_rcc.c...
compiling timer.c...
compiling adc.c...
compiling gpio.c...
compiling uart.c...
compiling system_stm32f4xx.c...
assembling startup_stm32f401xe.s...
linking...
Program Size: Code=1776 RO-data=420 RW-data=0 ZI-data=1656
".\Objects\M1String.axf" - 0 Error(s), 0 Warning(s).
Build Time Elapsed: 00:00:02

```

1.3 Keil project M1String build output

=====						
	Code (inc. data)	RO Data	RW Data	ZI Data	Debug	
1776	42	420	0	1656	32699	Grand Totals
1776	42	420	0	1656	32699	ELF Image Totals
1776	42	420	0	0	0	ROM Totals
=====						
Total RO	Size (Code + RO Data)			2196 (2.14kB)	
Total RW	Size (RW Data + ZI Data)			1656 (1.62kB)	
Total ROM	Size (Code + RO Data + RW Data)			2196 (2.14kB)	
=====						

1.4 M1String code .map file

C code uses 1776 bytes of code memory with optimization set to -O0 as shown below.

Conclusion:

So, from the above map file, we can see that the Assembly implementation uses 2.07 kB of memory on the other hand, the C implementation uses 2.14 kB of memory.

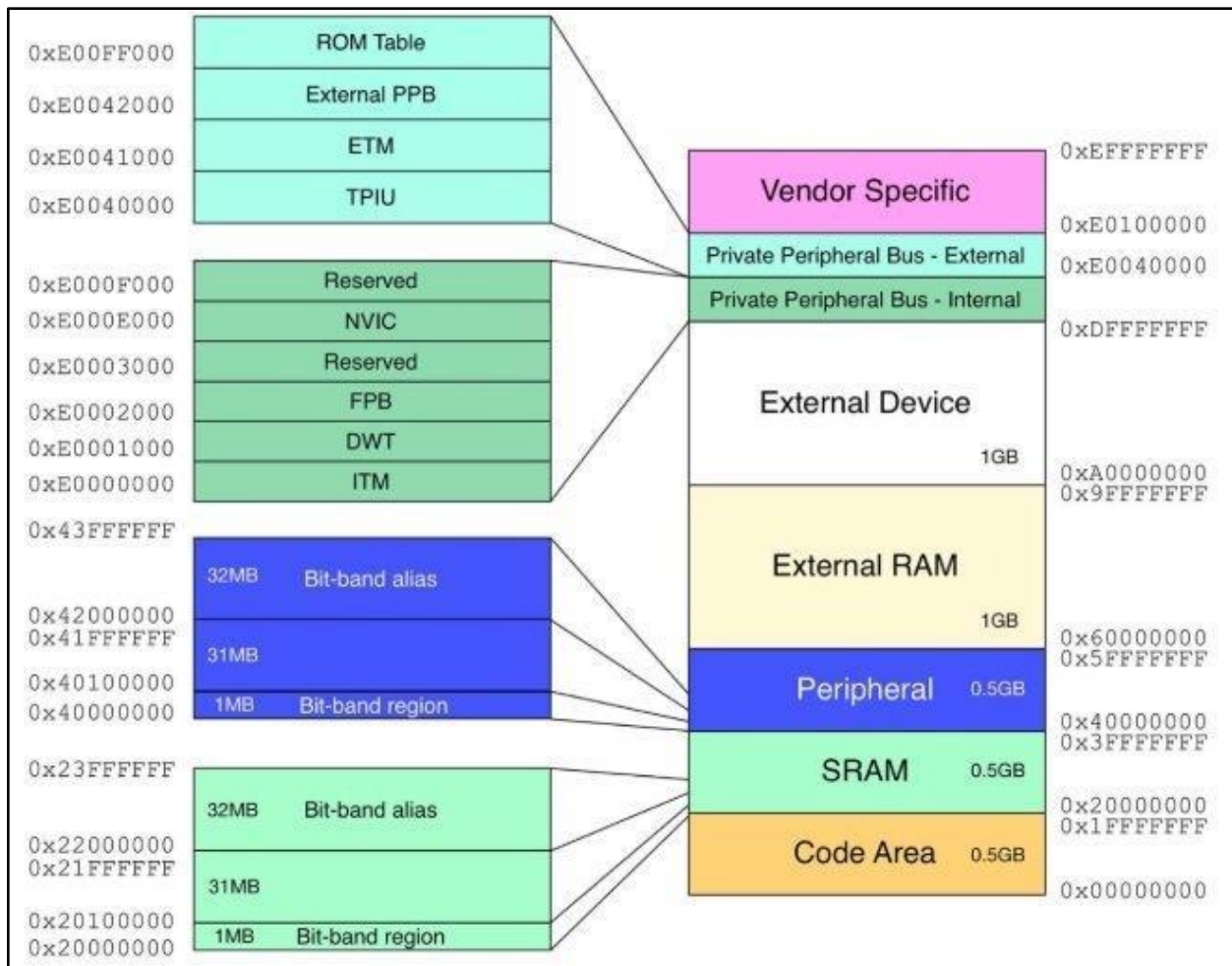
The C language code uses more memory than assembly language code for the same functionality.

Due to the absence of compiler-generated overhead, the assembly language project is more memory-efficient compared to the C

Que 2] Look at the .map file for this project. Explain the memory model of ARM Cortex-M4 with respect to the code memory, data memory, IRQ handlers and peripherals. Explain with the help of a diagram where required.

Ans:

Memory Model of ARM Cortex-M4:



ARM Cortex-M processors use 32-bit processor cores. The number of bits in the processor's design tells us how much memory it can work with.

In the case of ARM Cortex-M4 microcontrollers, they can manage up to 4 gigabytes (4GB) of memory.

The ARM Cortex-M4 architecture has a specific memory model that divides memory into different regions to serve different purposes.

Memory regions are as follows:

The ARM Cortex-M4 has a specific memory model that organizes memory into different regions for various purposes:

1. Code Memory

- The region of code memory is 0x0000_0000 to 0x1FFF_FFFF
- This is where the program code is stored.
- Static initialized data can also be placed here.
- It spans a memory range of 0.5 GB.

2. Data Memory:

- The region of data memory is 0x2000_0000 to 0x3FFF_FFFF
- SRAM (Static Random-Access Memory) is located in this region.
- It is used for temporary data storage, including the heap, stack, and temporary function variables.
- Additionally, this area contains a bit-banded alias and a bit-band region.
- It spans a memory range of 0.5 GB.

3. Peripherals:

- The region allocated for peripherals is 0x4000_0000 to 0x5FFF_FFFF.
- Peripheral registers, such as GPIO (General-Purpose Input/Output) ports, UART (Universal Asynchronous Receiver/Transmitter), I2C (Inter-Integrated Circuit), Timers, and more, are located here.
- These registers control and communicate with various hardware peripherals.
- This region spans 0.5 GB of memory.

4. IRQ Handlers:

- The region allocated for IRQ handlers is Internal memory space from 0xE000E100 to 0xE000ECFF
- IRQ (Interrupt Request) handlers are stored in the NVIC (Nested Vector Interrupt Control) part of memory.
- NVIC maps to the Private Peripheral Bus.
- IRQ handlers manage interrupts, allowing the processor to respond to external events or requests efficiently.

5. External RAM:

- This part of memory, from 0x6000.0000 to 0x9FFF.FFFF.
- This is used for connecting and using things like SD cards or external flash drives.

Reference:

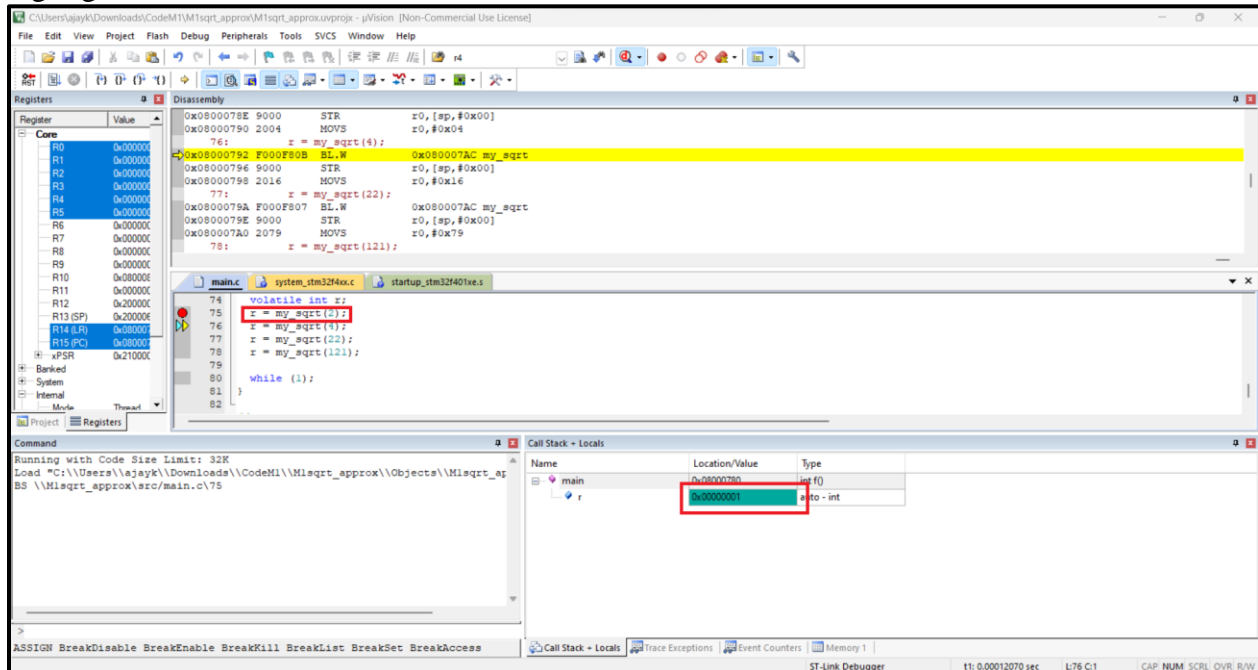
[Cortex m4 architecture](#) : Above used memory model diagram.

[Cortex-M4 reference Manual](#) : Explanation of memory model.

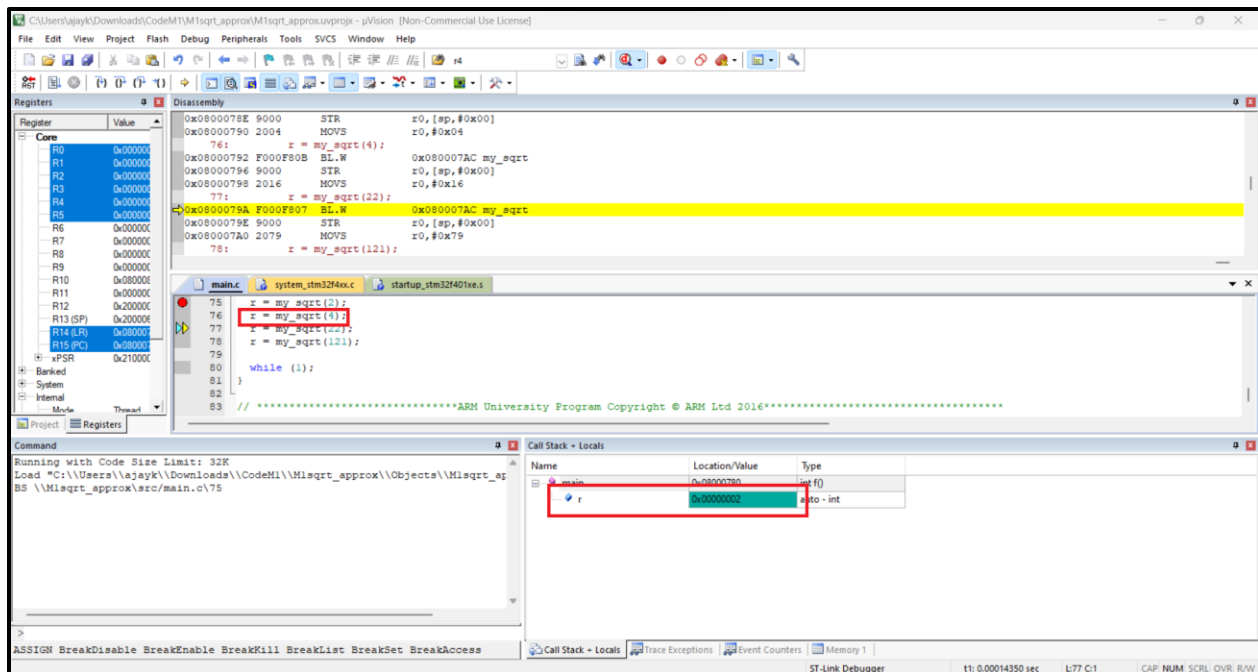
Que 3] Test your code with these inputs: 2, 4, 22, and 121. Record the results.

Ans:

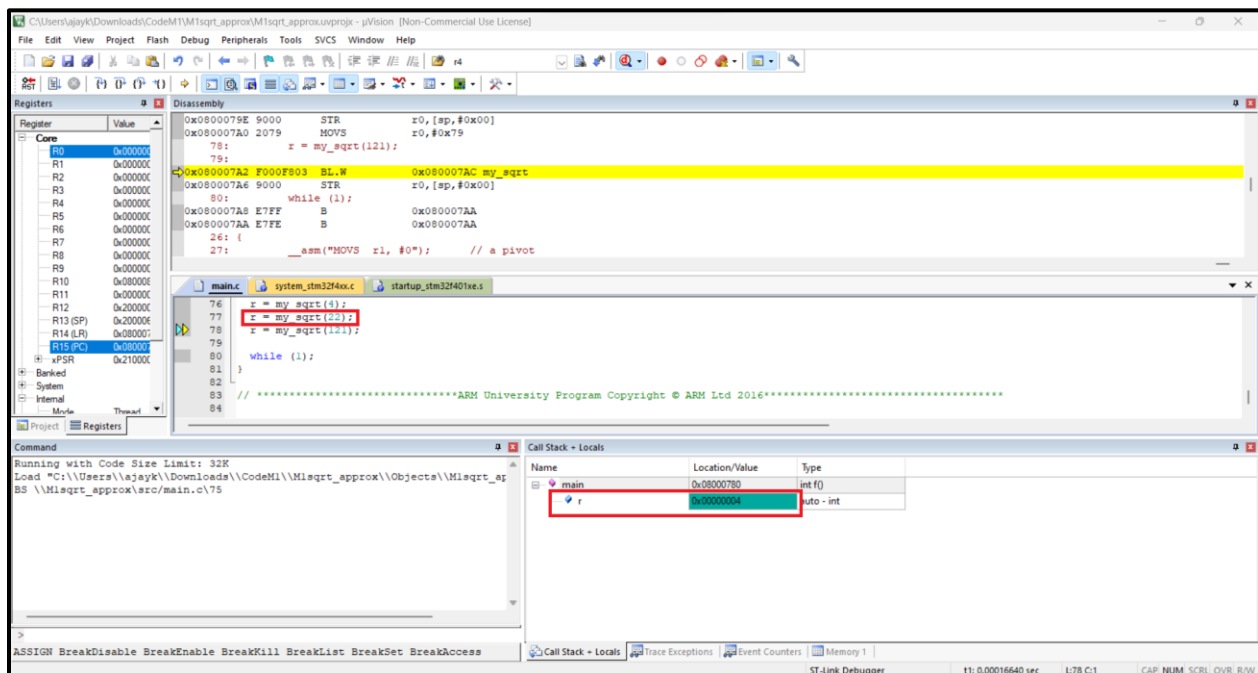
For input **2**, we get a square root approximation in integer as **1** as indicated in variable **r** highlighted below.



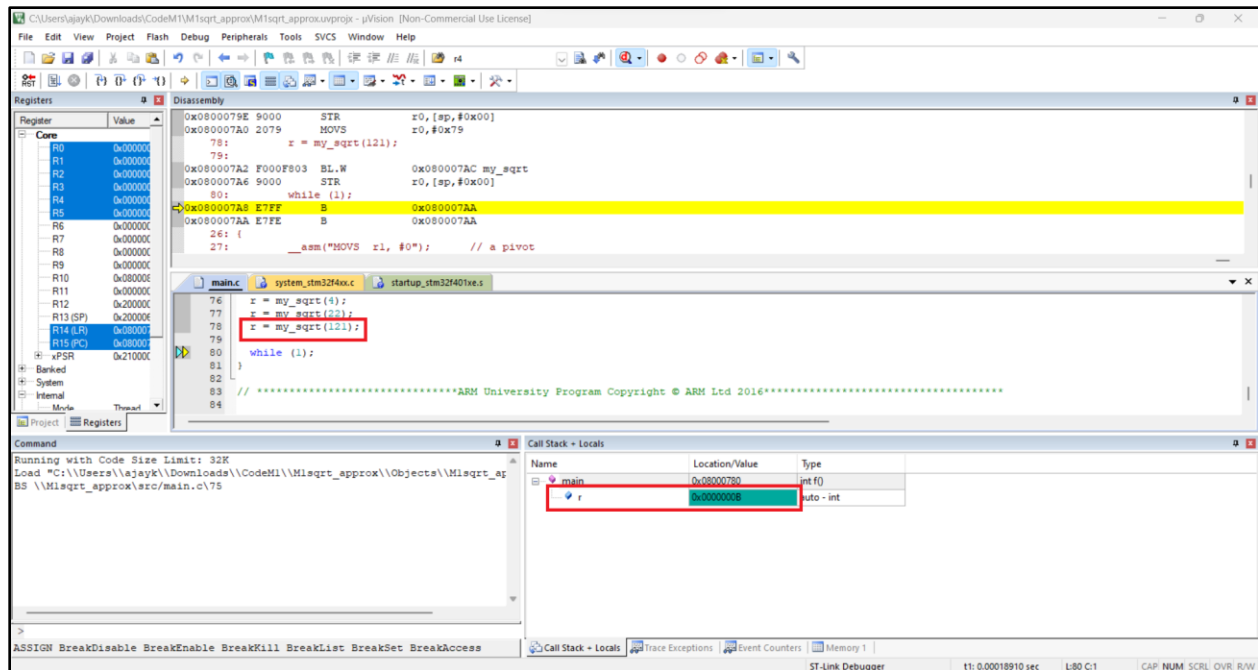
For input **4**, we get a square root approximation in integer as **2** as indicated in variable **r** highlighted below.



For input **22**, we get a square root approximation in integer as **4** as indicated in variable **r** highlighted below.



For input **121**, we get square root approximation in integer as **0x0B**, which equates to **11** in decimal as indicated in variable **r** highlighted below.



Que 4] Estimate the number of CPU cycles used for this calculation.

Estimate the number of CPU cycles used for this calculation and the size of the code in memory.

Ans:

The following analysis is done to approximate the number of CPU cycles:

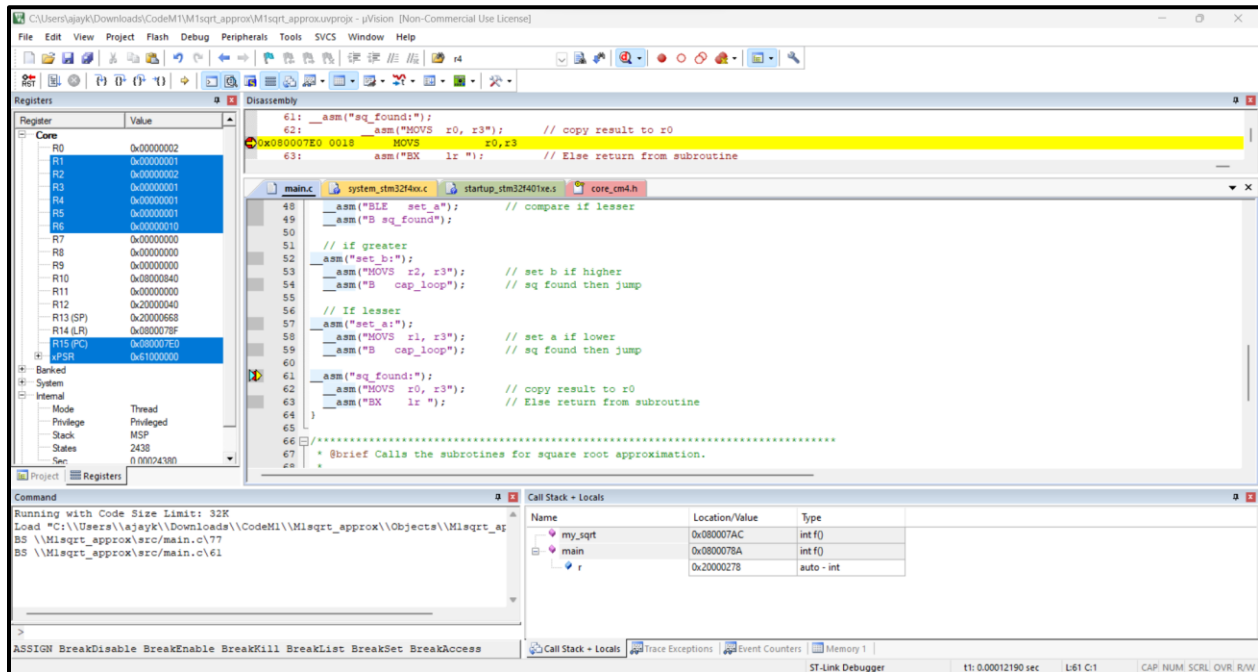
To count the number of loop iterations, r6 is used, and the code is modified the r6 to increment inside the loop.

- **Three instructions** for setting the a, b, and c pivots initially.
- In the loop, **ten instructions** when a and b pivots are being set during approximation.
- **Seven instructions** when the previous approximation matches the current approximation and exit the loop.
- **One instruction** to copy the approximated square root value to r0.

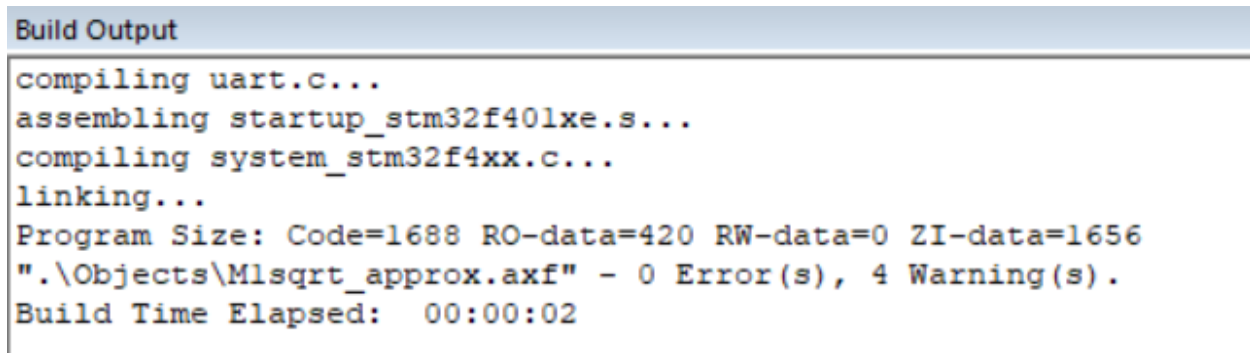
Below is the screenshot when running the square root approximation for input **2**. As indicated, the r6 value (loop iterations) is 0x10, which in decimal is 16.

- In 16 iterations, 15 iterations are used for adjusting a and b pivots. Hence, the total CPU cycles used during this is $15 * 10 = 150$
- The last iteration is used to exit the loop, which takes **seven** instructions.
- Also, 4 total instructions are used to set the pivot values at the beginning and copy the result to r0.

In total, **161 CPU cycles** are used while approximating the square root for input 2.



The code uses 1688 bytes of code memory with optimization set to -O0 as shown below.



Que 3] Auto-generate documentation using Doxygen. Provide either an HTML directory or PDF file documenting your codebase.

Ans: Generated doxygen is included in the .zip submission.

Appendix

1. M1String.c code :

```
/*
 * @file_name : main.c
 *
 * @authors : Kshitija Dhondage
 *
 * @brief : This file contains the main, my_strcpy (string copy),and my_capitalize
(string capitalize) function definitions
 *
 */

/**
 * @brief Copy the string from source to the destination
 *
 * @param[in] *str
 * String pointer (source) from which the string is to be copied.
 *
 * @param[in] *dst
 * String pointer (destination) to which the string is to be copied.
 *
 * @return
 * None
 */
void my_strcpy(const char *src, char *dst)
{
    char *dst_ptr = dst;
    char *src_ptr = (char*)src;

    do {
        *dst_ptr = *src_ptr;
        src_ptr++;
        dst_ptr++;
    } while (*src_ptr != '\0');
}

/**
```

```

* @brief Convert the string to the uppercase.
*
* @param[in] *str
* String pointer pointing to the string that is to be converted to the uppercase.
*
* @return
* None
*/
void my_capitalize(char *str)
{
    int i = 0;

    while (str[i]) {
        if (str[i] >= 'a' && str[i] <= 'z')
            str[i] = str[i] - 'a' + 'A';

        i++;
    }
}

/**
* @brief Main function Entry point function
*
* @param[in] Void
*
* @return
* int
*/
int main(void)
{
    const char a[] = "Hello world!";
    char b[20];

    my_strcpy(a, b);
    my_capitalize(b);

    while (1);
}

*****

```

1. M1sqrt_approx code:

```
/******  
*****  
  
* @file   main.c  
  
* @brief  Code for Project 1 Module 1 Square root approximation  
  
* @version v1.00  
  
* @date   25, September, 2023  
  
* @author  Ajay Kandagal (ajka9053@colorado.edu)  
  
*  
  
* @details Contains ARM assembly subroutines for square root approximation using  
*          bisection method.  
  
*****  
*****/  
  
  
/******  
*****  
  
* @brief  Assembly subroutine for integer square root approximation.  
  
*  
  
* @details The logic uses the Bisection Method for square root approximation. The  
* size of the registers is assumed to be 32-bit for setting the upper pivot. The  
* approximation runs as long as the exact square root is found or the previously  
* approximation is the same as the current approximation.  
  
*  
  
* @param  sq_number Number for which square root needs to be calculated.  
  
*  
  
* @return Returns integer approximated square root value.  
  
*  

```

```

*****
*****/

__attribute__((naked)) int my_sqrt(int sq_number)
{
    __asm("MOVS r1, #0");           // a pivot
    __asm("MOV r2, #46431"); // b-pivot: Max possible sqrt for 32-bit unsigned
int
    __asm("MOVS r3, #-1");          // c pivot

    __asm("cap_loop:");
        __asm("MOVS r4, r3");          // c prev

        __asm("ADD r3, r1, r2"); // add a_pivot and b_pivot
        __asm("LSR r3, r3, #1"); // divide by 2

        __asm("MUL r5, r3, r3"); // square

        __asm("CMP r4, r3"); // check if old approximation is same new
approximation
        __asm("BNE set_pivots");
        __asm("B sq_found");

    __asm("set_pivots:");
        __asm("CMP r5, r0"); // check if equal to given number
        __asm("BHI set_b"); // compare if greater
        __asm("BLE set_a"); // compare if lesser
        __asm("B sq_found");

        // if greater

```



```

__asm("set_b:");
    __asm("MOVS r2, r3");        // set b if higher
    __asm("B cap_loop");

    // If lesser
__asm("set_a:");
    __asm("MOVS r1, r3");        // set a if lower
    __asm("B cap_loop");

__asm("sq_found:");
    __asm("MOVS r0, r3");        // copy result to r0
    __asm("BX lr");             // return from subroutine
}

/*****
*****

* @brief Calls the subroutines for square root approximation.
*
* @details The function tests the square root subroutines by passing some sample
* values. The square root approximated value can be monitored using the debugger and
* adding break points at subroutine calls.
*

*****/

int main(void)
{
    volatile int r;
    r = my_sqrt(2);

```

```
    r = my_sqrt(4);  
    r = my_sqrt(22);  
    r = my_sqrt(121);  
  
    while (1);  
}
```

```
// *****ARM University Program Copyright © ARM  
Ltd 2016*****
```