

Dijkstra's algorithm to compute
shortest path through a graph

→ class Network:

def __init__(self, nodes):

self.v = nodes

self.graph = [[0 for column in range(nodes)]
for row in range(nodes)]

def printTable(self, dist, src, path):

print("Shortest Path Table of {0}".format(chr(ord('A') + src)))

for node in range(self.v):

print("{0}\t{1}\t{2}".format(chr(ord('A') + node),
dist[node], path[node]))

def minDistance(self, dist, sptSet):

min = sys.maxsize

for v in range(self.v):

if dist[v] < min and sptSet[v] == False:

min = dist[v]

min_index = v

return min_index

def dijkstra(self, src):

dist = [sys.maxsize] * self.v

dist[src] = 0

sptSet = [False] * self.v

path = {}

for _ in range(self.v):

path[_] = []

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for cout in range(self.V):
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    u = self.minDistance(dist, sptSet)
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    sptSet[u] = True
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    for v in range(self.V):
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        if self.graph[u][v] > 0 and sptSet[v] == False and
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            dist[v] > dist[u] + self.graph[u][v]:
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                dist[v] = dist[u] + self.graph[u][v]
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        if u == src:
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            path[v].append(chr(ord('A') + v))
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        else:
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```
            path[v].append(chr(ord('A') + u))
```

```
            path[v].append(chr(ord('A') + v))
```

```
self.printTable(dist, src, path)
```