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# Kshitij Dwivedi

# Research Interests

o Computer vision, Computational neuroscience, Transfer learning, Interpretability

#### Education

**PhD** in Computer Science, Expected graduation year (2022).

2020-2022 Goethe University of Frankfurt am Main, Germany (moved with supervisor).

Supervisor: Dr. Gemma Roig .

2018–2019 Singapore University of Technology & Design, Singapore.

Supervisor: Dr. Gemma Roig .

M. Tech in Electrical Engineering.

2009–2014 Indian Institute of Technology, Kanpur, India.

B. Tech in Electrical Engineering.

2009–2014 Indian Institute of Technology, Kanpur, India.

# Research Experience

July-Sep, Research Intern (remote), Allen Institute for AI, Seattle, USA.

2021 Interpreting representations learned by navigation agents (CVPR 22)

2019-present **Visiting student**, *FU*, Berlin, Germany, Supervisor: Dr. Radoslaw Martin Cichy.

Modeling human visual system to explain fMRI, EEG responses

(Co-organized challenge to predict human brain responses: Algonauts 19, Algonauts 21)

2018-present **PhD Student**, Supervisor: Dr. Gemma Roig.

Applying computer vision to understand human visual system (JoCN 20, PLOS CB 21), Transfer learning (CVPR 19, ECCV 20)

2017–2017 Research Engineer, ATR, Kyoto, Japan, Supervisor: Dr. Yukiyasu Kamitani.

Reconstruction of perceived images from brain activity using deep learning and GAN

(Frontiers in Computational Neuroscience, 19)

2014–2017 **Senior Software Engineer**, Samsung R&D Institute India, Bangalore.

Computer Vision applications (e.g. segmentation, tracking) for Samsung smartphone cameras (US Patent on segmentation, Tracking paper, Saliency paper)

2012-2012 Intern, Mercedes-Benz Research & Development North America, Palo Alto, USA.

Vehicle detection for driver assistance functions

#### **Achievements**

- o Selected as Lead TA in Neuromatch Academy summer school, 2020
- Selected to attend Brain, Minds and Machines (BMM) summer school 2019
- SUTD President's Graduate Fellowship (January, 2018 July, 2019)
- o First place in LSUN Saliency Challenge, CVPR 2016.

# Technical Skills

Programming Python, C, C++, Matlab.

Frameworks pytorch, tensorflow, caffe, torch.

#### **Publications**

- [1] **K. Dwivedi**, G. Roig, A. Kembhavi, and R. Mottaghi, "What do navigation agents learn about their environment?," in *Computer Vision and Pattern Recognition (CVPR)*, 2022.
- [2] M. Graumann, C. Ciuffi, **K. Dwivedi**, G. Roig, and R. M. Cichy, "The spatiotemporal neural dynamics of object location representations in the human brain," *Nature Human Behaviour*, pp. 1–16, 2022.
- [3] **K. Dwivedi**, M. F. Bonner, R. M. Cichy, and G. Roig, "Unveiling functions of the visual cortex using task-specific deep neural networks," *PLOS Computational Biology*, 2021.
- [4] R. M. Cichy, **K. Dwivedi**, B. Lahner, A. Lascelles, P. lamshchinina, M. Graumann, A. Andonian, N. A. R. Murty, K. Kay, G. Roig, and A. Oliva, "The Algonauts Project 2021 Challenge: How the Human Brain Makes Sense of a World in Motion," *arXiv*, 2021.
- [5] K. Dwivedi, J. Huang, R. M. Cichy, and G. Roig, "Duality diagram similarity: a generic framework for initialization selection in task transfer learning," in *European Conference* on Computer Vision (ECCV), 2020.
- [6] **K. Dwivedi**, R. M. Cichy\*, and G. Roig\*, "Unravelling representations in scene-selective brain regions using scene parsing deep neural networks," *Journal of Cognitive Neuroscience*, 2020 (\* jointly supervised work).
- [7] **K. Dwivedi** and G. Roig, "Representation similarity analysis for efficient task taxonomy and transfer learning," in *Computer Vision and Pattern Recognition (CVPR)*, 2019.
- [8] R. M. Cichy, G. Roig, A. Andonian, K. Dwivedi, B. Lahner, A. Lascelles, Y. Mohsenzadeh, K. Ramakrishnan, and A. Oliva, "The Algonauts Project: A Platform for Communication between the Sciences of Biological and Artificial Intelligence," Conference on Cognitive Computational Neuroscience (CCN), 2019.
- [9] G. Shen\*, **K. Dwivedi\***, K. Majima, T. Horikawa, and Y. Kamitani, "End-to-end deep image reconstruction from human brain activity," *Frontiers in Computational Neuroscience*, 2019 (\* equal contribution).
- [10] J. Huang, **K. Dwivedi**, and G. Roig, "Deep anchored convolutional neural networks," in Computer Vision and Pattern Recognition Workshops (CVPRW) on Compact and Efficient Feature Representation and Learning (CEFRL), 2019.
- [11] K. Dwivedi, N. Singh, S. Shanmugham, and M. Kumar, "Deepattent: Saliency prediction with deep multiscale residual network," in Proceedings of International Conference on Computer Vision and Image Processing (CVIP), 2018
  (1st place in LSUN Saliency Challenge, CVPR 2016).

- [12] **K. Dwivedi**, P. Prabhudesai, and S. R. Shanmugam, "A hybrid method for long term moving object tracker," in *Signal Processing and Communications (SPCOM)*, 2016 International Conference on, pp. 1–5, IEEE, 2016.
- [13] B. Ghosh and **K. Dwivedi**, "Micromagnetic analysis of a double-barrier synthetic antiferromagnetic mtj stack," *Applied Nanoscience*, vol. 5, no. 7, pp. 771–775, 2015.
- [14] B. Ghosh and **K. Dwivedi**, "Micromagnetic analysis of heusler alloy-based perpendicular double barrier synthetic antiferromagnetic free layer mtjs," *Journal of Theoretical and Applied Physics*, vol. 9, no. 3, pp. 207–212, 2015.

#### **Talks**

- Estimating Transfer learning performance using Representational Similarity, Samsung Research Institute, Bangalore, 2022
- What can Representational Similarity tell us about the Human Visual Cortex and Transfer Learning? , Allen Institute for Artificial Intelligence (AI2), Seattle, 2022
- From the functional mapping of the visual cortex to transfer learning using Representational Similarity, Facebook Reality Labs, New York, 2021
- Estimating Transfer learning performance using Representational Similarity, FiveAI, Oxford, 2021
- Estimating Transfer learning performance using Representational Similarity, Google Brain, Toronto, 2021
- Algonauts 2021: hands-on tutorial on development kit for challenge participation, CCN 2021 Algonauts session
- Algonauts 2021: How the Human Brain Makes Sense of a World in Motion, OHBM 2021 Brainhack
- Unveiling low-level to high-level functions of visual cortex using task-specific deep neural networks, TeaP 2021 Symposium on developments in deep neural network models of perception: From low- to high-level vision

# Conference and Workshop abstracts

- M.P. Balode, K. Dwivedi, G. Roig, R.M. Cichy, "Unraveling the temporal cortical dynamics of indoor scene navigation using behavioral and deep neural network models", Society for Neuroscience, 2021.
- **K. Dwivedi**, M.F. Bonner, R.M. Cichy, G. Roig, "Unveiling functions of visual cortex using task-specific deep neural networks", Neuromatch 2.0, 2020.
- K. Dwivedi, M.F. Bonner, G. Roig, "Explaining Scene-selective Visual Area Using Task-specific and Category-specific DNN Units", Vision Science Society, 2019.
- **K. Dwivedi**, G. Roig, "Importance of object selection in Relational Reasoning tasks", NeurIPS Workshop on Relational Representation Learning, 2018.
- K. Dwivedi, G. Roig, "Evaluation of plug and play modules for multi-domain learning", ECCV workshop on Interactive and Adaptive Learning, 2018.

#### Supervision

FU Berlin Bachelor's Thesis, Marta Paula Balode, Raphael Leuner, Martin Pflaum.

Master's Thesis, Andrei Kitaitsev, Vanshika Bawa.

GU Frankfurt Bachelor's Thesis, Domenic Bersch, Quang Anh Le Hong.

# Master's Thesis, Daniel Pietschmann, Yannic Vorpahl.

# Teaching

- o Lead TA, Neuromatch Academy Summer School 2020
- o TA, Multivariate EEG online course 2020, University of Granada
- o TA, Computer Vision 2020-21, Goethe University Frankfurt
- o TA, Data structure and algorithms 2013, IIT Kanpur