report

January 23, 2025

1 Report Outlab02: Lagrange Interpolation

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1.1 Code

This is the code that is used to analyze and generate the plots

1.1.1 Imports

```
[2]: import math
import pathlib

import pandas as pd
import numpy as np
import matplotlib.pyplot as plt
import matplotlib.gridspec as gridspec
```

1.1.2 Functions

```
[3]: def f(x):
    '''Function of interest'''
    return np.exp(x)

def f_n_plus_1(x):
    '''(n + 1)th derivative of f(x)'''
    return np.exp(x)

def M_n_plus_1(x):
    '''Absolute value of f^(n+1)'th largest value over the interval'''
    return np.max(np.abs(f_n_plus_1(x)))

def pi_n_plus_1(x, xi: np.array):
    return np.prod(x[:, np.newaxis] - xi, axis=1)
```

```
def B(x, xi):
    '''Error bound'''
    n = len(xi)
    return M_n_plus_1(x) * np.abs(pi_n_plus_1(x, xi)) / math.factorial(n)
```

1.1.3 Helper Functions

```
[4]: DATADIR = pathlib.Path(f'./data/')

def get_data(n: int) -> tuple[pd.DataFrame, pd.DataFrame]:
    datadir = DATADIR / f'n{n}'
    dfi = pd.read_csv(datadir / 'input.csv')
    dfo = pd.read_csv(datadir / 'output.csv')

# Get absolute error
dfo['|E(x)|'] = np.abs(dfo['E(x)'])

# Get error bound
dfo['B(x)'] = B(dfo.x.values, dfi.x.values)

return dfi, dfo
```

```
[7]: def plot_lagrange(dfi: pd.DataFrame, dfo: pd.DataFrame, n: int) -> None:
         fig = plt.figure(tight_layout=True)
         gs = gridspec.GridSpec(4, 1)
         # Plot the function and the Lagrange Interpolation Polynomial
         ax1 = fig.add subplot(gs[:3, 0])
         ax1.set_title(fr'$f(x)=\ensuremath{\mbox{exp}(x)}, n={n}, m=100$')
         ax1.scatter('x', 'y', data=dfi, label='$y_i = f(x_i)$', c='red', marker='s')
         ax1.plot('x', 'f(x)', data=dfo, label='$f(x)$')
         ax1.plot('x', 'L(x)', data=dfo, label=f'p_{n-1}(x))
         ax1.legend()
         ax1.tick_params(
             axis='x',
                               # changes apply to the x-axis
             which='both', # both major and minor ticks are affected
             labelbottom=False
         )
         # Plot Absolute Error and Error Bound
         ax2 = fig.add subplot(gs[3, 0], sharex=ax1)
         ax2.plot('x', '|E(x)|', data=dfo, label=r'$\text{Err}(x)=|p_{%d} - f(x)|$'u
      \Rightarrow% (n - 1), c='C2')
```

```
ax2.legend()
ax2.set_xlabel('$x$')

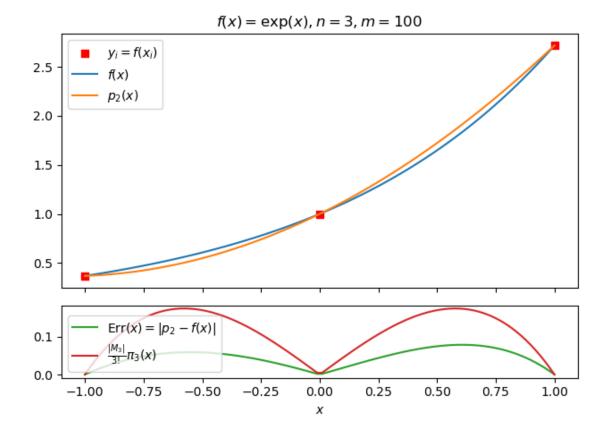
ax2.plot('x', 'B(x)', data=dfo, c='C3', label=r'$\frac{|M_{%d}|}{%d!}

\[
\delta\]\pi_{\dd}(x)\$' % (n, n, n))
ax2.legend()
ax2.set_xlabel('\$x\$')

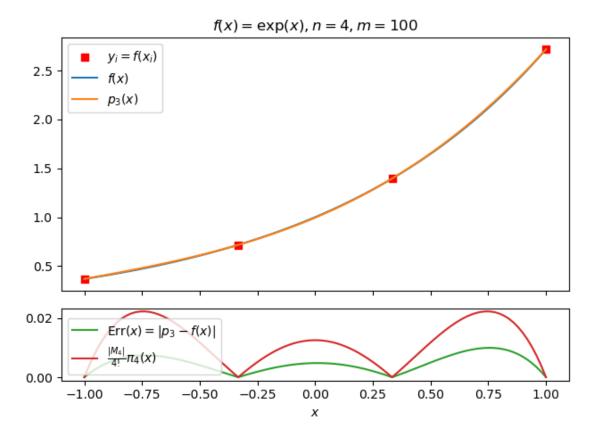
plt.savefig(DATADIR / f'n{n}' / 'plot.png')
plt.show()
```

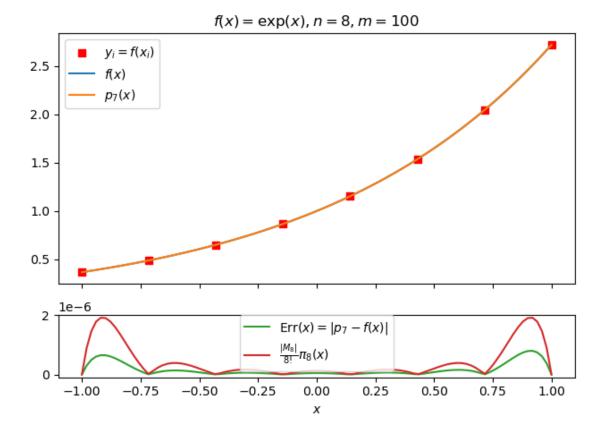
1.2 Plots

```
[8]: n = 3
dfi, dfo = get_data(n)
plot_lagrange(dfi, dfo, n)
```



```
[9]: n = 4
dfi, dfo = get_data(n)
plot_lagrange(dfi, dfo, n)
```





1.3 Notes and Remarks

As we can see from the graphs above as n increases the interpolation error decreases. This can be observed by looking at the lower part of each plot, where the maximum value on he y axis is ≈ 1.5 for n=3, ≈ 0.02 for n=4, and 2×10^{-6} for n=8. The n=3 case is not enough to provide a good approximation for the function. However, just increasing the number of interpolated points to n=4 already gives a workable approximation.