02-512 Assignment 06

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1

(a) The variables we are trying to find are the rate of infection, λ_1 and the rate of recovery, λ_2.

We can run the CTMM as a simulation and compare it with real data. The output of the simulation will be sequence of states over time where each state will be (S_t, I_t, R_t).

Let (Sr_t, Ir_t, Rr_t) be the real data. One possible objective function to minimize is

$$L(\lambda_1, \lambda_2) = \sum_{realdatapoints} (S_t - Sr_t)^2 + (I_t - Ir_t)^2 + (R_t - Rr_t)^2$$

You can use steepest/gradient descent, Newton-Raphson's method, or a similar algorithm to find parameters yielding a local minimum. Rather than analytically computing the gradient, you'd have to approximate it using finite difference methods. Performance may be a concern, depending on how long the simulation has to run for.

(b) Let G be the growth rate, x_1 be the conc of nutrient 1 x_2 be the conc of nutrient 2.

$$G = \theta_1 x_1^2 + \theta_2 x_1 + \theta_3 x_2^2 + \theta_4 x_2 + \theta_5$$

Where $\vec{\theta}$ are the parameters we're trying to estimate.

Let $Gr(x_1, x_2)$ be the experimenally determined growth rate.

One possible objective function to minimize is

$$L(x_1, x_2) = \sum (Gr(x_1, x_2) - G(x_1, x_2))^2$$

You can use steepest descent once again, like in part a.

(c) Call parameters we are estimating, f_B and f_b, which are the frequencies of the B allele and b allele respectively.

Let B be the number of people observed with brown eyes, and b be the number of people observed with blue eyes.

The likelihood function is as follows:

$$Pr(B = B, b = b | p = p) =$$

2

(a) Say there are m biomarkers. Let $\vec{\theta}$ be an $m + 1$ dimensional vector of parameters.

Let $\mu = \theta_{m+1} + \sum_{i=1}^{m} \theta_i x_i$ in the following

$$L(\mu, \sigma^2; \theta) = \frac{1}{2\pi\sigma^2} \left(\frac{1}{e} \right)^{\frac{\sum_{i=1}^{n}(x_i - \mu)^2}{2\sigma^2}}$$

(b) Say there are m biomarkers. Let $\vec{\theta}$ be an $2m + 1$ dimensional vector of parameters. Let $\mu = \theta_{2m+1} + \sum_{i=1}^{m} \theta_i x_i^2 + \sum_{i=m+1}^{2m} \theta_i x_i$ in the same likelihood function from part a.

(c) Performance, over/underfitting.

(d)

Each state in the markov model represents a parameter configuration. For some state, each neighbor represents the same configuration, either plus or minus Δ in one parameter (for all parameters). Thus the graph is a complete graph where any state connects to two times the number of parameters other states.

First note that given any two adjacent states q_i, q_j,

$$\frac{\pi_j}{\pi_i} = \frac{Pr(data|q_j)}{Pr(data|q_i)} = \left(\frac{1}{e} \right)^{\frac{\sum_{i=1}^{n}(x_i - \mu(q_j))^2 - \sum_{i=1}^{n}(x_i - \mu(q_i))^2}{2\sigma^2}}$$

Where $\mu(q_i)$ is the μ calculated as described in part a, for the parameters represented by q_i.

Then one iteration is as follows (starting at some state q_i)

1. Pick a random neighbor state q_j,

2. If $\frac{\pi_j}{\pi_i} \geq 1$ then move to q_j.

3. If $\frac{\pi_j}{\pi_i} < 1$ then with probability move to q_j with that probability, else stay in q_i.

(e) Solving is easier to do in this case because it's more straightforward and the problem is tractable. There may be cases where it's not so easy to solve. Then Sampling makes more sense.

3

Given two points $(t1, x1), (t2, x2)$, the eqn of a line for general t, x is as follows:

$$t - t2 = (x2 - x1)/(t2 - t1) * (x - x2)$$

The the following is the piecewise linear function interpolation, found by plugging in values from the table into the above equation:

If $0 \leq t < 2$, $t - 2 = (5/2)(x - 5)$
If $2 \leq t < 5$, $t - 5 = ((6 - 5)/(5 - 2))(x - 6)$
If $5 \leq t < 8$, $t - 8 = ((10 - 6)/(8 - 5))(x - 10)$
If $8 \leq t \leq 10$, $t - 10 = ((20 - 10)/(8 - 10))(x - 20)$

(b) Let $(t_1, x_1) = (0, 0), (t_2, x_2) = (2, 5), ..., (t_5, x_5) = (10, 20)$

Let $[5]$ be short notation for $1, 2, 3, 4, 5$.

Then:

$$x = \sum_{i=1}^{5} \frac{\prod_{j \in [5]: j \neq i}(t - t_j)}{\prod_{j \in [5]: j \neq i}(t_i - t_j)} x_i$$

(c) We have 4 quadratic equations of the form

$$S_{i,i+1}(t) = c_{i,0} + c_{i,1}t + c_{i,2}t^2$$

for $i = 1$ to $i = 4$. The derivative of each equation is of the form

$$\frac{dS_{i,i+1}}{dt} = c_{i,1} + 2c_{i,2}t$$

.

Given the constraints of the problem, we can solve for all $3 * 4 = 12$ parameters by expressing the constraints as equations:

$S_{1,2}(0) = 0$
$S_{1,2}(2) = 5$

$S_{2,3}(2) = 5$
$S_{2,3}(5) = 6$

$S_{3,4}(5) = 6$
$S_{3,4}(8) = 10$

$S_{4,5}(8) = 10$
$S_{4,5}(10) = 20$

Constraints for the derivative continuity:

$\frac{dS_{1,2}}{dt}(2) = \frac{dS_{2,3}}{dt}(2)$

$\frac{dS_{2,3}}{dt}(5) = \frac{dS_{3,4}}{dt}(5)$

$\frac{dS_{3,4}}{dt}(8) = \frac{dS_{4,5}}{dt}(8)$

Additional constraint:

$\frac{dS_{1,2}}{dt}(0) = 0$

Now we have 12 parameters and 12 constraints, we represent it as a linear system and solve using a gaussian elimination.

(Let $(t_1, x_1) = (0, 0), (t_2, x_2) = (2, 5), ..., (t_5, x_5) = (10, 20)$)

$$
\begin{bmatrix}
1 & t_1 & t_1^2 & & & & & & & & & \\
1 & t_2 & t_2^2 & & & & & & & & & \\
0 & 1 & 2t_2 & 0 & -1 & -2t_2 & & & & & & \\
& & & 1 & t_2 & t_2^2 & & & & & & \\
& & & 1 & t_3 & t_3^2 & & & & & & \\
& & & 0 & 1 & 2t_3 & 0 & -1 & -2t_3 & & & \\
& & & & & & 1 & t_3 & t_3^2 & & & \\
& & & & & & 1 & t_4 & t_4^2 & & & \\
& & & & & & 0 & 1 & 2t_4 & 0 & -1 & -2t_4 \\
& & & & & & & & & 1 & t_4 & t_4^2 \\
& & & & & & & & & 1 & t_5 & t_5^2 \\
0 & 1 & 2t_1 & & & & & & & & &
\end{bmatrix}
\begin{bmatrix}
c_{1,0} \\ c_{1,1} \\ c_{1,2} \\ c_{2,0} \\ c_{2,1} \\ c_{2,2} \\ c_{3,0} \\ c_{3,1} \\ c_{3,2} \\ c_{4,0} \\ c_{4,1} \\ c_{4,2}
\end{bmatrix}
=
\begin{bmatrix}
x_1 \\ x_2 \\ 0 \\ x_2 \\ x_3 \\ 0 \\ x_3 \\ x_4 \\ 0 \\ x_4 \\ x_5 \\ 0
\end{bmatrix}
$$

This solves to:

$$
\vec{c} =
\begin{bmatrix}
0 \\
0 \\
5/4 \\
-40/3 \\
31/3 \\
-4/3 \\
160/3 \\
-49/3 \\
4/3 \\
-160 \\
37 \\
-2
\end{bmatrix}
$$

4

(a)

If b_i is 0, there are no boojum on island i. Based on this observation, we note the following:

$$
Pr(b_i = 0|f) = (1 - f)^{s_i}
$$
$$
Pr(b_i = 1|f) = 1 - Pr(b_i = 0|f) = 1 - (1 - f)^{s_i}
$$
$$
Pr(b|f) = \prod_{i=1}^{n} Pr(b_i = b_i)
$$

(b)

$$
\hat{f} = \frac{\sum_{i=1}^{n} y_i}{\sum_{i=1}^{n} s_i}
$$

(c)

$$E[y_i] = b_i * \hat{f} * s_i$$

(d)

Submitted online

(e)

TODO

$$E[y_i] = b_i * \hat{f} * s_i$$