

List of topics in this lecture

- All Runge-Kutta methods are stable. All consistent RK methods are convergent.
 - Linear multi-step methods (LMM), general design, general form
 - Polynomial interpolation, order of accuracy of interpolation
 - Construction of Adams methods
 - Orders of accuracy of Adams-Bashforth methods and Adams-Moulton methods
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Stability of Runge-Kutta methods

Consider an explicit Runge-Kutta method:

$$k_i = h f \left(u_n + \sum_{j=1}^{i-1} a_{ij} k_j, t_n + c_i h \right), \quad i = 1, \dots, p$$

$$u_{n+1} = u_n + \sum_{i=1}^p b_i k_i$$

We write it in terms of numerical operator.

$$u_{n+1} = L_{num}(u_n), \quad \text{where } L_{num}(u_n) = u_n + h\psi(u_n, t_n)$$

In general, $\psi(u, t)$ is Lipschitz continuous when $f(u, t)$ is Lipschitz continuous.

$$|\psi(u, t) - \psi(v, t)| \leq C_L |u - v|$$

It follows that the Runge-Kutta method is stable.

$$\begin{aligned} |L_{num}(u_n) - L_{num}(v_n)| &\leq |u_n - v_n| + |h\psi(u_n, t_n) - h\psi(v_n, t_n)| \\ &\leq (1 + C_L h) |u_n - v_n| \end{aligned}$$

Example:

Euler method:

$$u_{n+1} = u_n + hf(u_n, t_n) \equiv u_n + h\psi(u_n, t_n)$$

$$\Rightarrow \psi(u, t) = f(u, t)$$

Therefore, ψ and f have the same Lipschitz continuity.

Heun's method:

$$u_{n+1} = u_n + \frac{h}{2} \left[f(u_n, t_n) + f(u_n + hf(u_n, t_n), t_n + h) \right] \equiv u_n + h\psi(u_n, t_n)$$

$$\Rightarrow \psi(u, t) = \frac{1}{2}f(u, t) + \frac{1}{2}f(u + hf(u, t), t + h)$$

Suppose f is Lipschitz continuous.

$$\begin{aligned} & |\psi(u, t) - \psi(v, t)| \\ & \leq \frac{1}{2} |f(u, t) - f(v, t)| + \frac{1}{2} |f(u + hf(u, t), t + h) - f(v + hf(v, t), t + h)| \\ & \leq \frac{1}{2} C_L |u - v| + \frac{1}{2} C_L |(u - v) + h(f(u, t) - f(v, t))| \\ & \leq C_L |u - v| + \frac{h}{2} C_L |f(u, t) - f(v, t)| \\ & \leq C_L |u - v| + \frac{h}{2} C_L^2 |u - v| = \left(C_L + \frac{h}{2} C_L^2 \right) |u - v| \end{aligned}$$

$$\Rightarrow \psi \text{ is Lipschitz continuous.}$$

Conclusion: All explicit Runge-Kutta methods are stable.

We will see that implicit Runge-Kutta methods have even better stability.

Therefore, all consistent Runge-Kutta methods are convergent!

Advantage and disadvantage of Runge-Kutta methods

Advantage:

It is single-step. Given u_0 , it requires no additional condition to get started.

We can change time step at any step.

Disadvantage:

“p-stage” means each time step requires p evaluations of function $f(u, t)$. If this function evaluation is computationally expensive, the method is slow.

Next we study multi-step methods, which require only 1 function evaluation per time step.

Linear Multi-step Methods (LMM)

The general picture:

Start with given $u(t)$ at r time levels $\{t_n, t_{n+1}, \dots, t_{n+r-1}\}$.

To calculate $u(t)$ at t_{n+r} , we use

- a linear combination of $u(t)$ at time levels $\{t_n, t_{n+1}, \dots, t_{n+r-1}\}$,
- a linear combination of $f(u(t), t)$ at time levels $\{t_n, t_{n+1}, \dots, t_{n+r-1}\}$, and
- possibly $f(u(t), t)$ at time level t_{n+r}

If $f(u(t), t)$ at t_{n+r} is used, the method is implicit.

Repeat the process with $u(t)$ at a new set of r time levels, $\{t_{n+1}, \dots, t_{n+r-1}, t_{n+r}\}$...

The general form:

An r -step linear multi-step method has the form

$$\sum_{j=0}^r \alpha_j u_{n+j} = h \sum_{j=0}^r \beta_j f(u_{n+j}, t_{n+j}), \quad \alpha_r = 1$$

By convention, we set $\alpha_r = 1$.

Remarks:

- Here “linear” means “the RHS of the method is a linear combination of f ”. It does not mean “function f is linear in u ”. In particular, a linear multi-step method can be used to solve a non-linear ODE.
- A linear multi-step method is completely specified by coefficients $\{\alpha_j\}$ and $\{\beta_j\}$.
- It is explicit if and only if $\beta_r = 0$.
- It is a multi-step method if and only if $r > 1$.
- For numerical implementation, we use

$$u_{n+r} = \sum_{j=0}^{r-1} (-\alpha_j) u_{n+j} + h \sum_{j=0}^r \beta_j f(u_{n+j}, t_{n+j})$$

- At each time step, it requires ONLY 1 evaluation of function f .

The Adams methods:

$$u_{n+r} = u_{n+r-1} + h \sum_{j=0}^r \beta_j f(u_{n+j}, t_{n+j})$$

Coefficients $\{\alpha_j\}$ of Adams methods are given by

$$\alpha_j = \begin{cases} 1, & j=r \\ -1, & j=r-1 \\ 0, & j < (r-1) \end{cases}$$

There are two types of Adams methods: explicit and implicit.

Adams-Bashforth methods are characterized by

$$\beta_r = 0 \quad ==> \quad \text{explicit}$$

Adams-Moulton methods are characterized by

$$\beta_r \neq 0 \quad ==> \quad \text{implicit}$$

Now we look at how to construct these Adams methods.

Basic idea of Adams methods:

- Find a polynomial approximation for $f(u(t), t)$, based on values of f at $(s+1)$ time levels, $\{t_n, t_{n+1}, \dots, t_{n+s}\}$. Let $p(t)$ denote the polynomial approximation.
- Integrate the ODE from t_{n+r-1} to t_{n+r} and use the polynomial $p(t)$ to replace $f(u(t), t)$. The relation between r and s will be discussed below.

$$\begin{aligned} u(t_{n+r}) &= u(t_{n+r-1}) + \int_{t_{n+r-1}}^{t_{n+r}} u'(t) dt = u(t_{n+r-1}) + \int_{t_{n+r-1}}^{t_{n+r}} f(u(t), t) dt \\ &\approx u(t_{n+r-1}) + \int_{t_{n+r-1}}^{t_{n+r}} p(t) dt \end{aligned}$$

The Adams methods have the form

$$u_{n+r} = u_{n+r-1} + \int_{t_{n+r-1}}^{t_{n+r}} p(t) dt$$

For explicit Adams methods, we set $r = s + 1$ so that t_{n+r} is not one of the time levels used in polynomial interpolation, $\{t_n, t_{n+1}, \dots, t_{n+s}\}$.

For implicit Adams methods, we set $r = s$. Time level $t_{n+r} = t_{n+s}$ is used in interpolation. As a result, the unknown u_{n+r} also appears on the RHS of the method.

We study the key component in this construction: polynomial interpolation.

Polynomial interpolation:

Given m data points of function $g(x)$:

$$\{x_j, y_j\}, \quad j = 1, 2, \dots, m$$

where $y_j = g(x_j)$.

Goal: Find a polynomial of degree $(m-1)$ or less, $p(x)$, such that

$$p(x_j) = y_j, \quad j = 1, 2, \dots, m$$

That is, the fitting polynomial goes through all m data points exactly.

Solution: We can write out the polynomial $p(x)$ directly.

We introduce a sequence of m special polynomials, each of degree $(m-1)$.

Let

$$p_j(x) \equiv \prod_{\substack{k=1 \\ k \neq j}}^m \left(\frac{x - x_k}{x_j - x_k} \right), \quad j = 1, 2, \dots, m$$

Polynomial $p_j(x)$ is of degree $(m-1)$ and satisfies

$$p_j(x_i) = \begin{cases} 1, & i = j \\ 0, & \text{otherwise} \end{cases}$$

Claim: the polynomial interpolation, $p(x)$, is given by

$$p(x) = \sum_{j=1}^m y_j p_j(x), \quad p_j(x) \equiv \prod_{\substack{k=1 \\ k \neq j}}^m \left(\frac{x - x_k}{x_j - x_k} \right)$$

Verifying the claim:

- $p(x)$ is a polynomial of degree $(m-1)$ or less;
- $p(x)$ goes through all m data points exactly:

$$p(x_i) = \sum_{j=1}^m y_j p_j(x_i) = y_i$$

Example:

Consider 3 data points of function $g(x)$ at $\{x_1 = -2, x_2 = -1, x_3 = 0\}$.

$$\{y_j = g(x_j), \quad j = 1, 2, 3\}$$

The 3 special polynomials have the general expression

$$p_j(x) \equiv \prod_{\substack{k=1 \\ k \neq j}}^m \left(\frac{x - x_k}{x_j - x_k} \right), \quad j = 1, 2, 3$$

Notice that in $p_j(x)$,

Numerator = product of $(x - x_k)$ over index k , excluding $k = j$.

Denominator = (Numerator | $x = x_j$).

For our specific data set, we write out the 3 special polynomials

$$p_1(x) \equiv \frac{(x+1)x}{(x+1)x \Big|_{x=-2}} = \frac{(x+1)x}{(-1)(-2)} = \frac{1}{2}(x^2 + x)$$

$$p_2(x) \equiv \frac{(x+2)x}{(x+2)x \Big|_{x=-1}} = \frac{(x+2)x}{(1)(-1)} = -(x^2 + 2x)$$

$$p_3(x) \equiv \frac{(x+2)(x+1)}{(x+2)(x+1) \Big|_{x=0}} = \frac{(x+2)(x+1)}{(2)(1)} = \frac{1}{2}(x^2 + 3x + 2)$$

The polynomial interpolation of the 3 data points is

$$p(x) = y_1 p_1(x) + y_2 p_2(x) + y_3 p_3(x)$$

Construction of Adams methods

We first calculate the interpolation of $f(u(t), t)$ at 3 time levels, $\{t_n, t_{n+1}, t_{n+2}\}$. Here $s = 2$.

Then we use the interpolation to construct the Adams methods (explicit and implicit).

The value of r depends on whether the method is explicit ($r = 3$) or implicit ($r = 2$).

We transform t by a shifting and a scaling to utilize the polynomial interpolation obtained above for $\{x_1 = -2, x_2 = -1, x_3 = 0\}$.

Let
$$x = \frac{t - t_{n+2}}{h}$$

$$\{t_n, t_{n+1}, t_{n+2}\} \longrightarrow \{x_1 = -2, x_2 = -1, x_3 = 0\}$$

Let $p^{\{x\}}(x)$ denote the polynomial interpolation in variable x .

Let $p^{\{t\}}(t)$ denote the polynomial interpolation in variable t .

$p^{\{t\}}(t)$ is related to $p^{\{x\}}(x)$ as

$$p^{\{t\}}(t) = p^{\{x\}}\left(\frac{t-t_{n+2}}{h}\right)$$

Below we will denote $p^{\{x\}}(x)$ simply as $p(x)$ when there is no confusion.

Adams-Bashforth method (explicit, $s = 2$):

Explicit method $\implies r = s + 1 = 3$ (when $s = 2$)

It uses values of $f(u(t), t)$ at 3 time levels, $\{t_n, t_{n+1}, t_{n+2}\}$, to calculate u_{n+3} .

The Adams-Bashforth method is constructed as

$$u_{n+3} = u_{n+2} + \int_{t_{n+2}}^{t_{n+3}} p\left(\frac{t-t_{n+2}}{h}\right) dt = u_{n+2} + h \int_0^1 p(x) dx, \quad x = \frac{t-t_{n+2}}{h}$$

Let us calculate $\int_0^1 p_j(x) dx$ for $j = 0, 1, 2$.

$$\int_0^1 p_1(x) dx = \int_0^1 \frac{1}{2}(x^2 + x) dx = \frac{1}{2} \cdot \frac{1}{3} + \frac{1}{2} \cdot \frac{1}{2} = \frac{5}{12}$$

$$\int_0^1 p_2(x) dx = \int_0^1 -(x^2 + 2x) dx = \frac{-16}{12}$$

$$\int_0^1 p_3(x) dx = \int_0^1 \frac{(x^2 + 3x + 2)}{2} dx = \frac{23}{12}$$

$$\begin{aligned} \implies \int_0^1 p(x) dx &= \int_0^1 (y_1 p_1(x) + y_2 p_2(x) + y_3 p_3(x)) dx \\ &= \frac{1}{12} (5y_1 - 16y_2 + 23y_3) \end{aligned}$$

Based on the correspondence between $\{x_1, x_2, x_3\}$ and $\{t_n, t_{n+1}, t_{n+2}\}$, we have

$$y_1 = g(x_1) \longleftrightarrow f(u(t_n), t_n)$$

$$y_2 = g(x_2) \longleftrightarrow f(u(t_{n+1}), t_{n+1})$$

$$y_3 = g(x_3) \longleftrightarrow f(u(t_{n+2}), t_{n+2})$$

The 3-step Adams-Bashforth method is

$$u_{n+3} = u_{n+2} + \frac{h}{12} [5f(u_n, t_n) - 16f(u_{n+1}, t_{n+1}) + 23f(u_{n+2}, t_{n+2})]$$

Adams-Moulton method (implicit, $s = 2$):

Implicit method $\implies r = s = 2$ (when $s = 2$).

It uses values of $f(u(t), t)$ at 3 time levels, $\{t_n, t_{n+1}, t_{n+2}\}$, to calculate u_{n+2} .

The unknown u_{n+2} is used in interpolation so the method is implicit.

The Adams-Moulton method is constructed as

$$u_{n+2} = u_{n+1} + \int_{t_{n+1}}^{t_{n+2}} p\left(\frac{t-t_{n+2}}{h}\right) dt = u_{n+1} + h \int_{-1}^0 p(x) dx, \quad x = \frac{t-t_{n+2}}{h}$$

Let us calculate $\int_{-1}^0 p_j(x) dx$ for $j = 0, 1, 2$.

$$\int_{-1}^0 p_1(x) dx = \int_{-1}^0 \frac{1}{2}(x^2 + x) dx = \frac{-1}{12}$$

$$\int_{-1}^0 p_2(x) dx = \int_{-1}^0 -(x^2 + 2x) dx = \frac{8}{12}$$

$$\int_{-1}^0 p_3(x) dx = \int_{-1}^0 \frac{(x^2 + 3x + 2)}{2} dx = \frac{5}{12}$$

$$\begin{aligned} \implies \int_{-1}^0 p(x) dx &= \int_{-1}^0 (y_1 p_1(x) + y_2 p_2(x) + y_3 p_3(x)) dx \\ &= \frac{1}{12}(-y_1 + 8y_2 + 5y_3) \end{aligned}$$

The 2-step Adams-Moulton method is

$$u_{n+2} = u_{n+1} + \frac{h}{12}[-f(u_n, t_n) + 8f(u_{n+1}, t_{n+1}) + 5f(u_{n+2}, t_{n+2})]$$

A list of Adams-Bashforth methods:

1-step Adams-Bashforth:

$$u_{n+1} = u_n + hf(u_n, t_n) \quad \text{This is the same as the forward Euler.}$$

2-step Adams-Bashforth:

$$u_{n+2} = u_{n+1} + \frac{h}{2}[-f(u_n, t_n) + 3f(u_{n+1}, t_{n+1})]$$

3-step Adams-Bashforth:

$$u_{n+3} = u_{n+2} + \frac{h}{12} [5f(u_n, t_n) - 16f(u_{n+1}, t_{n+1}) + 23f(u_{n+2}, t_{n+2})]$$

4-step Adams-Bashforth:

$$u_{n+4} = u_{n+3} + \frac{h}{24} [-9f(u_n, t_n) + 37f(u_{n+1}, t_{n+1}) - 59f(u_{n+2}, t_{n+2}) + 55f(u_{n+3}, t_{n+3})]$$

A list of Adams-Moulton methods:

1-step Adams-Moulton:

$$u_{n+1} = u_n + \frac{h}{2} [f(u_n, t_n) + f(u_{n+1}, t_{n+1})] \quad \text{This is the same as the trapezoidal.}$$

2-step Adams-Moulton:

$$u_{n+2} = u_{n+1} + \frac{h}{12} [-f(u_n, t_n) + 8f(u_{n+1}, t_{n+1}) + 5f(u_{n+2}, t_{n+2})]$$

3-step Adams-Moulton:

$$u_{n+3} = u_{n+2} + \frac{h}{24} [f(u_n, t_n) - 5f(u_{n+1}, t_{n+1}) + 19f(u_{n+2}, t_{n+2}) + 9f(u_{n+3}, t_{n+3})]$$

4-step Adams-Moulton:

$$u_{n+4} = u_{n+3} + \frac{h}{720} [-19f(u_n, t_n) + 106f(u_{n+1}, t_{n+1}) - 264f(u_{n+2}, t_{n+2}) + 646f(u_{n+3}, t_{n+3}) + 251f(u_{n+4}, t_{n+4})]$$

Order of accuracy of Adams methods

First we study that of polynomial interpolation.

Order of accuracy of polynomial interpolation

Consider the polynomial interpolation of function $g(t)$ at $(s + 1)$ time levels,

$\{t_n, t_{n+1}, \dots, t_{n+s}\}$. In our application, $g(t) = f(u(t), t)$.

Let “Intp” denote the interpolation operator.

$$\text{Intp: } g(t) \longrightarrow p(t)$$

Remark: Intp is a linear operator.

$$\text{Intp}(c_1 g_1(t) + c_2 g_2(t)) = c_1 \cdot \text{Intp}(g_1(t)) + c_2 \cdot \text{Intp}(g_2(t))$$

Forecast of the result:

The error of the interpolation is

$$E(h) = g(t) - \text{Intp}(g(t)) = O(h^{s+1}) \quad \text{over } t \in [t_n, t_{n+s+1}]$$

That is, the error = $O(h^m)$ where m is # of points used in interpolation.

Derivation of the result:

To isolate the effect of h , we map t to x : $x = \frac{t - t_{n+s}}{h}$

$\{t_n, t_{n+1}, \dots, t_{n+s}\}$ are mapped to $\{x_1, x_2, \dots, x_{s+1}\}$

$$t_n \longrightarrow x_1 = -s$$

$$t_{n+1} \longrightarrow x_2 = -(s-1)$$

\vdots

$$t_{n+s} \longrightarrow x_{s+1} = 0$$

We write the interpolation mapping as

$$\text{Intp}(g(t)) = \sum_{j=1}^{s+1} g(t_{n+j-1}) p_j^{(x)}(x), \quad x = \frac{t - t_{n+s}}{h}$$

We point out several properties of “Intp”:

- Function $p_j^{(x)}(x)$ is independent of h .
- The range of x is also independent of h :

$$t \in [t_n, t_{n+s+1}] \longrightarrow x \in [x_1, x_{s+2}] = [-s, 1].$$

- The range of $p_j^{(x)}(x)$ over $x \in [-s, 1]$ is independent of h , and, therefore, is bounded.
- The effect of h is solely contained in $g(t_{n+j-1})$.

Using these properties of “Intp”, we conclude that for any $q > 0$ we have

$$\text{Intp}(O(h^q)) = \sum_{j=1}^{s+1} O(h^q) p_j^{(x)}(x) = O(h^q) \quad \text{over } t \in [t_n, t_{n+s+1}]$$

In other words, the interpolation of a small function is also small.

This result is the key for deriving the error of polynomial interpolation.

By definition, the error of interpolation is

$$E(t, h) = g(t) - \text{Intp}(g(t))$$

We expand $g(t)$ around t_n .

$$g(t) = \underbrace{\sum_{m=0}^s g^{(m)}(t_n)(t-t_n)^m}_{\text{Polynomial of degree } s} + O(h^{s+1}) \quad \text{over } t \in [t_n, t_{n+s+1}]$$

Recall that the polynomial interpolation based on $(s + 1)$ points is exact for polynomials of degree s . It follows that

$$\begin{aligned} \text{Intp}(g(t)) &= \text{Intp}\left(\sum_{m=0}^s g^{(m)}(t_n)(t-t_n)^m\right) + \text{Intp}(O(h^{s+1})) \\ &= \sum_{m=0}^s g^{(m)}(t_n)(t-t_n)^m + O(h^{s+1}) \quad \text{over } t \in [t_n, t_{n+s+1}] \\ \Rightarrow E(t, h) &= g(t) - \text{Intp}(g(t)) = O(h^{s+1}) \quad \text{over } t \in [t_n, t_{n+s+1}] \end{aligned}$$

We summarize this result into a theorem.

Theorem:

Consider the polynomial interpolation of a smooth function $g(t)$ at $(s + 1)$ time levels $\{t_n, t_{n+1}, \dots, t_{n+s}\}$. The error of the interpolation is

$$E(t, h) = g(t) - \text{Intp}(g(t)) = O(h^{s+1}) \quad \text{over } t \in [t_n, t_{n+s+1}].$$

OR concisely,

on a grid of size h , error of Intp = $O(h^m)$ where m is # of points used.

We now use this theorem to derive the order of accuracy of Adams methods.

The r -step Adams methods have the form

$$u_{n+r} = u_{n+r-1} + \int_{t_{n+r-1}}^{t_{n+r}} p^{(t)}(t) dt$$

The local truncation error is

$$e_n(h) = u(t_{n+r}) - u(t_{n+r-1}) - \int_{t_{n+r-1}}^{t_{n+r}} \text{Intp}(f(u(t), t)) dt$$

Since $u(t)$ is an exact solution, we have

$$u(t_{n+r}) - u(t_{n+r-1}) = \int_{t_{n+r-1}}^{t_{n+r}} u'(t) dt = \int_{t_{n+r-1}}^{t_{n+r}} f(u(t), t) dt.$$

We write local truncation error $e_n(h)$ as

$$\begin{aligned} e_n(h) &= \int_{t_{n+r-1}}^{t_{n+r}} \left[f(u(t), t) - \text{Intp}(f(u(t), t)) \right] dt \\ &= \int_{t_{n+r-1}}^{t_{n+r}} O(h^{s+1}) dt = h \cdot O(h^{s+1}) = O(h^{s+2}) \end{aligned}$$

where $(s + 1)$ is the number of points used in interpolation, which is based on time levels $\{t_n, t_{n+1}, \dots, t_{n+s}\}$. Here s may be different from r .

The global error is

$$E_N(h) = O\left(\frac{e_n(h)}{h}\right) = O(h^{s+1})$$

Order of r -step Adams-Bashforth (explicit):

For Adams-Bashforth, $r = s + 1$

\implies Order $= s + 1 = r$

Order of r -step Adams-Moulton (implicit):

For Adams-Moulton, $r = s$

\implies Order $= s + 1 = r + 1$

Conclusion:

r -step Adams-Bashforth has order r .

r -step Adams-Moulton has order $(r + 1)$.