AM213B Assignment #5

Problem 1 (Theoretical)

Consider the BTCS and Crank-Nicolson methods for solving $u_t = u_{xx}$.

Part 1:

Carry out von Neumann stability analysis to show that

- The BTCS method is unconditionally stable
- The Crank-Nicolson method is unconditionally stable.

Part 2:

Carry out Taylor expansions to show that the local truncation error of the Crank-Nicolson method is

$$e_i^n(\Delta x, \Delta t) = \Delta t O((\Delta t)^2 + (\Delta x)^2)$$

In the final expression, convert r back to $\Delta t/(\Delta x)^2$.

Problem 2 (Theoretical)

Consider matrix

$$A = \frac{1}{(\Delta x)^2} \begin{pmatrix} -2 & 1 & & \\ 1 & -2 & \ddots & \\ & \ddots & \ddots & 1 \\ & & 1 & -2 \end{pmatrix}_{N \times N}, \qquad \Delta x = \frac{1}{N+1}$$

Part 1:

Verify that the set below are eigenvalues and eigenvectors of matrix A.

$$\lambda^{(k)} = \frac{2}{(\Delta x)^2} \left(\cos(k\pi \Delta x) - 1 \right) \\ w^{(k)} = \left\{ \sin(k\pi i \Delta x), \quad i = 1, 2, ..., N \right\}$$

Part 2:

Verify that

$$\frac{1}{(\Delta x)^2} \Big(\cos(k\pi(i-1)\Delta x) - 2\cos(k\pi i\Delta x) + \cos(k\pi(i+1)\Delta x) \Big)$$
$$= \frac{2}{(\Delta x)^2} \Big(\cos(k\pi \Delta x) - 1 \Big) \cdot \cos(k\pi i\Delta x)$$

Explain why $u^{(k)} = \{\cos(k\pi i \Delta x), i = 1, 2, ..., N\}$ is NOT an eigenvector of A.

Problem 3 (Computational)

Consider the IBVP of the heat equation:

$$\begin{cases} u_{t} = u_{xx}, & x \in (0, 2), t > 0 \\ u(x, 0) = f(x), & x \in (0, 2) \\ u(0, t) = g_{L}(t), & u(2, t) = g_{R}(t) \end{cases}$$

where
$$f(x) = 0.5x$$
, $g_{L}(t) = \cos(2t)$, $g_{R}(t) = \sin(2t)$

Implement the FTCS method to solve the IBVP.

Solve the IBVP to T = 3. Use $\Delta x = 0.01$ and Δt specified below:

- Try $\Delta t = \frac{(\Delta x)^2}{2} \cdot \frac{1}{0.99}$, which is slightly above the stability threshold;
- Try $\Delta t = \frac{(\Delta x)^2}{2} \cdot \frac{1}{1.01}$, which is slightly below the stability threshold.

For each Δt , plot u(x, t) vs x at t = 0.02, 0.5, 1, and 3 in one figure.

Hint:

Find *N* (# of internal points) according to the prescribed Δx .

Problem 4 (continue with the IBVP in problem 3)

Discretize the IBVP in the framework of **method of lines (MOL)**.

Implement the 2-statge DIRK method to solve the resulting ODE system.

Part 1:

Solve the IBVP to T = 3 with $\Delta x = 0.01$ and $\Delta t = 0.01$

Plot u(x, t) vs x at t = 0.02, 0.5, 1, and 3 in one figure.

Part 2:

Repeat the calculation with $\Delta x = 0.01$ and $\Delta t = 0.01/2$. Use the two numerical solutions to estimate the error, which is the error associated with the time discretization.

<u>Plot the estimated error vs x at t = 0.5, 1, and 3 in one figure</u>. Use linear scales for both the error and x. Plot the estimated error vs x at t = 0.02 in a separate figure.

Hint:

The MOL ODE system has the matrix-vector form

$$\frac{d\vec{u}(t)}{dt} = A\vec{u}(t) + \vec{b}(t)$$

$$\vec{u}(t) = \begin{pmatrix} u_1(t) \\ u_2(t) \\ \vdots \\ u_{N-1}(t) \\ u_N(t) \end{pmatrix}, \qquad \vec{b}(t) = \frac{1}{(\Delta x)^2} \begin{pmatrix} g_L(t) \\ 0 \\ \vdots \\ 0 \\ g_R(t) \end{pmatrix}$$

$$A = \frac{1}{(\Delta x)^2} \begin{pmatrix} -2 & 1 \\ 1 & -2 & \ddots \\ & \ddots & \ddots & 1 \\ & & 1 & 2 \end{pmatrix}, \qquad \Delta x = \frac{L}{N+1}$$

Find N according to the prescribed Δx . Implement the 2-statge DIRK method.

Problem 5

Consider the IBVP with an insulated boundary condition:

$$\begin{cases} u_t = u_{xx}, & x \in (0, 2), t > 0 \\ u(x, 0) = p(x), & x \in (0, 2) \\ u_x(0, t) = 0, & u(2, t) = q(t) \end{cases}$$

where
$$p(x) = (1-x)^2$$
, $q(t) = \cos(2t)$

Numerical grid:

$$\Delta x = \frac{L}{N + 0.5}$$
, $x_i = (i - 0.5)\Delta x$, $x_0 = -0.5\Delta x$, $x_1 = 0.5\Delta x$, $x_{N+1} = L$

The FTCS method:

$$u_i^{n+1} = u_i^n + \frac{\Delta t}{(\Delta x)^2} \left(u_{i-1}^n - 2u_i^n + u_{i+1}^n \right), \quad i = 1, 2, ..., N$$

$$u_0^n = u_1^n, \quad u_{N+1}^n = q(n\Delta t)$$

where N = # of internal points.

Use the FTCS method to solve the IBVP to T = 3 with N = 199 and $\Delta t = 4 \times 10^{-5}$. Plot u(x, t) vs x at t = 0.02, 0.5, 1, and 3 in one figure.