1/30/2018 dtree.py

01/30/18 10:10:27 /Users/caiglencross/Documents/MachineLearning/ps2/source/dtree.py

```
2
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               : HMC CS 158
3
   Class
              : 2018 Jan 30
   Date
5
   Description: Decision Tree Classifier
6
7
8
   # Use only the provided packages!
9
   import collections
   from util import *
10
11
12
  # numpy libraries
13
   import numpy as np
14
15 # scikit-learn libraries
16
   from sklearn import tree
17
18
   19
   # classes
20
   21
   class Tree(object) :
22
23
24
       Array-based representation of a binary decision tree.
25
26
       See tree._tree.Tree (a Python wrapper around a C class).
27
       The binary tree is represented as a number of parallel arrays. The i-th
28
       element of each array holds information about the node 'i'. Node 0 is the
       tree's root. NOTE: Some of the arrays only apply to either leaves or split
29
30
       nodes, resp. In this case the values of nodes of the other type are
31
       arbitrary!
32
33
       Attributes
34
35
         node_count : int
36
             The number of nodes (internal nodes + leaves) in the tree.
37
38
         children_left : array of int, shape [node_count]
39
             children left[i] holds the node id of the left child of node i.
40
             For leaves, children_left[i] == TREE_LEAF. Otherwise,
41
             children_left[i] > i. This child handles the case where
42
             X[:, feature[i]] <= threshold[i].</pre>
43
44
         children_right : array of int, shape [node_count]
             children_right[i] holds the node id of the right child of node i.
45
46
             For leaves, children right[i] == TREE LEAF. Otherwise,
             children_right[i] > i. This child handles the case where
47
48
             X[:, feature[i]] > threshold[i].
49
50
         feature : array of int, shape [node count]
51
             feature[i] holds the feature to split on, for the internal node i.
52
53
         threshold : array of double, shape [node_count]
54
             threshold[i] holds the threshold for the internal node i.
55
56
         value: array of double, shape [node count, 1, max n classes]
57
             value[i][0] holds the counts of each class reaching node i
```

```
1/30/2018
                                            dtree.py
  58
  59
             impurity : array of double, shape [node count]
  60
                 impurity[i] holds the impurity at node i.
  61
  62
             n node samples : array of int, shape [node count]
  63
                 n_node_samples[i] holds the number of training samples reaching node
       i.
          .....
  64
  65
          TREE_LEAF = tree._tree.TREE_LEAF
  66
           TREE UNDEFINED = tree. tree.TREE UNDEFINED
  67
           def __init__(self, n_features, n_classes, n_outputs=1) :
  68
  69
               if n_outputs != 1 :
  70
                   raise NotImplementedError("each sample must have a single label")
  71
  72
               self.n_features = n_features
  73
               self.n_classes
                                  = n_classes
  74
               self.n_outputs
                                  = n_outputs
  75
  76
               capacity = 2047 # arbitrary, allows max_depth = 10
               self_node_count
  77
                                  = capacity
  78
               self.children_left = np.empty(self.node_count, dtype=int)
  79
               self.children_right = np.empty(self.node_count, dtype=int)
  80
               self.feature
                                  = np.empty(self.node_count, dtype=int)
               self.threshold
  81
                                  = np.empty(self.node_count)
  82
               self.value
                                  = np.empty((self.node_count, n_outputs, n_classes))
              self.impurity
  83
                                  = np.empty(self.node count)
               self.n_node_samples = np.empty(self.node_count, dtype=int)
  84
  85
  86
              # private
  87
               self._next_node
                                  = 1 # start at root
  88
               self._classes
                                  = None
  89
  90
          91
          # helper functions
  92
          def _get_value(self, y) :
  93
  94
  95
               Get count of each class.
  96
  97
               Parameters
  98
  99
                  y —— numpy array of shape (n,), target classes
  100
  101
               Returns
  102
  103
                  value -- numpy array of shape (n classes,), class counts
                           value[i] holds count of each class
  104
              1111111
  105
  106
               if len(y) == 0:
                   raise Exception("cannot separate empty set")
  107
  108
  109
               counter = collections.defaultdict(lambda: 0)
 110
               for label in y :
                   counter[label] += 1
  111
  112
  113
               value = np.empty((self.n_classes,))
               for i, label in enumerate(self. classes) :
  114
```

value[i] = counter[label]

115

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1/30/2018
                                               dtree.py
  117
                return value
  118
           def _entropy(self, y) :
  119
  120
  121
               Compute entropy.
  122
  123
               Parameters
  124
  125
                    y -- numpy array of shape (n,), target classes
 126
  127
               Returns
  128
  129
                   H -- entropy
  130
  131
  132
               # compute counts
  133
               _, counts = np.unique(y, return_counts=True)
  134
  135
               ### ====== TODO : START ====== ###
  136
               # part a: compute entropy
  137
               # hint: use np.log2 to take log
  138
               H = 0
  139
               total_sum = np.sum(counts)
  140
               for c in counts:
  141
                    prob_y = float(c)/total_sum
  142
                    H \leftarrow -1.0* \text{ prob_y} * \text{np.log2(prob_y)}
  143
               ### ====== TODO : END ====== ###
  144
  145
                return H
  146
           def information gain(self, X_i, y):
  147
  148
  149
               Compute information gain.
  150
  151
               Parameters
  152
  153
                    Χj
                                   -- numpy array of shape (n,), samples (one feature
       only)
  154
                                    -- numpy array of shape (n,), target classes
                    У
  155
  156
               Returns
  157
  158
                                -- float, information gain using best threshold
                    info_gain
                    best_threshold -- float, threshold with best information gain
  159
  160
               n = len(Xj)
  161
  162
               if n != len(y) :
                    raise Exception("feature vector and class vector must have same
  163
       length")
  164
  165
               # compute entropy
  166
               H = self._entropy(y)
  167
               # reshape feature vector to shape (n,1)
  168
  169
               X_i = X_i \cdot reshape((n,1))
 170
               values = np.unique(Xj) # unique values in Xj, sorted
  171
               n_values = len(values)
  172
  173
               # compute optimal conditional entropy by trying all thresholds
```

thresholds = np.empty(n_values - 1) # possible thresholds

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1/30/2018
                                             dtree.py
               H_{conds} = np.empty(n_{values} - 1)
  175
                                                   # associated conditional entropies
               for i in xrange(n values - 1) :
  176
                   threshold = (values[i] + values[i+1]) / 2.
  177
  178
                   thresholds[i] = threshold
  179
                   X1, y1, X2, y2 = self._split_data(Xj, y, 0, threshold)
  180
                   ### ====== TODO : START ====== ###
  181
  182
                   # part c: compute conditional entropy
  183
                   H_{cond} = 0
  184
                   H_1 = self_entropy(y1)
                   H_2 = self.\_entropy(y2)
  185
                   H_{cond} = (float(len(X1))/n)*H_1 + (float(len(X2))/n)*H_2
  186
  187
  188
                   ### ====== TODO : END ====== ###
  189
                   H_{conds}[i] = H_{cond}
  190
  191
               # find minimium conditional entropy (maximum information gain)
  192
               # and associated threshold
  193
               best H cond = H conds.min()
  194
               indices = np.where(H_conds == best_H_cond)[0]
  195
               best_index = np.random.choice(indices)
  196
               best_threshold = thresholds[best_index]
  197
  198
               # compute information gain
  199
               info_gain = H - best_H_cond
  200
  201
               return info_gain, best_threshold
  202
           def _split_data(self, X, y, feature, threshold) :
  203
  204
  205
               Split dataset (X,y) into two datasets (X1,y1) and (X2,y2)
               based on feature and threshold.
  206
  207
  208
               (X1,y1) contains the subset of (X,y) such that X[i,feature] <=
       threshold.
  209
               (X2,y2) contains the subset of (X,y) such that X[i,feature] > threshold.
  210
  211
               Parameters
  212
  213
                   Χ
                            -- numpy array of shape (n,d), samples
  214
                            -- numpy array of shape (n,), target classes
                   feature -- int, feature index to split on
  215
  216
                   threshold -- float, feature threshold
  217
  218
               Returns
  219
  220
                   X1
                            -- numpy array of shape (n1,d), samples
                            -- numpy array of shape (n1,), target classes
  221
                   y1
                   X2
  222
                            -- numpy array of shape (n2,d), samples
                            -- numpy array of shape (n2,), target classes
  223
  224
  225
               n, d = X.shape
  226
               if n != len(y) :
  227
                   raise Exception ("feature vector and label vector must have same
       length")
  228
  229
               X1, X2 = [], []
  230
               y1, y2 = [], []
               ### ====== TODO : START ====== ###
  231
  232
```

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1/30/2018
                                              dtree.py
  233
               #TODO: filter on the matching indicies where feature level is gt or lt
               X1 = X[X[:,feature] <= threshold,:]</pre>
  234
  235
               y1 = y[X[:,feature] <= threshold]</pre>
  236
  237
               X2 = X[X[:,feature] > threshold, :]
  238
               y2 = y[X[:,feature] > threshold]
  239
  240
               ### ====== TODO : END ====== ###
  241
               X1, X2 = np.array(X1), np.array(X2)
  242
               y1, y2 = np.array(y1), np.array(y2)
  243
  244
               return X1, y1, X2, y2
  245
           def _choose_feature(self, X, y) :
  246
  247
  248
               Choose a feature with max information gain from (X,y).
  249
  250
               Parameters
  251
  252
                                -- numpy array of shape (n,d), samples
                   Χ
                                 -- numpy array of shape (n,), target classes
  253
                   У
  254
  255
               Returns
  256
                   best_feature -- int, feature to split on
  257
  258
                   best_threshold -- float, feature threshold
  259
  260
               n, d = X.shape
  261
               if n != len(y) :
  262
                   raise Exception ("feature vector and label vector must have same
       length")
  263
  264
               # compute optimal information gain by trying all features
  265
               thresholds = np.empty(d) # best threshold for each feature
                          = np.empty(d) # best information gain for each feature
  266
  267
               for j in xrange(d) :
  268
                   if (X[:,j] == X[0,j]).all() :
  269
                       # skip if all feature values equal
  270
                       score, threshold = -1, None # use an invalid (but numeric) score
  271
                   else:
  272
                       score, threshold = self._information_gain(X[:,j], y)
  273
                   thresholds[j] = threshold
  274
                   scores[j] = score
  275
  276
               # find maximum information gain
  277
               # and associated feature and threshold
  278
               best score = scores.max()
  279
               indices = np.where(scores == best_score)[0]
  280
               best_feature = np.random.choice(indices)
  281
               best threshold = thresholds[best feature]
  282
  283
               return best_feature, best_threshold
  284
           def _create_new_node(self, node, feature, threshold, value, impurity) :
  285
  286
  287
               Create a new internal node.
  288
  289
               Parameters
  290
  291
                              -- int, current node index
                   node
```

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1/30/2018
                                             dtree.py
  292
                   feature -- int, feature index to split on
  293
                   threshold -- float, feature threshold
  294
                           -- numpy array of shape (n_classes,), class counts of
                   value
       current node
  295
                   impurity -- float, impurity of current node
  296
  297
               self.children_left[node] = self._next_node
  298
               self. next node += 1
  299
               self.children_right[node] = self._next_node
               self._next_node += 1
  300
  301
               self.feature[node]
  302
                                         = feature
               self.threshold[node]
  303
                                         = threshold
               self.value[node]
  304
                                         = value
  305
               self.impurity[node]
                                         = impurity
               self.n node samples[node] = sum(value)
  306
  307
           def _create_new_leaf(self, node, value, impurity) :
  308
  309
  310
               Create a new leaf node.
  311
  312
               Parameters
  313
                   node
  314
                            -- int, current node index
  315
                   value
                            -- numpy array of shape (n_classes,), class counts of
       current node
                   impurity -- float, impurity of current node
  316
  317
  318
               self.children_left[node] = Tree.TREE_LEAF
  319
               self.children right[node] = Tree.TREE LEAF
  320
               self.feature[node]
                                         = Tree.TREE UNDEFINED
  321
               self.threshold[node]
                                        = Tree.TREE UNDEFINED
  322
  323
               self.value[node]
                                         = value
                                       = impurity
  324
               self.impurity[node]
  325
               self.n node samples[node] = sum(value)
  326
  327
           def _build_helper(self, X, y, node=0) :
  328
  329
               Build a decision tree from (X,y) in depth-first fashion.
  330
  331
               Parameters
  332
  333
                   Χ
                          -- numpy array of shape (n,d), samples
  334
                          -- numpy array of shape (n,), target classes
                   У
  335
                          -- int, current node index (index of root for current
                   node
       subtree)
  336
  337
               n, d = X.shape
  338
  339
  340
               value = self._get_value(y)
               impurity = self. entropy(y)
  341
  342
               ### ====== TODO : START ====== ###
  343
  344
               # part d: decision tree induction algorithm
  345
               # you can modify any code within this TODO block
  346
  347
               # base case
               # 1) all samples have same labels
```

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1/30/2018
              # 2) all feature values are equal
  349
               if impurity == 0 or len(np.unique(X, axis=0))==1: # you should modify
  350
       this condition
  351
                  # this line is so that the code can run
  352
                  # you can comment it out (or not) once you add your own code
 353
  354
  355
                  # create a single leaf
  356
                   self. create new leaf(node, value, impurity)
  357
  358
              else:
  359
                  # this line is so that the code can run
  360
                  # you can comment it out (or not) once you add your own code
  361
                  # pass
  362
                  # choose best feature (and find associated threshold)
  363
                  best_feature, best_threshold = self._choose_feature(X, y)
  364
                  # make new decision tree node
  365
  366
                   self. create new node(node, best feature, best threshold, value,
       impurity)
  367
                  # split data on best feature
  368
                  X1, y1, X2, y2 = self._split_data(X,y,best_feature, best_threshold)
  369
                  # build left subtree using recursion
                   self._build_helper(X1, y1, self.children_left[node])
  370
  371
                  # build right subtree using recursion
  372
                   self._build_helper(X2, y2, self.children_right[node])
  373
              ### ====== TODO : END ====== ###
  374
  375
          376
          # main functions
  377
  378
          def fit(self, X, y) :
  379
  380
               Build a decision tree from (X,y).
  381
  382
               Parameters
 383
  384
                        -- numpy array of shape (n,d), samples
  385
                       -- numpy array of shape (n,), target classes
  386
  387
               Returns
  388
  389
                   self -- an instance of self
  390
  391
  392
              # v must contain only integers
  393
               if not np.equal(np.mod(y, 1), 0).all() :
                   raise NotImplementedError("y must contain only integers")
  394
  395
  396
              # store classes
  397
               self._classes = np.unique(y)
  398
  399
              # build tree
  400
               self._build_helper(X, y)
  401
  402
              # resize arrays
  403
               self.node_count
                                  = self_next_node
               self.children left = self.children_left[:self.node_count]
  404
  405
               self.children_right = self.children_right[:self.node_count]
               self.feature
                                   = self.feature[:self.node_count]
```

1/30/2018 dtree.py

```
407
              self.threshold
                                   = self.threshold[:self.node count]
              self.value
                                   = self.value[:self.node count]
408
409
              self.impurity
                                   = self.impurity[:self.node count]
410
              self.n_node_samples = self.n_node_samples[:self.node_count]
411
              return self
412
413
414
         def predict(self, X) :
415
416
              Predict target for X.
417
418
              Parameters
419
420
                  X — numpy array of shape (n,d), samples
421
422
              Returns
423
424
                  y -- numpy array of shape (n,n_classes), values
425
426
427
              n, d = X.shape
428
              y = np.empty((n, self.n_classes))
429
              ### ====== TODO : START ====== ###
430
431
              # part e: make predictions
432
433
              # for each sample
434
                  start at root of tree
435
                  follow edges to leaf node
436
                  find value at leaf node
              #print "feature vector: ", self.feature
#print "value vector: ", self.value
437
438
439
              for i in range(0,n):
440
                  sample = X[i,:]
441
                  #print sample
442
                  current node = 0
443
                  while(self.children_left[current_node] != -1):
444
                      current_feature = self.feature[current_node]
                      current_threshold = self.threshold[current_node]
445
                      #print "current node: ", current_node
446
                      #print "current feature: ", current_feature
#print "current threshold: ", current_threshold
447
448
                      if sample[current_feature] <= current_threshold:</pre>
449
450
                           current node = self.children left[current node]
451
                          #print "splitting left!"
452
453
                           current node = self.children right[current node]
                          #print "splitting right!"
454
455
                  #print "current node at end: ", current_node
                  #print self.value[current node]
456
457
                  y[i] = self.value[current_node]
458
459
460
              ### ====== TODO : END ====== ###
461
462
              return y
463
464
465
     class Classifier(object) :
466
```

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1/30/2018
                                               dtree.py
           Classifier interface.
  467
  468
  469
  470
           def fit(self, X, y):
                raise NotImplementedError()
  471
  472
  473
           def predict(self, X):
  474
                raise NotImplementedError()
  475
  476
       class DecisionTreeClassifier(Classifier) :
  477
  478
  479
           def __init__(self, criterion="entropy", random_state=None) :
  480
  481
                A decision tree classifier.
  482
  483
               Attributes
  484
  485
                    classes —— numpy array of shape (n classes, ), the classes
       labels
  486
                    n_classes_ -- int, the number of classes
  487
                    n_features_ -- int, the number of features
                    n_outputs_ -- int, the number of outputs
tree_ -- the underlying Tree object
  488
  489
               111111
  490
  491
               if criterion != "entropy":
  492
                    raise NotImplementedError()
  493
  494
                self.n_features_ = None
                self.classes_ = None
  495
                self.n_classes_ = None
  496
  497
                self.n_outputs_ = None
  498
                self.tree = None
  499
                self.random_state = random_state
  500
  501
           def fit(self, X, y):
  502
  503
                Build a decision tree classifier from the training set (X, y).
  504
  505
                Parameters
  506
  507
                        -- numpy array of shape (n,d), samples
  508
                         -- numpy array of shape (n,), target classes
  509
  510
                Returns
  511
  512
                    self -- an instance of self
  513
  514
  515
                n samples, self.n features = X.shape
  516
  517
               # determine number of outputs
  518
                if y.ndim != 1 :
                    raise NotImplementedError("each sample must have a single label")
  519
  520
                self.n_outputs_ = 1
  521
  522
               # determine classes
  523
                classes = np.unique(y)
                self.classes_ = classes
  524
                self.n_classes_ = classes.shape[0]
```

```
1/30/2018
                                          dtree.py
 526
 527
              # set random state
              np.random.seed(self.random_state)
 528
 529
 530
              self.tree_ = Tree(self.n_features_, self.n_classes_, self.n_outputs_)
 531
              self.tree_.fit(X, y)
 532
 533
              return self
 534
 535
          def predict(self, X) :
 536
              Predict class value for X.
 537
 538
 539
              Parameters
 540
 541
                      -- numpy array of shape (n,d), samples
 542
 543
              Returns
 544
 545
                      -- numpy array of shape (n,), predicted classes
 546
 547
 548
              if self.tree is None :
                  raise Exception("Classifier not initialized. Perform a fit first.")
 549
 550
 551
              # defer to self.tree
 552
              X = X.astype(tree. tree.DTYPE)
 553
              proba = self.tree_.predict(X)
              predictions = self.classes_.take(np.argmax(proba, axis=1), axis=0)
 554
 555
              return predictions
 556
 557
 558
      559
      # functions
 560
      561
 562
      def load movie dataset():
          """Load movie dataset."""
 563
 564
          # Note: This is not a good representation (use one-hot encoding instead),
 565
                  but it is easier and sufficient for a toy dataset.
                     animated = 0, comedy = 1, drama = 2
 566
                     short = 0, medium = 1, long = 2
 567
          # length:
 568
          # director: adamson = 0, lasseter = 1, singer = 2
                     not famous = 0, famous = 1
 569
          # actors:
 570
          # liked:
                     no = 0, famous = 1
          data = np.array([[1, 0, 0, 0, 1],
 571
 572
                          [0, 0, 1, 0, 0],
                          [2, 1, 0, 0, 1],
 573
                          [0, 2, 1, 1, 0],
 574
                          [1, 2, 1, 1, 0],
 575
                          [2, 1, 2, 1, 1],
 576
 577
                          [0, 0, 2, 0, 1],
 578
                          [1, 2, 0, 1, 1],
 579
                          [2, 1, 1, 0, 1]])
          names = ['type', 'length', 'director', 'famous_actor', 'liked']
 580
 581
 582
          X = data[:,:-1]
 583
          Xnames = names[:-1]
 584
          y = data[:,-1]
```

yname = names [-1]

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1/30/2018
                                              dtree.py
  586
  587
           return X, y, Xnames, yname
  588
  589
  590
       def print tree(decision tree, feature names=None, class names=None, root=0,
       depth=1):
  591
  592
           Print decision tree.
  593
  594
           Only works with decision tree.n outputs = 1.
           https://healthyalgorithms.com/2015/02/19/ml-in-python-getting-the-decision-
  595
       tree-out-of-sklearn/
  596
  597
           Parameters
  598
  599
               decision tree -- tree (sklearn.tree. tree.Tree or Tree)
               feature_names -- list, feature names
  600
                            -- list, class names
  601
               class_names
  602
  603
           t = decision_tree
  604
           if t.n_outputs != 1:
  605
  606
               raise NotImplementedError()
  607
  608
           if depth == 1:
  609
               print 'def predict(x):'
  610
  611
           indent = '
                          ' * depth
  612
  613
           # determine node numbers of children
           left child = t.children left[root]
  614
           right child = t.children right[root]
  615
  616
  617
           # determine predicted class for this node
           values = t.value[root][0]
  618
  619
           class ndx = np.argmax(values)
  620
           if class_names is not None:
  621
               class_str = class_names[class_ndx]
  622
           else:
  623
               class_str = str(class_ndx)
  624
  625
           # determine node string
  626
           node_str = "(node %d: impurity = %.2f, samples = %d, value = %s, class =
       %s)" % \
  627
               (root, t.impurity[root], t.n node samples[root], values, class str)
  628
           # main code
  629
  630
           if left_child == tree._tree.TREE_LEAF:
               print indent + 'return %s # %s' % (class_str, node_str)
  631
           else:
  632
  633
               # determine feature name
  634
               if feature_names is not None:
                   name = feature names[t.feature[root]]
  635
  636
               else:
                    name = "x_%d" % t.feature[root]
  637
  638
  639
               print indent + 'if %s <= %.2f: # %s' % (name, t.threshold[root],</pre>
       node str)
```

print_tree(t, feature_names, class_names, root=left_child,

depth=depth+1)

```
1/30/2018
                                           dtree.py
 641
 642
              print indent + 'else:'
 643
              print_tree(t, feature_names, class_names, root=right_child,
      depth=depth+1)
 644
 645
 646
      647
 648
      649
      def main():
 650
          np.random.seed(1234)
 651
 652
 653
          # load movie dataset
 654
          X, y, Xnames, yname = load_movie_dataset()
 655
 656
          # scikit-learn DecisionTreeClassifier
 657
 658
          print 'Using DecisionTreeClassifier from scikit-learn...'
 659
 660
          from sklearn.tree import DecisionTreeClassifier as DTC
 661
          clf = DTC(criterion='entropy', random_state=1234)
 662
          clf.fit(X, y)
          print_tree(clf.tree_, feature_names=Xnames, class_names=["No", "Yes"])
 663
 664
          y pred = clf.predict(X)
 665
          print 'y_pred = ', y_pred
 666
          .....
 667
 668
          Output
 669
 670
          def predict(x):
              if director \leq 0.50: # (node 0: impurity = 0.92, samples = 9, value = [
 671
          6.1. class = Yes)
 672
                  return Yes # (node 1: impurity = 0.00, samples = 3, value = [ 0.
      3.], class = Yes)
 673
              else:
 674
                  if type <= 1.50: # (node 2: impurity = 1.00, samples = 6, value = [
         [3.], class = No)
 675
                      if director \leq 1.50: # (node 3: impurity = 0.81, samples = 4,
      value = [ 3. 1.], class = No)
 676
                          return No # (node 4: impurity = 0.00, samples = 3, value = [
         [0.], class = No)
 677
                      else:
                          return Yes # (node 5: impurity = 0.00, samples = 1, value =
 678
       [ 0.
            1.], class = Yes)
 679
                  else:
 680
                      return Yes # (node 6: impurity = 0.00, samples = 2, value = [
          2.], class = Yes)
          y_pred = [1 0 1 0 0 1 1 1 1]
 681
 682
 683
          111111
 684
 685
          # save the classifier -- requires GraphViz and pydot
          import StringIO, pydot
 686
 687
          dot_data = StringIO.StringIO()
 688
          tree.export_graphviz(clf, out_file=dot_data,
 689
                              feature_names=Xnames,
                              class_names=["No", "Yes"])
 690
 691
          graph = pydot.graph from dot data(dot data.getvalue())
          #graph.write_pdf("dtree_movie.pdf")
```

```
1/30/2018
                                              dtree.py
           .....
  693
  694
  695
           print
  696
  697
           #==========
           # home-grown DecisionTreeClassifier
  698
  699
           print 'Using my DecisionTreeClassifier...'
  700
  701
           # test cases
  702
           n features = X.shape[1]
  703
           n_classes = len(np.unique(y))
  704
           my_tree = Tree(n_features, n_classes, 1)
  705
  706
           # entropy -> entropy
  707
           # soln -- 0.918295834054
           print 'H =', my_tree._entropy(y)
  708
  709
  710
           # _split_data -> X1, y1, X2, y2
  711
           # soln --
  712
               [X1,y1] = [[1 0 0 0 1]]
                                           [X2,y2] = [[2 1 0 0 1]]
  713
           #
                           [0 0 1 0 0]
                                                      [2 1 2 1 1]
  714
           #
                           [0 2 1 1 0]
                                                      [2 1 1 0 1]]
  715
           #
                           [1 2 1 1 0]
           #
                           [0 0 2 0 1]
  716
  717
                           [1 2 0 1 1]]
           X1, y1, X2, y2 = my_tree_split_data(X, y, 0, 1.5)
  718
           print '[X1,y1] =\n', np.column_stack((X1, y1))
  719
  720
           print '[X2,y2] =\n', np.column_stack((X2, y2))
  721
  722
           # _information_gain -> information gain, threshold
  723
           # soln -- (0.25162916738782293, 1.5)
  724
           print '(I,t) =', my_tree._information_gain(X[:,0], y)
  725
  726
           # soln -- See below. You may get a different decision tree but y_pred should
  727
       be the same.
  728
           clf2 = DecisionTreeClassifier(random_state=1234)
  729
           clf2.fit(X, y)
  730
           print_tree(clf2.tree_, feature_names=Xnames, class_names=["No", "Yes"])
  731
           y_pred2 = clf2.predict(X)
  732
           print 'y_pred2 =', y_pred2
  733
  734
           assert (y_pred == y_pred2).all(), "predictions are not the same"
  735
           .....
  736
  737
           0utput
  738
           def predict(x):
  739
  740
               if director \leq 0.50: # (node 0: impurity = 0.92, samples = 9, value = [
           [6.], class = Yes)
                   return Yes # (node 1: impurity = 0.00, samples = 3, value = [ 0.
  741
       3.], class = Yes)
  742
               else:
  743
                   if director <= 1.50: # (node 2: impurity = 1.00, samples = 6, value
       = [ 3.
               3.], class = No)
  744
                        if type <= 1.50: # (node 3: impurity = 0.81, samples = 4, value
               1.], class = No)
       = [ 3.
 745
                            return No # (node 5: impurity = 0.00, samples = 3, value = [
           0.], class = No)
  746
                        else:
```

1/30/2018 dtree.py 747 return Yes # (node 6: impurity = 0.00, samples = 1, value = [0. 1.], class = Yes)748 else: 749 return Yes # (node 4: impurity = 0.00, samples = 2, value = [2.], class = Yes) $y_pred2 = [1 0 1 0 0 1 1 1 1]$ 750 751 752 753 print 754 755 756 # train Decision Tree classifier on Titanic data print 'Classifying Titanic data set...' 757 758 titanic = load_data("titanic_train.csv", header=1, predict_col=0) 759 X = titanic.X760 761 y = titanic.y 762 clf = DTC(criterion='entropy') 763 764 clf.fit(X, y) 765 y_pred = clf.predict(X) 766 767 clf2 = DecisionTreeClassifier() 768 clf2.fit(X, y) 769 y_pred2 = clf2.predict(X) 770 771 assert (y_pred == y_pred2).all(), "predictions are not the same" 772 773 774 775 print 'Done' 776 777 778 if __name__ == "__main__":

main()