Faculty of Information Technology, Monash University

COMMONWEALTH OF AUSTRALIA

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FIT2004: Algorithms and Data Structures

Week 10: Minimum Spanning Trees

These slides are prepared by M. A. Cheema and are based on the material developed by Arun Konagurthu and Lloyd Allison.

Announcements

- Assignment 4 released
 - o Due:31-May-2019, 23:55:00
- Start preparing for the final exam
 - Listen to the lectures (or read slides)
 - Read Lecture Notes
 - Solve tutorial questions
 - Most importantly, do not hesitate to seek help



Recommended reading

- Lecture Notes: Chapters 14 and 15
- Cormen et al. Introduction to Algorithms.
 - Chapter 23, Pages 624-638
- http://www.csse.monash.edu.au/~lloyd/tildeAlgDS/Graph/Undirected/
- http://www.csse.monash.edu.au/~lloyd/tildeAlgDS/Graph/DAG/

Outline

- 1. Introduction
- 2. Prim's Algorithm
- 3. Kruskal's Algorithm

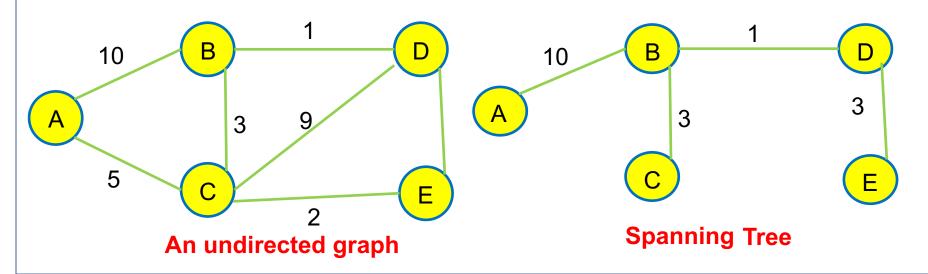
What is a Spanning Tree

Tree:

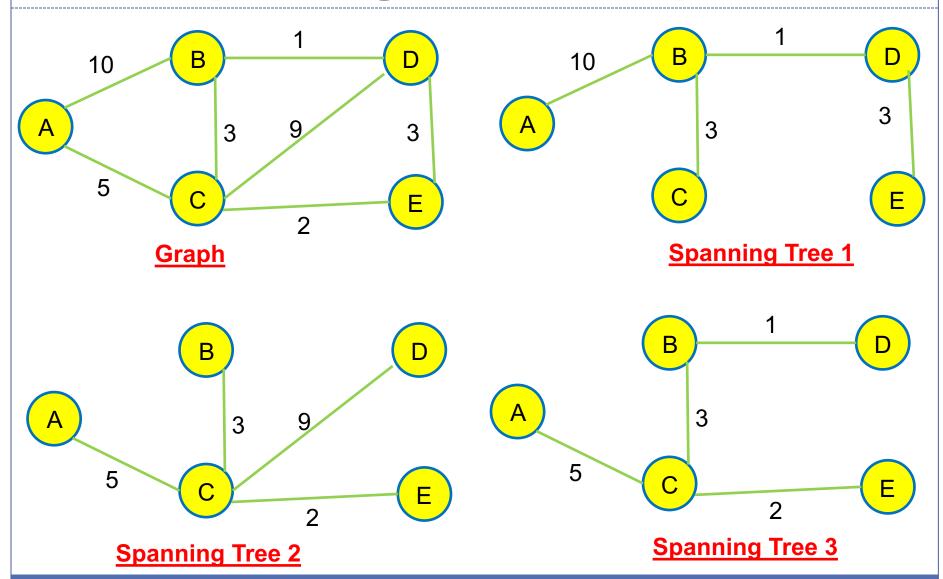
A tree is a connected undirected graph with no cycles in it.

Spanning Tree:

• A spanning tree of a general undirected weighted graph G is a tree that spans G (i.e., a tree that includes every vertex of G) and is a subgraph of G (i.e., every edge in the spanning tree belongs to G).



Spanning Tree Examples



What is a Spanning Tree

Tree:

A tree is a connected undirected graph with no cycles in it.

Spanning Tree:

• A spanning tree of a general undirected weighted graph G is a tree that spans G (i.e., a tree that includes every vertex of G) and is a subgraph of G (i.e., every edge in the spanning tree belongs to G).

Is it true that a spanning tree of a connected graph G is a maximal set of edges of G that contains no cycles?

Yes

Is it true that a spanning tree of a connected graph G is a minimal set of edges that connect all vertices?

Yes

Minimum Spanning Tree (MST)

- Weight of a spanning tree is the sum of the weights of the edges in the tree.
- A Minimum spanning tree of a weighted general graph G is a tree that spans G, whose weight is minimum over all possible spanning trees for this graph.
- There may be more than one minimum spanning trees for a graph G (e.g., two or more spanning trees with the same minimum weight).

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What is the weight of the MST in this graph?

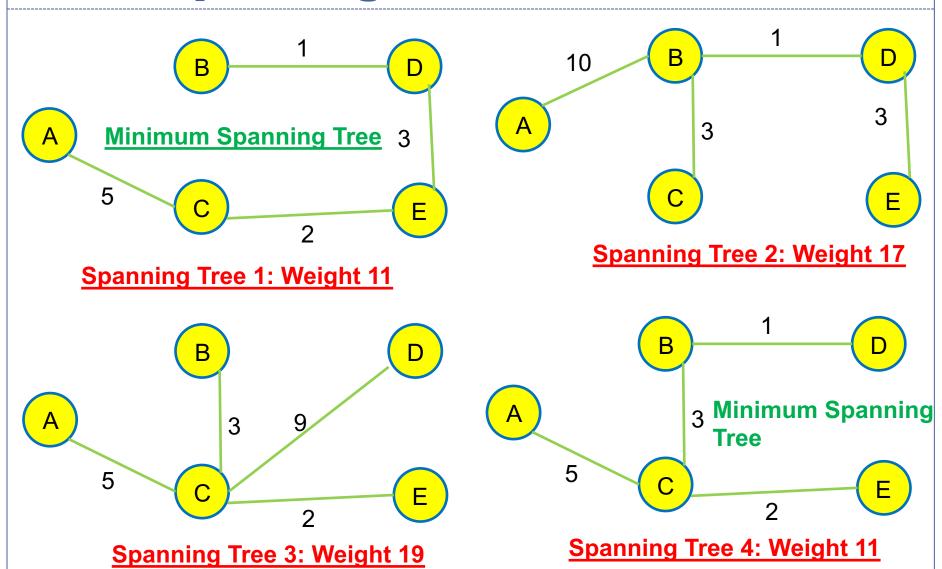
How many MSTs we have in this graph?

5

C

E

Spanning Trees and MSTs



MST Algorithms

Let M denote the MST we are constructing, initialized to be empty

An edge e is said to be safe if {M U e} is a subset of a MST

General Strategy:

- M = null
- while M can be grown safely:
- find an edge e=<x,y> along which M is safe to grow
- M = {M} union {<x,y>}
- return M

We will study two **greedy** algorithms that follow this strategy

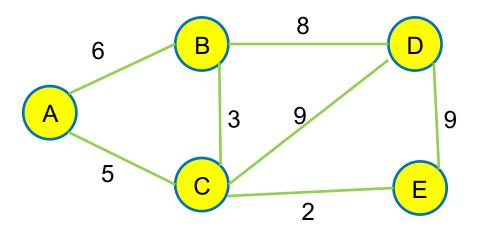
- Prim's Algorithm (very similar to Dijkstra's Algorithm)
 - In fact, Dijkstra published his algorithm for both MST and shortest path in the same paper (1959)
 - The algorithm is also often called Prim-Dijkstra Algorithm
 - M is always a tree and, in each iteration, we choose the shortest edge connected to M avoiding cycles
 - Time complexity: O(E log V)
- Kruskal's Algorithm
 - We process edges in ascending order of edge weights and M is a forest (i.e., a set of trees)
 - Time complexity: O(E log V)

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Prim's Algorithm: Overview

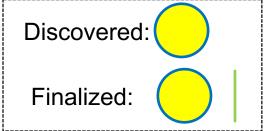
- Start by picking any vertex v to be the root of the tree M.
- While the tree M does not contain <u>all</u> vertices in the graph
 - Find shortest edge e connected to the growing subtree M that does not create a cycle
 - o add e to the tree M

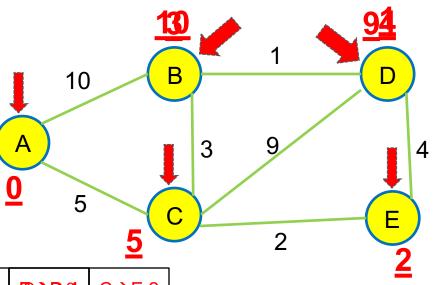


Prim's Algorithm

Differences with Dijkstra's are shown in red

- Initialize a list called Discovered and insert a random node A in it with distance 0
- While Discovered is not empty
 - Get the vertex v from the Discovered List with smallest weight
 - For each outgoing edge (v, u, w) of v
 - ▼ If u is not in Discovered/Finalized
 - Insert u in Discovered with weight w and edge
 v → u
 - x Else If u.weight > w
 - o If u is not finalized, update the weight of u in Discovered to w and edge to v→u
 - Move v from Discovered to Finalized along with its corresponding edge





Discovered: A, 0 \bigcirc B) A \rightarrow C,5 \bigcirc D,4 \bigcirc C \rightarrow E,2

Finalized (in MST): A $A \rightarrow C$ $C \rightarrow E$ $B \rightarrow C$ $B \rightarrow D$

Prim's Algorithm

```
# Initializations
Discovered = random(V) # Start by choosing any vertex randomly
Finalized = null; # Initially the MST is null
while Discovered not empty: # loops |V| times
#INV: Finalized is a (growing) subset of a minimum spanning tree
    v = EXTRACT MIN(Discovered) # get vertex v from Discovered with minimum weight
    Finalized = Finalized + \langle x,v \rangle # \langle x,v \rangle is the edge corresponding to the weight of v
    for each adjacent edge of (v,u,w) adjacent to v:
        if u is not Discovered/Finalized:
            insert u in Discovered with weight w and edge <v,u>
        else:
            if u is not Finalized:
                if u.weight > w:
                    update weight of u to w and edge to <v,u>
Return Finalized
```

Time Complexity?

Prim's Algorithm: Complexity

It is very similar to Dijkstra's Algorithm and its complexity is the same as Dijkstra's Algorithm

O(V log V + E log V) if min-heap is used

Since the input graph G is connected, $E \ge V-1$. Hence, the complexity can be simplified to O(E log V).

Proof of correctness

```
# Initializations
Discovered = random(V) # Start by choosing any vertex randomly
Finalized = null; # Initially the MST is null
while Discovered not_empty: # loops |V| times
#INV: Finalized is a (growing) subset of a minimum spanning tree
    v = EXTRACT_MIN(Discovered) # get vertex v from Discovered with minimum weight
    Finalized = Finalized + \langle x,v \rangle # \langle x,v \rangle is the edge corresponding to the weight of v
    for each adjacent edge of (v,u,w) adjacent to v:
        if u is not Discovered/Finalized:
             insert u in Discovered with weight w and edge <v,u>
        else:
             if u is not Finalized:
                 if u.weight > w:
                     update weight of u to w and edge to <v,u>
Return Finalized
```

Prim's Algorithm: Correctness

#INV: Finalized is a (growing) subset of a minimum spanning tree

Base Case:

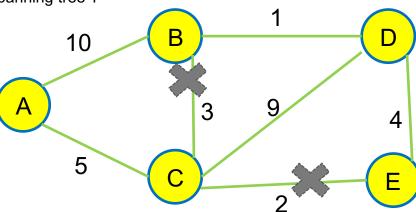
The invariance is true initially when Finalized is empty

Inductive step:

- Assume Finalized is currently a subset of a MST. We show that after Prim's algorithm adds an edge, invariance still holds
- Suppose the algorithm chooses a vertex E and an edge <C,E> having minimum weight w
- Assume {Finalized Union <C,E>} is <u>not</u> a subset of <u>any</u> minimum spanning tree. We show that this assumption is wrong.
- Let M be a minimum spanning tree that contains Finalized <u>but</u> excludes <C,E>.
 - E must be connected to Finalized in M (because M is a spanning tree). Since M does not contain <C,E>, there must be a path that connects Finalized (e.g., red vertices) with E (e.g., see blue edges).
 - Let <C,B> be the first edge on the path that connects Finalized to E.
- If we remove <C,B> from M and add <C,E> we will still get a spanning tree. Let this spanning tree be called T.
- Since the weight of <C,E> is smaller or equal to the weight of <C,B>, the weight of T is smaller than or equal to M. Hence, either M is not a minimum spanning tree or T is also a minimum spanning tree.

• Hence, Finalized after adding <C,E> is a subset of a minimum spanning tree T

i.e., the invariance holds after adding the edge <C,E>



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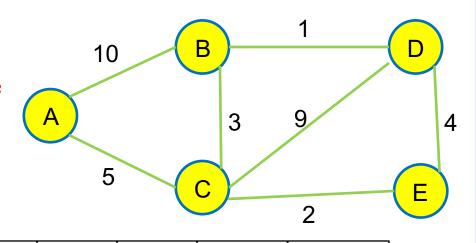
Kruskal's Algorithm

It is also a greedy algorithm like Prim's

- Sort the edges in ascending order of weights
- For each edge (v, u) in ascending order
 - If adding (v,u) does not create a cycle in Finalized
 - ➤ Add (v,u) in Finalized
- Return Finalized

How to determine if the edge will create a cycle???





Sorted Edges:

B→D,1 C→E,2

E,2 | C→B,3

E**→**D,4

A**→**C,5

C→**D**,9

A→B,10

Finalized (in MST):

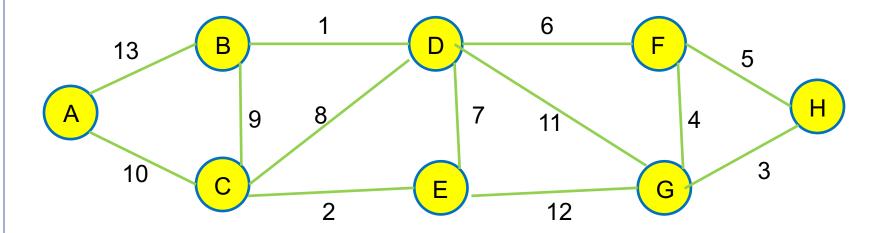
B→D

C→E

C→B

A→C

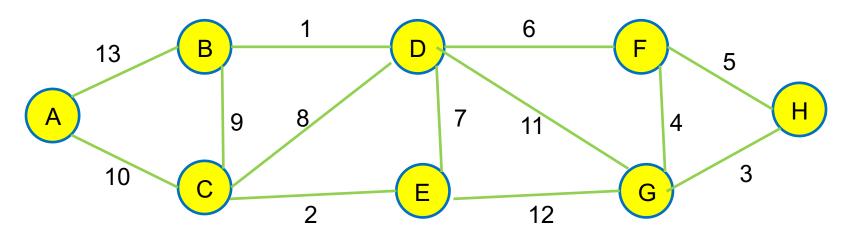
Kruskal's Algorithm



Each connected component is considered a set.

Is it true that an edge (u,v) creates a cycle if and only if both u and v belong to the same connected component (i.e., set)?

Kruskal's Algorithm



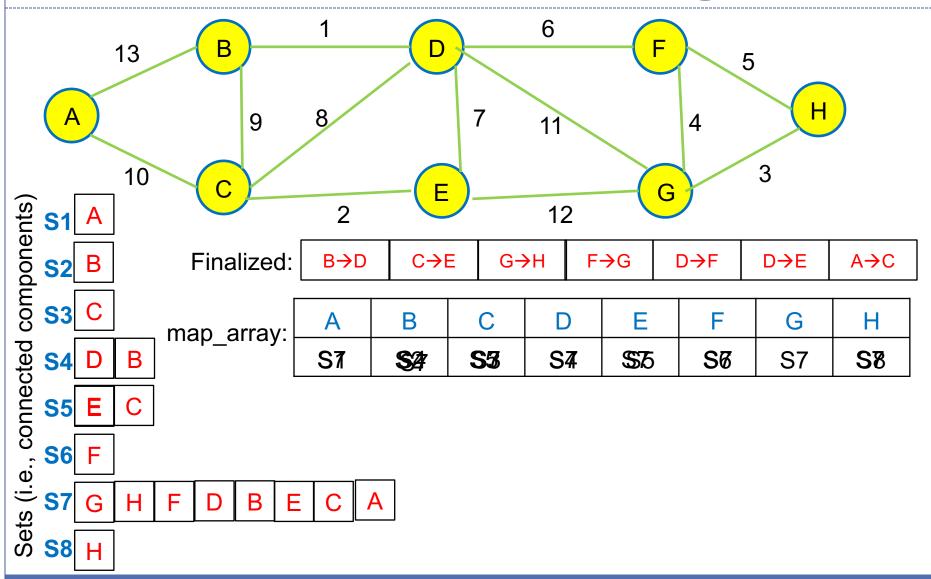
Union-Find Data Structure

- \bullet For each set $S_{\text{i}}\text{,}$ maintain the vertices in it as a linked list.
- Create an array (called map_array) that will record, for each vertex, the set that it belongs to. E.g.,
 - O If vertex 3 belongs to set S4, then map array[3] = S4

SET ID(u)

- Return map_array[u] # Cost O(1)
- UNION_SETS(S_i , S_j) # Let S_i be the smaller set. We will merge S_i into S_j
- For each vertex v in Si
 - \circ map_array[v] = S_j # Update the set of v in map_array
- Append S_i to the linked list of S_i
- # Time complexity of UNION_SETS?
- O(x) where x is the number of elements in the smaller set.

Illustration of Kruskal's Algorithm



Kruskal's Algorithm: Complexity

return Finalized

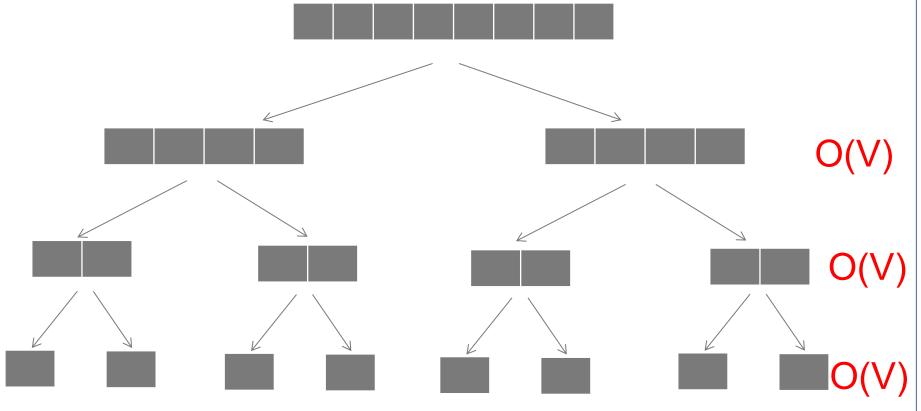
But this is not tight as we assumed the cost of UNION_SETS to be O(V) for each call leading to overall cost of O(EV). A closer look reveals that the total cost of UNION_SETS is O(V log V)

Time Complexity:

- Initialization: O(V)
- Sorting edges: O(E log E)
 - E log E \leq E log V² = 2 E log V \rightarrow O(E log V)
- For loop executes O(E) times
 - SET_ID() takes O(1)
 - UNION_SET() takes O(x) where x is the smaller set (in worst case O(V))
- Total cost: O(EV)

Complexity of UNION_SETS

- The cost of UNION_SETS(S1,S2) is O(x) where x is the size of the smaller set.
- What is the worst case for UNION_SETS(S1,S2)?
 - o The worst case for UNION_SETS(S1,S2) is when both sets are of equal size.



Height: O(log V)

Overall Complexity: O(V log V)

Kruskal's Algorithm: Complexity

return Finalized

Time Complexity:

- Initialization: O(V)
- Sorting edges: O(E log E)
 - E log E = E log V^2 = 2 E log V \rightarrow O(E log V)
- For loop executes O(E) times
 - SET ID() takes O(1)
- UNION_SET() takes O(V log V) in total
- Total cost: O(E log V + V log V) → O(E log V)

Kruskal's Algorithm: Correctness

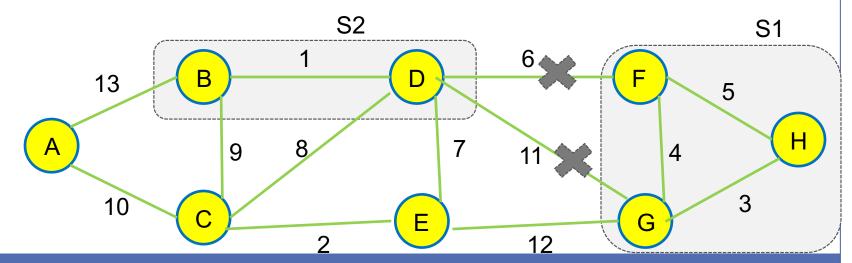
INV: Finalized is a subset of a minimal spanning tree

Base Case:

The invariance is true initially when Finalized is empty

Inductive step

- Assume that Finalized is currently a subset of a MST. We show that after Kruskal's adds an edge, it is still a subset of a MST.
- At an arbitrary step, the algorithm combines two sets (UNION_SETS) say S1 and S2 using an edge <D,F> with weight w.
- Assume that {Finalized Union <D,F>} is <u>not</u> a subset of <u>any</u> MST. We show that this cannot be true.
- Let M be a minimum spanning tree that contains Finalized but excludes <D,F> (see the tree formed by red and blue edges).
- The sets S1 and S2 must be connected by at least one edge in every spanning tree (e.g., M).
- Let <D,G> be the first edge on the path that connects S1 and S2 in the minimum spanning tree M.
- We will get a spanning tree if we add <D,F> in M and remove <D,G>. Let's call this spanning tree T.
- The weight of T is smaller or equal to M because the weight of <D,F> is smaller or equal to <D,G>.
- Hence, T is also a minimum spanning tree if M is a minimum spanning tree, i.e., the invariance holds after adding <D,F> in Finalized



FIT2004: Lec-10: Minimum Spanning Trees

Summary

Take home message

 Prim's Algorithm and Kruskal's algorithm both are greedy algorithm that correctly determine minimum spanning trees.

Things to do (this list is not exhaustive)

- Make sure you understand
 - the two algorithms especially how to implement Union-Find data structure for Kruskal's algorithm
 - the proofs of correctness for each of the two algorithms
- Start preparing for the final exam

Coming Up Next

Network Flow