COMMONWEALTH OF AUSTRALIA

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FIT3155 S1/2020: Advanced Algorithms and Data Structures

Week 10: Linear Programming

Faculty of Information Technology, Monash University

Linear Programming introduction

- Arose out of efforts dating back to World War-II when Mathematicians were asked to solve logistics problems for military operations.
- Linear Programming is an combinatorial optimization method to operate specific systems optimally under resource constraints.
- It was introduced by Dantzig in 1947 in a paper entitled "Programming in Linear Structure"
- A method of solving such problems (**simplex method**) was proposed in 1949.

Dantzig



"George Dantzig will go down in history as one of the founders and chief contributors to the field of mathematical programming, and as the creator of the simplex algorithm for linear programming, perhaps the most important algorithm developed in the 20th century." – Richard Karp.

Consider this problem

- ullet A small manufacturer makes two products A and B
- ullet Each of these products require 2 resources R_1 and R_2
- Each unit of A requires 1 unit of R_1 and 3 units of R_2
- ullet Each unit of ${\it B}$ requires 1 unit of R_1 and 2 units of R_2
- ullet But the manufacturer has only ullet units of R_1 and ullet units of R_2
- On every unit of A sold the manufacturer makes \$6 profit
- ullet On every unit of ${\it B}$ sold the manufacturer makes \$5 **profit**

Problem statement

How many units of the product A and B should the manufacturer produce to **maximize** profit?

Problem statements

- A small manufacturer makes two products
 A and B
- Each of these products require 2 resources R₁ and R₂
- Each unit of A requires 1 unit of $R_1...$
- ullet ...and 3 units of R_2
- Each unit of *B* requires 1 unit of $R_1...$
- ullet ...and ullet units of R_2
- But the manufacturer has only 5 units of R₁...
- ullet ...and 12 units of R_2
- On every unit of A sold the manufacturer makes \$6 profit
- On every unit of B sold the manufacturer makes \$5 profit

Formalism

Problem statements

- $\bullet \ \ \, \text{A small manufacturer makes two products} \\ \ \, A \ \ \, \text{and} \ \, B$
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$$z = 6x + 5y$$

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$$x + y \le 5$$

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Formalism

x = #units of product A produced y = #units of product B produced

 $maximize(profit) \ z = 6x + 5y$

$$x + y \le 5$$

$$3x + 2y \le 12$$

$$x, y \ge 0$$

Now let's introduce some technical jargon

Decision Variables

The variable x and y are called **decision variables**

Objective function

The profit function (z = 6x + 5y) that is being optimized is called the **objective function.**

Constraints

The restrictions

$$x + y \le 5$$
$$3x + 2y \le 12$$
$$x, y > 0$$

are called (linear) **constraints**. These restrict the values the decision variables can take.

We now have a linear programming formulation

x = number of units of product A produced y = number of units of product B produced

maximize (profit)
$$z = 6x + 5y$$

$$x + y \le 5$$
$$3x + 2y \le 12$$
$$x, y \ge 0$$

All standard Linear Programming (LP) problems have...

A linear objective function

A set of linear constraints

A non-negativity constraint on all decision variables

Linear Programming problem in its standard form

Maximize

$$z = c_1 * x_1 + c_2 * x_2 + \dots + c_n * x_n$$

Subject to the constraints:

$$a_{11} * x_1 + a_{12} * x_2 + \dots + a_{1n} * x_n \le b_1$$

$$a_{21} * x_1 + a_{22} * x_2 + \dots + a_{2n} * x_n \le b_2$$

$$\vdots$$

$$a_{m1} * x_1 + a_{m2} * x_2 + \dots + a_{mn} * x_n \le b_m$$

and

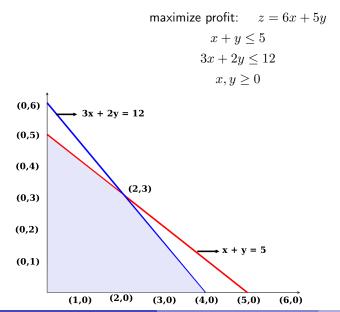
$$x_1, x_2, \cdots x_n \geq 0$$

Gaining insights from a graphical solution – although it is practically useless!

A graphical solution is applicable in practice to solutions involving 2 (or even 3 decision variables).

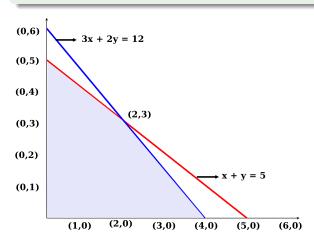
Let's use the example linear programming problem we have considered so far to gain some insights about solutions of **general** linear programs.

Graphical Solution



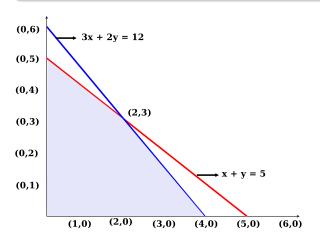
Feasible region

...is the region where the given linear program has **feasible solutions** satisfying all its constraints



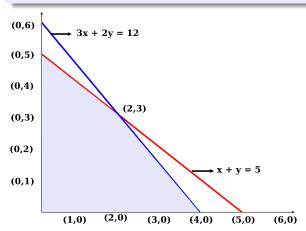
Insight 1

Feasible region is a convex polyhedron.



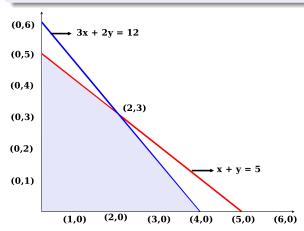
Insight 2

For any point in the **feasible region**, there is always a point on the boundary of the feasible region that will **dominate** it (i.e., will give a better evaluation of the **objective function**)



Insight 3

Further, among all points on the boundary of the feasible regions, there is at least one corner point of the feasible region that will always dominate, given the objective function.



Now lets approach this Graphical solution with some Algebra

- We will approach a solution algebraically this is quite simple!
- An important step here is to convert the inequality constraints into equality constraints.
- This is achieved by adding slack variables to convert an inequality to an equality.

Algebraic (graphical) solution – changing inequality constraints to equality constraints

First constraint: $x + y \le 5$ becomes

$$x + y + s = 5$$

where s > 0

Similarly the second constraint $3x + 2y \le 12$ becomes

$$3x + 2y + t = 12$$

where $t \ge 0$

Objective function can be written as:

Maximize
$$z = 6x + 5y$$

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Algebraic (graphical) solution – Formulation of the problem

Therefore, solving this problem:

Maximize

$$z = 6x + 5y$$

Subject to the constraints:

$$x + y \le 5$$

$$3x + 2y \le 12$$

and $x, y \ge 0$

...is same as solving this problem:

Maximize

$$z = 6x + 5y$$

Subject to the constraints:

$$x + y + s = 5$$

$$3x + 2y + t = 12$$

and $x, y, s, t \ge 0$

Algebraic (graphical) solution – Can a solution to be found in this setup?

Maximize

$$z = 6x + 5y$$

Subject to the constraints:

$$x + y + s = 5$$

$$3x + 2y + t = 12$$

and $x, y, s, t \ge 0$

There are 4 variables and 2 equations! Can a solution be found?

Algebraic (graphical) solution – Can a solution to be found in this setup?

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$$z = 6x + 5y$$

Subject to the constraints:

$$x + y + s = 5$$

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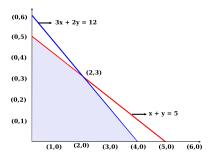
and $x, y, s, t \ge 0$

There are 4 variables and 2 equations! Can a solution be found?

Solutions can be found for any 2 variables, if the remaining 2 variables are 'fixed'!

Algebraic (graphical) solution – possible ways of fixing variables

Fix x, y	and solve for s,t
Fix x, s	and solve for y, t
Fix x, t	and solve for y, s
Fix y, s	and solve for x, t
Fix y, t	and solve for x, s
Fix s,t	and solve for x, y



Algebraic (graphical) solution

Maximize

$$z = 6x + 5y$$

Subject to the constraints:

$$x + y + s = 5$$

$$3x + 2y + t = 12$$

and $x, y, s, t \ge 0$

By fixing the variables in the left hand column to zeros, we get:

Non-Basic Variables	Basic Variables
Fixing $x = 0, y = 0$	We get $s = 5, t = 12$
Fixing $x = 0, s = 0$	We get $y = 5, t = 2$
Fixing $x = 0, t = 0$	We get $y = 6, s = -1$
Fixing $y = 0, s = 0$	We get $x = 5, t = -3$
Fixing $y = 0, t = 0$	We get $x = 4, s = 1$
Fixing $s = 0, t = 0$	We get $x = 2, y = 3$

Counter-intuitive terminology alert!!!

In the context of linear programming, we get to hear the following terms that might appear counter-intuitive:

Non-basic variables

- Non-basic variables are the variable that are fixed to zero
- They are so called, because they are OUTSIDE the basis of the linear programming problem – you can ignore this part.

Basic variables

- The remaining **free** variables are called **basic** variables.
- Basic variables are those that are WITHIN the basis of the linear programming problem – you can ignore this part.

Objective

$$z = 6x + 5y$$

Non-Basic Variables	Basic Variables	value of objective
Fix x = 0, y = 0	s = 5, t = 12	

Objective

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Non-Basic Variables	Basic Variables	value of objective
Fix x = 0, y = 0	s = 5, t = 12	z = 0
Fix x = 0, s = 0	y = 5, t = 2	'

Objective

$$z = 6x + 5y$$

Non-Basic Variables	Basic Variables	value of objective
Fix x = 0, y = 0	s = 5, t = 12	z = 0
Fix $x = 0, s = 0$	y = 5, t = 2	z=25
Fix x = 0, t = 0	y = 6, s = -1	'

Objective

$$z = 6x + 5y$$

Non-Basic Variables	Basic Variables	value of objective
Fix x = 0, y = 0	s = 5, t = 12	z = 0
Fix $x = 0, s = 0$	y = 5, t = 2	z=25
Fix x = 0, t = 0	y = 6, s = -1	Infeasible
Fix y = 0, s = 0	x = 5, t = -3	'

Objective

$$z = 6x + 5y$$

Non-Basic Variables	Basic Variables	value of objective
Fix x = 0, y = 0	s = 5, t = 12	z = 0
Fix $x = 0, s = 0$	y = 5, t = 2	z=25
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Fix $y = 0, s = 0$	x = 5, t = -3	Infeasible
Fix y = 0, t = 0	x = 4, s = 1	'

Objective

$$z = 6x + 5y$$

Non-Basic Variables	Basic Variables	value of objective
Fix x = 0, y = 0	s = 5, t = 12	z = 0
Fix x = 0, s = 0	y = 5, t = 2	z=25
Fix x = 0, t = 0	y = 6, s = -1	Infeasible
Fix y = 0, s = 0	x = 5, t = -3	Infeasible
Fix y = 0, t = 0	x = 4, s = 1	z=24
Fix s = 0, t = 0	x = 2, y = 3	

Algebraic (graphical) Solution – exhaustive search

Objective

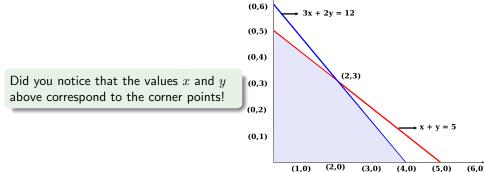
$$z = 6x + 5y$$

Now let's evaluate the objective function corresponding to all possible ways of choosing/fixing variables to become non-basic variables:

Non-Basic Variables	Basic Variables	value of objective
Fix x = 0, y = 0	s = 5, t = 12	z = 0
Fix x = 0, s = 0	y = 5, t = 2	z=25
Fix x = 0, t = 0	y = 6, s = -1	Infeasible
Fix y = 0, s = 0	x = 5, t = -3	Infeasible
Fix y = 0, t = 0	x = 4, s = 1	z = 24
$Fix\ s = 0, t = 0$	x = 2, y = 3	z=27

Algebraic (graphical) solution – exhaustive search

Non-Basic Variables	Basic Variables	value of objective
Fix x = 0, y = 0	s = 5, t = 12	z = 0
Fix $x = 0, s = 0$	y = 5, t = 2	z = 25
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Fix y = 0, t = 0	x = 4, s = 1	z = 24
Fix $s = 0, t = 0$	x = 2, y = 3	z = 27



• Let some general linear programming formulation contain

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 - ► N decision variables

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 - ▶ *m* linear constraints

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- Assign N out of N+m (decision+slack) variables to 0, and solve for the remaining m variables.

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- There are $^{N+m}C_N$ such possibilities, sigh!
- Substitute the values of that N decision variables take into the objective function.
- Once all possibilities are explored, choose the optimum over all the solutions.

Disadvantages of Algebraic (graphical) method

- ullet Grows combinatorially for large N
- Evaluates infeasible solutions.
- Does not tell you if the optima has been reached. The search is exhaustive (brute-force).
- Does not give progressively better solutions (in terms of the objective function) – the search is fairly random.

Simplex Method to solving linear programming problems

Simplex Method is a way to solve this problem. Advantages of simplex are:

- Polynomial time (in practice, but not in worst case)
- Does NOT evaluate infeasible solutions.
- Explores progressively better solutions.
- Tells you when the optima has been reached and stops.

Simplex Method – explored in two forms

We will now see two forms of the simplex method using the example we have been considering:

- Algebraic form of simplex: this will give you the insights of what it really is doing!
- Tabular (or tableau) form of simplex: this will allow you to crank-turn rather easily and implement a program in the lab!

Maximize

$$z = 6x + 5y$$

Subject to the constraints:

$$x + y + s = 5$$

$$3x + 2y + t = 12$$

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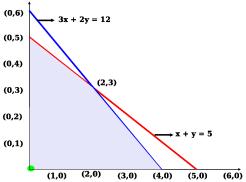
and $x, y, s, t \ge 0$

Start

Start by choosing x and y as **non-basic variables** (i.e., variables that are set to zero.)

This gives the solutions to s and t as s=5 and t=12 respectively.

Visualize what this solution of (x, y) = (0, 0) implies:



Maximize

$$z = 6x + 5y$$

Subject to the constraints:

$$x + y + s = 5$$

$$3x + 2y + t = 12$$

and $x, y, s, t \ge 0$

First iteration

Rewrite the constraints in terms of s and t (now basic variables)

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First iteration

Rewrite the constraints in terms of s and t (now basic variables)

$$s = 5 - x - y$$

Maximize

$$z = 6x + 5y$$

Subject to the constraints:

$$x + y + s = 5$$

$$3x + 2y + t = 12$$

and $x, y, s, t \ge 0$

First iteration

Rewrite the constraints in terms of s and t (now basic variables)

$$s = 5 - x - y$$

$$t = 12 - 3x - 2y$$

Maximize

$$z = 6x + 5y$$

Subject to the constraints:

$$x + y + s = 5$$

$$3x + 2y + t = 12$$

and $x, y, s, t \ge 0$

First iteration

Rewrite the constraints in terms of s and t (now basic variables)

$$s = 5 - x - y$$

$$t = 12 - 3x - 2y$$

Objective is simply: z = 6x + 5y

Problem as we transformed it in the previous slide

Maximize

$$z = 6x + 5y$$

Subject to the constraints (notice we have rewritten the constraints as in the previous slide):

$$s = 5 - x - y$$

$$t = 12 - 3x - 2y$$

and $x, y, s, t \ge 0$

• Recall, currently x = 0 and y = 0. Therefore the objective function, substituting these values, is z = 0.

^{*}To increase the objective function, if the coefficient of the variable in the objective function is positive, you increase the variable. Else, if its coefficient is negative you decrease the variable.

Problem as we transformed it in the previous slide

Maximize

$$z = 6x + 5y$$

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• Recall, currently x = 0 and y = 0. Therefore the objective function, substituting these values, is z = 0. Can we improve z?

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Maximize

$$z = 6x + 5y$$

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- Recall, currently x = 0 and y = 0. Therefore the objective function, substituting these values, is z = 0. Can we improve z?
- Yes. We can either **increase*** the value of x or **increase*** the value of y.

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Problem as we transformed it in the previous slide

Maximize

$$z = 6x + 5y$$

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$$s = 5 - x - y$$

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- Recall, currently x = 0 and y = 0. Therefore the objective function, substituting these values, is z = 0. Can we improve z?
- Yes. We can either **increase*** the value of x or **increase*** the value of y.
- In simplex, you improve only one variable at a time.

^{*}To increase the objective function, if the coefficient of the variable in the objective function is positive, you increase the variable. Else, if its coefficient is negative you decrease the variable.

Problem as it stands!

Maximize

$$z = 6x + 5y$$

Subject to the constraints

$$s = 5 - x - y$$

$$t = 12 - 3x - 2y$$

and $x, y, s, t \ge 0$

 Choose to increase x (since it has a larger coefficient of the two choices, hence gives higher increase of the objective).

Problem as it stands!

Maximize

$$z = 6x + 5y$$

Subject to the constraints

$$s = 5 - x - y$$

$$t = 12 - 3x - 2y$$

- ullet Choose to increase x (since it has a larger coefficient of the two choices, hence gives higher increase of the objective).
- However, having chosen to increase x, we can either increase it:

Problem as it stands!

Maximize

$$z = 6x + 5y$$

Subject to the constraints

$$s = 5 - x - y$$

$$t = 12 - 3x - 2y$$

- Choose to increase x (since it has a larger coefficient of the two choices, hence gives higher increase of the objective).
- However, having chosen to increase x, we can either increase it:
 - from x = 0 to x = 5 according to the **first** constraint.

Problem as it stands!

Maximize

$$z = 6x + 5y$$

Subject to the constraints

$$s = 5 - x - y$$

$$t = 12 - 3x - 2y$$

- Choose to increase x (since it has a larger coefficient of the two choices, hence gives higher increase of the objective).
- However, having chosen to increase x, we can either increase it:
 - from x = 0 to x = 5 according to the first constraint. Anything more will violate the non-negativity constraint for the slack variable s. Or

Problem as it stands!

Maximize

$$z = 6x + 5y$$

Subject to the constraints

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- Choose to increase x (since it has a larger coefficient of the two choices, hence gives higher increase of the objective).
- However, having chosen to increase x, we can either increase it:
 - from x = 0 to x = 5 according to the first constraint. Anything more will violate the non-negativity constraint for the slack variable s. Or
 - from x=0 to x=4 according to the **second** constraint.

Problem as it stands!

Maximize

$$z = 6x + 5y$$

Subject to the constraints

$$s = 5 - x - y$$

$$t = 12 - 3x - 2y$$

- Choose to increase x (since it has a larger coefficient of the two choices, hence gives higher increase of the objective).
- ullet However, having chosen to increase x, we can either increase it:
 - from x = 0 to x = 5 according to the first constraint. Anything more will violate the non-negativity constraint for the slack variable s. Or
 - from x=0 to x=4 according to the second constraint. Anything more will violate the non-negativity constraint for t.

Problem as it stands!

Maximize

$$z = 6x + 5y$$

Subject to the constraints

$$s = 5 - x - y$$

$$t = 12 - 3x - 2y$$

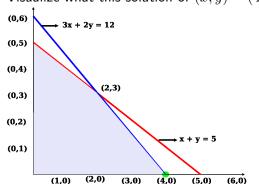
- Choose to increase x (since it has a larger coefficient of the two choices, hence gives higher increase of the objective).
- However, having chosen to increase x, we can either increase it:
 - from x=0 to x=5 according to the first constraint. Anything more will violate the non-negativity constraint for the slack variable s. Or
 - from x=0 to x=4 according to the second constraint. Anything more will violate the non-negativity constraint for t.
- Choosing the **minimum** of x=5 and x=4 will ensure that both $s,t\geq 0$.

• Since we have chosen the **minimum increase** of x from x=0 to x=4, x enters the basis, while t exits the basis (x=4, $\implies t=0$).

- Since we have chosen the **minimum increase** of x from x=0 to x=4, x enters the basis, while t exits the basis (x=4, $\implies t=0$).
- The new set of **non-basic variables** are therefore y **and** t, and **basic variables** are x **and** s. That is, x = 4, s = 1, y = 0, t = 0.

- Since we have chosen the **minimum increase** of x from x=0 to x=4, x enters the basis, while t exits the basis (x=4), x=0.
- The new set of **non-basic variables** are therefore y and t, and **basic variables** are x and s. That is, x = 4, s = 1, y = 0, t = 0.

Visualize what this solution of (x, y) = (4, 0) implies



- Since we have chosen the **minimum increase** of x from x=0 to x=4, x enters the basis, while t exits the basis (x=4, $\implies t=0$).
- The new set of **non-basic variables** are therefore y and t, and **basic variables** are x and s. That is, x = 4, s = 1, y = 0, t = 0.

Rewrite the constraints in terms of the new basic variables

Rewrite the second constraint (t = 12 - 3x - 2y), now with x as the **basic variable**:

$$\mathbf{x} = 4 - \frac{2}{3}y - \frac{1}{3}t$$

The first constraint in the previous iteration was s=5-x-y. Rewriting this by substituting x from above, becomes:

$$s = 1 - \frac{1}{3}y + \frac{1}{3}t$$

Problem as it is now transformed – second iteration

$$\mathbf{x} = 4 - \frac{2}{3}y - \frac{1}{3}t$$
$$s = 1 - \frac{1}{3}y + \frac{1}{3}t$$

Objective was previously to maximize:

$$z = 6x + 5y$$

now becomes (in terms of the new non-basic variables y and t)

$$z = 24 + y - 2t$$

Problem as it is now transformed – second iteration

$$x = 4 - \frac{2}{3}y - \frac{1}{3}t$$
$$s = 1 - \frac{1}{3}y + \frac{1}{3}t$$

Objective was previously to maximize:

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$$z = 24 + y - 2t$$

Notice how the objective function is growing

Previously, z=0 (with x and y as the non-basic variables). Now, z=24 when y=0 and t=0 are the non-basic variables

Problem as it is now transformed – second iteration

$$\mathbf{x} = 4 - \frac{2}{3}y - \frac{1}{3}t$$
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Notice how the objective function is growing

Previously, z=0 (with x and y as the non-basic variables). Now, z=24 when y=0 and t=0 are the non-basic variables

Can z be increased further?

(Note: What we are doing here is a **repetition** of the steps/logic undertaken in the previous iteration)

 To increase z further, we can either increase y (since coefficient in the objective is positive) or decrease t (since the coefficient in the objective is negative.

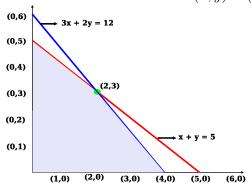
ullet Decreasing t is infeasible because t is already zero and any further decrease will violate non-negativity constraint. Therefore, our only choice here is to **increase** y

• However, y can only be increased from y=0 to y=3 (based on the second equation) for the solution to be feasible.

Since we have chosen to **increase** y **from 0 to 3**, the new **basic variables** are x, y whose current values are x = 2 and y = 3 and the non-basic variables are s = 0, t = 0.

Since we have chosen to **increase** y **from 0 to 3**, the new **basic variables** are x, y whose current values are x = 2 and y = 3 and the non-basic variables are s = 0, t = 0.

Visualize what this solution of (x, y) = (2, 3) implies:



Since we have chosen to **increase** y **from 0 to 3**, the new **basic variables** are x, y whose current values are x = 2 and y = 3 and the non-basic variables are s = 0, t = 0.

Rewrite the constraints in terms of the new basic variables we rewrite the second equation $(s = 1 - \frac{1}{3}y + \frac{1}{3}t)$ with y as the **basic** variable:

$$y = 3 - 3s + t$$

But, the first equation in the iteration is $x=4-\frac{2}{3}y-\frac{1}{3}t$. Rewriting this by substituting y from above, we get:

$$x = 2 + 2s - t$$

Problem as it is now transformed

$$x = 2 + 2s - t$$

$$y = 3 - 3s + t$$

Objective was to maximize:

$$z = 24 + y - 2t$$

now becomes (in terms of new non-basic variables)

$$z = 27 - 3s - t$$

Problem as it is now transformed

$$x = 2 + 2s - t$$

$$y = 3 - 3s + t$$

Objective was to maximize:

$$z = 24 + y - 2t$$

now becomes (in terms of new **non-basic** variables)

$$z = 27 - 3s - t$$

Observe that z=27 when s=0 and t=0 as the new **non-basic variables**

Problem as it is now transformed

$$x = 2 + 2s - t$$

$$y = 3 - 3s + t$$

Objective was to maximize:

$$z = 24 + y - 2t$$

now becomes (in terms of new **non-basic** variables)

$$z = 27 - 3s - t$$

Observe that z=27 when s=0 and t=0 as the new non-basic variables Can z be increased further?

Problem as it is now transformed

$$x = 2 + 2s - t$$

$$y = 3 - 3s + t$$

Objective was to maximize:

$$z = 24 + y - 2t$$

now becomes (in terms of new **non-basic** variables)

$$z = 27 - 3s - t$$

Observe that z=27 when s=0 and t=0 as the new non-basic variables Can z be increased further?

The only way to increase z further is to either **decrease** s and/or **decrease** t. Both both these choices are infeasible Therefore STOP!

When simplex method stopped, the values of **basic variables** were x=2 and y=3 (we get these by substituting s=0 and t=0 (non-basic variables) into the constraints in the previous slide.

These are the **optimum values** of the decision variables x and y for this example problem.

Visualize what this solution of (x, y) = (2, 3) implies:

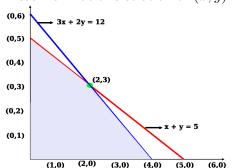


Tableau form of Simplex does **exactly** the same thing but in a convenient tabular way (that can be converted into a computer program)

Now let's see the same simplex method now in **tableau form** (This is now a crank-turning exercise).

			_		
x	y	s	t	RHS	θ

				0			
	6	5	0	0			
	x	y	s	t		RHS	θ
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				0	0 0	
	6	5	0	0		
	x	y	s	t	RHS	θ
s						
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					_		· .
		6	5	0	0		
		x	y	s	t	RHS	θ
0	s						
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		6	=	0	0	- 1		
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		\boldsymbol{x}	y	s	t		RHS	θ
0	s	1	1	1	0		5	
0	t							

		6	5	0	0		
		x	y	s	t	RHS	θ
0	s	1	1	1	0	5	
0	t	3	2	0	1	12	

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		6	5	0	0		
		x	y	s	t	RHS	θ
0	s	1	1	1	0	5	
0	t	3	2	0	1	12	
	$c_j - z_j$						

	C CO CC		u. c .	cco. a		 , 6,6	
		6	5	0	0		
		x	y	s	t	RHS	θ
0	s	1	1	1	0	5	
0	t	3	2	0	1	12	
	$c_j - z_j$	6					
-							

						 9 8	
		6	5	0	0		
		x	y	s	t	RHS	θ
0	s	1	1	1	0	5	
0	t	3	2	0	1	12	
	$c_j - z_j$	6	5				

					0	- 0 - 0	
		6	5	0	0		
		x	y	s	t	RHS	θ
0	s	1	1	1	0	5	
0	t	3	2	0	1	12	
	$c_j - z_j$	6	5	0			

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		U	5	U	U		
		\boldsymbol{x}	y	s	t	RHS	θ
0	s	1	1	1	0	5	
0	t	3	2	0	1	12	
	$c_j - z_j$	6	5	0	0		

					0	- 0 - 0	
		6	5	0	0		
		x	y	s	t	RHS	θ
0	s	1	1	1	0	5	
0	t	3	2	0	1	12	
	$c_j - z_j$	6	5	0	0	0	

					0		
		6	5	0	0		
		x	y	s	t	RHS	θ
0	s	1	1	1	0	5	5
0	t	3	2	0	1	12	
	$c_j - z_j$	6	5	0	0	0	

					0		
		6	5	0	0		
		x	y	s	t	RHS	θ
0	s	1	1	1	0	5	5
0	t	3	2	0	1	12	4
	$c_j - z_j$	6	5	0	0	0	

					0		
		6	5	0	0		
		x	y	s	t	RHS	θ
0	s	1	1	1	0	5	5
0	t	3	2	0	1	12	4
	$c_j - z_j$	6	5	0	0	0	
	s						
	x						

		6	5	0	Û		
		$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	y	s	t	RHS	θ
0	s	1	1	1	0	5	5
0	t	3	2	0	1	12	4
	$c_j - z_j$	6	5	0	0	0	
0	s						
6	x						

		6	5	0	0		
		x	y	s	t	RHS	θ
0	s	1	1	1	0	5	5
0	t	3	2	0	1	12	4
	$c_j - z_j$	6	5	0	0	0	
0	s						
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		6	5	0	0		
		x	y	s	t	RHS	θ
0	s	1	1	1	0	5	5
0	t	3	2	0	1	12	4
	$c_j - z_j$	6	5	0	0	0	
0	s	0	1/3	1	-1/3	1	
6	x	1	2/3	0	1/3	4	

		6	5	0	0		
		x	y	s	t	RHS	θ
0	s	1	1	1	0	5	5
0	t	3	2	0	1	12	4
	$c_j - z_j$	6	5	0	0	0	
0	s	0	1/3	1	-1/3	1	
6	x	1	2/3	0	1/3	4	
	$c_j - z_j$						
	·						

		6	5	0	0		
		x	y	s	t	RHS	θ
0	s	1	1	1	0	5	5
0	t	3	2	0	1	12	4
	$c_j - z_j$	6	5	0	0	0	
0	s	0	1/3	1	-1/3	1	
6	x	1	2/3	0	1/3	4	
	$c_j - z_j$	0	1	0	-2	24	
	·						

		6	5	0	0		
		x	y	s	t	RHS	θ
0	s	1	1	1	0	5	5
0	t	3	2	0	1	12	4
	$c_j - z_j$	6	5	0	0	0	
0	s	0	1/3	1	-1/3	1	
6	x	1	2/3	0	1/3	4	
	$c_j - z_j$	0	1	0	-2	24	
	·						

		6	5	0	0		
		x	y	s	t	RHS	θ
0	s	1	1	1	0	5	5
0	t	3	2	0	1	12	4
	$c_j - z_j$	6	5	0	0	0	
0	s	0	1/3	1	-1/3	1	3
6	x	1	2/3	0	1/3	4	6
	$c_j - z_j$	0	1	0	-2	24	

			_	_	0	, 0 0	ı
		6	5	0	0		
		x	y	s	t	RHS	θ
0	s	1	1	1	0	5	5
0	t	3	2	0	1	12	4
	$c_j - z_j$	6	5	0	0	0	
0	s	0	1/3	1	-1/3	1	3
6	x	1	2/3	0	1/3	4	6
	$c_j - z_j$	0	1	0	-2	24	
	y						
	x						

		6	5	0	0		
		x	y	s	t	RHS	θ
0	s	1	1	1	0	5	5
0	t	3	2	0	1	12	4
	$c_j - z_j$	6	5	0	0	0	
0	s	0	1/3	1	-1/3	1	3
6	x	1	2/3	0	1/3	4	6
	$c_j - z_j$	0	1	0	-2	24	
	y	0	1	3	-1	3	
	x						

		6	5	0	0		
		x	y	s	t	RHS	θ
0	s	1	1	1	0	5	5
0	t	3	2	0	1	12	4
	$c_j - z_j$	6	5	0	0	0	
0	s	0	1/3	1	-1/3	1	3
6	x	1	2/3	0	1/3	4	6
	$c_j - z_j$	0	1	0	-2	24	
	y	0	1	3	-1	3	
	x	1	0	-2	1	2	

		6	5	0	0		
		x	y	s	t	RHS	θ
0	s	1	1	1	0	5	5
0	t	3	2	0	1	12	4
	$c_j - z_j$	6	5	0	0	0	
0	s	0	1/3	1	-1/3	1	3
6	x	1	2/3	0	1/3	4	6
	$c_j - z_j$	0	1	0	-2	24	
5	\overline{y}	0	1	3	-1	3	
6	x	1	0	-2	1	2	

		6	5	0	0		
		x	y	s	t	RHS	θ
0	s	1	1	1	0	5	5
0	t	3	2	0	1	12	4
	$c_j - z_j$	6	5	0	0	0	
0	s	0	1/3	1	-1/3	1	3
6	x	1	2/3	0	1/3	4	6
	$c_j - z_j$	0	1	0	-2	24	
5	y	0	1	3	-1	3	
6	x	1	0	-2	1	2	
	$c_j - z_j$						

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0 + 2 2 0 1 12 1
0
c_j-z_j 6 5 0 0
0 s 0 1/3 1 -1/3 1 3
6 $x \mid 1 \mid 2/3 \mid 0 \mid 1/3 \mid 4 \mid 6$
c_j-z_j 0 1 0 -2 24
5 y 0 1 3 -1 3
6 $x \mid 1 0 -2 1 \mid 2 \mid$
$c_j - z_j$ 0 0 -3 -1 27

Listen to the lecture recording while going through this tableau method

		6	5	0	0		
		x	\dot{y}	s	t	RHS	θ
0	s	1	1	1	0	5	5
0	t	3	2	0	1	12	4
	$c_j - z_j$	6	5	0	0	0	
0	s	0	1/3	1	-1/3	1	3
6	x	1	2/3	0	1/3	4	6
	$c_j - z_j$	0	1	0	-2	24	
5	\overline{y}	0	1	3	-1	3	
6	x	1	0	-2	1	2	
	$c_j - z_j$	0	0	-3	-1	27	

STOP!!!