

## exercise

June 6, 2024

```
[ ]: import numpy as np
      from numpy.linalg import inv
      import matplotlib.pyplot as plt
```

### 1 Exercice 11

$$y = \begin{bmatrix} 3.5 \\ 0.5 \\ 3.7 \\ 2.8 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 2 \\ 1 & 0 \\ 1 & 3 \\ 1 & 1 \end{bmatrix}$$

$$W = \begin{bmatrix} 3 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 3 \end{bmatrix}$$

```
[ ]: y = np.array([[3.5],[0.5],[3.7],[2.8]])
      A = np.array([[1,2],[1,0],[1,3],[1,1]])
      W = 3 * np.identity(4)

      AT = np.transpose(A)
      AT_W_A = np.matmul(AT,np.matmul(W,A))
      inv_AT_W_A = inv(AT_W_A)
      AT_W_y = np.matmul(AT,np.matmul(W,y))

      x_hat = np.matmul(inv_AT_W_A,AT_W_y)
```

$$\hat{x} = \begin{bmatrix} 1.08 \\ 1.03 \end{bmatrix}$$

```
[ ]: y_hat = np.matmul(A,x_hat)
      e_hat = y - y_hat
```

$$\hat{e} = \begin{bmatrix} 0.36 \\ -0.58 \\ -0.47 \\ 0.69 \end{bmatrix}$$

$$W = \begin{bmatrix} 5 & 0 & 0 & 0 \\ 0 & 5 & 0 & 0 \\ 0 & 0 & 5 & 0 \\ 0 & 0 & 0 & 5 \end{bmatrix}$$

```
[ ]: W = 5 * np.identity(4)

AT = np.transpose(A)
AT_W_A = np.matmul(AT,np.matmul(W,A))
inv_AT_W_A = inv(AT_W_A)
AT_W_y = np.matmul(AT,np.matmul(W,y))

x_hat = np.matmul(inv_AT_W_A,AT_W_y)
y_hat = np.matmul(A,x_hat)
e_hat = y - y_hat
```

$$\hat{e} = \begin{bmatrix} 0.36 \\ -0.58 \\ -0.47 \\ 0.69 \end{bmatrix}$$

$$W = \begin{bmatrix} 5 & 0 & 0 & 0 \\ 0 & 5 & 0 & 0 \\ 0 & 0 & 5 & 0 \\ 0 & 0 & 0 & 5 \end{bmatrix}$$

## 2 Exercice 12

$$h(t) = a \cos \omega t + b \sin \omega t$$

$$x = \begin{bmatrix} a & b \end{bmatrix}^T$$

$$h = \begin{bmatrix} -3 & -16 & 6 & 9 & -8 \end{bmatrix}^T$$

$$t = \begin{bmatrix} -0.4 & -0.2 & 0.0 & 0.2 & 0.4 \end{bmatrix}^T$$

```
[ ]: h = np.array([[ -3],[ -16],[ 6],[ 9],[ -8]])
t = np.array([[ -0.4],[ -0.2],[ 0.0],[ 0.2],[ 0.4]])
omega = 10

Acol1 = np.cos(omega * t)
Acol2 = np.sin(omega * t)

A = np.column_stack((Acol1,Acol2))
```

## 2.1 12-a

$$A = \begin{bmatrix} -0.65 & 0.76 \\ -0.42 & -0.91 \\ 1 & 0 \\ -0.42 & 0.91 \\ -0.65 & -0.76 \end{bmatrix}$$

```
[ ]: AT = np.transpose(A)
     AT_A = np.matmul(AT,A)
     inv_AT_A = inv(AT_A)
     AT_h = np.matmul(AT,h)

     x_hat = np.matmul(inv_AT_A,AT_h)
```

$$\hat{x} = [7.32 \quad 9.47]^T$$

```
[ ]: h_hat = np.matmul(A,x_hat)
```

$$\hat{h} = [2.39 \quad -11.66 \quad 7.32 \quad 5.57 \quad -11.95]^T$$

```
[ ]: fig, ax = plt.subplots()
     ax.plot(t,h, label="raw")
     ax.plot(t,h_hat, "k--", label="fitted")
     ax.set_xlabel("t")
     ax.set_ylabel("h")
```

```
[ ]: Text(0, 0.5, 'h')
```

