

Lab 1: IEC 61850 GOOSE Communication Setup and Analysis

Objectives

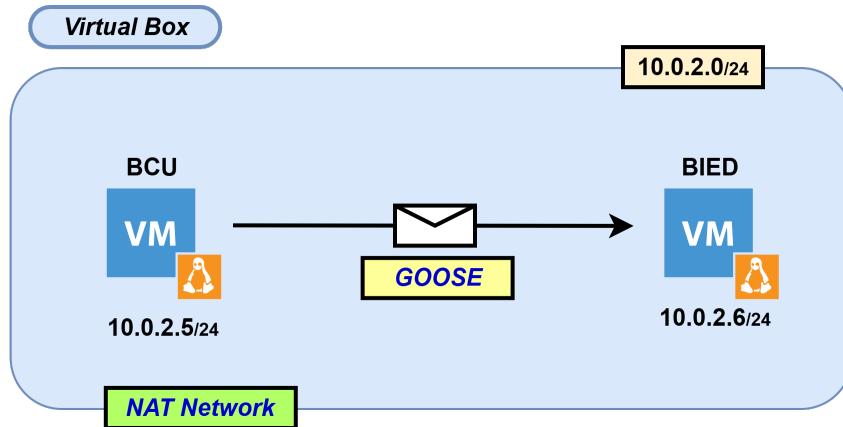


Figure 1: Virtualized lab setup for GOOSE communication using NAT networking

General Installations

Open the terminal (**Ctrl + Alt + T**) —

To update

Note: Choose ‘yes(Y)’ when prompted

```
sudo apt update
```

Guest Additions

```
sudo apt install -y dkms build-essential
sudo mkdir -p /media/cdrom
sudo mount /dev/cdrom /media/cdrom
cd /media/cdrom
sudo ./VBoxLinuxAdditions.run
sudo reboot -h now
```

networking tools (if not present)

```
sudo apt install net-tools
```

Wireshark

```
sudo apt install wireshark
```

Choose ‘yes (Y)’ when prompted. And verify the installation.

```
wireshark -v
```

Install OpenSSL

```
sudo apt install openssl
sudo apt install libssl-dev
```

NAT Network Configuration

1. Create an NAT network.
 - Name: LAN
 - IPv4 Prefix: 10.0.2.0/24
2. Attach both the VMs to the created NAT network “LAN”
3. Manually set the IP addresses of the VMs as below:
 - Gateway: 10.0.2.1
 - Netmask: 255.255.255.0
 - BCU : 10.0.2.5
 - BIED : 10.0.2.6
 - DNS: If IISc WLAN is used, 10.16.25.15,10.16.25.13; otherwise, 8.8.8.8, 8.8.4.4)
4. Reboot the VMs.

```
ip a
```

Ping Test

From BCU

```
ping 10.0.2.6
```

and from BIED

```
ping 10.0.2.5
```

Capture ICMP packets on both devices using Wireshark.

```
sudo wireshark
```

Install libIEC61850 library and build

```
sudo apt install git build-essential cmake
mkdir bcu
cd bcu
git clone https://github.com/mz-automation/libiec61850.git
cd libiec61850
mkdir build
cd build
cmake ..
make
```

Lab01: optional

- Modify the lab 01 to change the CB Status in between and send the updated packets from BCU to the BIED.

publisher - code snapshot

```
int i = 0;

for (i = 0; i < 8; i++) {
    Thread_sleep(1000);

    if(i==4){
        /*
         * Change CB Status from ON to OFF
         */
        /* ON position      10 */
        MmsValue_setBitStringBit(stVal, 0, false); // MSB
        MmsValue_setBitStringBit(stVal, 1, true);
        MmsValue* t = MmsValue_newUtcTimeByMsTime(
            Hal_getTimeInMs());

        GoosePublisher_increaseStNum(publisher);
        GoosePublisher_publish(publisher, dataSetValues);
    }
    else
    {
        if (GoosePublisher_publish(publisher, dataSetValues) ==
            -1) {
            printf("Error sending message!\n");
        }
    }
}

GoosePublisher_destroy(publisher);
}
```