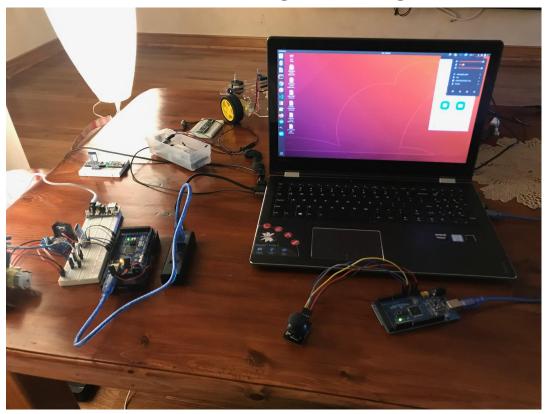
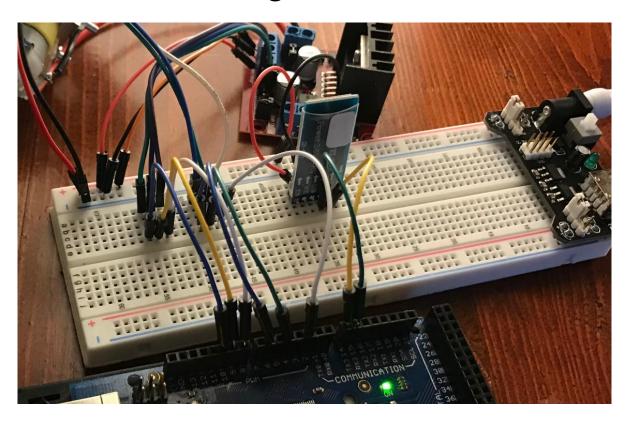
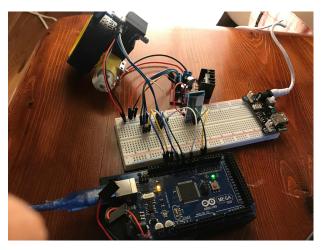
Arduino motor controlling through Bluetooth joystick







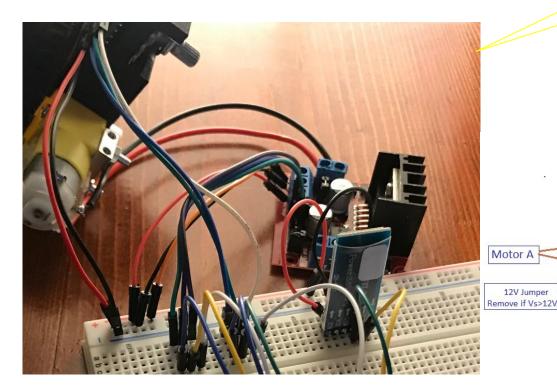


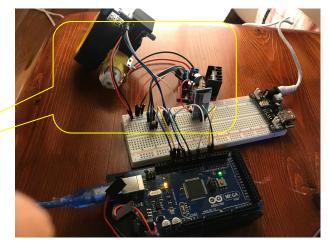


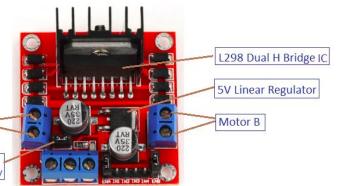




H-Bridge Motor Driver to Breadboard



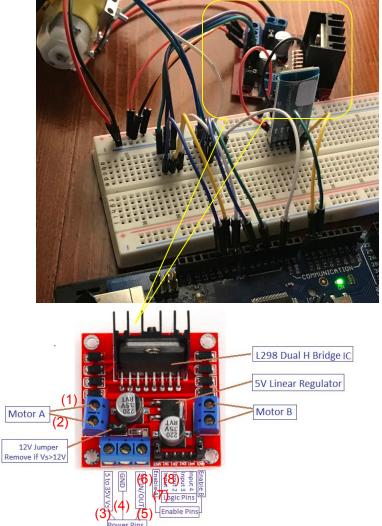




Power Pins

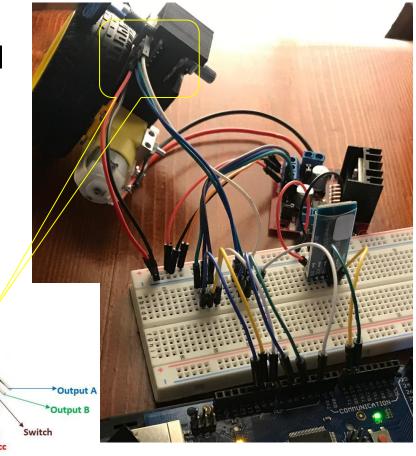
H-Bridge Motor Driver <--> Breadboard <--> Arduino

Motor A	Motor Driver	Breadboard	Arduino
Motor A (black)	Motor A (1)		
Motor A (red)	Motor A (2)		
	5 ~ 35 V -Motor Power (3)	Redline Bus	
	GND (4)	Blueline Bus	GND
	5 V - Motor Driver Login Power (5)	Redline Bus	5V
	ENA (6)		D 8 (PWM)
	IN1 (7)		D 9 (PWM)
	IN2 (8)		D 10(PWM)



Rotary Encoder <--> Breadboard <--> Arduino

Rotary Encoder	Breadboard	Arduino
Output A (CLK)	White wire	D2 (PWM)
Output B (DT)	Green wire	D4 (PWM)
Switch (SW)	Blue wire	D6 (PWM)
VCC	Red wire	5V
GND	Black wire	GND

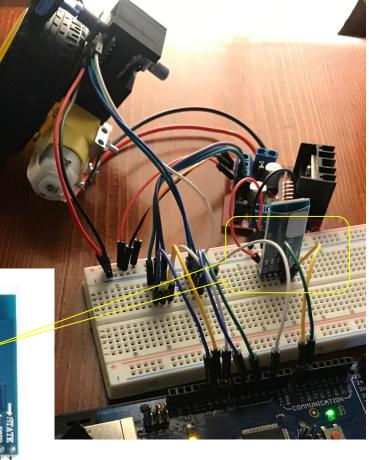


Bluetooth <--> Breadboard <--> Arduino

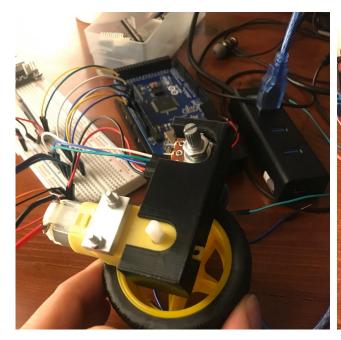
Bluetooth	Breadboard	Arduino
RX	White wire	TX3
TX	Green wire	RX3
VCC	Red wire	5V
GND	Black wire	GND







Encoder <--> Wheel



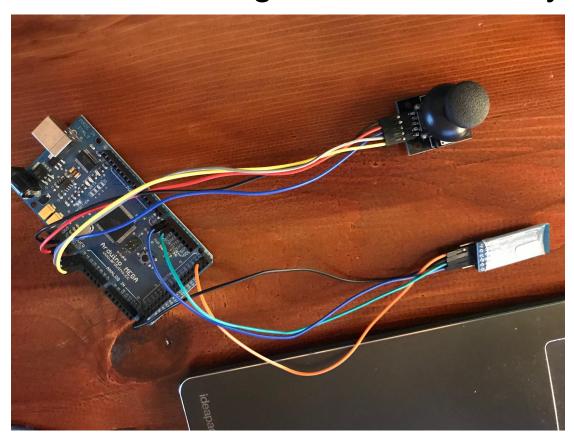




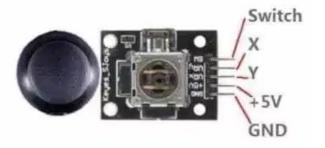
DC Motor Control Pin Map

```
#define PIN WHEEL ENCODER CLK LEFT
#define PIN WHEEL ENCODER DT LEFT
#define PIN WHEEL ENCODER SW LEFT
                                         6
#define PIN MOTOR PWM LEFT 8
#define PIN MOTOR INO LEFT
#define PIN MOTOR IN1 LEFT
                              10
// Bluetooth is connected to Serial3 (RX3,TX3)
// Serial3.Begin (115200);
```

Arduino Wiring for Bluetooth Joystick Control







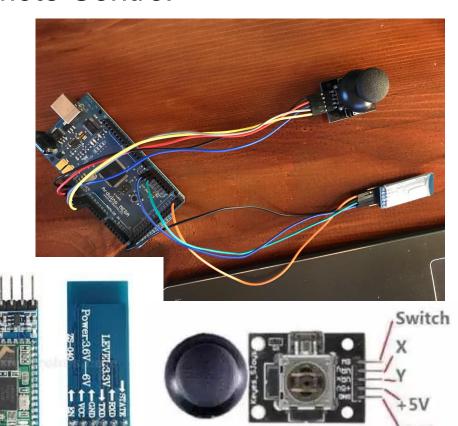
Arduino Wiring for Bluetooth Remote Control

Bluetooth <--> Arduino

Bluetooth	Breadboard	Arduino
RX	White wire	TX3
TX	Green wire	RX3
VCC	Red wire	5V
GND	Black wire	GND

Joystick <--> Arduino

Joystick	Breadboard	Arduino
SW	Yellow wire	A2
X	Grey wire	A1
Υ	Blue wire	A0
+5	Red wire	5V
GND	Black wire	GND



Bluetooth Joystick Controller Pin Map

```
#define PIN_JOY_X A0
#define PIN_JOY_Y A1
#define PIN_JOY_SW A2
```

```
// Bluetooth is connected to Serial3 (RX3,TX3) // Serial3.Begin (115200);
```