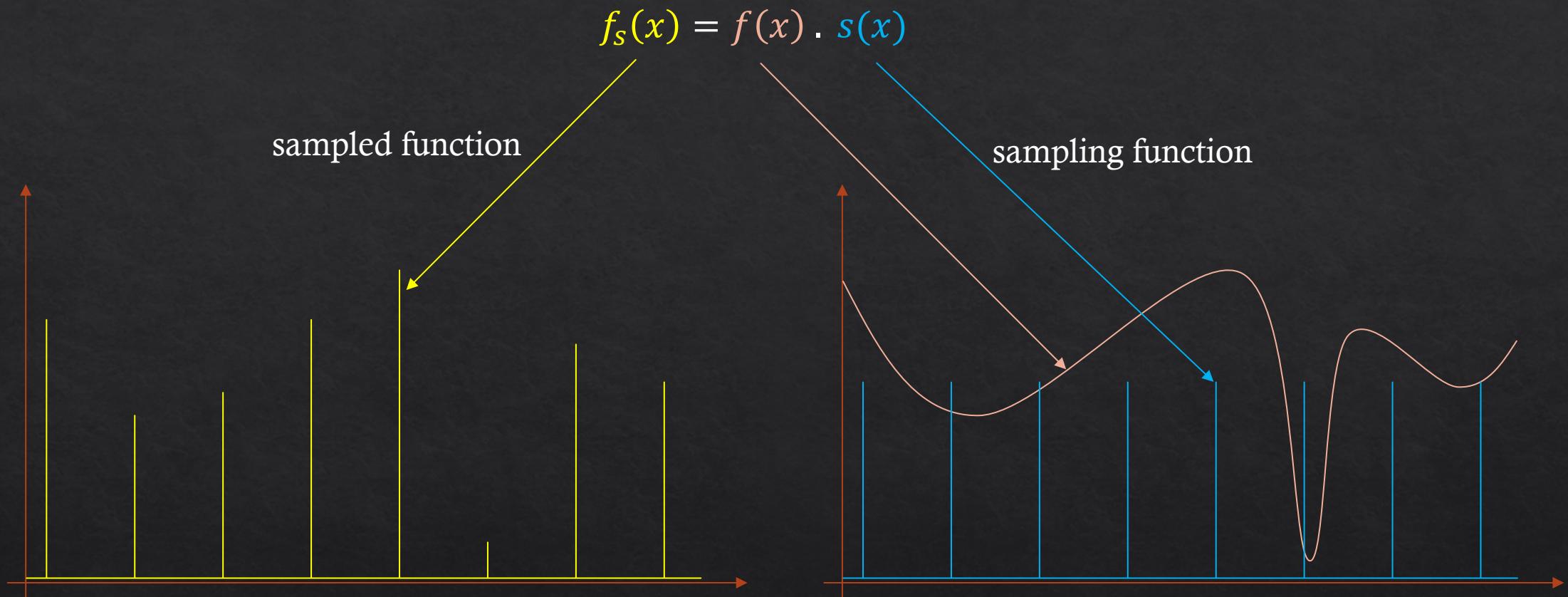


Computer Graphics

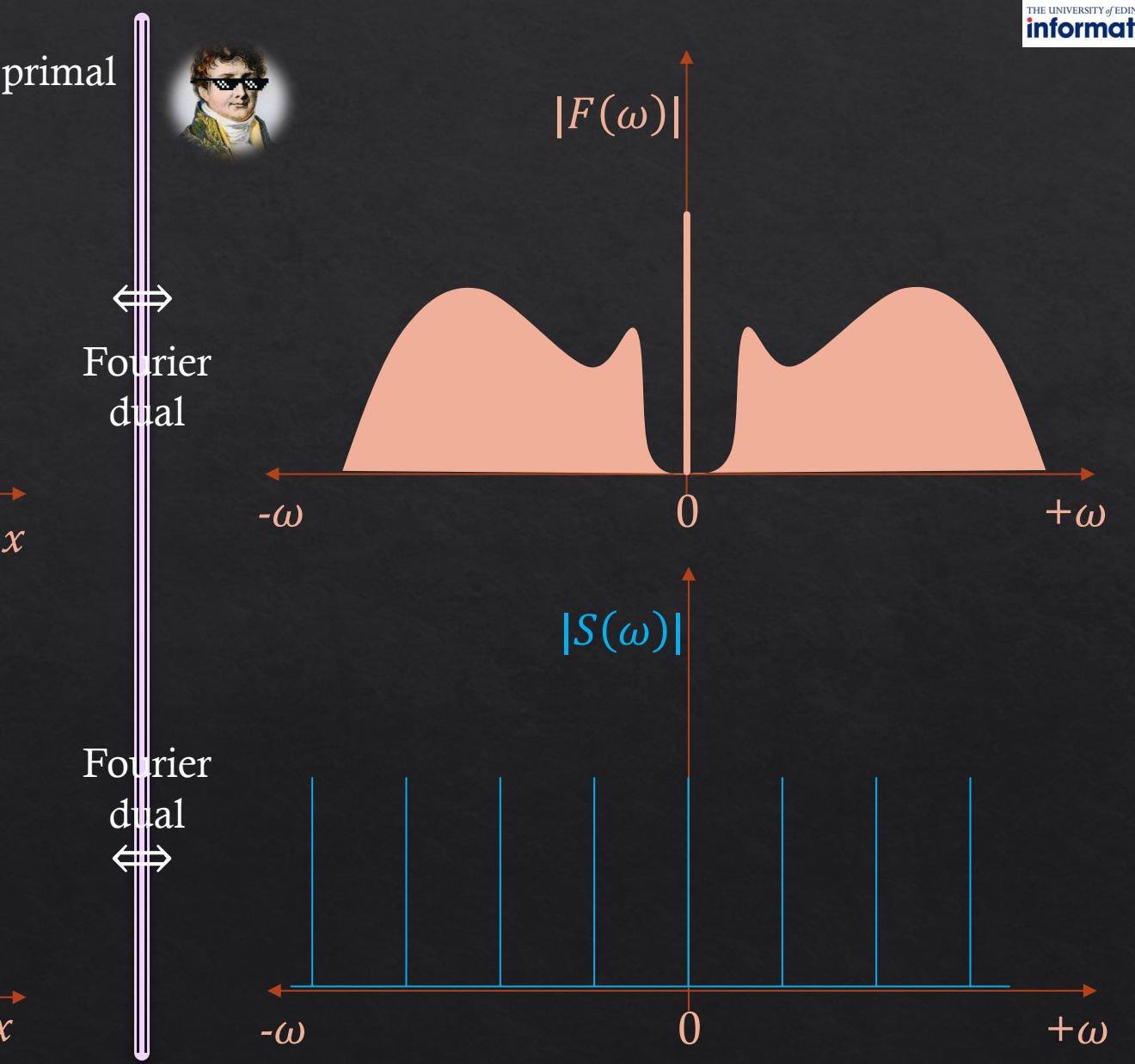
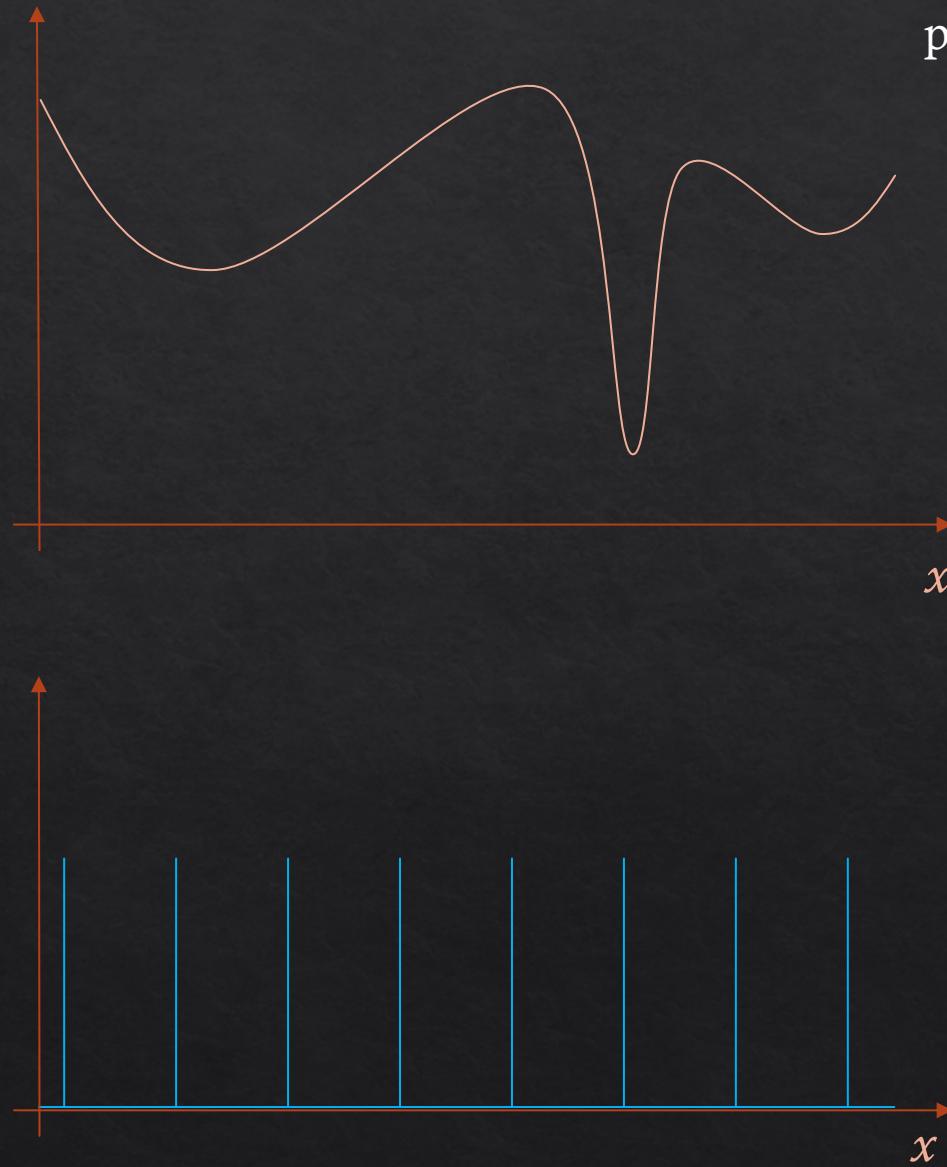
Lecture 12: Sampling II

Kartic Subr

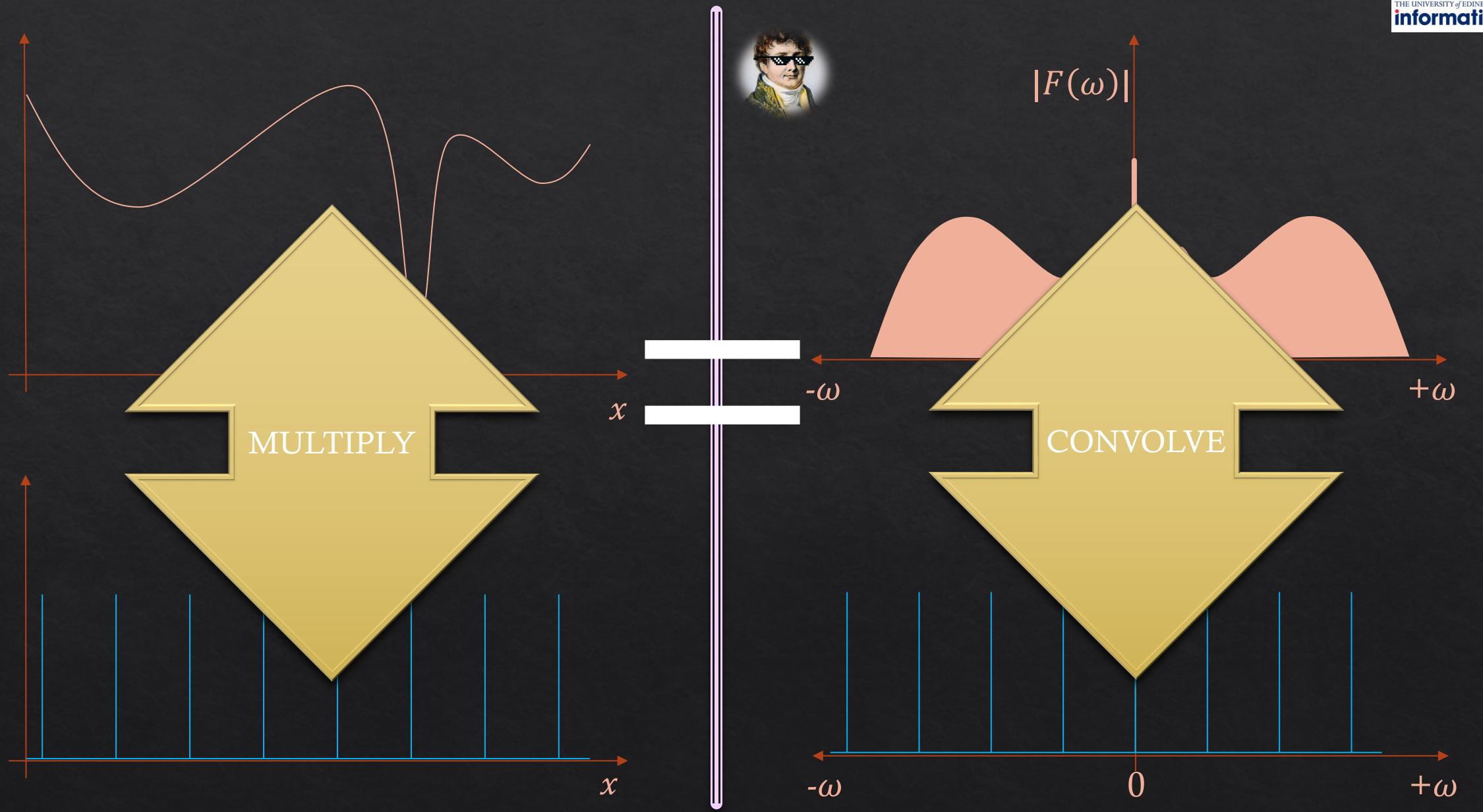
Sampling = multiplication



Functions in Fourier domain



Convolution theorem

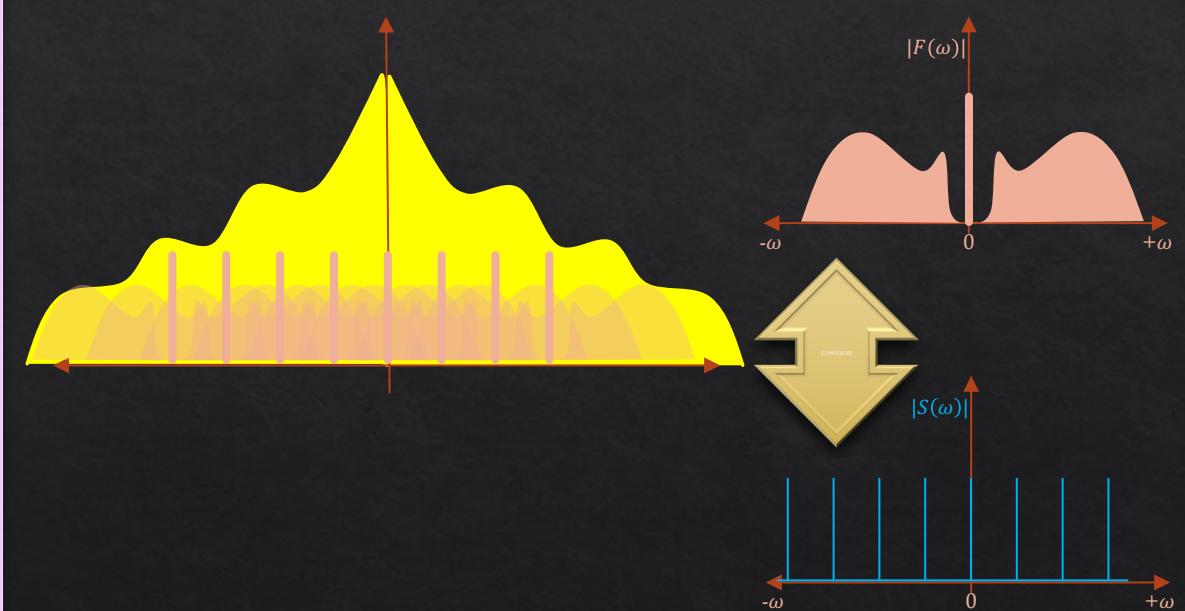


Sampling = convolution (Fourier domain)

$$f_s(x) = f(x) \cdot s(x)$$



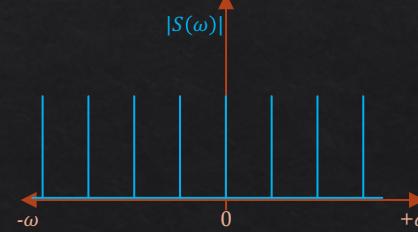
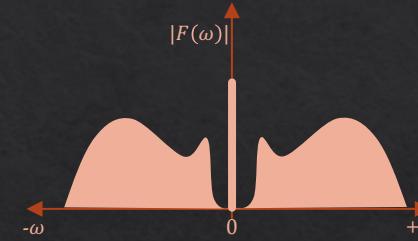
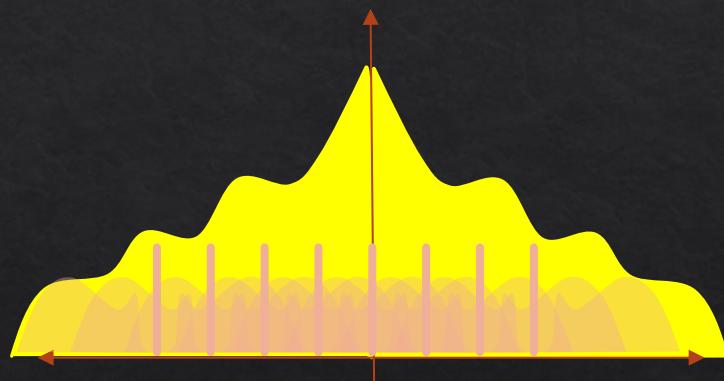
$$F_s(\omega) = F(\omega) \otimes S(\omega)$$



Convolution results in overlapping spectra



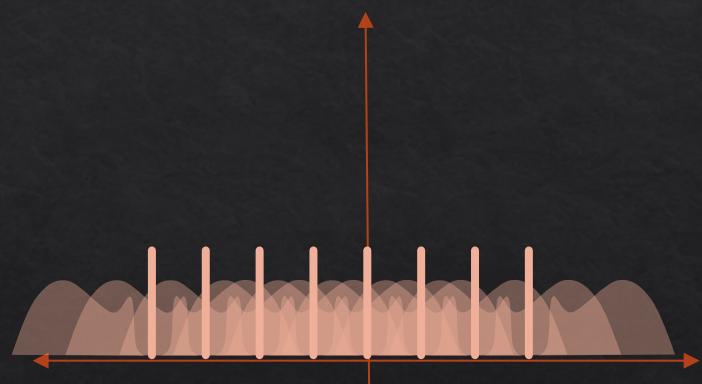
$$F_s(\omega) = F(\omega) \otimes S(\omega)$$



To move these away, change sampling function



$$F_s(\omega) = F(\omega) \otimes S(\omega)$$



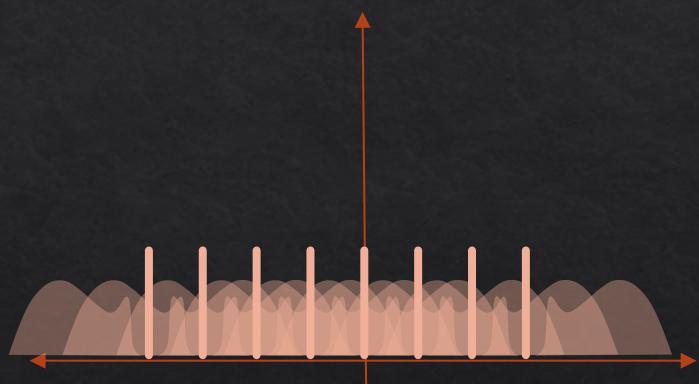
Change



Stretching S to higher frequencies ...



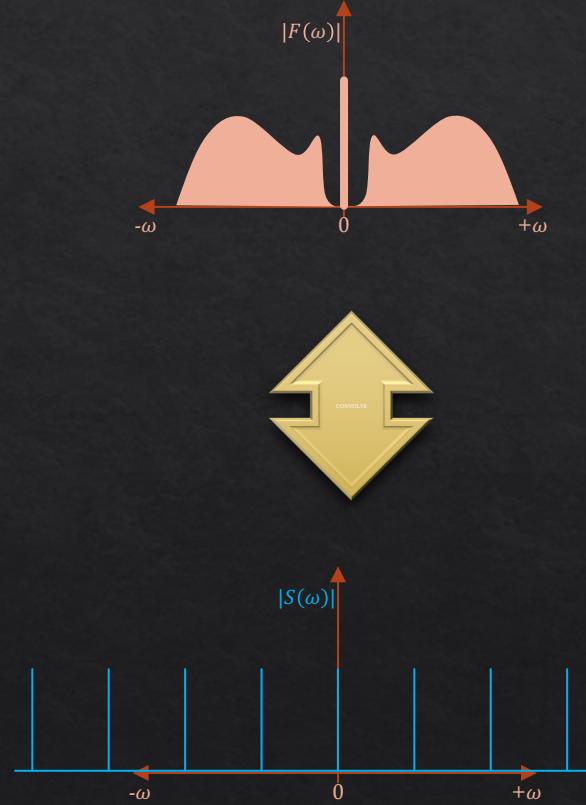
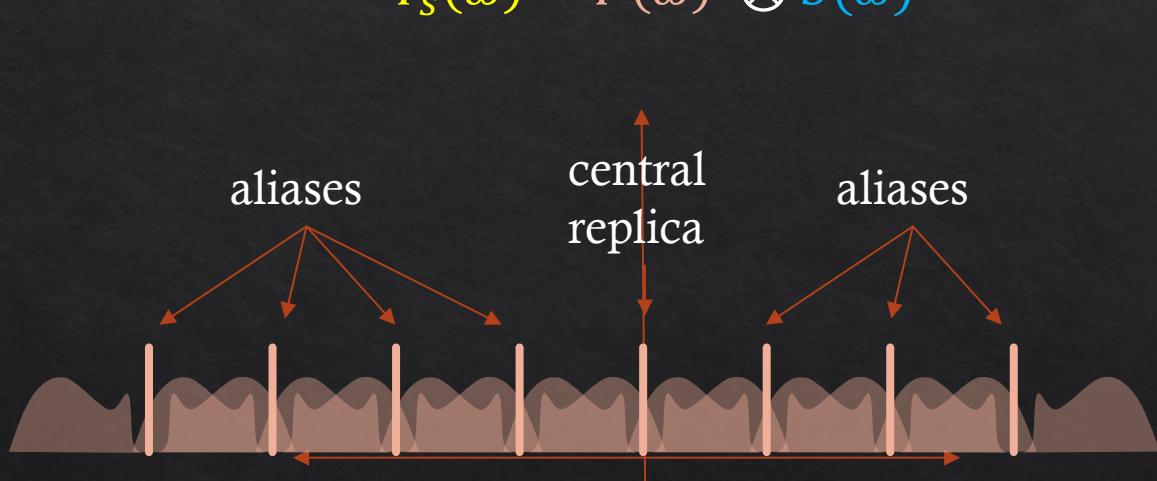
$$F_s(\omega) = F(\omega) \otimes S(\omega)$$



Change



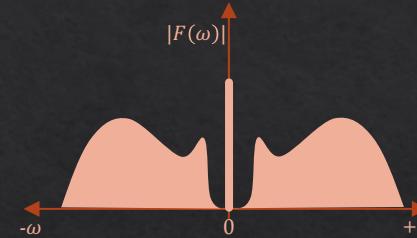
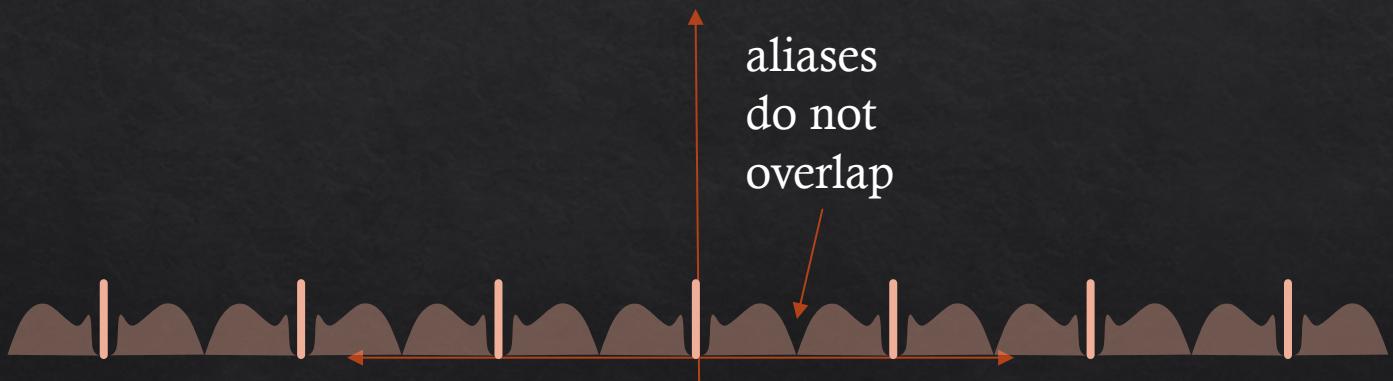
We can see the central replica and aliases



Pushing further removes overlaps

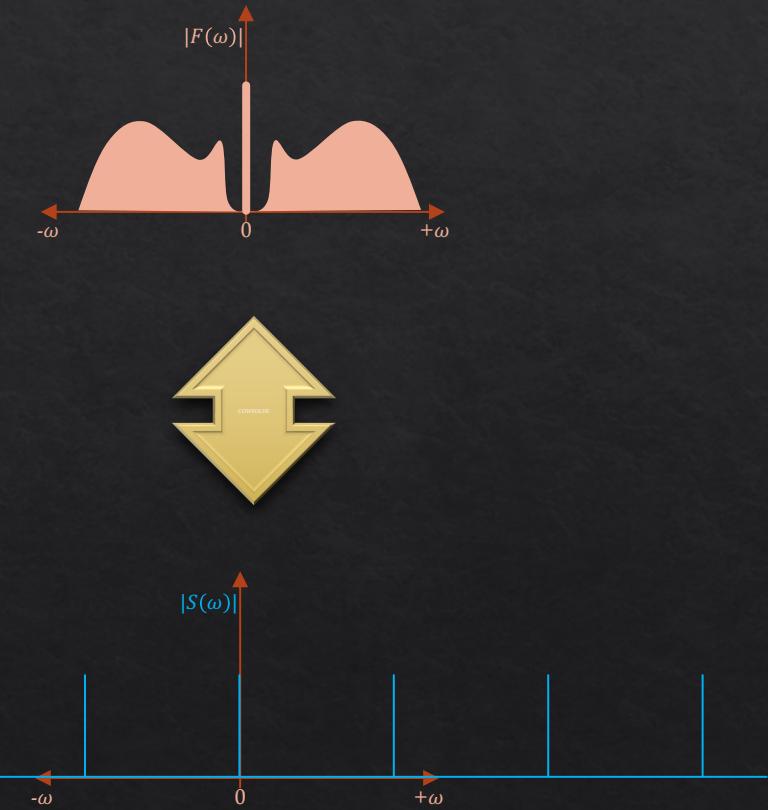
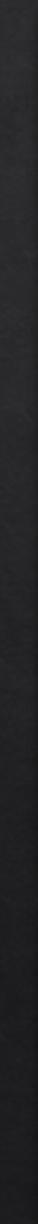
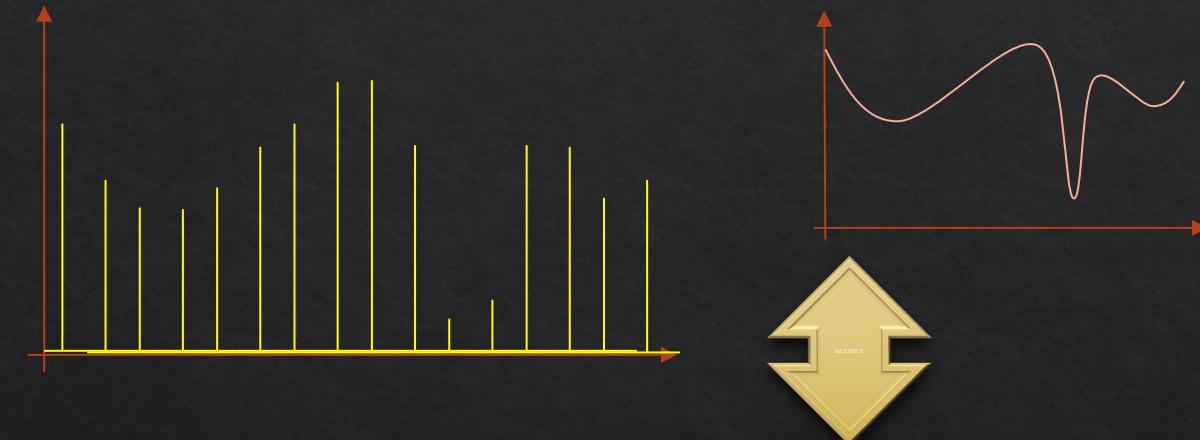


$$F_s(\omega) = F(\omega) \otimes S(\omega)$$



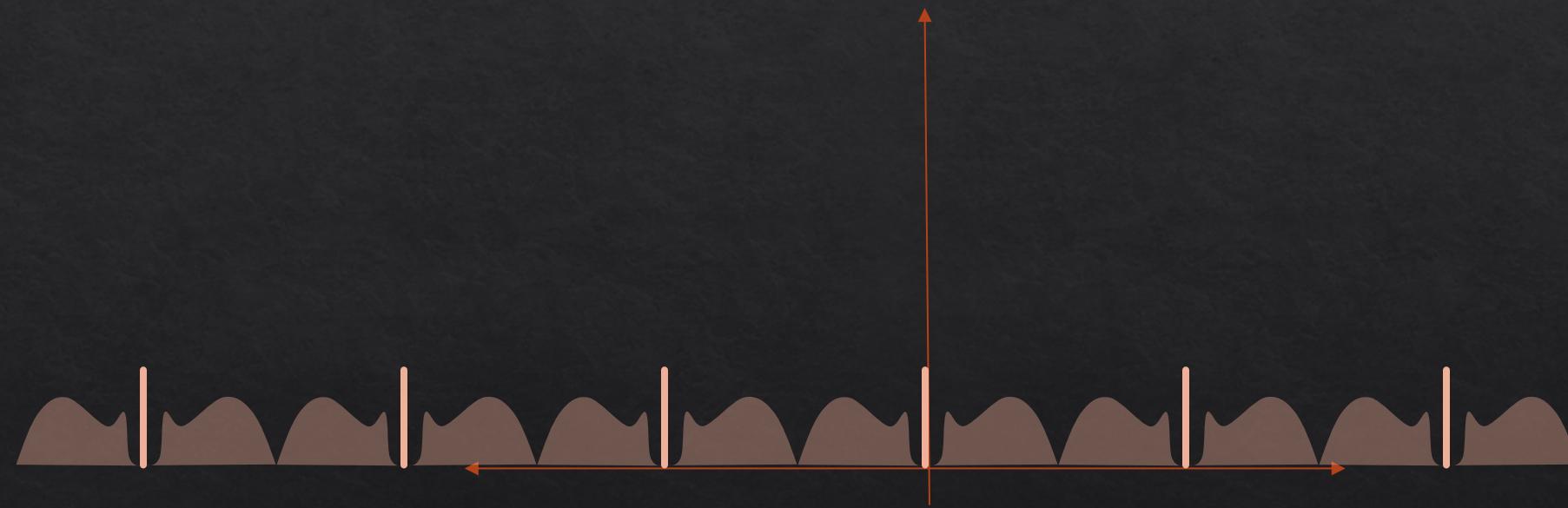
Higher sampling rate = stretched out spectrum

$$f_s(x) = f(x) \cdot s(x)$$



Removing aliases: 1) Increase sampling rate

$$F_s(\omega) = F(\omega) \otimes S(\omega)$$



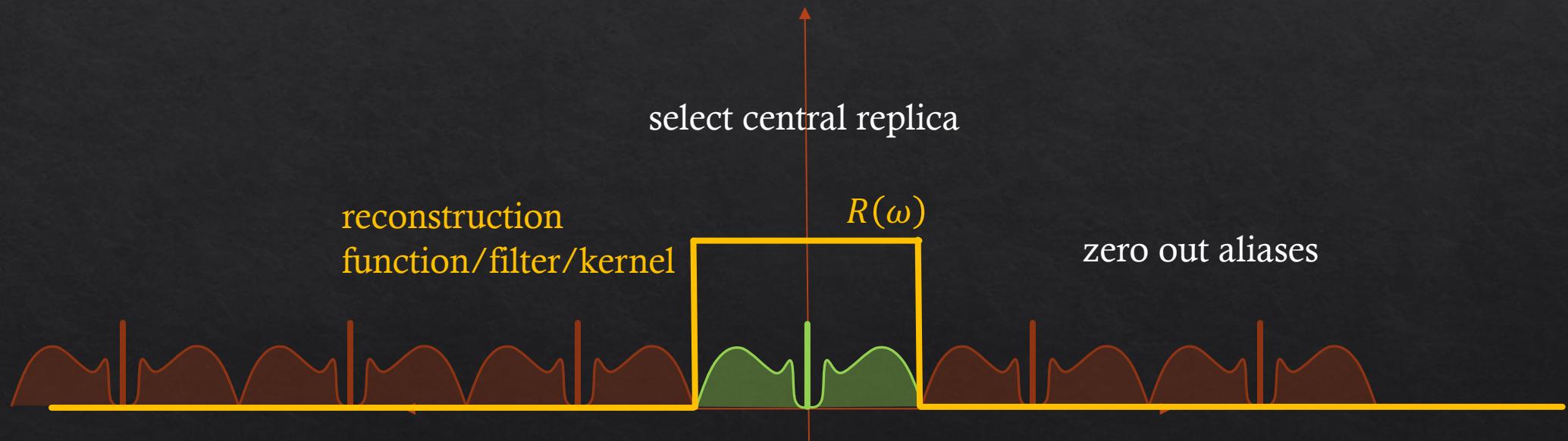
Removing aliases: 2) Crop signal (Fourier)

reconstructed signal

$$F_r(\omega) = R(\omega) \cdot (F(\omega) \otimes S(\omega)) = F(\omega)$$

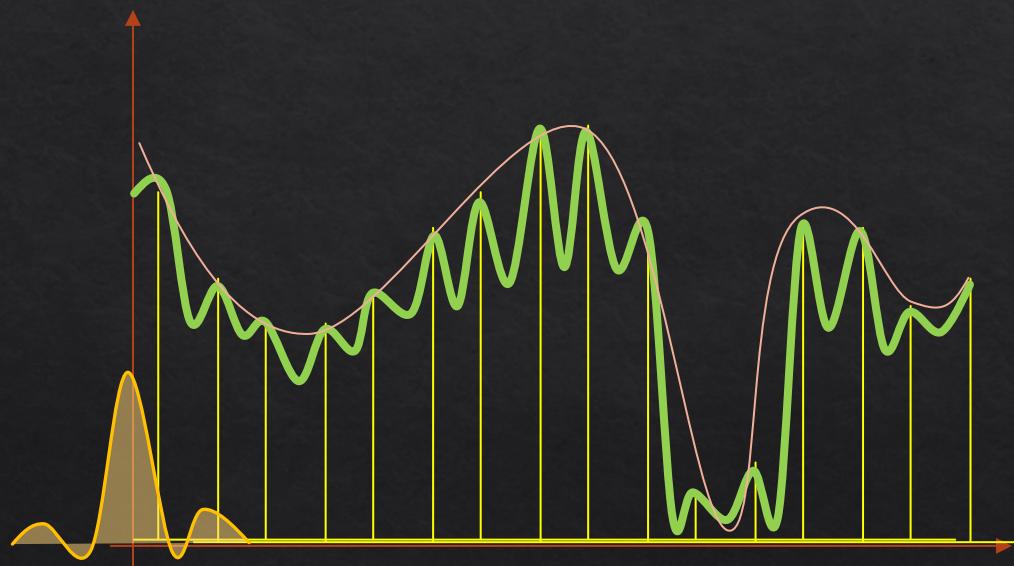
multiply convolve

original signal
if sampling is
sufficiently dense

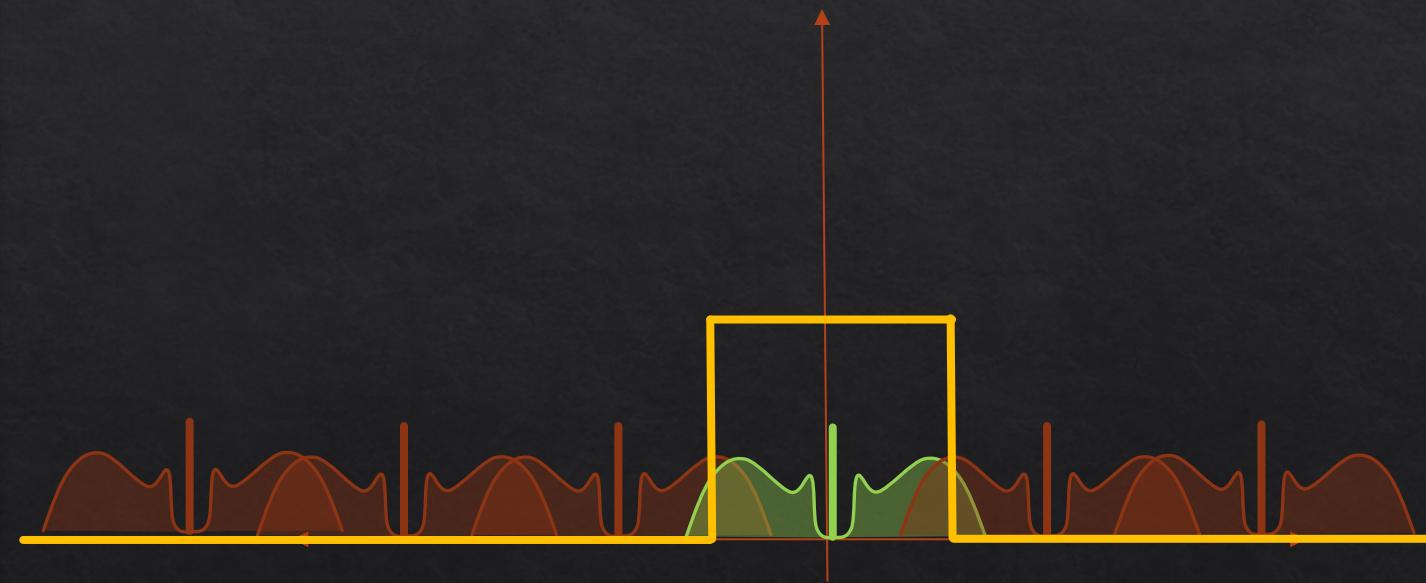


Convolve (Primal) = Crop (Fourier)

$$f_r(x) = r(x) \otimes (f(x) \cdot s(x))$$

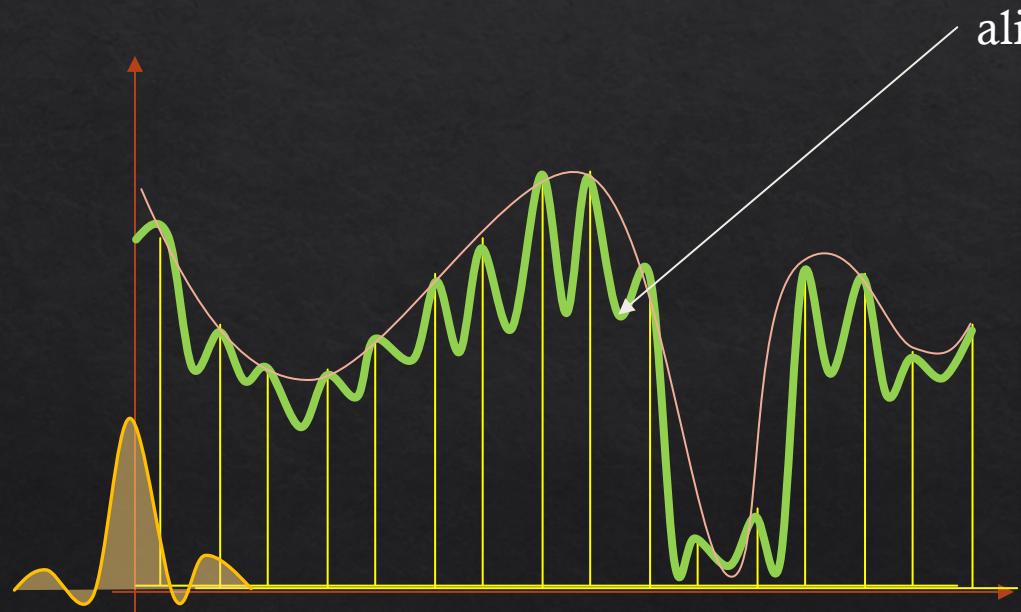


$$F_r(\omega) = R(\omega) \cdot (F(\omega) \otimes S(\omega)) = F(\omega)$$



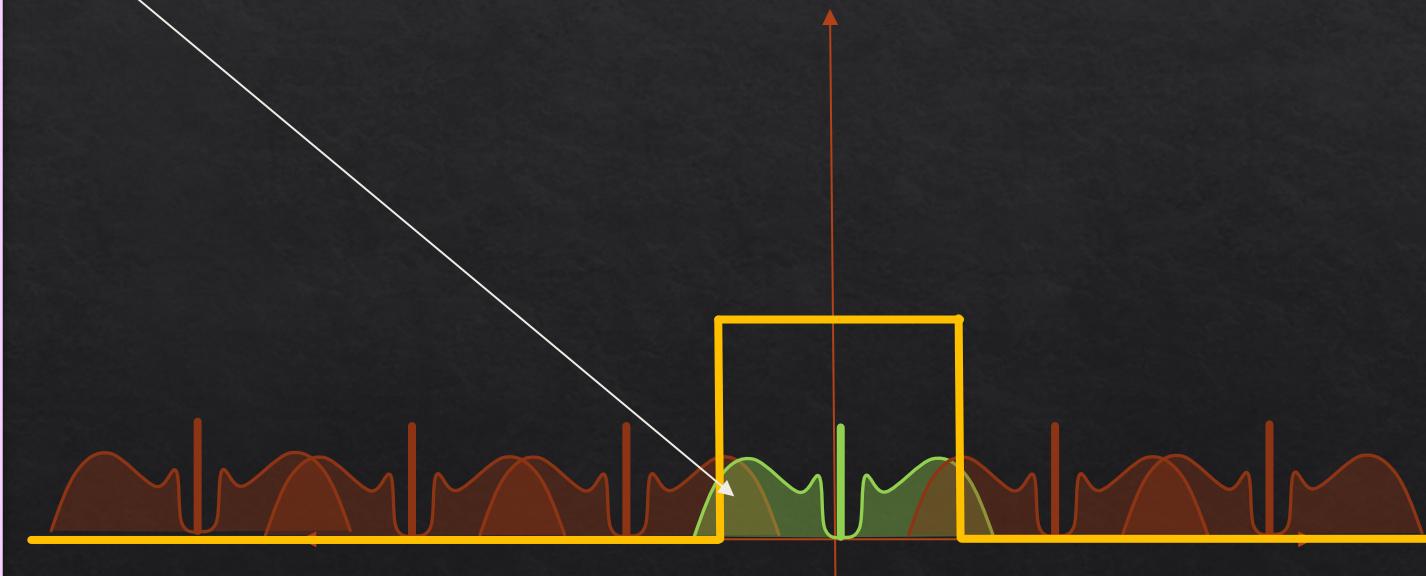
Convolve (Primal) = Crop (Fourier)

$$f_r(x) = r(x) \otimes (f(x) \cdot s(x))$$

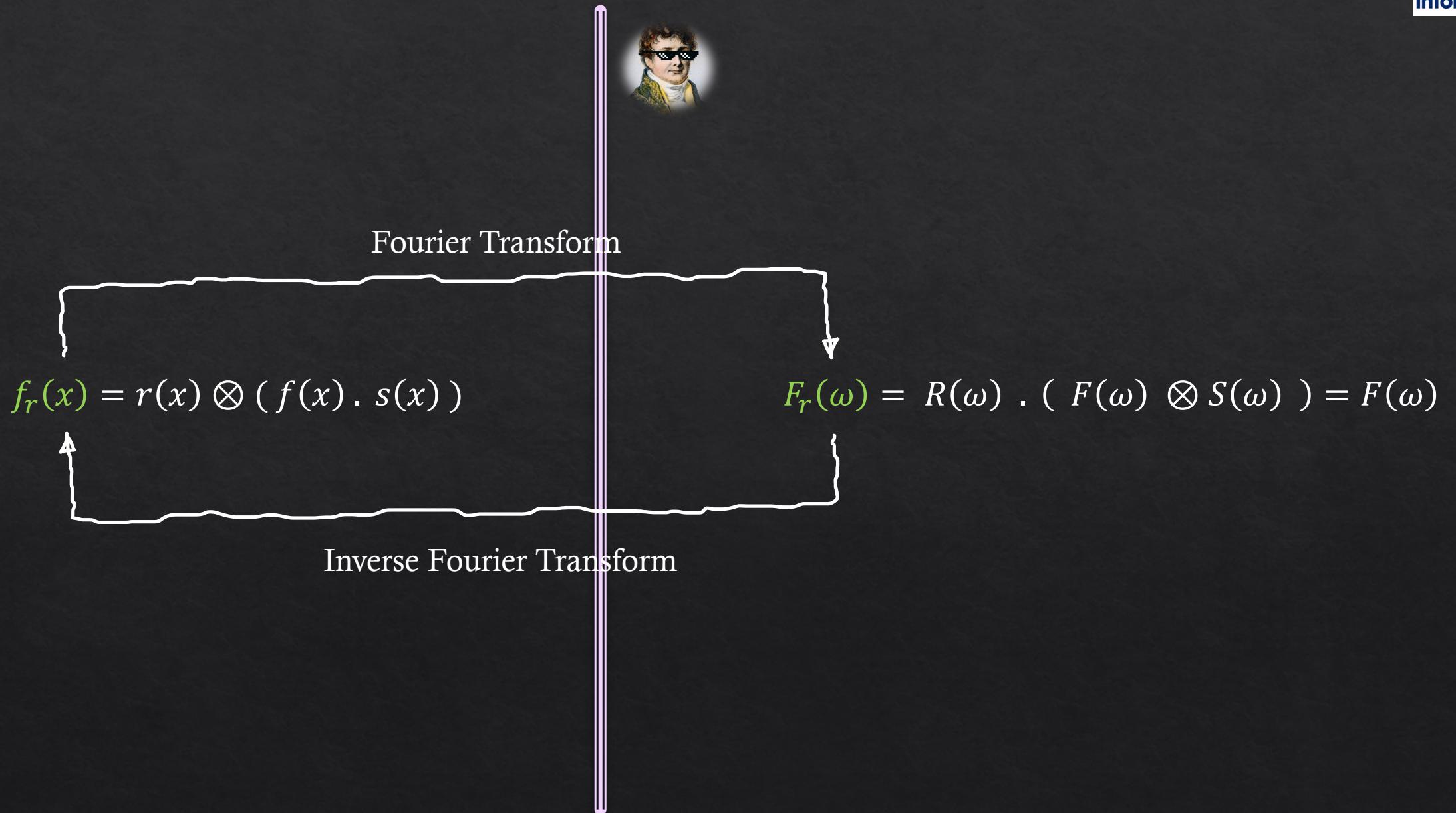


$$F_r(\omega) = R(\omega) \cdot (F(\omega) \otimes S(\omega)) = F(\omega)$$

aliasing



Convolve (Primal) = Crop (Fourier)

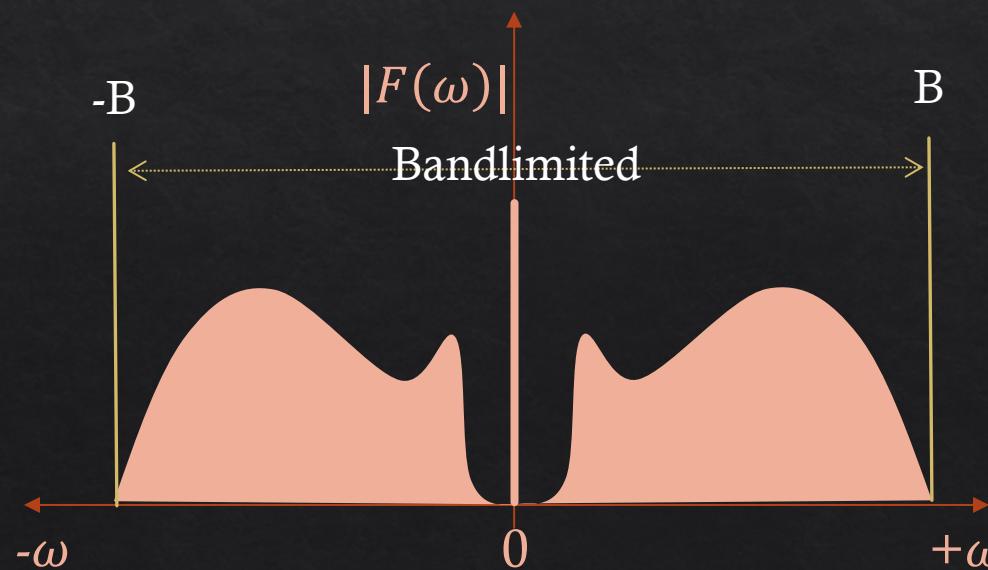


(Nyquist-Shannon) Sampling Theorem

Sampling rate $> 2B$ guarantees no aliasing

Provided:

- 1) Function is bandlimited (B is max frequency)
- 2) Sampling is regular (comb function)

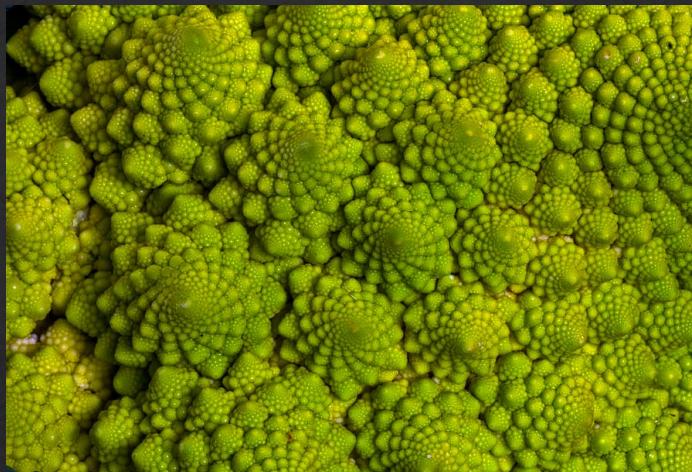
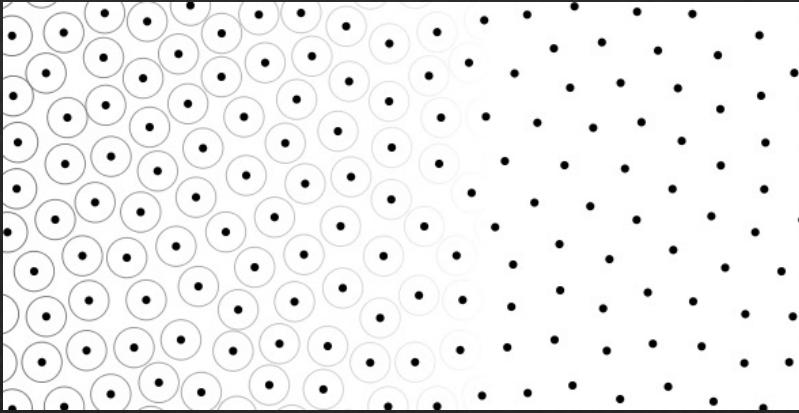


For any dimension: e.g. pixels in 2D

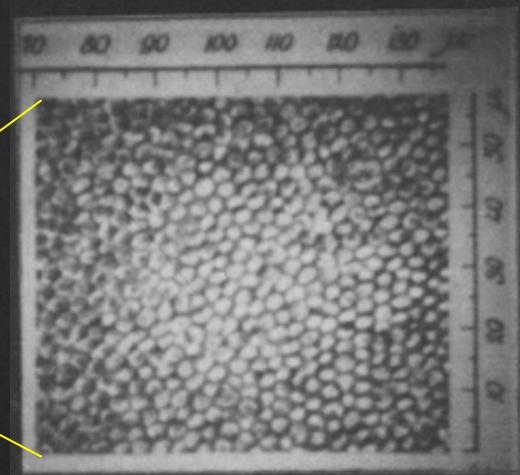
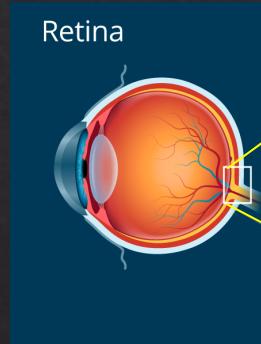
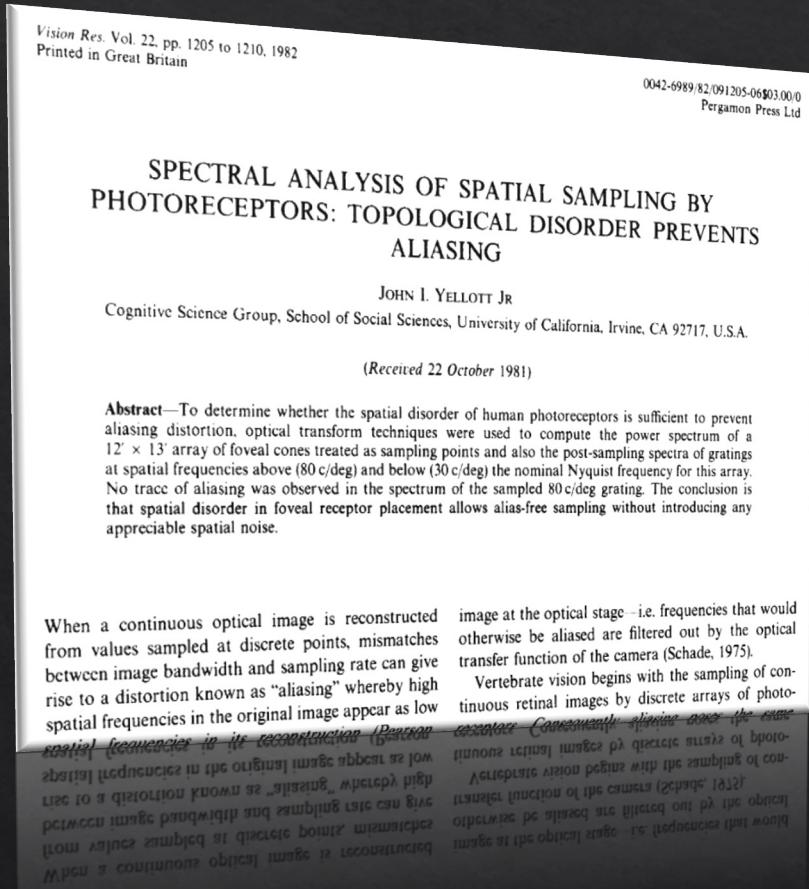


Minimum distance between samples

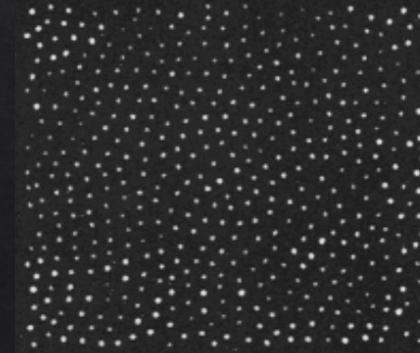
structure + random



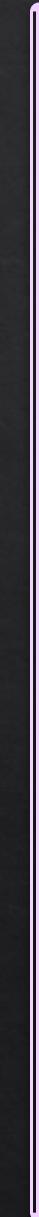
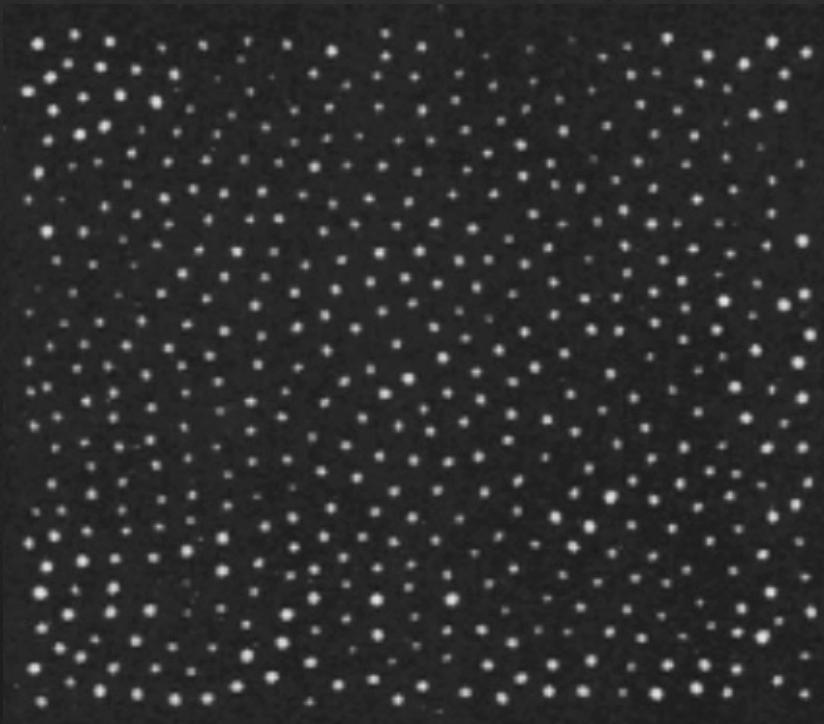
Reconstruction in animals' visual systems



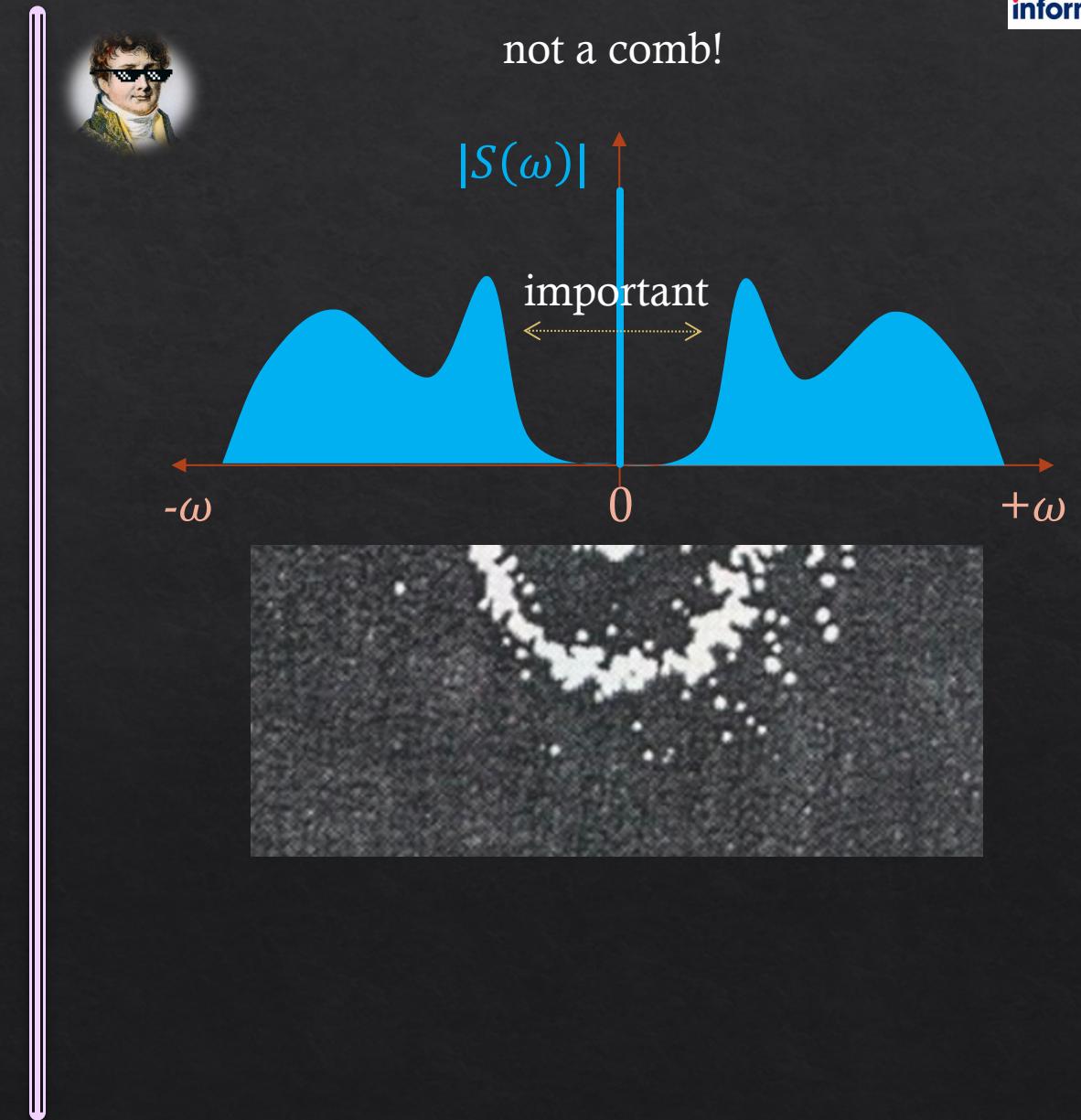
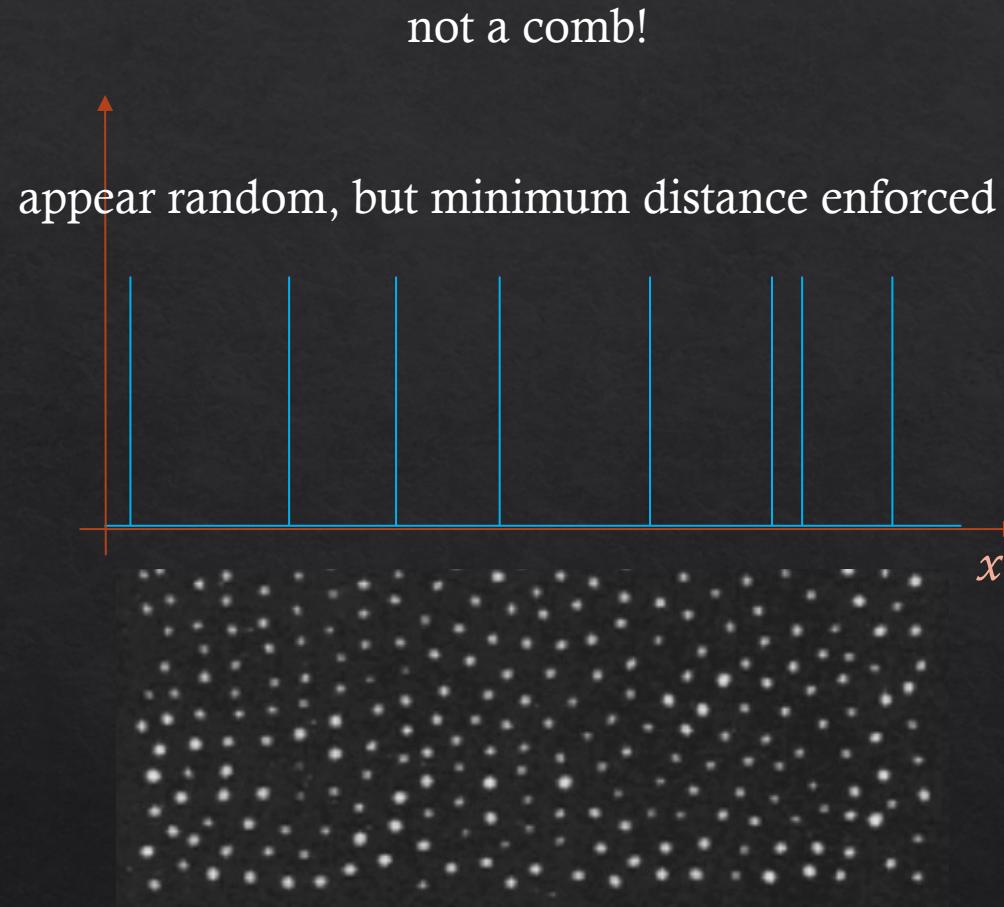
regular structure but not a grid



Reconstruction in animals' visual systems



Gap in low-frequencies in Fourier spectrum

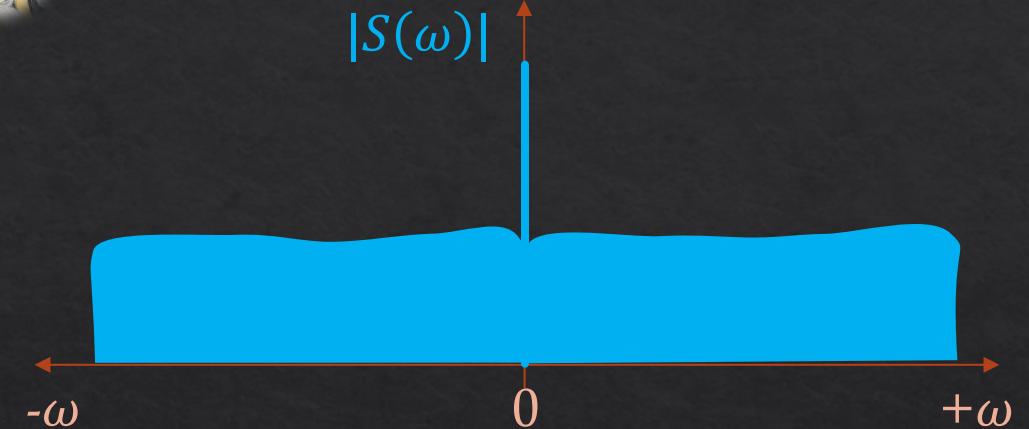


Random sampling spectrum is flat

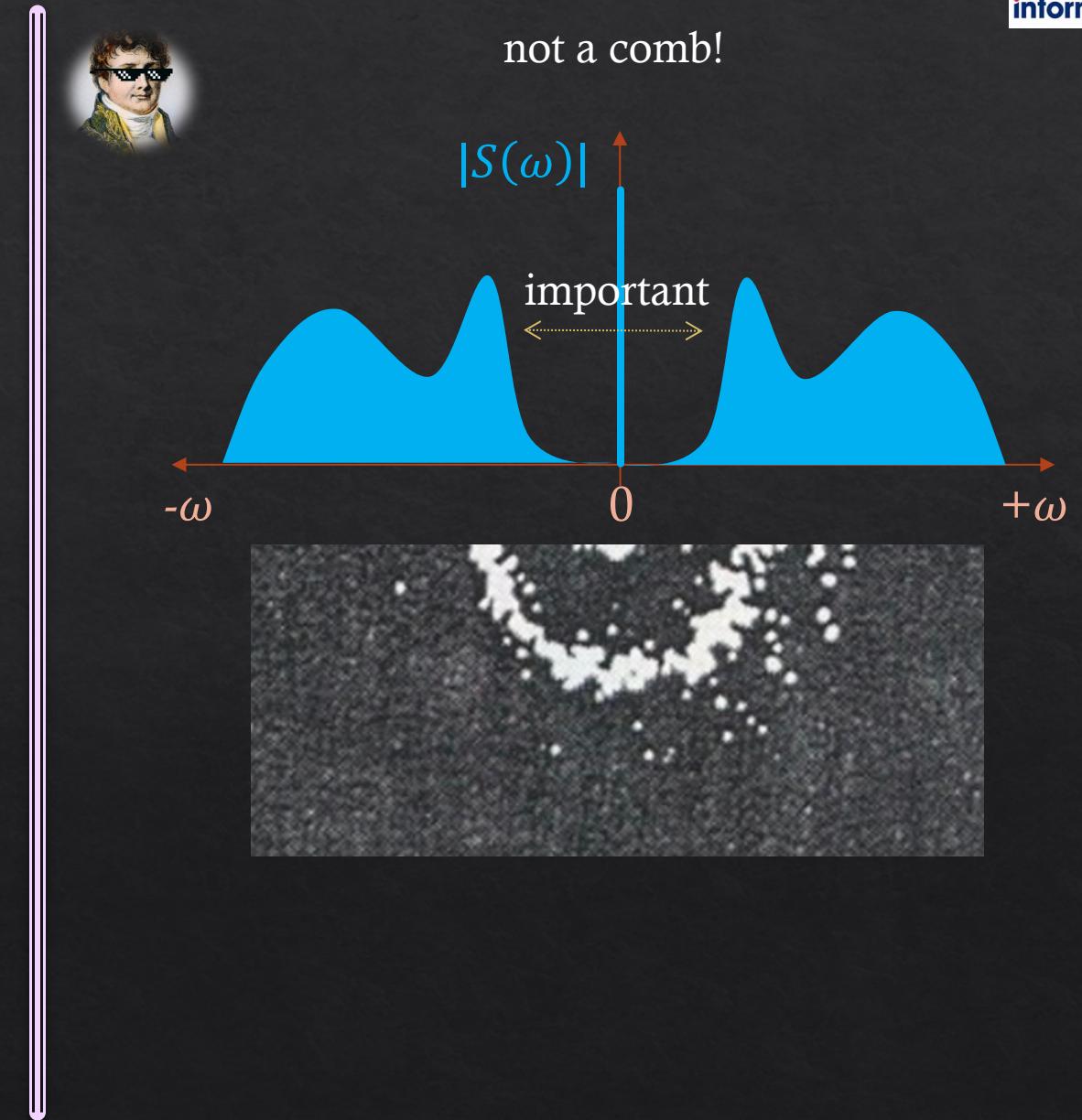
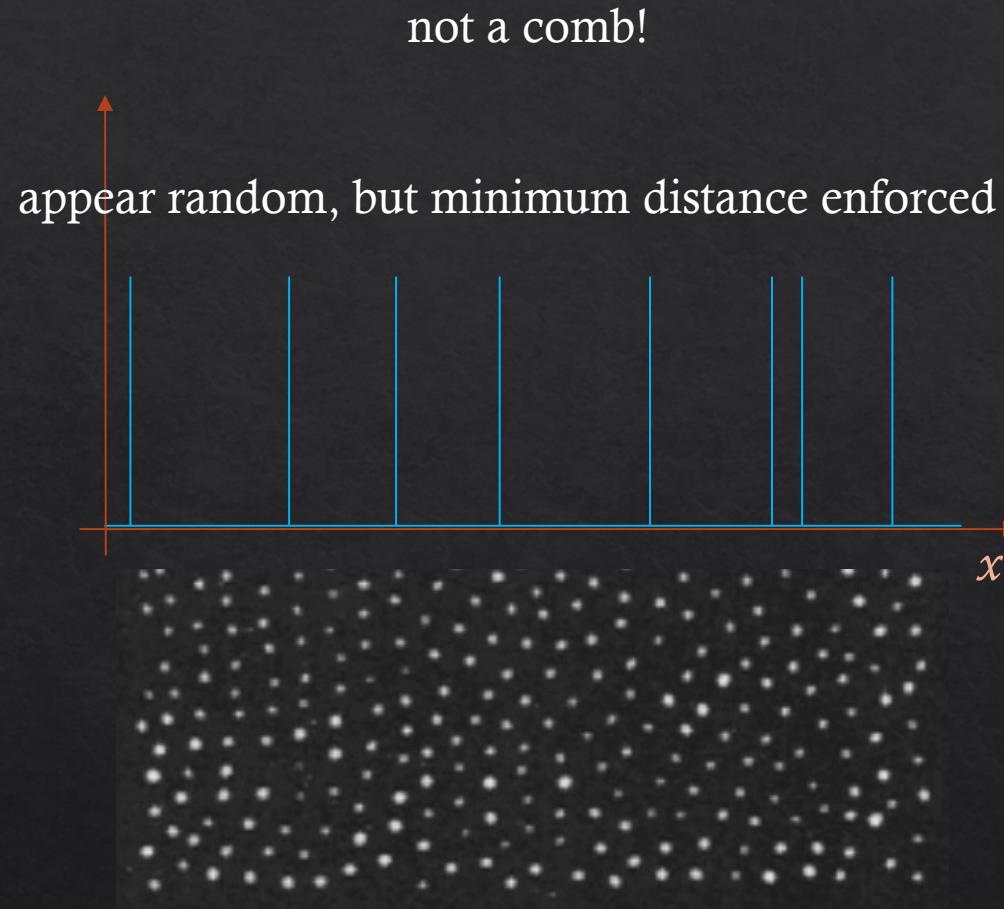
not a comb!



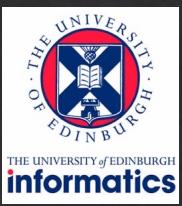
not a comb!



Gap in low-frequencies in Fourier spectrum

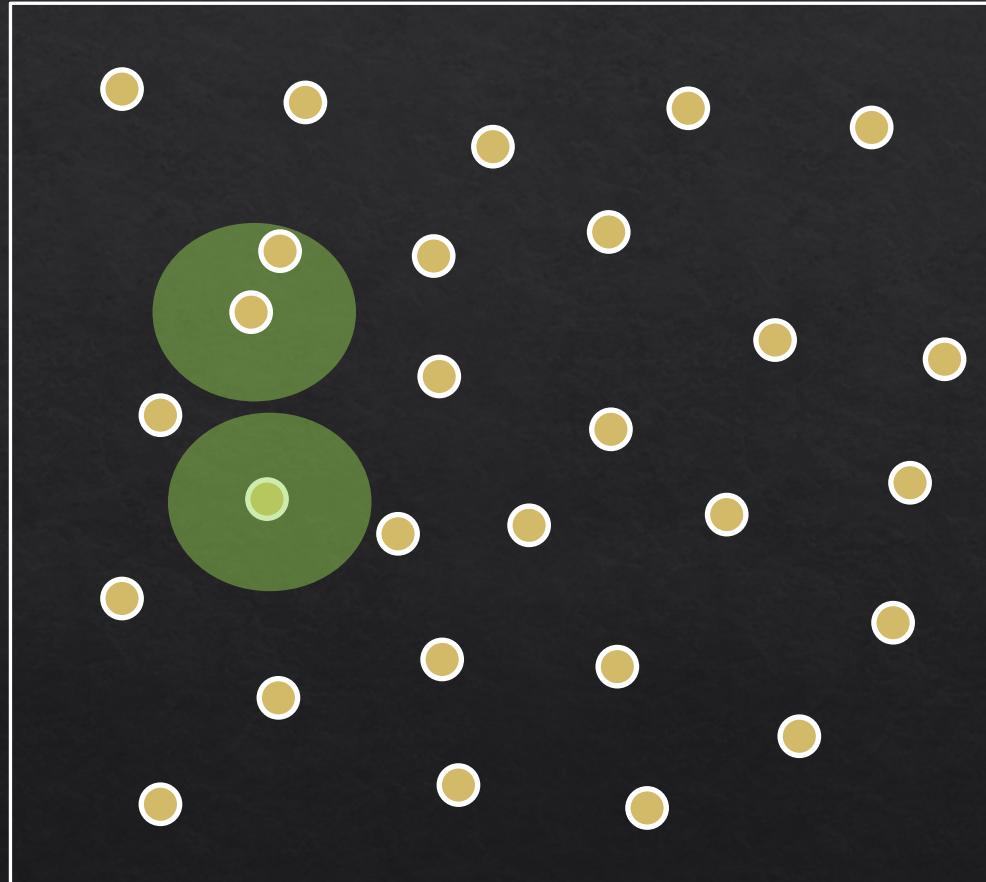


Generating samples: Poisson disk sampling

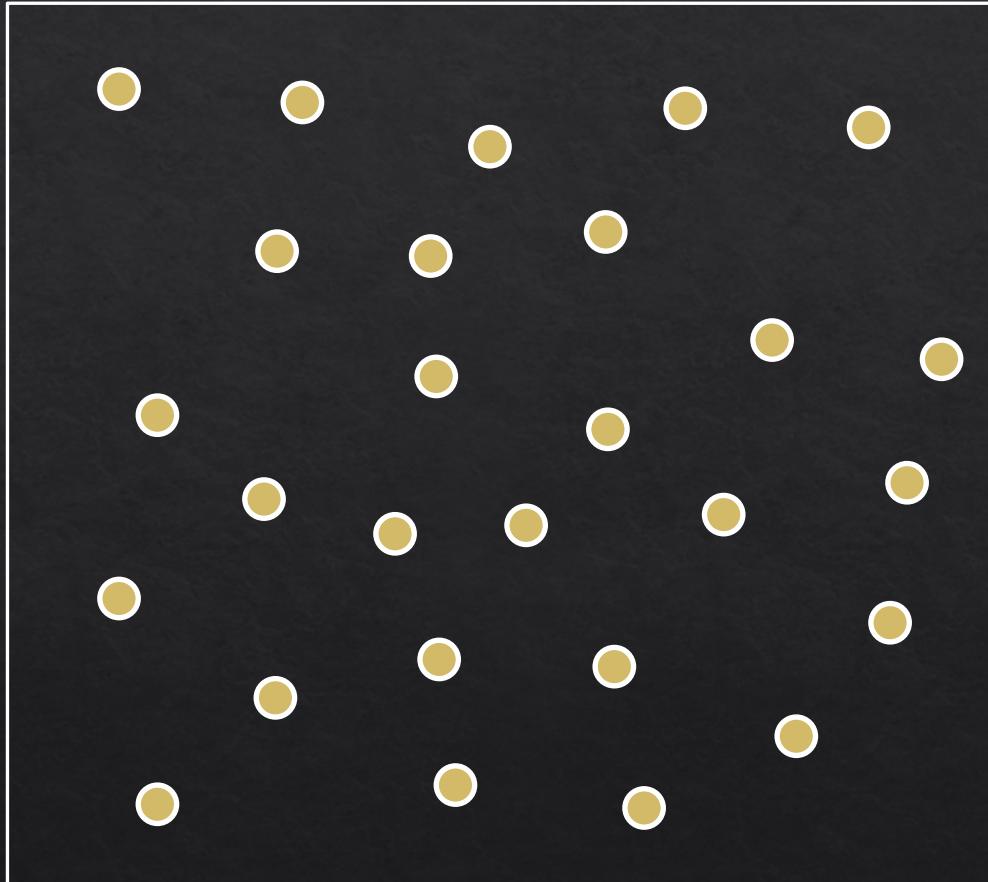


Generating samples: Poisson disk sampling

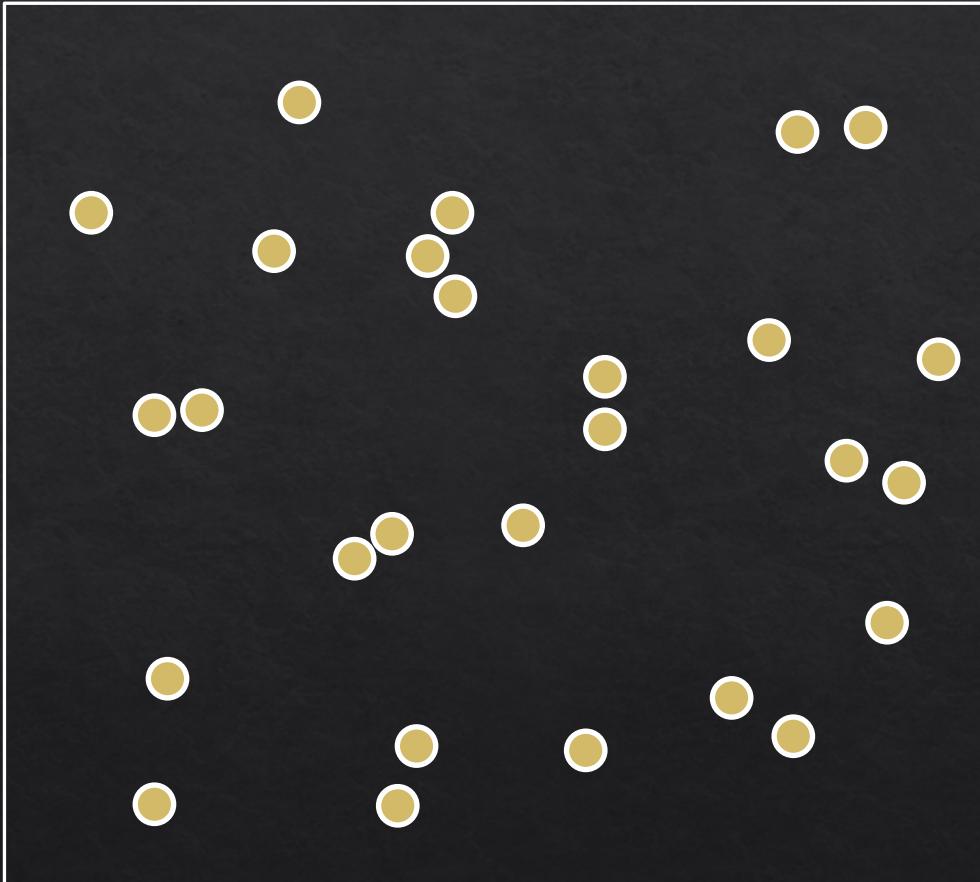
reject sample if
closer than
minimum distance
to any sample



Dart throwing



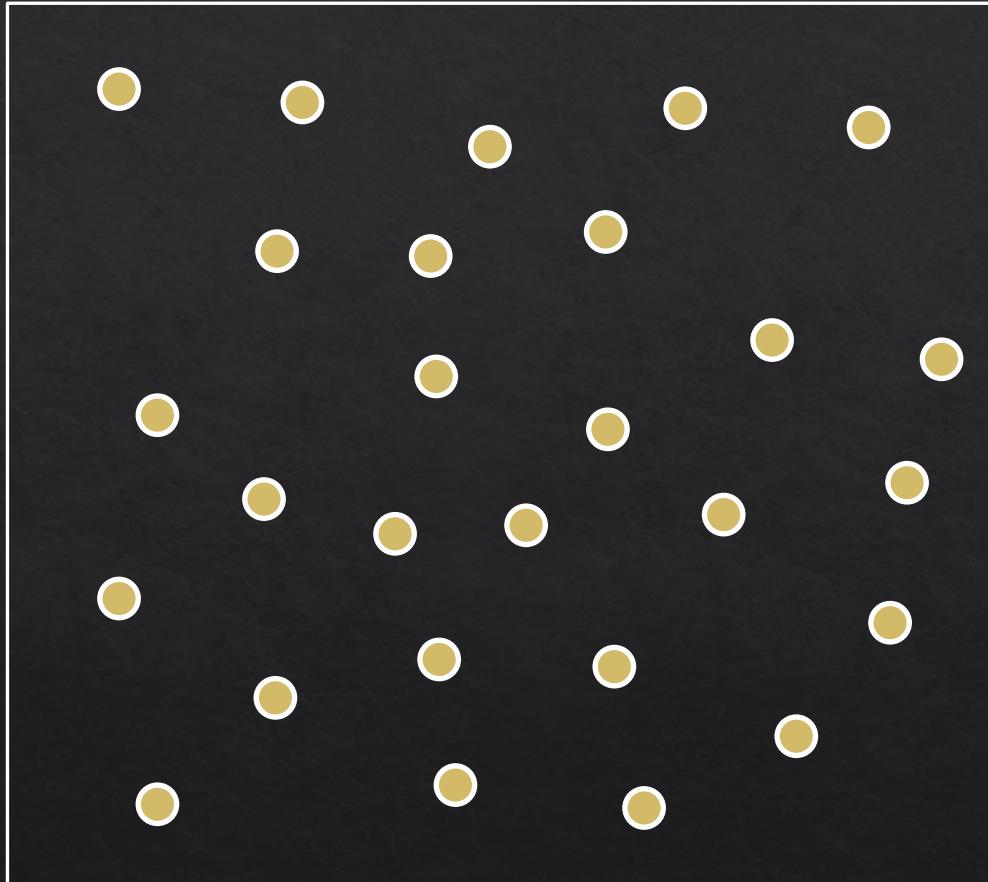
Another approach: start with random samples



Move them until constraint satisfied



Relaxation method



Monte Carlo path tracing → sampling

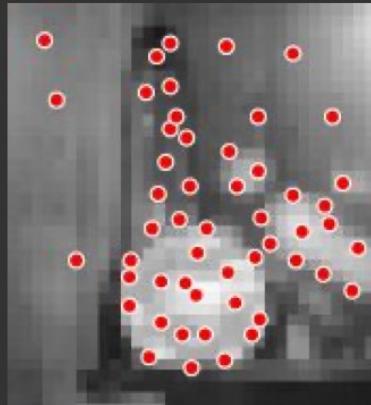
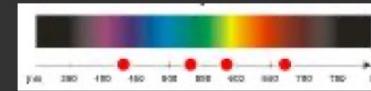


Image space



Visible spectrum



Aperture



Exposure time



Material reflectance
functions



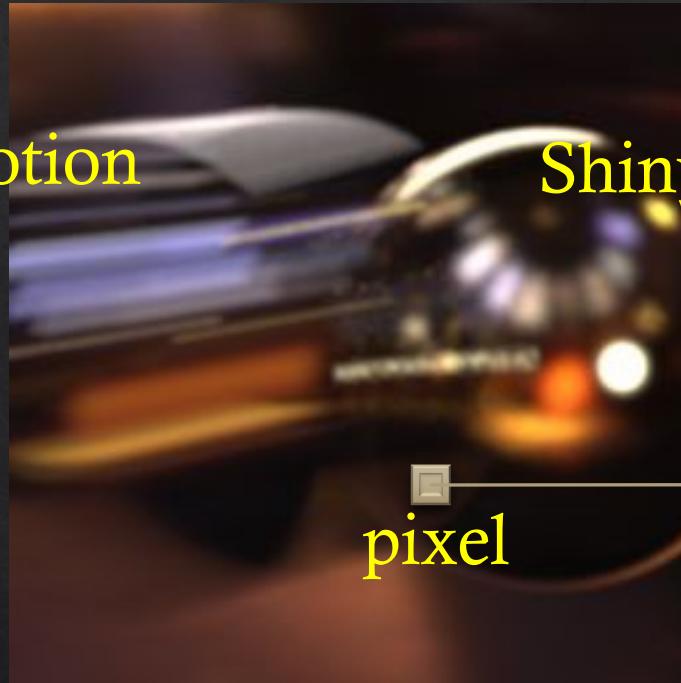
Direct illumination



Indirect illumination

Light transport = integration

Shiny ball in motion



Shiny ball, out of focus

$\iiint \dots$
multi-dim integral

Integrand: radiance ($\text{W m}^{-2} \text{ Sr}^{-1}$)

Domain: pixel area \times shutter time \times aperture area \times 1st bounce \times 2nd bounce

Variance and bias



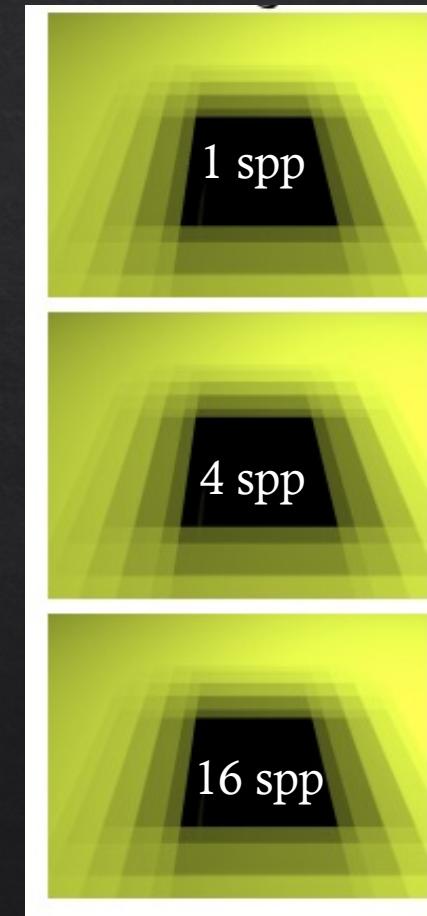
High variance



High bias

For any dimension: e.g. light paths > 2D

comb (regular grid)



But this is numerical integration, not reconstruction !

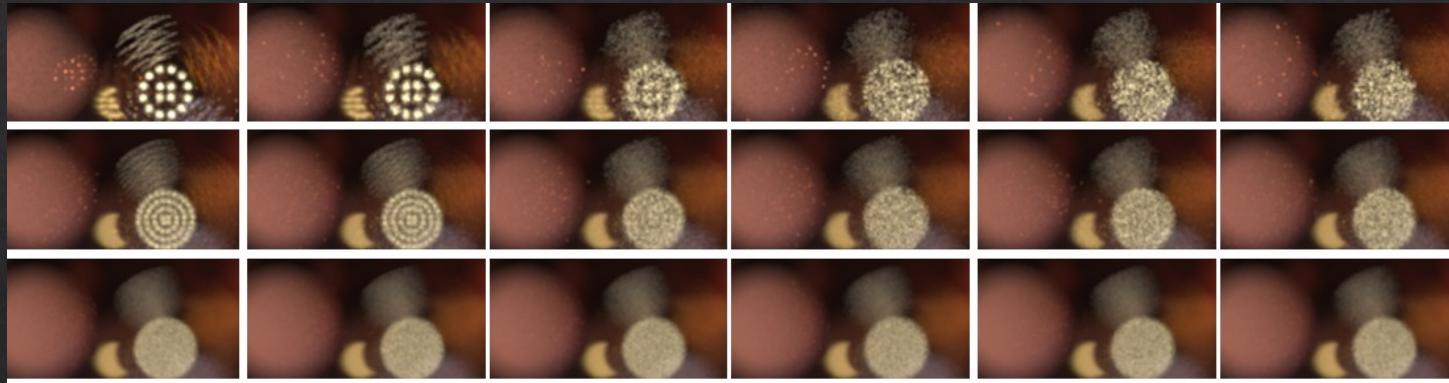
What is the connection between these two classes of problems?

Adding randomness is good. Why?

comb (regular grid)

→ jittered grid

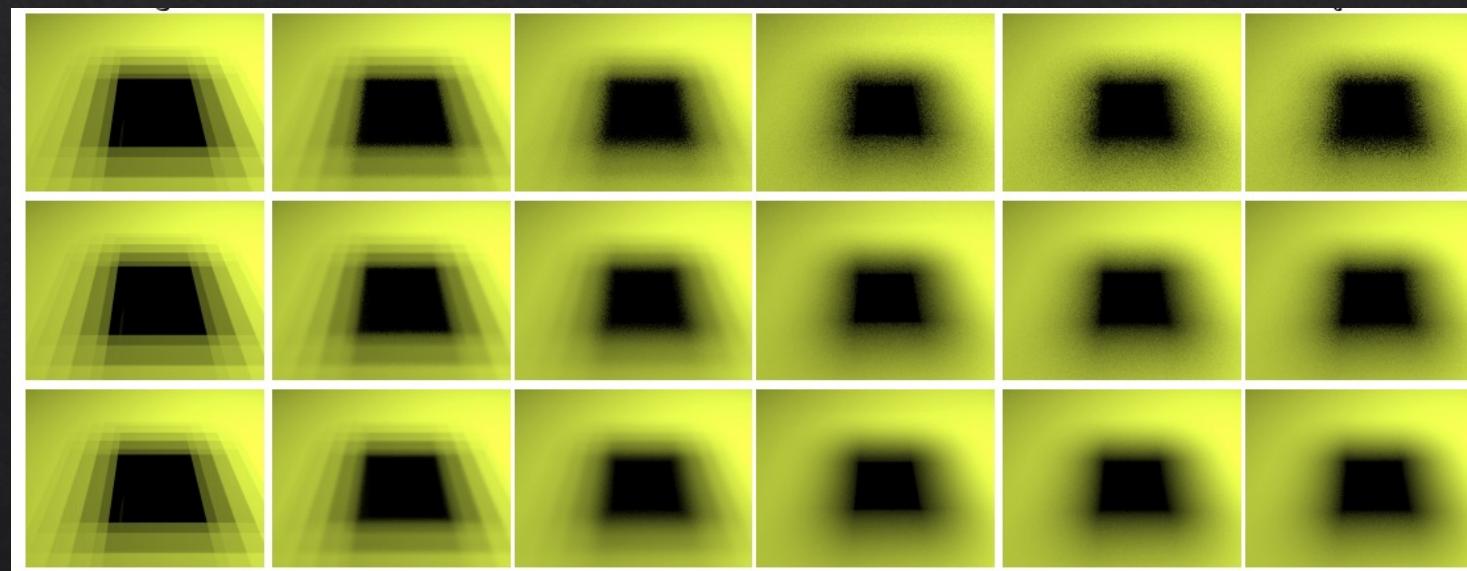
16 spp



structured artifacts are visually disturbing

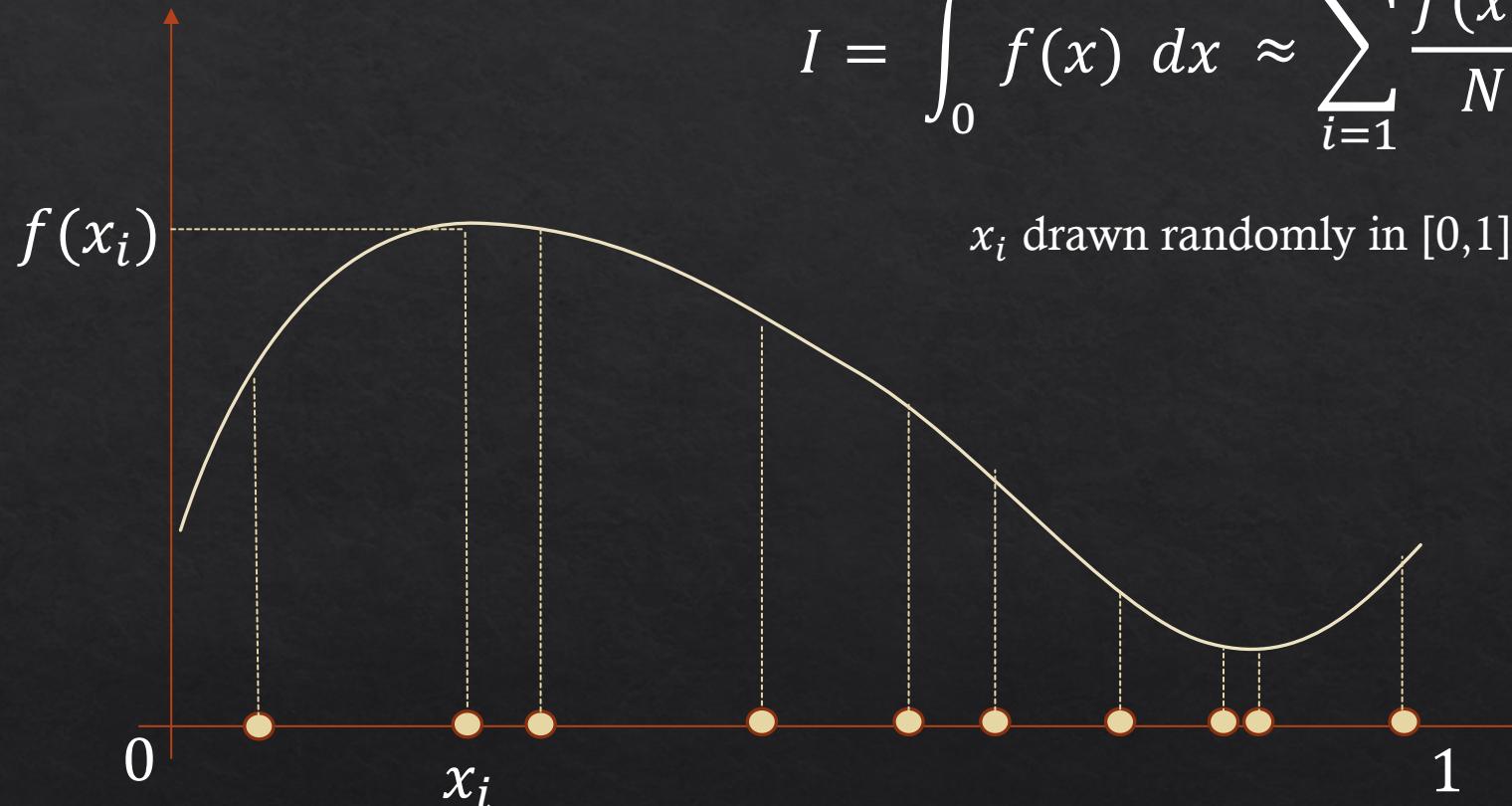
random noise is less objectionable although undesirable

1 spp

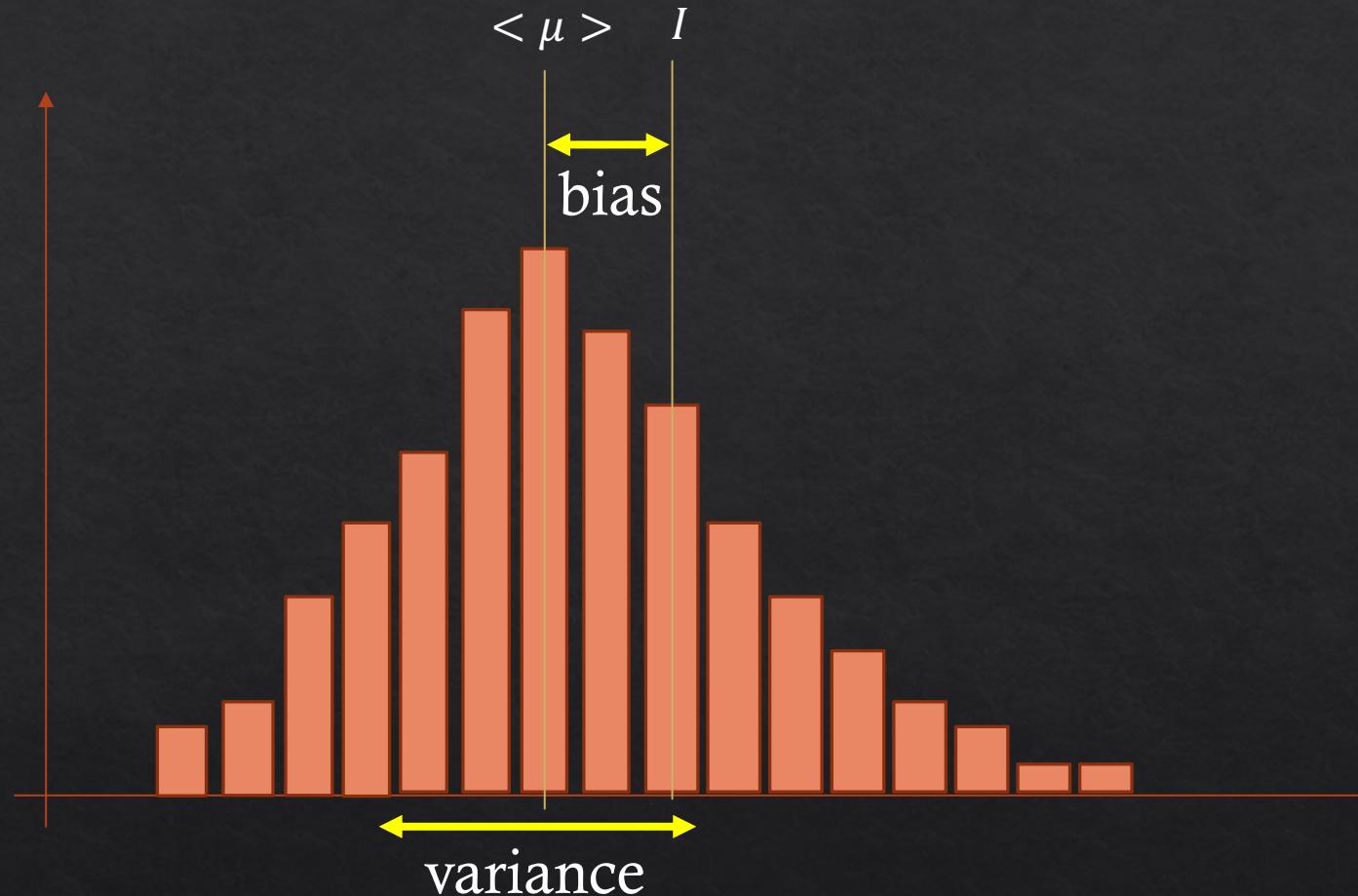


Monte Carlo integration is an approximation

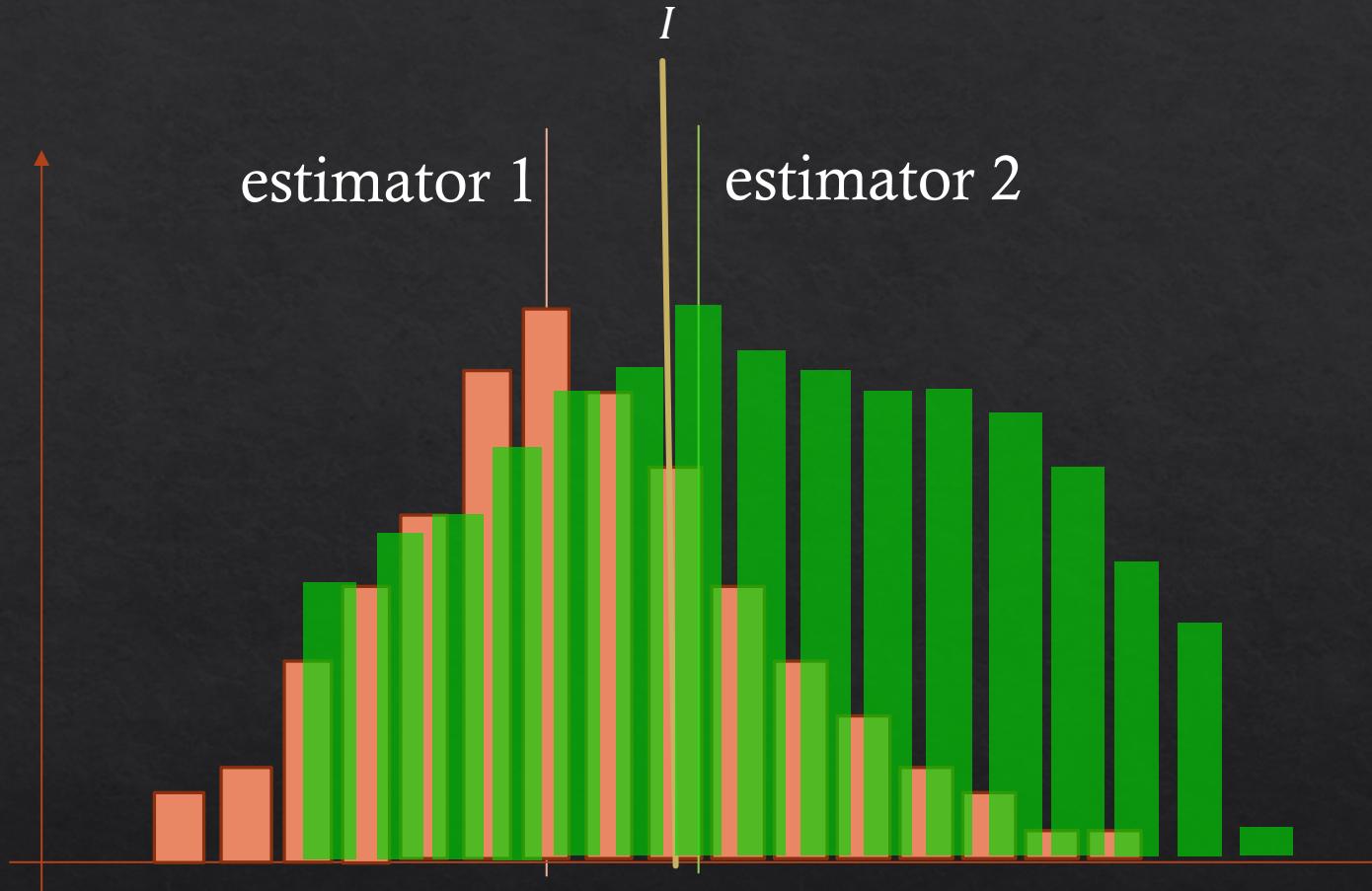
$$I = \int_0^1 f(x) \, dx \approx \sum_{i=1}^N \frac{f(x_i)}{N}$$



Error due to sampling: histogram of estimates



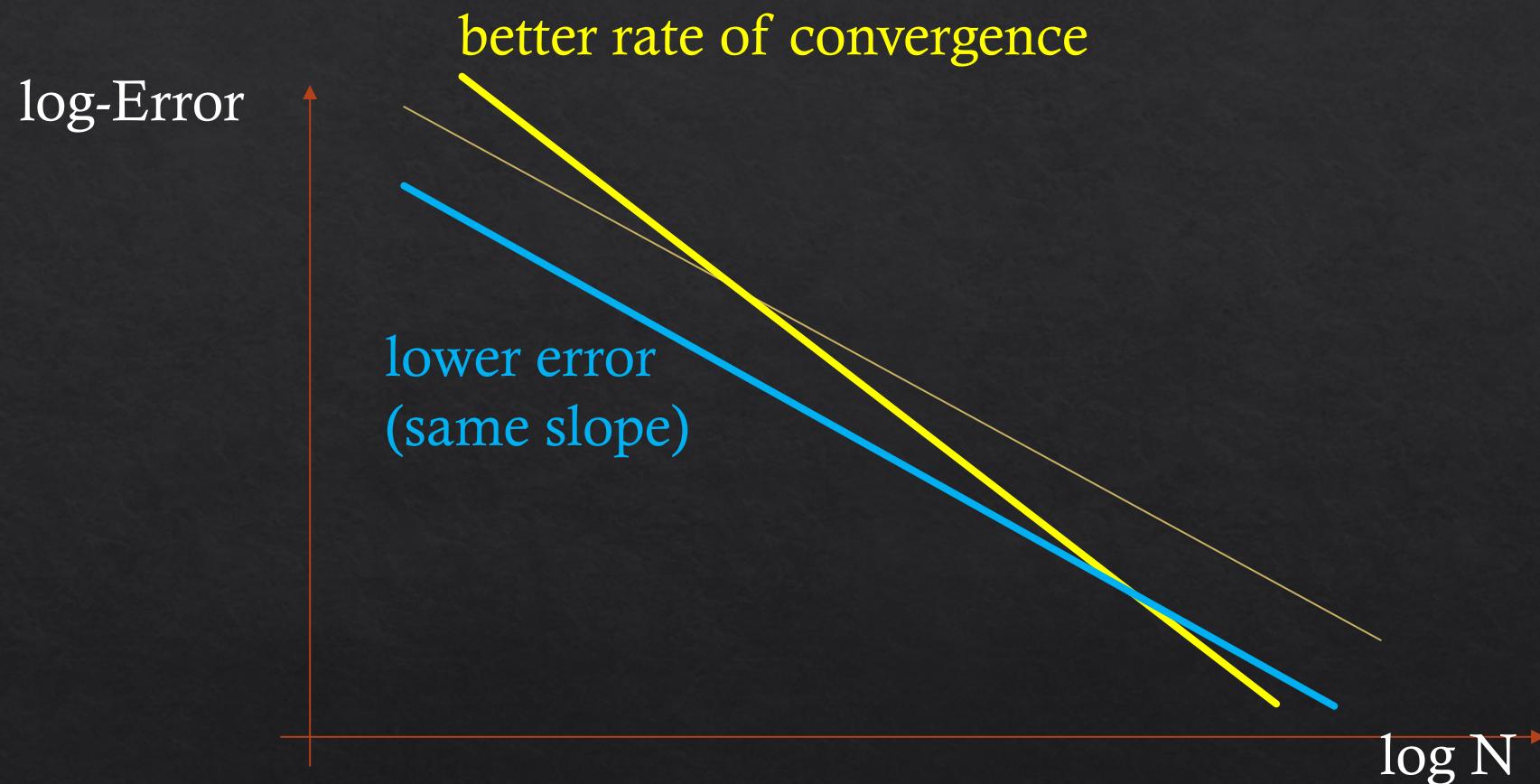
Which estimator is better?



Convergence as N is increased

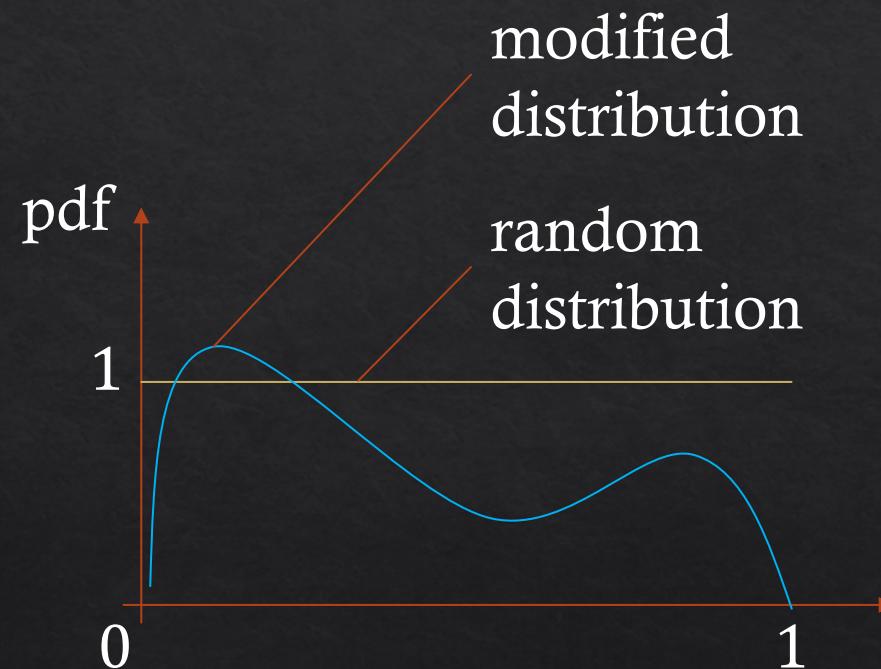


Two classes of improvements



But how?

change sampling distribution



introduce sample correlations
(e.g. using a grid-structure)

