

# Sukriti Kushwaha

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## EDUCATION

**Worcester Polytechnic Institute (WPI)**, Worcester, MA Aug. 2021 – May 2025  
Bachelor of Science, double major in Robotics Engineering and Computer Science, GPA 3.87/4.0

## PROFESSIONAL EXPERIENCE

**Summer Research Intern** | *MATLAB, Parallel Computing, Simulation & Modeling* May 2024 – Aug. 2024  
[MIT Lincoln Laboratory, Lexington, MA](#)

- Analyzed capabilities of **synthetic data generation** tool for remote spaced-based sensors using **MATLAB**
- Presented findings and recommendations in a **technical talk** delivered to group leaders to aid sponsor projects

**Systems Engineering Intern** | *C++, Python, Sensor Fusion, Web Dev, Raspberry Pi, Arduino* May 2023 – Jul. 2023  
[Northrop Grumman, Baltimore MD](#)

- Programmed **sweeping controls** for gimbal mechanism in **C++** powered by Arduino Uno and Raspberry Pi to secure client contract for prototype **ground-based radar** antenna system.
- Created **web server** using **Python flask** and **UDP socket** to control heading and pitch to **one degree** of accuracy.

## PROJECTS

**Advanced Tour Guide Robot** | *Human-Robot Interaction, ROS2, LLM, LiDAR, OCR, Python, C* [Code](#)

- Operates elevators using **3d-printed** arm and custom **button detection model**, enabling **multi-floor navigation**
- Engages user via Llama **LLM**, **ASR** and interactive **React GUI** powered by **Jetson Orin Nano**

**Neural Nemesis** | *Deep Learning, Computer Vision, CNN, Python* [Results](#)

- Depicted over-reliance of **monocular depth estimation CNNs** on non-depth features by training an **adversarial patch** using **VGG-16** to induce incorrect depth estimations
- Printed adversarial patch and physically placed it in target scenarios to showcase practical applications

**Dreaming Data** | *Deep Learning, Diffusion Model, Python* [Results](#)

- Created and trained custom implementation of a **denoising diffusion probabilistic model** capable of synthesizing over **50,000 new images** representative of a given dataset

**Trajectory Generation of Robotics Manipulator** | *Semantic Segmentation, Trajectory Generation* [Results](#)

- Employed **MATLAB** to calculate the **forward and inverse kinematics** of a **4-degree robot arm**, enabling precise mapping of joint movements in the task space to efficiently grasp a ball
- Conducted **image segmentation** and **object recognition** by applying **HSV color masks** to identify colored balls

**Escape Room** | *MQTT, Sensor Fusion, C++, IMU, ultrasonic rangefinder, IR emitter, IR position finder*

- Programmed set of Romi 32U4 robots to collaboratively escape from grid-based maze using **MQTT protocol**
- Implemented **hysteresis control**, **PID tuning**, and sensor fusion with **Kalman filter** to optimize performance

## LEADERSHIP

**Engineering Ambassador**, [Engineering Ambassadors](#), WPI Apr. 2023 – Present

- Engaged younger generation of students in STEM through effective communication of technical information
- Designed hands-on **STEM activities** to accompany technical talks and aid understanding of new material

**President**, [Society of Women Engineers](#), WPI Jan. 2024 – Dec. 2024

- Promoted inclusivity for women in STEM by organizing **15+** professional development and networking events
- Supported executive board officers in **creative** and **diverse** event ideation, resolved internal conflicts

## AWARDS & RECOGNITION

- Best Hardware**, SHADE Android App [Results](#)  
GoatHacks Hackathon, WPI, 2025
- Third Place**, *Public Perceptions on Central Bank Digital Currencies* [Results](#)  
Undergraduate Poster Competition, SWE National Conference, 2024
- "Most Futuristic Design"**, *Space Encase: Micrometeoroid and Orbital Debris Mitigation* [Results](#)  
Intern Innovative Challenge, MIT Lincoln Laboratory, 2024