

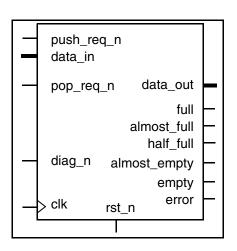
DW_fifo_s1_sf

Synchronous (Single Clock) FIFO with Static Flags

Version, STAR and Download Information: IP Directory

Features and Benefits

- Fully registered synchronous flag output ports
- D flip-flop-based memory array for high testability
- All operations execute in a single clock cycle
- FIFO empty, half full, and full flags
- FIFO error flag indicating underflow, overflow, and pointer corruption
- Parameterized word width
- Parameterized word depth
- Parameterized almost full and almost empty flags
- Parameterized reset mode (synchronous or asynchronous, memory array initialized or not)



Description

DW_fifo_s1_sf is a fully synchronous, single-clocked FIFO. It combines the DW_fifoctl_s1_df FIFO controller and the DW_ram_r_w_s_dff flip-flop-based RAM DesignWare components.

The FIFO provides parameterized width and depth, and a full complement of flags: full, almost full, half full, almost empty, empty, and error.

Reset can be selected at instantiation to be either synchronous or asynchronous, and can either include or exclude the RAM array.

The DW_fifo_s1_sf is recommended for relatively small configurations. For large FIFOs, you should consider using the DW_fifoctl_s1_sf in conjunction with a compiled, full-custom RAM array.

Table 1-1 Pin Description

Pin Name	Width	Direction	Function
clk	1 bit	Input	Input clock
rst_n	1 bit	Input	Reset input, active low asynchronous if <i>rst_mode</i> = 0 or 2, synchronous if <i>rst_mode</i> = 1 or 3
push_req_n	1 bit	Input	FIFO push request, active low
pop_req_n	1 bit	Input	FIFO pop request, active low

Table 1-1 Pin Description (Continued)

Pin Name	Width	Direction	Function
diag_n	1 bit	Input	Diagnostic control, active low
data_in	width bit(s)	Input	FIFO data to push
empty	1 bit	Output	FIFO empty output, active high
almost_empty	1 bit	Output	FIFO almost empty output, active high
half_full	1 bit	Output	FIFO half full output, active high
almost_full	1 bit	Output	FIFO almost full output, active high
full	1 bit	Output	FIFO full output, active high
error	1 bit	Output	FIFO error output, active high
data_out	width bit(s)	Output	FIFO data to pop

Table 1-2 Parameter Description

Parameter	Values	Function	
width	1 to 2048 Default: 8	Width of the data_in and data_out buses	
depth	2 to 1024 Default: 4	Number of memory elements used in FIFO (addr_width = ceil(log ₂ (<i>depth</i>))	
ae_level	1 to <i>depth</i> – 1 Default: 1	Almost empty level (the number of words in the FIFO at or below which the almost_empty flag is active)	
af_level	1 to <i>depth</i> – 1 Default: 1	Almost full level (the number of empty memory locations in the FIFO at which the almost_full flag is active. Refer to Figure 1.)	
err_mode	0 to 2 Default: 0	Error mode 0 = underflow/overflow and pointer latched checking, 1 = underflow/overflow latched checking, 2 = underflow/overflow unlatched checking	
rst_mode	0 to 3 Default: 0	Reset mode 0 = asynchronous reset including memory, 1 = synchronous reset including memory, 2 = asynchronous reset excluding memory, 3 = synchronous reset excluding memory	

Table 1-3 Synthesis Implementations

Implementation Name	Function	License Feature Required	
rtl ^a	Synthesis Model	DesignWare	

a. The implementation "rtl" replaces the obsolete implementations "rpl," "cl1," and "cl2." Information messages listing implementation replacements (SYNDB-37) may be generated by DC at compile time. Existing designs that specify an obsolete implementation ("rpl," "cl1," and "cl2") will automatically have that implementation replaced by the new superseding implementation ("rtl") noted by an information message (SYNDB-36) generated during DC compilation. The new implementation is capable of producing any of the original architectures automatically based on user constraints.

Table 1-4 Simulation Models

Model	Function
DW06.DW_FIFO_S1_SF_CFG_SIM	Design unit name for VHDL simulation
dw/dw06/src/DW_fifo_s1_sf_sim.vhd	VHDL simulation model source code
dw/sim_ver/DW_fifo_s1_sf.v	Verilog simulation model source code

Table 1-5 Error Mode Description

error_mode	Error Types Detected	Error Output	diag_n
0	Underflow/Overflow and Pointer Corruption	Latched	Connected
1	Underflow/Overflow	Latched	N/C
2	Underflow/Overflow	Not Latched	N/C

Writing to the FIFO (Push)

A push is executed when the push_req_n input is asserted (LOW) and either:

■ The full flag is inactive (LOW),

or:

- The full flag is active (HIGH), and
- The pop_req_n input is asserted (LOW).

Thus, a push can occur even if the FIFO is full, as long as a pop is executed in the same cycle.

Asserting <code>push_req_n</code> in either of the above cases causes the data at the <code>data_in</code> port to be written to the next available location in the FIFO. This write occurs on the <code>clk</code> following the assertion of <code>push_req_n</code>. The data at the <code>data_in</code> port must be stable for a setup time before the rising edge of <code>clk</code>.

An error occurs if a push is attempted while the FIFO is full. That is, if:

■ The push_req_n input is asserted (LOW),

- The full flag is active (HIGH), and
- The pop_req_n input is inactive (HIGH).

Reading from the FIFO (Pop)

A pop operation occurs when pop_req_n is asserted (LOW), as long as the FIFO is not empty. Asserting pop_req_n causes the internal read pointer to be incremented on the next rising edge of clk. Thus, the RAM read data must be captured on the clk following the assertion of pop_req_n.

Refer to the timing diagrams for details of the pop operation.

An error occurs if:

- The pop_req_n input is active (LOW), and
- The empty flag is active (HIGH).

Simultaneous Push and Pop

Push and pop can occur at the same time if there is data in the FIFO, even when the FIFO is full. With the FIFO not empty, the internal read pointer points to the next address to be popped and the pop data is available at the data_out output. When pop_req_n and push_req_n are both asserted, the following events occur on the next rising edge of clk:

- Pop data is captured by the next stage of logic after the FIFO, and
- The new data is pushed into the same location from which the data was popped.

Thus, there is no conflict in a simultaneous push and pop when the FIFO is full. A simultaneous push and pop cannot occur when the FIFO is empty, since there is no pop data to prefetch. However, push data is captured in the FIFO.

Reset

The rst_mode parameter selects whether reset is asynchronous ($rst_mode = 0$ or 2) or synchronous ($rst_mode = 1$ or 3). If an asynchronous mode is selected, asserting rst_n (setting it LOW) immediately causes the internal address pointers to be set to 0, and the flags and error outputs to be initialized. If a synchronous mode is selected, the address pointers, flags, and error outputs are initialized at the rising edge of clk after the assertion of rst_n .

The error outputs and flags are initialized as follows:

- The empty and almost_empty are initialized to 1, and
- All other flags and the error output are initialized to 0.

If *rst_mode* = 0 or 1, the RAM array is also initialized when rst_n is asserted. If *rst_mode* = 2 or 3, only the address pointers, and error and flag outputs are initialized; the RAM array is not initialized.

Errors

The *err_mode* parameter determines which possible fault conditions are detected, and whether the error output remains active until reset or for only the clock cycle in which the error is detected.

When the *err_mode* parameter is set to 0 at design time, the diag_n input provides an unconditional synchronous reset to the value of the read pointer. This can be used to intentionally cause the FIFO address pointers to become corrupted, forcing a pointer inconsistency-type error.

For normal operation when $err_mode = 0$, $diag_n$ should be driven inactive (HIGH). When the err_mode parameter is set to 1 or 2, the $diag_n$ input is ignored (unconnected).

error

The error output indicates a fault in the operation of the FIFO control logic. There are several possible causes for the error output to be activated:

- 1. Overflow (push and no pop while full).
- 2. Underflow (pop while empty).
- 3. Empty pointer mismatch (read pointer \neq write pointer when empty).
- 4. Full pointer mismatch (read pointer ≠ write pointer when full).
- 5. In between pointer mismatch (read pointer = write pointer when neither empty nor full).

When *err_mode* = 0, all five causes are detected, and the error output (once activated) remains active until reset. When *err_mode* = 1, only causes 1 and 2 are detected, and the error output (once activated) remains active until reset. When *err_mode* = 2, only causes 1 and 2 are detected, and the error output only stays active for the clock cycle in which the error is detected. Refer to Table 1-5 on page 3 for *err_mode* descriptions. The error output is set LOW when rst_n is applied.

Controller Status Flag Outputs

Refer to Figure 1-1 on page 6 for operation of the status flags.

empty

The empty output indicates that there are no words in the FIFO available to be popped. The empty output is set HIGH when rst_n is applied.

almost_empty

The almost_empty output is asserted when there are no more than ae_level words currently in the FIFO available to be popped. The ae_level parameter defines the almost empty threshold. The almost_empty output is useful for preventing the FIFO from underflowing. The almost_empty output is set HIGH when rst_n is applied.

half_full

The half_full output is active (HIGH) when at least half the FIFO memory locations are occupied. The half_full output is set LOW when rst_n is applied.

almost full

The almost_full output is asserted when there are no more than af_level empty locations in the FIFO. The af_level parameter defines the almost full threshold and is useful for preventing the FIFO from overflowing. The almost_full output is set LOW when rst_n is applied.

full

The full output indicates that the FIFO is full and there is no space available for push data. The full output is set LOW when rst_n is applied.

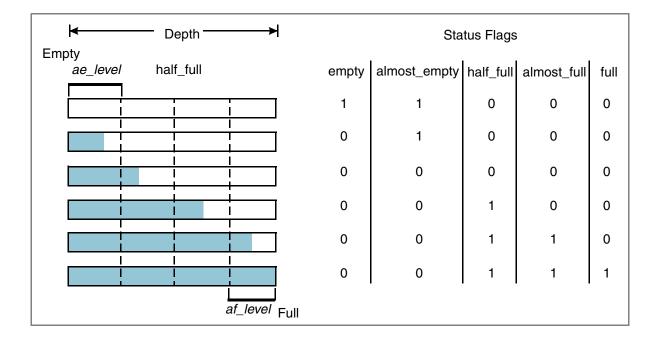
Application Notes

The *ae_level* parameter value is chosen at design time to give the input flow control logic enough time to begin pushing data into the FIFO before the last word is popped by the output flow control logic.

The *af_level* parameter value is chosen at design time to give the output flow control logic enough time to begin popping data out of the FIFO before the FIFO is full. In other situations, this time is needed to cause the input flow control logic to interrupt the pushing of data into the FIFO.

Figure 1-1 on page 6 shows the status flags of the DW_fifo_s1_sf FIFO at various FIFO storage levels.

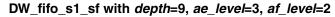
Figure 1-1 DW_fifo_s1_sf FIFO Status Flags



Timing Waveforms

The following figures show timing diagrams for various conditions of DW_fifo_s1_sf.

Figure 1-2 Status Flag Timing Waveforms While Pushing



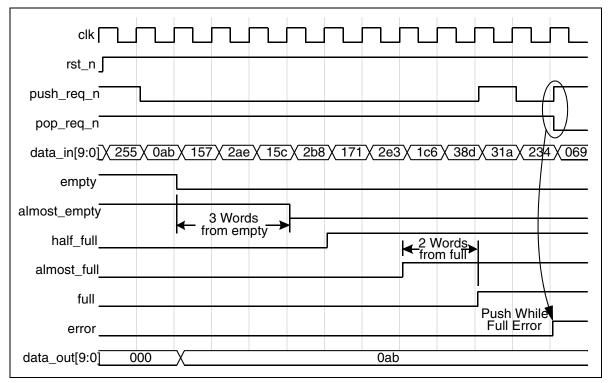
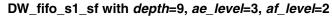


Figure 1-3 Status Flag Timing Waveforms While Popping



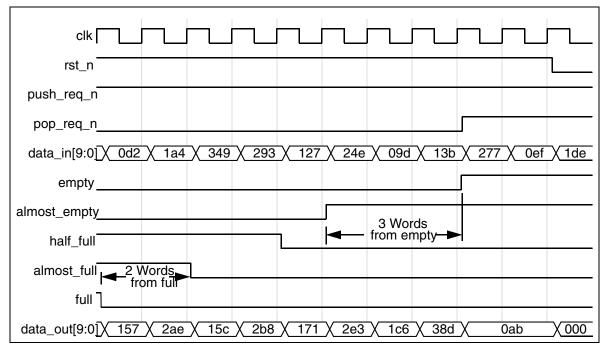
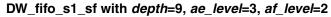
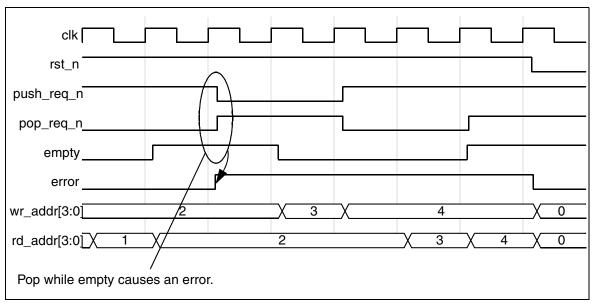


Figure 1-4 Error Flag Timing Waveforms





DW_fifo_s1_sf with ae_level=3, af_level=2, err_mode=2

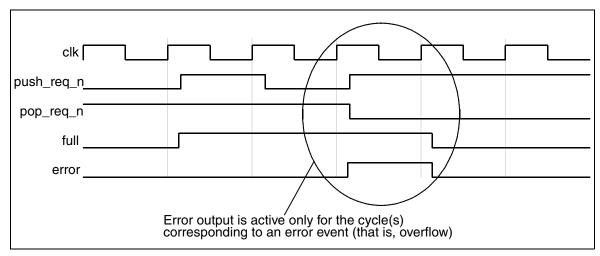


Figure 1-5 Error Flag Timing Waveforms (continued)



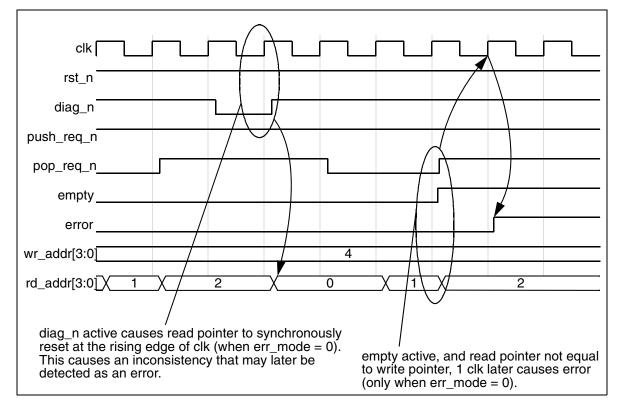


Figure 1-6 Error Flag Timing Waveforms (continued)

DW_fifo_s1_sf with depth=9, ae_level=3, af_level=2, err_mode=1 or 2

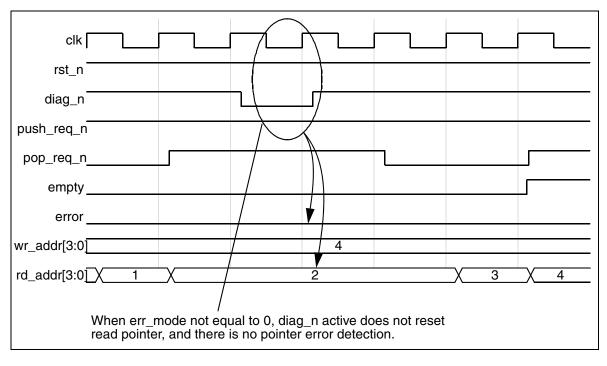
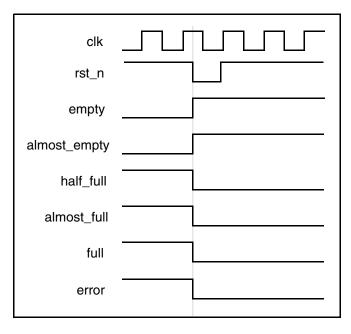
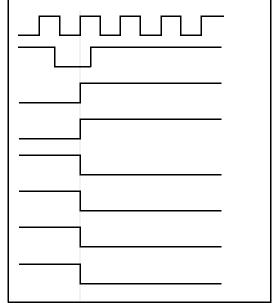


Figure 1-7 Reset Timing Waveforms

DW_fifo_s1_sf with depth = 9, rst_mode = 0 or 2
(Asynchronous Reset)



DW_fifo_s1_sf with depth = 9, rst_mode = 1 or 3
(Synchronous Reset)



Related Topics

- Memory FIFO Overview
- DesignWare Building Block IP Documentation Overview

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HDL Usage Through Component Instantiation - VHDL

```
library IEEE, DWARE, DWARE;
use IEEE.std logic 1164.all;
use DWARE.DWpackages.all;
use DWARE.DW foundation comp.all;
entity DW_fifo_s1_sf_inst is
  generic (inst_width : INTEGER := 8;
                       : INTEGER := 4;
           inst depth
           inst_ae_level : INTEGER := 1;
           inst_af_level : INTEGER := 1;
           inst err mode : INTEGER := 0;
           inst_rst_mode : INTEGER := 0 );
  port (inst_clk
                        : in std logic;
                        : in std_logic;
        inst rst n
        inst_push_req_n : in std_logic;
        inst_pop_req_n : in std_logic;
        inst_diag_n
                        : in std_logic;
        inst_data_in
                        : in std_logic_vector(inst_width-1 downto 0);
                    : out std_logic;
        empty inst
        almost_empty_inst : out std_logic;
       half_full_inst : out std_logic;
        almost_full_inst : out std_logic;
        full_inst : out std_logic;
        error_inst
                        : out std_logic;
        data_out_inst
                        : out std_logic_vector(inst_width-1 downto 0) );
end DW fifo s1 sf inst;
architecture inst of DW fifo s1 sf inst is
begin
  -- Instance of DW fifo s1 sf
  U1 : DW fifo s1 sf
    generic map ( width => inst_width,    depth => inst_depth,
                ae level => inst ae level, af level => inst af level,
                err_mode => inst_err_mode,    rst_mode => inst_rst_mode )
   port map ( clk => inst_clk,
                                rst_n => inst_rst_n,
              push_req_n => inst_push_req_n, pop_req_n => inst_pop_req_n,
              diaq n => inst_diag_n,
                                      data_in => inst_data_in,
               empty => empty_inst, almost_empty => almost_empty_inst,
              half_full => half_full_inst, almost_full => almost_full_inst,
               full => full inst, error => error inst,
               data_out => data_out_inst );
end inst;
-- pragma translate_off
configuration DW_fifo_s1_sf_inst_cfg_inst of DW_fifo_s1_sf_inst is
  for inst
```

end for; -- inst
end DW_fifo_s1_sf_inst_cfg_inst;
-- pragma translate_on

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HDL Usage Through Component Instantiation - Verilog

```
module DW fifo s1 sf inst(inst clk, inst rst n, inst push req n,
                          inst pop reg n, inst diag n, inst data in,
                          empty_inst, almost_empty_inst, half_full_inst,
                          almost full inst, full inst, error inst,
                          data_out_inst );
  parameter width = 8;
  parameter depth = 4;
  parameter ae_level = 1;
 parameter af_level = 1;
  parameter err mode = 0;
  parameter rst_mode = 0;
  input inst clk;
  input inst_rst_n;
  input inst_push_req_n;
  input inst_pop_req_n;
  input inst_diag_n;
  input [width-1 : 0] inst_data_in;
  output empty_inst;
  output almost_empty_inst;
  output half_full_inst;
  output almost_full_inst;
  output full inst;
  output error_inst;
  output [width-1 : 0] data_out_inst;
  // Instance of DW_fifo_s1_sf
  DW_fifo_s1_sf #(width, depth, ae_level, af_level, err_mode, rst_mode)
    U1 (.clk(inst clk),
                          .rst n(inst rst n),
                                                 .push req n(inst push req n),
        .pop_req_n(inst_pop_req_n),
                                      .diag_n(inst_diag_n),
        .data_in(inst_data_in),
                                 .empty(empty_inst),
        .almost_empty(almost_empty_inst), .half_full(half_full_inst),
        .almost_full(almost_full_inst),
                                          .full(full_inst),
        .error(error inst), .data out(data out inst) );
endmodule.
```

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