

$$\lim_{t \rightarrow a} r(t) = \langle \lim_{t \rightarrow a} f(t), \lim_{t \rightarrow a} g(t), \lim_{t \rightarrow a} h(t) \rangle$$

$$r'(t) = \langle f'(t), g'(t), h'(t) \rangle dt$$

$$\frac{d}{dt}[u(t)v(t)] = u'(t)v(t) + u(t)v'(t)$$

$$L = \int_a^b \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2} dt$$

If $\lim_{(x,y) \rightarrow (a,b)} f(x,y) = L$ then $\forall \epsilon > 0$

s.t. if $(x,y) \in D$ and $0 < \sqrt{(x-a)^2 + (y-b)^2} < \delta$

then $|f(x,y) - L| < \epsilon$

Test limit along many paths, $x=0, y=x^2, x=y^2, y=0$ etc

Equation of plane tangent to surface $z=f(x,y)$:

$$Z - Z_0 = f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$$

The linear approximation of $f(x,y)$ at a point

is the equation of the plane tangent to the surface

Point estimate: $L(a,b) = f(x_0, y_0)(a - x_0) + f_y(x_0, y_0)(b - y_0) + f(x_0, y_0)$

Differential: $df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \dots$

Chain rule: construct a diagram

$$\begin{array}{c} w \\ \swarrow \quad \searrow \\ x \quad \quad y \\ \swarrow \quad \searrow \quad \swarrow \quad \searrow \\ s \quad t \quad s \quad t \end{array} \quad \begin{array}{l} \frac{\partial w}{\partial s} = \frac{\partial w}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial w}{\partial y} \frac{\partial y}{\partial s} \\ \frac{\partial w}{\partial t} = \frac{\partial w}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial w}{\partial y} \frac{\partial y}{\partial t} \end{array}$$

$$\frac{dx}{dy} = -\frac{\frac{\partial f}{\partial x}}{\frac{\partial f}{\partial y}} = -\frac{F_x}{F_y} : \frac{2x}{\partial x} = -\frac{\frac{\partial f}{\partial y}}{\frac{\partial f}{\partial x}} \quad \frac{2y}{\partial y} = \frac{\frac{\partial f}{\partial x}}{\frac{\partial f}{\partial y}}$$

$$D_u f(x,y) = f_x(x,y)a + f_y(x,y)b \Rightarrow \nabla f = \langle f_x, f_y \rangle$$

make sure to make the vector into a unit vector if it isn't already

f increases the fastest in the direction of the gradient vector and the maximum rate of change is $|\nabla f(a,b)|$.

Tangent Plane to a level surface

$$F_x(x_0, y_0, z_0)(x - x_0) + F_y(x_0, y_0, z_0)(y - y_0) + F_z(x_0, y_0, z_0)(z - z_0) = 0$$

Minimum and Maximum:

$$D = D(a,b) = f_{xx}(a,b)f_{yy}(a,b) - [f_{xy}(a,b)]^2$$

If $D > 0$ and $f_{xx}(a,b) > 0$, then $f(a,b)$ is a min

If $D > 0$ and $f_{xx}(a,b) < 0$, then $f(a,b)$ is a saddle point

If $D = 0$, test gives no information

Global minimum and maximum

1. Find values of f at critical points in D
2. Find the extreme values of f on the boundary of D
3. The largest values from step 1 and 2 is the absolute maximum value.

$$\nabla f(x_0, y_0, z_0) = \lambda \nabla g(x_0, y_0, z_0)$$

where $g(x,y,z) = K$.

$$\nabla f(x_0, y_0, z_0) = \lambda \nabla g(x_0, y_0, z_0) + \mu \nabla h(x_0, y_0, z_0)$$

where $g(x,y,z) = K$ and $h(x,y,z) = C$

$$\iint_D f(x,y) dA = \int_a^b \int_{g_1(x)}^{g_2(x)} f(x,y) dy dx = \int_c^d \int_{h_1(y)}^{h_2(y)} f(x,y) dx dy$$

$$r^2 = x^2 + y^2 \quad x = r \cos \theta \quad y = r \sin \theta \quad R = \{(\theta, r) \mid a \leq r \leq b, \alpha \leq \theta \leq \beta\}$$

$$\iint_R f(x,y) dA = \int_a^b \int_{\alpha}^{\beta} f(r \cos \theta, r \sin \theta) r dr d\theta$$

$$A(s) = \iint_D \sqrt{1 + \left(\frac{\partial z}{\partial x}\right)^2 + \left(\frac{\partial z}{\partial y}\right)^2} dA$$

Over Box $[a,b] \times [c,d] \times [r,s]$

$$\iiint_B f(x,y,z) dV = \int_c^d \int_a^b \int_r^s f(x,y,z) dx dy dz$$

$$\int_{\text{domain}} \int_{\text{range}} \int_{\text{upper equation}}^{\text{lower equation}} (\text{Integrand}) dV$$

$$m = \iiint_E \rho(x,y,z) dV$$

Moments:

$$M_{yz} = \iiint_E x \rho(x,y,z) dV \quad M_{xz} = \iiint_E y \rho(x,y,z) dV$$

$$M_{xy} = \iiint_E z \rho(x,y,z) dV$$

$$\text{center of mass: } \left(\frac{M_{yz}}{m}, \frac{M_{xz}}{m}, \frac{M_{xy}}{m} \right)$$

moments of inertia

$$I_x = \iiint_E (y^2 + z^2) \rho(x,y,z) dV$$

$$I_y = \iiint_E (x^2 + z^2) \rho(x,y,z) dV$$

$$I_z = \iiint_E (x^2 + y^2) \rho(x,y,z) dV$$

Cylindrical Coordinates

$$\begin{aligned} x &= r \cos \theta, y = r \sin \theta, z = z \\ r^2 &= x^2 + y^2, \tan \theta = \frac{y}{x}, z = z \\ \iiint_E f(x,y,z) dV &= \int_{\alpha}^{\beta} \int_{h_1(\theta)}^{h_2(\theta)} \int_{u_1(r, \cos \theta, \sin \theta)}^{u_2(r, \cos \theta, \sin \theta)} f(r \cos \theta, r \sin \theta, z) r dz dr d\theta \end{aligned}$$

Spherical Coordinate

$$\begin{aligned} x &= \rho \sin \phi \cos \theta, y = \rho \sin \phi \sin \theta, z = \rho \cos \phi \\ \rho^2 &= x^2 + y^2 + z^2 \\ \rho &= \text{radius of sphere} \\ E &= \{(\rho, \theta, \phi) \mid a \leq \rho \leq b, \alpha \leq \theta \leq \beta, c \leq \phi \leq d\} \end{aligned}$$

$$\iiint_E f(x,y,z) dV = \int_c^d \int_{\alpha}^{\beta} \int_a^b f(\rho \sin \phi \cos \theta, \rho \sin \phi \sin \theta, \rho \cos \phi) \rho^2 \sin \phi d\rho d\theta d\phi$$

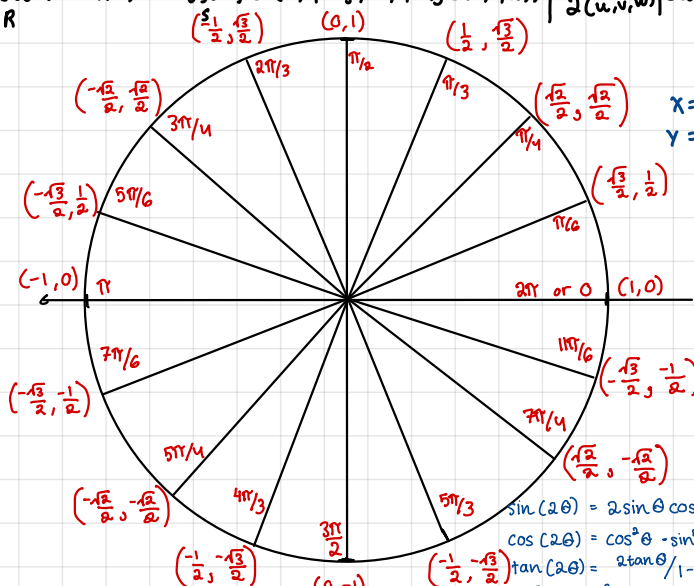
Jacobian:

$$\begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{vmatrix} \text{ in } \mathbb{R}^2 \quad \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{vmatrix} \text{ in } \mathbb{R}^3$$

Change of variables:

find u and v s.t. integral is easier to find
Transform the region on the xy plane to the uv plane
Find the new boundaries of integration
solve this integral

$$\iiint_R f(x,y,z) dV = \iiint_S f(x(u,v,w), y(u,v,w), z(u,v,w)) \left| \frac{\partial(x,y,z)}{\partial(u,v,w)} \right| du dv dw$$



$$\begin{aligned} x &= \cos \theta \\ y &= \sin \theta \end{aligned}$$

$$\begin{aligned} \text{Surface Integral: } \iint_S f(x,y,z) dS &= \iint_D f(x(u,v), y(u,v), z(u,v)) \sqrt{\left(\frac{\partial x}{\partial u}\right)^2 + \left(\frac{\partial x}{\partial v}\right)^2} du dv \\ n &= \frac{1}{\sqrt{1 + f_x^2 + f_y^2}} \langle -f_x, -f_y, 1 \rangle \\ \text{Surface Integral of } F \text{ across } S: \iint_S F \cdot n dS &= \iint_D F(x(u,v), y(u,v), z(u,v)) \cdot \frac{1}{\sqrt{1 + f_x^2 + f_y^2}} \langle -f_x, -f_y, 1 \rangle \sqrt{1 + f_x^2 + f_y^2} du dv \\ &= \iint_D \langle -f_x F, -f_y F, F \rangle du dv \end{aligned}$$

$$\begin{aligned} \int_C f(x,y) ds &= \int_a^b f(x(t), y(t)) \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt \\ \int_C f(x,y) dx &= \int_a^b f(x(t), y(t)) \cdot x'(t) dt \\ \int_C f(x,y) dy &= \int_a^b f(x(t), y(t)) \cdot y'(t) dt \end{aligned}$$

$$\begin{aligned} m &= \int_C \rho(x,y) ds \\ \bar{x} &= \frac{1}{m} \int_C x \rho(x,y) ds \\ \bar{y} &= \frac{1}{m} \int_C y \rho(x,y) ds \end{aligned}$$

$$\begin{aligned} \int_C F \cdot dr &= \int_a^b F(r(t)) \cdot r'(t) dt \\ \int_C F dx + Q dy &= \iint_S \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} dA \end{aligned}$$

for 3d if $\text{curl } F = 0$ then F is conservative

$$\text{and therefore } \int_C F \cdot dr = \int_a^b \nabla f \cdot dr = f(r(b)) - f(r(a))$$

$$\begin{aligned} \frac{d}{dx} (x^n) &= n x^{n-1} \\ \frac{d}{dx} (f(x)g(x)) &= f'(x)g(x) + f(x)g'(x) \\ \frac{d}{dx} \left(\frac{f(x)}{g(x)} \right) &= \frac{g(x)f'(x) - f(x)g'(x)}{g(x)^2} \\ \frac{d}{dx} e^{f(x)} &= f'(x)e^{f(x)} \\ \frac{d}{dx} (a^x) &= a^x \ln a \\ \frac{d}{dx} (\log_a x) &= \frac{1}{x \ln a} \\ \frac{d}{dx} \csc x &= -\csc x \cot x \\ \frac{d}{dx} \sec x &= \sec x \tan x \\ \frac{d}{dx} \sin^{-1} x &= \frac{1}{\sqrt{1-x^2}} \\ \frac{d}{dx} \sec^{-1} x &= \frac{1}{x \sqrt{x^2-1}} \end{aligned}$$