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Typedefs - typedef type t_name → EX: typedef map<string, vector<int> > map_vect;

Lists: sequentially linked structure

Push_front, pop_front, push_back, pop_back, list.sort(opt_func) (vect → std::sort(beg, end, opt))

Cannot add integers to list iterators ex: itr + 4 → can for vector + string itr

Operators: as member functions → obj.operator=(s_obj)

→ Private variables can be accessed directly, s_obj can be accessed by rhs. || one parameter and const

Operators: as non-member functions → operator=(first, second)

→ Private variables cannot be accessed directly + two parameters

Friend Class: allows for access all the private member variables and functions of class as if public

Friend Function: allows for Friend function to access and work just like member function

Note: Friend class must be declared as public || We cannot create new operators or change # of args

Maps: #include <map> – search, insert, erase = O(log n) || keys are ordered (need op<) no duplicates

std::map<key_type, value_type> var_name - declaration || std::pair <const key_type, value_type> - entry

std::map<std::string, int>::const_iterator it - iterator

map.find(key) - find func → returns map itr to position of key else map.end() || .size()

map.insert(std::make_pair(val, val)); → inserts pair, returns pointer to insertion/place, bool of inserted

map.erase(iterator p) → deletes pair referred to by p || map.erase(itr first, itr, last) → deletes from first to

last- not last || size_type erase(const key_type& k) → erases pair containing k return bool of deleted

[] operator - Ex: ++count[s] looks for key of s, if none create and increment, if there, just increment

Map Iterators: std::map<type, type>::iterator it, can be incremented with ++, --. it can access first and second with it->first, it->second

Pairs: #include <utility>

std::pair<int, double> p1(8, 8.8) || std::make_pair(8, 9.0) - declarations || .first or .second - accessing

Sets: ordered containers storing unique “keys” || sorts with < to keys || Insert, erase, find = O(log n)

std::set<const val_type> set_1() - declaration NOTE: no []operator and have .size

pair<iterator, bool> set<key>::insert(const Key& entry) – returns pos of insertion or exist, bool if inserted

Iterator set<Key>::insert(iterator pos, const Key& entry) – return pos of insertion, pos is a “hint”

size_type set<Key>::erase(const Key& x); – returns 1 removed, 0 for not removed

void set<Key>::erase(itr p) – erases at iterator || void set<Key>::erase(iterator first, iterator last) – erase

Const_iterator set<key>::find(const Key& x) const; - find – returns pos or set.end() if not found

Binary Trees: empty or node that has pointers to two binary sub-trees;

top most node = root, left +right node = children + subtrees, node with null left + right = leaf

Binary Search Trees (BST): at each node of the tree, the value stored at the node is >= all the values stored in the left subtree and <= all the values stored in the right subtree

Balanced Tree: the number of nodes on each subtree is approximately the same

given : balanced tree from 1 - 7, 4 root ABCD - bring in print in order code

In-order Traversal - print from smallest to largest (print left, me, print right) - 1234567

Post-order Traversal - print children then parent (print left, print right, me) - 1325764

Pre-order Traversal - parents first then children - (print me, print left, print right) - 4213657

B+ Trees: trees that can have up to B children and B - 1 keys || Good for everything bc flat + wide

Depth-first - follow all the way to leaf then back up to decision point (in, pre, post order trav)

- Quick but takes a while if wrong decision is made early on

Breadth-first - nodes closer to roots visited first || solution closer to root found first || memory intensive

Ds_set - root, size → priv representation

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void destroy_tree(TreeNode<T>* p) {
    if (!p) return;
    destroy_tree(p->right);
    destroy_tree(p->left);
    delete p;
}

iterator find(const T& key_value, TreeNode<T>* p) {
    if (!p) return end();
    if (p->value > key_value)
        return find(key_value, p->left);
    else if (p->value < key_value)
        return find(key_value, p->right);
    else
        return iterator(p, this);
}

std::pair<iterator, bool> insert(const T& key_value, TreeNode<T>* p, TreeNode<T>* the_parent) {
    if (!p) {
        p = new TreeNode<T>(key_value);
        p->parent = the_parent;
        this->size++;
        return std::pair<iterator, bool>(iterator(p, this), true);
    }
    else if (key_value < p->value)
        return insert(key_value, p->left, p);
    else if (key_value > p->value)
        return insert(key_value, p->right, p);
    else
        return std::pair<iterator, bool>(iterator(p, this), false);
}

int erase(const T& key_value, TreeNode<T>* p) {
    if (!p) return 0;

    // look left & right
    if (p->value < key_value) {
        return erase(key_value, p->right);
    }
    else if (p->value > key_value) {
        return erase(key_value, p->left);
    }

    // Found the node. Let's delete it
    assert(p->value == key_value);
    if (!p->left && !p->right) { // leaf
        delete p;
        p = NULL;
        this->size--;
    }
    else if (!p->left) { // no left child
        TreeNode<T>* q = p;
        p = p->right;
        assert(p->parent == q);
        p->parent = q->parent;
        delete q;
        this->size--;
    }
    else if (!p->right) { // no right child
        TreeNode<T>* q = p;
        p = p->left;
        assert(p->parent == q);
        p->parent = q->parent;
        delete q;
        this->size--;
    }
    else { // Find rightmost node in left subtree
        TreeNode<T>* q = p->left;
        while (q->right) q = q->right;
        p->value = q->value;
        // recursively remove the value from the left subtree
        int check = erase(q->value, p->left);
        assert(check == 1);
    }
    return 1;
}

void print_in_order(std::ostream& ostr, const TreeNode<T>* p) const {
    if (p) {
        print_in_order(ostr, p->left);
        ostr << p->value << "\n";
        print_in_order(ostr, p->right);
    }
}

template <class T> class TreeNode {
public:
    TreeNode() : left(NULL), right(NULL) {}
    TreeNode(const T& init) : value(init), left(NULL), right(NULL) {}
    T value;
    TreeNode* left;
    TreeNode* right;
};

std::string s;
std::map<std::string, int> counters; // store each word and a

// read the input, keeping track of each word and how often w
while (std::cin >> s)
    ++counters[s];

// write the words and associated counts
std::map<std::string, int>::const_iterator it;
for (it = counters.begin(); it != counters.end(); ++it) {
    std::cout << it->first << "\t" << it->second << std::endl;
}

Height of tree
unsigned int find_height(TreeNode* root)
{
    if (root == nullptr) {
        return 0;
    }
    else {
        unsigned int left_height =
            find_height(root->left);
        unsigned int right_height =
            find_height(root->right);
        return 1 + std::max(left_height,
            right_height);
    }
}

Sum of odd map values
map<string, vector<int>> m;
unsigned int count = 0;
std::map<string,
vector<int>>::iterator it = m.begin();
while (it != m.end()) {
    for (unsigned int i=0;
i<it->second.size(); i++) {
        if (it->second[i]%2 == 1) {
            count += it->second[i];
        }
    }
    it++;
}

Smallest value in tree
template <class T>
TreeNode<T>*
FindSmallestInRange(const T& a,
const T& b, TreeNode<T>* root, T&
best_value){
    if(!root){ return NULL; }
    TreeNode<T>* left_subtree =
FindSmallestInRange(a,b,root->left,b
est_value);
    TreeNode<T>* right_subtree =
FindSmallestInRange(a,b,root->right,
best_value);
    if(root->value > a && root->value <
best_value){
        best_value = root->value;
        return root;
    }
    else if(left_subtree &&
left_subtree->value == best_value){
        return left_subtree;
    }
    else if(right_subtree){
        return right_subtree;
    }
    return NULL;
}

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