## **Non Linear Regression**

Non linear regression can be formulated as:

$$\min_{X} E(X) : X \in \mathcal{R}^{M}$$

where

$$E(X) = \frac{1}{2} \sum_{n=1}^{N} (f(X, A_n) - b_n)^2 = \frac{1}{2} R^T R$$

$$R = \begin{bmatrix} f(X, A_1) - b_1 \\ f(X, A_2) - b_2 \\ \dots \\ f(X, A_N) - b_N \end{bmatrix}$$

f is the non linear regression model  $\Re^K \to \Re^1$ , which maps row vector  $A_n$  (with size K) into scalar  $b_n$ , for a total of N observations. Non linear regression is usually an optimization that involves Jacobian of E and Hessian of E w.r.t. parameter E. We will find out how the Jacobian and Hessian of E related to the Jacobian and Hessian of E Jacobian and Hessian of E are defined as:

Lets expand Jacobian:

$$\begin{split} \nabla_{X}^{T}E &= \begin{bmatrix} \partial_{x_{1}}E \\ \partial_{x_{2}}E \\ \vdots \\ \partial_{x_{M}}E \end{bmatrix} \\ &= \begin{bmatrix} \sum_{n=1}^{N}(f(X,A_{n}) - b_{n})\partial_{x_{1}}f(X,A_{n}) \\ \sum_{n=1}^{N}(f(X,A_{n}) - b_{n})\partial_{x_{2}}f(X,A_{n}) \\ \vdots \\ \sum_{n=1}^{N}(f(X,A_{n}) - b_{n})\partial_{x_{M}}f(X,A_{n}) \end{bmatrix} \\ &= \begin{bmatrix} \partial_{x_{1}}f(X,A_{1}) & \partial_{x_{1}}f(X,A_{2}) & \dots & \partial_{x_{1}}f(X,A_{N}) \\ \partial_{x_{2}}f(X,A_{1}) & \partial_{x_{2}}f(X,A_{2}) & \dots & \partial_{x_{2}}f(X,A_{N}) \\ \vdots \\ \partial_{x_{M}}f(X,A_{1}) & \partial_{x_{M}}f(X,A_{2}) & \dots & \partial_{x_{M}}f(X,A_{N}) \end{bmatrix} \begin{bmatrix} f(X,A_{1}) - b_{1} \\ f(X,A_{2}) - b_{2} \\ \vdots \\ f(X,A_{N}) - b_{N} \end{bmatrix} \\ &= (\nabla_{X}^{T}f)R & relation between Jacobian of E and f \\ \nabla_{X}f &= \begin{bmatrix} \partial_{x_{1}}f(X,A_{1}) & \partial_{x_{2}}f(X,A_{1}) & \dots & \partial_{x_{M}}f(X,A_{1}) \\ \partial_{x_{1}}f(X,A_{2}) & \partial_{x_{2}}f(X,A_{2}) & \dots & \partial_{x_{M}}f(X,A_{2}) \\ \vdots & \vdots & \ddots & \vdots \\ \partial_{x_{1}}f(X,A_{N}) & \partial_{x_{2}}f(X,A_{N}) & \dots & \partial_{x_{M}}f(X,A_{N}) \end{bmatrix} \end{split}$$

where

Matrix convention in this document:

- different data in different rows
- different dimension in different columns
- number of data N
- number of dimension M

Lets expand Hessian:

$$\nabla^2_{XX}E \ = \begin{bmatrix} \partial^2_{x_1x_1}E & \partial^2_{x_1x_2}E & \dots & \partial^2_{x_1x_M}E \\ \partial^2_{x_2x_1}E & \partial^2_{x_2x_2}E & \dots & \partial^2_{x_2x_M}E \\ \dots & \dots & \dots & \dots \\ \partial^2_{x_Mx_1}E & \partial^2_{x_Mx_2}E & \dots & \partial^2_{x_Mx_M}E \end{bmatrix}$$

Consider the  $i^{th}$  row and  $j^{th}$  column :

$$\begin{split} [\nabla^2_{XX}E]_{i,j} & = \partial_{x_j} \sum_{n=1}^N (f(X,A_n) - b_n) \partial_{x_i} f(X,A_n) \\ & = \sum_{n=1}^N (f(X,A_n) - b_n) \partial^2_{x_i x_j} f(X,A_n) + \sum_{n=1}^N \partial_{x_j} f(X,A_n) \partial_{x_i} f(X,A_n) \end{split}$$

Hence we have:

$$\nabla_{XX}^{2}E = \sum_{n=1}^{N} (f(X, A_{n}) - b_{n}) \nabla_{XX}^{2} f(X, A_{n}) + (\nabla_{X}^{T} f) \nabla_{X} f$$

$$\label{eq:where} \textit{where} \quad \nabla^2_{XX} f(X, A_n) \ = \begin{bmatrix} \partial^2_{x_1 x_1} f(X, A_n) & \partial^2_{x_1 x_2} f(X, A_n) & \dots & \partial^2_{x_1 x_M} f(X, A_n) \\ \partial^2_{x_2 x_1} f(X, A_n) & \partial^2_{x_2 x_1} f(X, A_n) & \dots & \partial^2_{x_2 x_M} f(X, A_n) \\ \dots & \dots & \dots & \dots \\ \partial^2_{x_M x_1} f(X, A_n) & \partial^2_{x_M x_2} f(X, A_n) & \dots & \partial^2_{x_M x_M} f(X, A_n) \end{bmatrix}$$

Please note that Jacobian and Hessian matrices are of different sizes:

$$\begin{aligned} & sizeof(\nabla_X E) = 1 \times M \\ & sizeof(\nabla_{XX}^2 E) = M \times M \\ & sizeof(\nabla_X f) = N \times M \\ & sizeof(\nabla_{XX}^2 f) = M \times M \end{aligned}$$

## Reference

https://neos-guide.org/guide/types/least-squares/