

Chap1. Probability 53+6*8

1.1 Fundamental

- geometric series $\frac{a(1-r^N)}{1-r} = a + ar + ar^2 + ar^3 + \dots + ar^{N-1}$
- binomial theorem $(x+y)^N = \sum_{n=0}^N C_n^N x^n y^{N-n}$
- Taylor series

df	$= \frac{f_x}{1!}(dx) + \frac{f_{xx}}{2!}(dx)^2 + \frac{f_{xxx}}{3!}(dx)^3 + \dots$	univariate
df	$= \left[\frac{f_x}{1!}(dx) + \frac{f_y}{1!}(dy) + \frac{f_{xx}}{2!}(dx)^2 + 2\frac{f_{xy}}{2!}(dx)(dy) + \frac{f_{yy}}{2!}(dy)^2 + \frac{f_{xxx}}{3!}(dx)^3 + 3\frac{f_{xxy}}{3!}(dx)^2(dy) + 3\frac{f_{xyy}}{3!}(dx)(dy)^2 + \frac{f_{yyy}}{3!}(dy)^3 + \dots \right]$	bivariate
Δf	$= J_f(\Delta X) + \frac{1}{2!}(\Delta X)^T H(\Delta X) + \dots$ where $J_f = [f_{x_1}, f_{x_2}, \dots, f_{x_M}]$	multivariate
ΔF	$= J_F(\Delta X) + \dots$ where $J_F = \begin{bmatrix} J_{f1} \\ J_{f2} \\ \dots \\ J_{fN} \end{bmatrix}$	multifunction
- exponential $e^x = \sum_{n=0}^N \frac{x^n}{n!}$
- Poisson $\Pr(n | \lambda t) = e^{-\lambda t} \frac{(\lambda t)^n}{n!}$

1.2 Exponential

- definition of exp $e^x = \sum_{n=0}^N \frac{x^n}{n!}$
- definition of exp $e^x = \lim_{N \rightarrow \infty} \left(1 + \frac{x}{N}\right)^N$
- usage of exp
 - continuous discounting / continuous compounding
 - differentiation of exponential returns exponential
 - convolution of exponential returns exponential
 - product of exponential returns exponential
 - Fourier of exponential returns exponential
 - Euler identity, which is useful to model cycles

1.3 Distributions

	Gaussian	Bernoulli	Binomial	Geometric	Poisson	Exponential
pdf	$\Pr(X = x \mu, \sigma)$	$\Pr(S = n p)$	$\Pr(S = n N, p)$	$\Pr(S = n p)$	$\Pr(S = n \lambda T)$	$\Pr(T = t \lambda)$
mean	μ	p	Np	$1/p$	λT	$1/\lambda$
var	σ^2	pq	Npq	$(1/p) \times (q/p)$	λT	$(1/\lambda)^2$
char-fct	yes	yes	yes	yes	yes	yes
sum	yes		yes		yes	
min	yes			yes		yes
memoryless				yes		yes
comparison						yes
trick for mean			C_n^N	d/dp	$N!$	integration by parts
trick for var			$E[N(N-1)]$	$E[N(N-1)]$	$E[N(N-1)]$	integration by parts

Gaussian sum	$\text{Gaussian}(\mu_1, \sigma_1) + \text{Gaussian}(\mu_2, \sigma_2)$	=	$\text{Gaussian}(\mu_1 + \mu_2, \sqrt{\sigma_1^2 + \sigma_2^2})$
Binomial sum	$\text{Binomial}(N_1, p) + \text{Binomial}(N_2, p)$	=	$\text{Binomial}(N_1 + N_2, p)$
Poisson sum	$\text{Poisson}(\lambda_1 T) + \text{Poisson}(\lambda_2 T)$	=	$\text{Poisson}(\lambda_1 + \lambda_2, T)$

Characteristic function of a random variable X

$$\begin{aligned}
 \varphi_X(z) &= E[e^{izX}] & \varphi_X : \mathbb{R} &\rightarrow \mathbb{C} \\
 &= \int_{-\infty}^{+\infty} izx d\Pr(X < x) & \text{where } \Pr(X < x) &\text{ is cumulative distribution function of } X \\
 &= \int_{-\infty}^{+\infty} izx \Pr(X = x) dx & \text{where } \Pr(X = x) &\text{ is probability density function of } X \\
 \text{Taylor series : } \varphi_X(z) &= E[e^{izX}] \\
 &= E\left[e^{iz0} + iz e^{iz0} X + \frac{(iz)^2 e^{iz0} X^2}{2!} + \frac{(iz)^3 e^{iz0} X^3}{3!} + \frac{(iz)^4 e^{iz0} X^4}{4!} + \dots\right] \\
 &= 1 + izE[X] + \frac{(iz)^2}{2!} E[X^2] + \frac{(iz)^3}{3!} E[X^3] + \frac{(iz)^4}{4!} E[X^4] + \dots \quad \text{weighted sum of all moments}
 \end{aligned}$$

Identical characteristic functions implies equivalent sets of moments, in turn implies the same distribution :

$$\varphi_{X_1}(z) = \varphi_{X_2}(z) \quad \leftrightarrow \quad \Pr(X_1 = x) = \Pr(X_2 = x)$$

1.3a Gaussian

$$\begin{aligned}
 \text{pdf} \quad \Pr(X = x | U\Sigma) &= \frac{1}{\sqrt{(2\pi)^{\text{rank}(\Sigma)} \det(\Sigma)}} \exp\left(-\frac{1}{2}(X-U)^T \Sigma^{-1}(X-U)\right) \\
 \Pr(X = x | \mu\sigma) &= \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right) \\
 \text{mean} \quad E[\varepsilon] &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{+\infty} e^{-x^2/2} x dx \\
 &= \frac{-1}{\sqrt{2\pi}} \int_{-\infty}^{+\infty} de^{-x^2/2} \\
 &= \frac{-1}{\sqrt{2\pi}} [e^{-x^2/2}]_{-\infty}^{+\infty} = 0 \\
 E[X | \mu = 0, \sigma = 1] &= E[\varepsilon] = 0 \\
 E[X | \mu, \sigma] &= E[\mu + \sigma\varepsilon] = \mu \\
 \text{var} \quad V[\varepsilon] &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{+\infty} e^{-x^2/2} x^2 dx \\
 &= \frac{-1}{\sqrt{2\pi}} \int_{-\infty}^{+\infty} x de^{-x^2/2} \\
 &= \frac{-1}{\sqrt{2\pi}} [xe^{-x^2/2}]_{-\infty}^{+\infty} - \frac{-1}{\sqrt{2\pi}} \int_{-\infty}^{+\infty} e^{-x^2/2} dx \\
 &= \frac{-1}{\sqrt{2\pi}} [xe^{-x^2/2}]_{-\infty}^{+\infty} + 1 = 1 \quad \text{since } \lim_{x \rightarrow \pm\infty} \frac{x}{e^{x^2/2}} = \lim_{x \rightarrow \pm\infty} \frac{1}{xe^{x^2/2}} = 0 \\
 V[X | \mu = 0, \sigma = 1] &= V[\varepsilon] = 1 \\
 V[X | \mu, \sigma] &= V[\mu + \sigma\varepsilon] = \sigma^2 V[\varepsilon] = \sigma^2 \\
 \text{char-fct} \quad \varphi_X(z) &= E[e^{izX}] \\
 &= \frac{1}{\sqrt{2\pi\sigma^2}} \int_{-\infty}^{+\infty} e^{-(x-\mu)^2/2\sigma^2} e^{izx} dx \\
 &= \frac{1}{\sqrt{2\pi\sigma^2}} \int_{-\infty}^{+\infty} \exp\left(-\frac{x^2 - 2(\mu + i\sigma^2 z)x + \mu^2}{2\sigma^2}\right) dx \\
 &= \frac{1}{\sqrt{2\pi\sigma^2}} \int_{-\infty}^{+\infty} \exp\left(-\frac{(x - (\mu + i\sigma^2 z))^2 + \mu^2 - (\mu + i\sigma^2 z)^2}{2\sigma^2}\right) dx \\
 &= \exp\left(-\frac{\mu^2 - (\mu + i\sigma^2 z)^2}{2\sigma^2}\right) \\
 &= \exp\left(\frac{-\mu^2 + \mu^2 + 2i\mu\sigma^2 z + (i\sigma^2 z)^2}{2\sigma^2}\right) = \exp(i\mu z - (\sigma z)^2 / 2)
 \end{aligned}$$

$$\begin{array}{lll}
\text{sum} & X_1 & \sim \text{Gaussian}(\mu_1, \sigma_1) \\
& X_2 & \sim \text{Gaussian}(\mu_2, \sigma_2) \\
& Y & = X_1 + X_2
\end{array}$$

$$\begin{aligned}
\Pr(Y = y | X_1 X_2) &= \Pr(X_1 = y | \mu_1 \sigma_1) \otimes \Pr(X_2 = y | \mu_2 \sigma_2) \\
\varphi_Y(z) &= \varphi_{X_1}(z) \cdot \varphi_{X_2}(z) \\
&= \exp(i\mu_1 z - (\sigma_1 z)^2 / 2) \exp(i\mu_2 z - (\sigma_2 z)^2 / 2) \\
&= \exp(i(\mu_1 + \mu_2)z - (\sqrt{\sigma_1^2 + \sigma_2^2} z)^2 / 2) \\
X_1 + X_2 &\sim \text{Gaussian}(\mu_1 + \mu_2, \sqrt{\sigma_1^2 + \sigma_2^2})
\end{aligned}$$

$$\begin{array}{lll}
\text{min} & X_1 & \sim \text{Gauss}(\mu_1, \sigma_1) \\
& X_2 & \sim \text{Gauss}(\mu_2, \sigma_2) \\
& Y & = \min(X_1, X_2)
\end{array}$$

$$\begin{aligned}
\Pr(Y \leq y | X_1 X_2) &= 1 - \Pr(Y > y | X_1 X_2) \\
&= 1 - \Pr(X_1 > y | \mu_1 \sigma_1) \Pr(X_2 > y | \mu_2 \sigma_2) \\
&= 1 - (1 - \Pr(X_1 \leq y | \mu_1 \sigma_1))(1 - \Pr(X_2 \leq y | \mu_2 \sigma_2)) \\
&= \Pr(X_1 \leq y | \mu_1 \sigma_1) + \Pr(X_2 \leq y | \mu_2 \sigma_2) - \Pr(X_1 \leq y | \mu_1 \sigma_1) \Pr(X_2 \leq y | \mu_2 \sigma_2) \\
&= \left[\frac{1}{\sqrt{2\pi\sigma_1^2}} \int_{-\infty}^y e^{-(x-\mu_1)^2 / 2\sigma_1^2} dx \right. \\
&\quad \left. + \frac{1}{\sqrt{2\pi\sigma_2^2}} \int_{-\infty}^y e^{-(x-\mu_2)^2 / 2\sigma_2^2} dx \right. \\
&\quad \left. - \frac{1}{2\pi\sigma_1\sigma_2} \int_{-\infty}^y \int_{-\infty}^y e^{-(x_1-\mu_1)^2 / 2\sigma_1^2} e^{-(x_2-\mu_2)^2 / 2\sigma_2^2} dx_1 dx_2 \right] \\
\Pr(Y = y | X_1 X_2) &= \frac{d}{dy} \Pr(Y \leq y | X_1 X_2) \\
&= \dots
\end{aligned}$$

1.3b Bernoulli

$$\begin{array}{lll}
\text{pdf} & \Pr(X = x | p) & = \begin{cases} p & \text{if } x = 1 \\ 1 - p & \text{if } x = 0 \end{cases} \\
\text{mean} & E[X | p] & = p \times 1 + (1 - p) \times 0 = p \\
\text{var} & V[X | p] & = p \times 1^2 + (1 - p) \times 0^2 - E^2(X) = p - p^2 = pq \\
\text{char-fct} & \varphi_X(z) & = E(e^{izX}) \\
& & = pe^{iz1} + qe^{iz0} \\
& & = 1 - p + pe^{iz}
\end{array}$$

1.3c-f About event waiting

Relationship among various event and waiting distributions :

$$\begin{array}{lll}
\text{binomial} & = & \# \text{events} \\
\text{geometric} & = & \# \text{trials to first success} \\
\text{negative binomial} & = & \# \text{trials to Nth success} \\
\text{poisson} & = & \# \text{events per unit time} \\
\text{exponential} & = & \text{time to first success} \\
\text{gamma} & = & \text{time to Nth success}
\end{array}$$

Other models include :

- bivariate Poisson, which is sum of two correlated Poissons
- compound Poisson, which is sum of N Poissons

1.3c Binomial

When we perform a sequence of N independent Bernoulli trials, the total number of successful trial is a discrete random variable \aleph , with distribution described by Binomial distribution, which is valid within range $[0, N]$.

<i>pdf</i>	$\Pr(\aleph = n \mid Np)$	$=$	$C_n^N p^n q^{N-n} \quad \forall n \in [0, N]$	
<i>mean</i>	$E[\aleph \mid Np]$	$=$	$\sum_{n=0}^N C_n^N p^n q^{N-n} n$	
		$=$	$\sum_{n=1}^N C_n^N p^n q^{N-n} n$	<i>since the 1st term is zero</i>
		$=$	$\sum_{n=1}^N \frac{N!}{(N-n)!n!} p^n q^{N-n} n$	
		$=$	$Np \times \left[\sum_{n=1}^N \frac{(N-1)!}{((N-1)-(n-1))!(n-1)!} p^{n-1} q^{(N-1)-(n-1)} \right]$	
		$=$	$Np \times \left[\sum_{m=0}^{N-1} \frac{(N-1)!}{((N-1)-m)!m!} p^m q^{(N-1)-m} \right]$	<i>putting $m = n-1$</i>
		$=$	$Np \times (p+q)^{N-1}$	
		$=$	Np	
<i>var</i>	$E[\aleph(\aleph-1) \mid Np]$	$=$	$\sum_{n=0}^N C_n^N p^n q^{N-n} n(n-1)$	
		$=$	$\sum_{n=2}^N C_n^N p^n q^{N-n} n(n-1)$	<i>since the 1st and 2nd terms are zero</i>
		$=$	$\sum_{n=2}^N \frac{N!}{(N-n)!n!} p^n q^{N-n} n(n-1)$	
		$=$	$N(N-1)p^2 \times \left[\sum_{n=2}^N \frac{(N-2)!}{((N-2)-(n-2))!(n-2)!} p^{n-2} q^{(N-2)-(n-2)} \right]$	
		$=$	$N(N-1)p^2 \times \left[\sum_{m=0}^{N-2} \frac{(N-2)!}{((N-2)-m)!m!} p^m q^{(N-2)-m} \right]$	<i>putting $m = n-2$</i>
		$=$	$N(N-1)p^2 \times (p+q)^{N-2}$	
		$=$	$N(N-1)p^2$	
	$V[\aleph \mid Np]$	$=$	$E[\aleph(\aleph-1) \mid Np] + E[\aleph \mid Np] - E^2[\aleph \mid Np]$	
		$=$	$N(N-1)p^2 + Np - (Np)^2$	
		$=$	$Np - Np^2$	
		$=$	Npq	
<i>char-fct</i>	$\varphi_{\aleph}(z)$	$=$	$E[e^{iz\aleph}]$	
		$=$	$\sum_{n=0}^N C_n^N p^n q^{N-n} e^{izn}$	
		$=$	$\sum_{n=0}^N C_n^N (pe^{iz})^n q^{N-n}$	
		$=$	$(pe^{iz} + q)^N$	
<i>sum</i>	\aleph_1	\sim	$Bino(N_1, p)$	
	\aleph_2	\sim	$Bino(N_2, p)$	
	\aleph	$=$	$\aleph_1 + \aleph_2$	
	$\Pr(\aleph = n \mid \aleph_1 \aleph_2)$	$=$	$\Pr(\aleph_1 = n \mid N_1 p) \otimes \Pr(\aleph_2 = n \mid N_2 p)$	
	$\varphi_{\aleph}(z)$	$=$	$\varphi_{\aleph_1}(z) \cdot \varphi_{\aleph_2}(z)$	
		$=$	$(pe^{iz} + q)^{N_1} (pe^{iz} + q)^{N_2}$	
		$=$	$(pe^{iz} + q)^{N_1 + N_2}$	
	$\aleph_1 + \aleph_2$	\sim	$Binomial(N_1 + N_2, p)$	

1.3e Poisson

Poisson distribution is a discrete distribution, which counts the number of events occur within a time period t , assuming :

- events occur with a **known** expected event rate λ and
- events occur **independently** of the time since last event occurred.

<i>pdf</i>	$\begin{aligned} \Pr(\aleph_{bin} = n Np) &= C_n^N p^n q^{N-n} && \text{where } \aleph_{bin} \text{ is binomial distributed random variable} \\ \Pr(\aleph = n \lambda t) &= \lim_{N \rightarrow \infty} \Pr(\aleph_{bin} = n Np) && \text{where } \aleph \text{ is Poisson distributed random variable, so that } Np = \lambda t \\ &= \lim_{N \rightarrow \infty} C_n^N p^n q^{N-n} \\ &= \lim_{N \rightarrow \infty} \frac{N!}{(N-n)!n!} \left(\frac{\lambda t}{N}\right)^n \left(1 - \frac{\lambda t}{N}\right)^{N-n} \\ &= \lim_{N \rightarrow \infty} \frac{N(N-1)(N-2)\dots(N-n+1)}{n!} \left(\frac{\lambda t}{N}\right)^n \left(1 - \frac{\lambda t}{N}\right)^{-n} \left(1 - \frac{\lambda t}{N}\right)^N && \text{we will apply } \lim_{N \rightarrow \infty} \left(1 - \frac{\lambda t}{N}\right)^N = e^{-\lambda t} \\ &= \lim_{N \rightarrow \infty} \frac{N(N-1)(N-2)\dots(N-n+1)}{n!} \left(\frac{\lambda t}{N}\right)^n \left(1 - \frac{\lambda t}{N}\right)^N \\ &= \lim_{N \rightarrow \infty} \frac{(\lambda t)^n}{n!} \left(1 - \frac{\lambda t}{N}\right)^N \frac{N}{N-\lambda t} \frac{N-1}{N-\lambda t} \frac{N-2}{N-\lambda t} \dots \frac{N-n+1}{N-\lambda t} \\ &= \frac{(\lambda t)^n e^{-\lambda t}}{n!} && \text{since } \lim_{N \rightarrow \infty} \frac{N-i}{N-\lambda t} = 1 \text{ for all } i \end{aligned}$
<i>mean</i>	$\begin{aligned} E[\aleph \lambda t] &= \sum_{n=0}^{\infty} \frac{(\lambda t)^n e^{-\lambda t}}{n!} n \\ &= \sum_{n=1}^{\infty} \frac{(\lambda t)^n e^{-\lambda t}}{n!} n && \text{since } \frac{(\lambda t)^0 e^{-\lambda t}}{0!} \times 0 = 0 \\ &= \lambda t \sum_{n=1}^{\infty} \frac{(\lambda t)^{n-1} e^{-\lambda t}}{(n-1)!} \\ &= \lambda t \sum_{m=0}^{\infty} \frac{(\lambda t)^m e^{-\lambda t}}{m!} \\ &= \lambda t && \text{since } \sum_{m=0}^{\infty} \frac{(\lambda t)^m e^{-\lambda t}}{m!} = 1 \end{aligned}$
<i>var</i>	$\begin{aligned} E[\aleph^2 \lambda t] &= \sum_{n=0}^{\infty} \frac{(\lambda t)^n e^{-\lambda t}}{n!} n^2 \\ &= \sum_{n=1}^{\infty} \frac{(\lambda t)^n e^{-\lambda t}}{n!} n^2 && \text{since } \frac{(\lambda t)^0 e^{-\lambda t}}{0!} \times 0^2 = 0 \\ &= \lambda t \sum_{n=1}^{\infty} \frac{(\lambda t)^{n-1} e^{-\lambda t}}{(n-1)!} n \\ &= \lambda t \sum_{m=0}^{\infty} \frac{(\lambda t)^m e^{-\lambda t}}{m!} (m+1) \\ &= \lambda t \times (E[\aleph \lambda t] + E[1 \lambda t]) \\ &= \lambda t \times (\lambda t + 1) && \text{since } \sum_{m=0}^{\infty} \frac{(\lambda t)^m e^{-\lambda t}}{m!} = 1 \end{aligned}$
	$\begin{aligned} V[\aleph \lambda t] &= E[\aleph^2 \lambda t] - E^2[\aleph \lambda t] \\ &= \lambda t \times (\lambda t + 1) - (\lambda t)^2 \\ &= \lambda t \end{aligned}$
<i>char-fct</i>	$\begin{aligned} \varphi_{\aleph}(z) &= E[e^{iz\aleph}] \\ &= \sum_{n=0}^{\infty} \frac{(\lambda t)^n e^{-\lambda t} e^{izn}}{n!} \\ &= \left(\sum_{n=0}^{\infty} \frac{(\lambda t \exp(iz))^n}{n!} \right) \times e^{-\lambda t} \\ &= e^{\lambda t \exp(iz)} \times e^{-\lambda t} && \text{since } e^x = \sum_{n=0}^{\infty} x^n / n! \\ &= e^{\lambda t(\exp(iz)-1)} \end{aligned}$

$$\begin{aligned}
\text{sum} \quad \mathbb{N}_k &\sim \text{Poisson}(\lambda_k, t) \\
\mathbb{N} &= \sum_{k=1}^K \mathbb{N}_k \\
\Pr(\mathbb{N} = n \mid \mathbb{N}_1 \dots \mathbb{N}_K) &= \Pr(\mathbb{N}_1 = n \mid \lambda_1 t) \otimes \Pr(\mathbb{N}_2 = n \mid \lambda_2 t) \otimes \dots \otimes \Pr(\mathbb{N}_K = n \mid \lambda_K t) \\
\varphi_{\mathbb{N}}(z) &= \varphi_{\mathbb{N}_1}(z) \cdot \varphi_{\mathbb{N}_2}(z) \cdot \dots \cdot \varphi_{\mathbb{N}_K}(z) \\
&= e^{\lambda_1 t (\exp(iz) - 1)} e^{\lambda_2 t (\exp(iz) - 1)} \dots e^{\lambda_K t (\exp(iz) - 1)} \\
&= e^{(\lambda_1 + \lambda_2 + \dots + \lambda_K) t (\exp(iz) - 1)} \\
\mathbb{N} &\sim \text{Poisson}(\sum_{k=1}^K \lambda_k, t)
\end{aligned}$$

2 representations

Since time period t is fixed, some people like to replace λt by λ' , resulting in simpler form

$$\begin{aligned}
\Pr(\mathbb{N} = n \mid \lambda' = \lambda t) &= \frac{\lambda'^n e^{-\lambda'}}{n!} \\
E[\mathbb{N} \mid \lambda' = \lambda t] &= \lambda' \\
V[\mathbb{N} \mid \lambda' = \lambda t] &= \lambda' \\
\varphi_{\mathbb{N}}(z) &= e^{\lambda' (\exp(iz) - 1)}
\end{aligned}$$

shooting star question

Suppose the probability of seeing one or more shooting stars in an hour is 0.44, what is that probability in half an hour?

$$\begin{aligned}
\Pr(\mathbb{N} = 0 \mid \lambda t = c) &= \left. \frac{(\lambda t)^n e^{-\lambda t}}{n!} \right|_{n=0, \lambda t=c} = 1 - 0.44 \\
&= e^{-c} = 0.56 \\
\Pr(\mathbb{N} = 0 \mid \lambda t = c/2) &= \frac{e^{-c/2}}{e^{-c/2}} = \sqrt{0.56} \\
\Pr(\mathbb{N} > 0 \mid \lambda t = c/2) &= 1 - \sqrt{0.56}
\end{aligned}$$

1.3f Exponential

Exponential distribution models the time to the first event of a sequence of Bernoulli trials.

$$\begin{aligned}
\text{pdf} \quad \Pr(T > t \mid \lambda) &= \left. \frac{(\lambda t)^n e^{-\lambda t}}{n!} \right|_{n=0} = e^{-\lambda t} \\
\Pr(T = t \mid \lambda) &= \partial_t \Pr(T < t \mid \lambda) \\
&= \partial_t (1 - \Pr(T > t \mid \lambda)) \\
&= \partial_t (1 - e^{-\lambda t}) \\
&= \lambda e^{-\lambda t}
\end{aligned}$$

$$\begin{aligned}
\text{mean} \quad E[T \mid \lambda] &= \int_0^\infty \lambda e^{-\lambda t} t dt \\
&= - \int_0^\infty t d e^{-\lambda t} \\
&= -[t e^{-\lambda t}]_0^\infty + \int_0^\infty e^{-\lambda t} dt \\
&= -[t e^{-\lambda t}]_0^\infty - [e^{-\lambda t}]_0^\infty / \lambda \\
&= 1 / \lambda
\end{aligned}$$

see remark in LHospital Rule

$$\begin{aligned}
\text{var} \quad E[T^2 \mid \lambda] &= \int_0^\infty \lambda e^{-\lambda t} t^2 dt \\
&= - \int_0^\infty t^2 d e^{-\lambda t} \\
&= -[t^2 e^{-\lambda t}]_0^\infty + 2 \int_0^\infty t e^{-\lambda t} dt \\
&= 2 / \lambda^2 \\
V[T \mid \lambda] &= E(T^2) - E(T)^2 \\
&= 2 / \lambda^2 - 1 / \lambda^2 = 1 / \lambda^2
\end{aligned}$$

see remark in LHospital Rule

L'Hospital Rule

Remark 1	$[e^{-\lambda t}]_0^\infty$	=	$1/e^{\lambda\infty} - 1/e^{\lambda 0}$	=	$0 - 1$	=	-1	\Rightarrow	$[e^{-\lambda t}]_0^\infty = -1$
Remark 2	$\lim_{t \rightarrow \infty} t e^{-\lambda t}$	=	$\lim_{t \rightarrow \infty} t / e^{\lambda t}$	=	$\lim_{t \rightarrow \infty} 1/(\lambda e^{\lambda t})$	=	0		
	$\lim_{t \rightarrow 0} t e^{-\lambda t}$	=	$0/e^{\lambda 0}$	=	$0/1$	=	0	\Rightarrow	$[t e^{-\lambda t}]_0^\infty = 0$
Remark 3	$\lim_{t \rightarrow \infty} t^2 e^{-\lambda t}$	=	$\lim_{t \rightarrow \infty} t^2 / e^{\lambda t}$	=	$\lim_{t \rightarrow \infty} 2t/(\lambda e^{\lambda t})$	=	$\lim_{t \rightarrow \infty} 2/(\lambda^2 e^{\lambda t})$	=	0
	$\lim_{t \rightarrow 0} t^2 e^{-\lambda t}$	=	$0^2 / e^{\lambda 0}$	=	$0/1$	=	0	\Rightarrow	$[t^2 e^{-\lambda t}]_0^\infty = 0$
Remark 4	$E_\lambda(t)$	=	$1/\lambda$						
	$\int_0^\infty \lambda e^{-\lambda t} dt$	=	$1/\lambda$						

char-fct $\varphi_T(z)$

$$\begin{aligned}
 &= E[e^{izT}] \\
 &= \int_0^\infty \lambda e^{-\lambda t} e^{izt} dt \\
 &= \int_0^\infty \lambda e^{(-\lambda + iz)t} dt \\
 &= \frac{\lambda}{-\lambda + iz} [e^{(-\lambda + iz)t}]_0^\infty \\
 &= \frac{\lambda}{-\lambda + iz} [e^{izt} / e^{\lambda t}]_0^\infty \\
 &= \frac{1}{1 - iz/\lambda}
 \end{aligned}$$

why? see below

complex number $\cos(zt) + i \sin(zt)$ lies on the unit circle of Argand diagram for all values of t :

$$\begin{aligned}
 \lim_{t \rightarrow \infty} e^{izt} / e^{\lambda t} &= \lim_{t \rightarrow \infty} \cos(zt) / e^{\lambda t} + i \lim_{t \rightarrow \infty} \sin(zt) / e^{\lambda t} = 0 \\
 \lim_{t \rightarrow 0} e^{izt} / e^{\lambda t} &= e^0 / e^0 = 1 \\
 [e^{izt} / e^{\lambda t}]_0^\infty &= 0 - 1 = -1
 \end{aligned}$$

sum

$$\begin{aligned}
 T_k &\sim \text{Exponential}(\lambda_k) \\
 T &= \sum_{k=1}^K T_k \\
 \Pr(T = t | T_1 \dots T_K) &= \Pr(T_1 = t | \lambda_1) \otimes \Pr(T_2 = t | \lambda_2) \otimes \dots \otimes \Pr(T_K = t | \lambda_K) \\
 \varphi_T(z) &= \varphi_{T_1}(z) \cdot \varphi_{T_2}(z) \cdot \dots \cdot \varphi_{T_K}(z) \\
 &= \frac{1}{1 - iz/\lambda_1} \frac{1}{1 - iz/\lambda_2} \dots \frac{1}{1 - iz/\lambda_K} \\
 T &\sim \text{Gamma}(K, \lambda) \quad \text{if } \lambda_1 = \lambda_2 = \dots = \lambda_K
 \end{aligned}$$

min and max

$$\begin{aligned}
 T_k &\sim \text{Exponential}(\lambda_k) \quad \forall k \in [1, K] \\
 T_{\min} &= \min_{k \in [1, K]} T_k \\
 T_{\max} &= \max_{k \in [1, K]} T_k
 \end{aligned}$$

$\Pr(T_{\min} > t)$	=	$\Pr(T_1 > t, T_2 > t, \dots, T_K > t)$	$\Pr(T_{\max} \leq t)$	=	$\Pr(T_1 \leq t, T_2 \leq t, \dots, T_K \leq t)$
	=	$\Pr(T_1 > t) \Pr(T_2 > t) \dots \Pr(T_K > t)$		=	$\Pr(T_1 \leq t) \Pr(T_2 \leq t) \dots \Pr(T_K \leq t)$
	=	$\prod_{k=1}^K e^{-\lambda_k t}$		=	$\prod_{k=1}^K (1 - e^{-\lambda_k t})$
	=	$e^{-(\sum_{k=1}^K \lambda_k) t}$		=	...
	=	$e^{-\lambda t}$ where $\lambda = \sum_{k=1, K} \lambda_k$			
$\Pr(T_{\min} = t)$	=	$\partial_t \Pr(T_{\min} < t)$	$\Pr(T_{\max} = t)$	=	$\partial_t \Pr(T_{\max} \leq t)$
	=	$\partial_t (1 - e^{-\lambda t})$		=	$\partial_t \prod_{k=1}^K (1 - e^{-\lambda_k t})$
	=	$\lambda e^{-\lambda t}$		=	...

$$\begin{aligned}
\text{memoryless} \quad \Pr(T > t + s \mid T > s) &= \frac{\Pr(T > t + s)}{\Pr(T > s)} \\
&= \frac{e^{-\lambda(t+s)}}{e^{-\lambda s}} \\
&= e^{-\lambda t} \\
&= \Pr(T > t) \\
\Pr(T = t + s \mid T > s) &= \Pr(T = t)
\end{aligned}$$

Comparison between two exponentials

$$\begin{aligned}
\Pr(T_1 < T_2) &= \int_{t=0}^{t=\infty} d \Pr(T_1 < t, T_2 = t) \\
&= \int_{t=0}^{t=\infty} \Pr(T_1 < t) d \Pr(T_2 = t) \\
&= \int_{t=0}^{t=\infty} \Pr(T_1 < t) \Pr(T_2 = t) dt \\
&= \int_{t=0}^{t=\infty} (1 - e^{-\lambda_1 t}) (\lambda_2 e^{-\lambda_2 t}) dt \\
&= \int_{t=0}^{t=\infty} (\lambda_2 e^{-\lambda_2 t} - \lambda_2 e^{-(\lambda_1 + \lambda_2)t}) dt \\
&= [-e^{-\lambda_2 t}]_0^\infty - [-\lambda_2 / (\lambda_1 + \lambda_2) \times e^{-(\lambda_1 + \lambda_2)t}]_0^\infty \\
&= 1 - \lambda_2 / (\lambda_1 + \lambda_2) \\
&= \lambda_1 / (\lambda_1 + \lambda_2)
\end{aligned}$$

Types of matrix

- symmetric
- triangular
- diagonal
- linear independent
- orthogonal
- orthonormal

	decomposition	shape of A	shape of output
rank	$A = WR$	A is rectangular	R is row linear independent
	$A = CW$		C is column linear independent
LU	$A = LU$	A is square	L/U are lower/upper triangular
	$PA = LU$		P/Q are permutation
	$PAQ = LU$		
	$A = LDU$		D is diagonal
Cholesky	$A = LL^T$	A is symmetric	L/U are lower/upper triangular
	$A = U^T U$		
LQ/QR	$A = LQ$	A is rectangular	L/U are lower/upper triangular
	$A = QR$		Q is orthonormal
SVD	$A = USV^T$	A is rectangular	U, V are orthonormal, S is diagonal
eigen	$A = Q\Lambda Q^T$	A is symmetric	Q is orthonormal, Λ is diagonal

2.1 Rank decomposition 2=[44]

2.1a Meaning of matrix multiplication

Given the following matrices :

- row vector matrix A with size $N \times M$ where N and M are the number and dimension of A
- transformation matrix (or projection matrix) Q with size $M' \times M$, which performs $\mathbb{R}^M \rightarrow \mathbb{R}^{M'}$
- linear combination matrix (or weight matrix) W with size $N' \times N$, which generates N' vectors from N vectors

then we have 4 interpretations :

1. $N \times N$ dot product of row-vector set A = AA^T
2. $M \times M$ covariance of row-vector set A = $A^T A$
3. $N' \times M'$ weighted sum of transformed A = WAQ^T Q is transformation matrix in this case
4. $N \times M$ normalized projection of A on Q = $AQ^T(QQ^T)^{-1}Q$ Q is projection matrix in this case

$$\begin{aligned}
 AQ^T &= \text{dot product} \\
 &= \text{length of projection} \times \text{magnitude of } Q \\
 AQ^T(QQ^T)^{-1} &= \text{length of projection} \\
 AQ^T(QQ^T)^{-1}Q &= \text{projection vector of A on Q}
 \end{aligned}$$

2.1b Span and nullity

1. $\text{span}(A) = \{x\}$ s.t. $\exists w, x = wA$ i.e. linear dependence
 $\text{null}(A) = \{x\}$ s.t. $Ax = 0$ i.e. zero projection
2. $A = WR$ where W is $N \times K$ and R is $K \times M$ i.e. A is decomposed into K linear independent row vectors R
 $A = CW$ where C is $N \times K'$ and W is $K' \times M$ i.e. A is decomposed into K' linear independent column vectors C
3. K is called row rank.
 K' is called column rank.
In general, we have : $\text{rank}(\text{span}(A)) = K = K'$
4. In general, we have : $\text{rank}(\text{span}(A)) + \text{rank}(\text{null}(A)) = M$

2.2 LU decomposition

LU decomposition is a sequence of elementary operations, including :

- swapping row vector A_{n1} with A_{n2}
- scaling row vector $A_n = scale \times A_n$
- linear operation on row vector $A_{n1} = A_{n1} + scale \times A_{n2}$

$$\begin{aligned}
 A &= LU & \text{where } L' \text{ is lower triangular with all one diagonal} \\
 PA &= LU & \text{partial pivoting} \\
 PAQ &= LU & \text{full pivoting} \\
 A &= L'DU' & \text{where } L'U' \text{ are lower/upper triangular with all one diagonal}
 \end{aligned}$$

2.3 Cholesky decomposition

Cholesky makes use of symmetric property for decomposition.

$$\begin{aligned}
 A &= LL^T \\
 &= \begin{bmatrix} l_{1,1} & 0 & 0 & \dots & 0 \\ l_{2,1} & l_{2,2} & 0 & \dots & 0 \\ l_{3,1} & l_{3,2} & l_{3,3} & \dots & 0 \\ \dots & \dots & \dots & \dots & \dots \\ l_{N,1} & l_{N,2} & l_{N,3} & \dots & l_{N,N} \end{bmatrix} \begin{bmatrix} l_{1,1} & l_{2,1} & l_{3,1} & \dots & l_{N,1} \\ 0 & l_{2,2} & l_{3,2} & \dots & l_{N,2} \\ 0 & 0 & l_{3,3} & \dots & l_{N,3} \\ \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & \dots & l_{N,N} \end{bmatrix}
 \end{aligned}$$

Here is the bootstrapping sequence :

$$\begin{aligned}
 l_{11} &= \sqrt{a_{11}} \\
 l_{21} &= a_{21}/l_{11} & l_{22} &= \sqrt{a_{22} - l_{21}^2} \\
 l_{31} &= a_{31}/l_{11} & l_{32} &= (a_{32} - l_{31}l_{21})/l_{22} & l_{33} &= \sqrt{a_{33} - l_{31}^2 - l_{32}^2} \\
 l_{41} &= a_{41}/l_{11} & l_{42} &= (a_{42} - l_{41}l_{21})/l_{22} & l_{43} &= (a_{43} - l_{41}l_{31} - l_{42}l_{32})/l_{33} & l_{44} &= \sqrt{a_{44} - l_{41}^2 - l_{42}^2 - l_{43}^2}
 \end{aligned}$$

2.4 LQ/QR decomposition

For every iteration, find the remainder that cannot explain by existing orthonormal basis.

$$\begin{aligned}
 A &= LQ \\
 \begin{bmatrix} A_1 \\ A_2 \\ A_3 \\ \dots \\ A_N \end{bmatrix} &= \begin{bmatrix} l_{1,1} & 0 & 0 & \dots & 0 \\ l_{2,1} & l_{2,2} & 0 & \dots & 0 \\ l_{3,1} & l_{3,2} & l_{3,3} & \dots & 0 \\ \dots & \dots & \dots & \dots & \dots \\ l_{N,1} & l_{N,2} & l_{N,3} & \dots & l_{N,N} \end{bmatrix} \begin{bmatrix} Q_1 \\ Q_2 \\ Q_3 \\ \dots \\ Q_N \end{bmatrix}
 \end{aligned}$$

where A_n and Q_n are row vectors

$$\begin{aligned}
 Q_1 &= \frac{A_1}{\|A_1\|} & l_{11} &= \|A_1\| \\
 Q_2 &= \frac{A_2 - A_2 Q_1^T Q_1}{\|A_2 - A_2 Q_1^T Q_1\|} & l_{21} &= A_2 Q_1^T & l_{22} &= \|A_2 - A_2 Q_1^T Q_1\| \\
 Q_3 &= \frac{A_3 - A_3 Q_1^T Q_1 - A_3 Q_2^T Q_2}{\|A_3 - A_3 Q_1^T Q_1 - A_3 Q_2^T Q_2\|} & l_{31} &= A_3 Q_1^T & l_{32} &= A_3 Q_2^T & l_{33} &= \|A_3 - A_3 Q_1^T Q_1 - A_3 Q_2^T Q_2\|
 \end{aligned}$$

2.5 SVD decomposition

$$1. \quad A = USV^T \quad \text{where } A \text{ is } N \times M, S \text{ is } N \times M, U \text{ is } N \times N, V \text{ is } M \times M$$

2. SVD by eigen decomposition

$$\begin{aligned}
 AA^T &= (USV^T)(USV^T)^T = US^2U^T & \text{eigen}(AA^T) \text{ gives } U \text{ and } S^2 \\
 A^T A &= (USV^T)^T (USV^T) = VS^2V^T & \text{eigen}(A^T A) \text{ gives } V \text{ and } S^2
 \end{aligned}$$

2.6 Eigen decomposition

2.6a Three forms of eigen decomposition

Eigen vectors Q are vectors, on applying transformation A gives scaled eigen vectors.

$$\begin{aligned} 1. \quad A &= Q \Lambda Q^T && \text{where } Q \text{ are row vectors (representation consistent with SVD)} \\ \rightarrow A^T &= Q^T \Lambda Q \\ 2. \quad Q A^T &= \Lambda Q && \text{where } Q \text{ are row vectors (representation consistent with 2.1a3)} \\ &&& \text{where } A \text{ are row vectors of projection matrix (or transformation)} \end{aligned}$$

Now, by putting $A^T \rightarrow A$, we have the common representation found in most textbooks :

$$\begin{aligned} 3. \quad Q_n A &= \lambda Q_n && \text{where } Q_n \text{ is a row vector} \\ A Q_n &= \lambda Q_n && \text{where } Q_n \text{ is a column vector} \end{aligned}$$

2.6b Span of eigen vectors

Span of eigen vectors sharing the same eigen value is also an eigen vector of the same eigen value.

$$\begin{aligned} Q_n A &= \lambda Q_n \\ Q_m A &= \lambda Q_m \\ \rightarrow (w_n Q_n + w_m Q_m) A &= w_n Q_n A + w_m Q_m A \\ &= w_n \lambda Q_n + w_m \lambda Q_m \\ &= \lambda (w_n Q_n + w_m Q_m) \end{aligned}$$

2.6c When A is special matrix

- When A is identity, any vectors are eigen vectors with eigen value 1.
- When A is diagonal, any unit vectors δ_n are eigen vectors with eigen value A_{nn} , where δ_n is all zero, but 1 for n^{th} element.
- When A is triangular, eigen values are roots of N degree polynomial :

$$\begin{aligned} Q_n A &= \lambda Q_n && \text{where } Q_n \text{ is a row vector} \\ \rightarrow Q_n A &= Q_n (\lambda I) \\ \rightarrow 0 &= Q_n (A - \lambda I) \\ \rightarrow 0 &= \det(A - \lambda I) && \text{determinant of triangular matrix equals to product of diagonal} \\ \rightarrow 0 &= \prod_{n=1}^N (A_{nn} - \lambda) \end{aligned}$$

2.6d When A is symmetric

When A is symmetric, eigen vectors are orthogonal.

$$\begin{aligned} Q_n A &= \lambda_n Q_n && \rightarrow Q_n = \lambda_n Q_n A^{-1} \\ Q_m A &= \lambda_m Q_m && \rightarrow Q_m = \frac{1}{\lambda_m} Q_m A \\ Q_n Q_m^T &= \lambda_n Q_n A^{-1} \left(\frac{1}{\lambda_m} Q_m A \right)^T \\ &= \frac{\lambda_n}{\lambda_m} Q_n A^{-1} A^T Q_m^T \\ &= \frac{\lambda_n}{\lambda_m} Q_n A^{-1} A Q_m^T && \text{suppose } A \text{ is symmetric} \\ &= \frac{\lambda_n}{\lambda_m} Q_n Q_m^T \\ 0 &= \left(1 - \frac{\lambda_n}{\lambda_m} \right) Q_n Q_m^T \\ Q_n Q_m^T &= 0 && \text{since } 1 - \frac{\lambda_n}{\lambda_m} \neq 0 \end{aligned}$$

2.6e When A is semipositive definite

When A is semipositive definite, then all eigen values are positive.

$$\begin{aligned}
 X^T A X &\geq 0 & \forall X \\
 X^T (Q \Lambda Q^T) X &\geq 0 & \forall X \\
 (X^T Q) \Lambda (X^T Q)^T &\geq 0 & \forall X \\
 Y \Lambda Y^T &\geq 0 & \text{where } Y = X^T Q \\
 \prod_{n=1}^N \Lambda_{nn} y_n^2 &\geq 0 & \forall Y \\
 \Lambda_{nn} &\geq 0 & \forall n
 \end{aligned}$$

2.6f Square root matrix and power matrix

$$\begin{aligned}
 \bullet \quad A &= Q \Lambda Q^T \\
 A^{1/2} A^{1/2} &= Q \Lambda^{1/2} \Lambda^{1/2} Q^T = (Q \Lambda^{1/2} Q^T)(Q \Lambda^{1/2} Q^T) \\
 A^{1/2} &= Q \Lambda^{1/2} Q^T \\
 \bullet \quad A &= Q \Lambda Q^T \\
 A^2 &= (Q \Lambda Q^T)(Q \Lambda Q^T) = Q \Lambda^2 Q^T \\
 A^3 &= (Q \Lambda Q^T)(Q \Lambda Q^T)(Q \Lambda Q^T) = Q \Lambda^3 Q^T
 \end{aligned}$$

2.6g Similar matrix

Similar matrices share the same eigen values.

$$\begin{aligned}
 B &= X A X^T && \text{definition of similarity} \\
 &= X (Q \Lambda Q^T) X^T \\
 &= (X Q) \Lambda (X Q)^T && \text{hence } B \text{ has the same eigen values as } A
 \end{aligned}$$

2.6h Implementation 1 : characteristic equation

This method solves for all eigen values.

$$\begin{aligned}
 Q_n A &= \lambda Q_n \\
 Q_n (A - \lambda I) &= 0 \\
 \det(A - \lambda I) &= 0 && \rightarrow \text{solve polynomial for all } \lambda\text{s}
 \end{aligned}$$

2.6i Implementation 2 : power method

This method solves for max eigen value only. Given initial guess row vector $V^{(1)}$, we repeatedly apply transformation A on it :

$$\begin{aligned}
 V^{(2)} &= V^{(1)} A \\
 V^{(3)} &= V^{(2)} A = V^{(1)} A A \\
 V^{(4)} &= V^{(3)} A = V^{(1)} A A A \\
 V^{(T+1)} &= V^{(T)} A = V^{(1)} \underbrace{A A \dots A}_T && \text{now suppose } V^{(1)} = W Q \\
 &= W Q \underbrace{A A \dots A}_T \\
 &= W \underbrace{Q A A \dots A}_{T-1} = \dots = W \Lambda^T Q = \sum_{n=1}^N w_n \Lambda_{nn}^T Q_n \\
 \frac{[V^{(T+1)}]_m}{[V^{(T)}]_m} &= \frac{[\sum_{n=1}^N w_n \Lambda_{nn}^T Q_n]_m}{[\sum_{n=1}^N w_n \Lambda_{nn}^{T-1} Q_n]_m} && \text{now suppose } \Lambda_{11}^T > \Lambda_{22}^T > \Lambda_{33}^T \\
 \lim_{T \rightarrow \infty} \frac{[V^{(T+1)}]_m}{[V^{(T)}]_m} &= \lim_{T \rightarrow \infty} \frac{[\sum_{n=1}^N w_n \Lambda_{nn}^T Q_n]_m}{[\sum_{n=1}^N w_n \Lambda_{nn}^{T-1} Q_n]_m} = \lim_{T \rightarrow \infty} \frac{[w_1 \Lambda_{11}^T Q_1]_m}{[w_1 \Lambda_{11}^{T-1} Q_1]_m} = \Lambda_{11}
 \end{aligned}$$

2.6j Implementation 3 : QR algorithm

This method solves for all eigen vectors. By repeated construction and decomposition :

<i>construction</i>		<i>decomposition</i>
$A^{(1)} = A$	\rightarrow	$A^{(1)} = Q^{(1)}R^{(1)}$
$A^{(2)} = R^{(1)}Q^{(1)}$	\rightarrow	$A^{(2)} = Q^{(2)}R^{(2)}$
$A^{(3)} = R^{(2)}Q^{(2)}$	\rightarrow	$A^{(3)} = Q^{(3)}R^{(3)}$
$A^{(T+1)} = R^{(T)}Q^{(T)}$		
$= Q^{(T)T}Q^{(T)}R^{(T)}Q^{(T)}$		Don't confuse iteration T with transpose.
$= Q^{(T)T}A^{(T)}Q^{(T)}$		
$= Q^{(T)T}Q^{(T-1)T}A^{(T-1)}Q^{(T-1)}Q^{(T)}$		Repeat the process on $A^{(T)}$
$= \dots$		
$= (Q^{(1)}Q^{(2)}\dots Q^{(T)})^T A(Q^{(1)}Q^{(2)}\dots Q^{(T)})$		
$= Q^T A Q$		where $Q = Q^{(1)}Q^{(2)}\dots Q^{(T)}$

As T tends to infinity, it is proved that (not shown here) :

$$\lim_{T \rightarrow \infty} A^{(T)} = U$$

2.7 Applications

2.7a Solving $AX=B$

Given $AX = B$, we can solve by :

- *matrix inverse* $A^T AX = A^T B$ $X = (A^T A)^{-1} (A^T B)$
- *LU decomposition* $A^T AX = A^T B$ $LUX = A^T B$ $X = U^{-1} L^{-1} A^T B$
- *Cholesky decomposition* $A^T AX = A^T B$ $LL^T X = A^T B$ $X = (L^T)^{-1} L^{-1} A^T B$
- *LQ decomposition* $AX = B$ $QRX = B$ $X = R^{-1} Q^T B$
- *SVD decomposition* $AX = B$ $USV^T X = B$ $X = VS^{-1} U^T B$
- *eigen decomposition* $A^T AX = A^T B$ $Q\Lambda Q^T X = B$ $X = Q\Lambda^{-1} Q^T B$

$$\begin{bmatrix} l_{1,1} & 0 & 0 & \dots & 0 \\ l_{2,1} & l_{2,2} & 0 & \dots & 0 \\ l_{3,1} & l_{3,2} & l_{3,3} & \dots & 0 \\ \dots & \dots & \dots & \dots & \dots \\ l_{M,1} & l_{M,2} & l_{M,3} & \dots & l_{M,M} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \dots \\ x_M \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ \dots \\ b_M \end{bmatrix}$$

$$\begin{bmatrix} x_1 = b_1 / l_{11} \\ x_2 = (b_2 - l_{21}x_1) / l_{22} \\ x_3 = (b_3 - l_{31}x_1 - l_{32}x_2) / l_{33} \\ \dots \\ x_M = (b_M - l_{M1}x_1 - l_{M2}x_2 - \dots) / l_{MM} \end{bmatrix}$$

- *inverse of L and U is bootstrapping*
- *inverse of S and Λ is simply element inverse*
- *inverse of Q is simply transpose*

2.7b Determinant

Given square matrix A , its determinant can be found :

- *Cramer rule*
- *LU decomposition* $\det(A) = \det(LU) = \det(L) \det(U) = \prod_{n=1}^N l_{n,n} \prod_{n=1}^N u_{n,n}$
- *Cholesky decomposition* $\det(A) = \det(LL^T) = \det(L) \det(L^T) = (\prod_{n=1}^N l_{n,n})^2$
- *LQ decomposition* $\det(A) = \det(QR) = \det(Q) \det(R) = \prod_{n=1}^N r_{n,n}$
- *SVD decomposition* $\det(A) = \det(USV^T) = \det(U) \det(S) \det(V^T) = \prod_{n=1}^N s_{n,n}$
- *eigen decomposition* $\det(A) = \det(Q\Lambda Q^T) = \det(Q) \det(\Lambda) \det(Q^T) = \prod_{n=1}^N \lambda_n$

2.7c PCA

Find the projection Q such that covariance of AQ is maximized and diagonalized. Here we try to hackle the first objective.

$$\begin{aligned} L &= (AQ)^T AQ - \lambda(Q^T Q - I) && \text{maximize covariance (after projection) such that } Q^T Q = I \\ &= Q^T (A^T A) Q - \lambda(Q^T Q - I) \\ \frac{\partial L}{\partial Q} &= 0 \\ (A^T A)Q &= \lambda Q \\ Q_{opt} &= \text{eigenvector}(A^T A) \end{aligned}$$

Comparison

Three different approaches for 2D linear regression :

- 2.7c PCA as covariance maximization $Q_{opt} = \text{eigenvector}(A^T A)$
- 3.2h non-vertical 2D linear regression $\text{slope} = \frac{\text{cov}(x, y)}{\text{var}(x)}$
- 3.3d PCA as constrained regression $X_{opt} = \text{eigenvector}((A - \bar{A})^T W (A - \bar{A}))$

3.1 From likelihood to least square

Let's start with maximum likelihood. Given a set of data points (observations), likelihood is defined as joint probability conditional on a hypothetic parameter set θ .

- $L(\theta) = \Pr(D = d_1, d_2, \dots, d_N | \theta)$ *joint probability*
- $L(\theta) = \prod_{n=1}^N \Pr(D_n = d_n | \theta)$ *product of probability*
- $\ln L(\theta) = \sum_{n=1}^N \ln \Pr(D_n = d_n | \theta)$ *sum of log probability*

We apply linear regression model $AX=B$ and Gaussian noise model :

- $\arg \max_{\theta} \ln L = \arg \max_X \ln \left[\frac{1}{\sqrt{(2\pi)^{\text{rank}(\Sigma)} \det(\Sigma)}} \exp\left(-\frac{1}{2}(AX - B)^T \Sigma^{-1}(AX - B)\right) \right]$
- $= \arg \max_X \left(-\frac{1}{2}(AX - B)^T \Sigma^{-1}(AX - B)\right)$ *removing constants, Σ is given*
- $= \arg \min_X (AX - B)^T \Sigma^{-1}(AX - B)$ *max problem becomes min problem*

We finally convert maximum likelihood to minimum error, i.e. various least square regressions :

- OLS *ordinary least square for uncorrelated-homoskedasticity* *when $\Sigma = I$, $\Sigma^{-1} = I$, $\det(\Sigma) = 1$*
- WLS *weighted least square for uncorrelated-heteroskedasticity* *when $\Sigma = [\sigma_n^2]$, $\Sigma^{-1} = [\sigma_n^{-2}]$, $\det(\Sigma) = \prod_{n=1}^N \sigma_n^2$*
- GLS *generalized least square for correlated Gaussian*

3.2 Various least square regressions

We will discuss 7 regressions and 2 interpretations :

- OLS $L = (AX - B)^T (AX - B)$
- WLS $L = (AX - B)^T W (AX - B)$
- GLS $L = (AX - B)^T \Sigma^{-1} (AX - B)$
- Tikhonov regularization $L = (AX - B)^T \Sigma^{-1} (AX - B) + (X - X_0)^T \Sigma_Q^{-1} (X - X_0)$ *given anchor X_0*
- nonlinear - Gauss Newton $L = (F(A | X) - B)^T \Sigma^{-1} (F(A | X) - B)$ *given initial guess X_0*
- nonlinear - Levenberg Marq $L = (F(A | X) - B)^T \Sigma^{-1} (F(A | X) - B) + \lambda(\Delta X)^T (\Delta X)$ *given initial guess X_0*
- nonlinear noise model - iterWLS $L = \sum_{n=1}^N g(A_n X - b_n)$
- interpretation in 2D *slope = cov(x, y) / var(x)*
- interpretation in regressor space $AX = \text{proj}_A(B)$

$$\text{where } F(A | X) = \begin{bmatrix} f(A_1 | X) \\ f(A_2 | X) \\ f(A_3 | X) \\ \dots \\ f(A_N | X) \end{bmatrix} \quad J_F = \begin{bmatrix} \partial f(A_1 | X) / \partial x_1 & \partial f(A_1 | X) / \partial x_2 & \partial f(A_1 | X) / \partial x_3 & \dots & \partial f(A_1 | X) / \partial x_M \\ \partial f(A_2 | X) / \partial x_1 & \partial f(A_2 | X) / \partial x_2 & \partial f(A_2 | X) / \partial x_3 & \dots & \partial f(A_2 | X) / \partial x_M \\ \partial f(A_3 | X) / \partial x_1 & \partial f(A_3 | X) / \partial x_2 & \partial f(A_3 | X) / \partial x_3 & \dots & \partial f(A_3 | X) / \partial x_M \\ \dots & \dots & \dots & \dots & \dots \\ \partial f(A_N | X) / \partial x_1 & \partial f(A_N | X) / \partial x_2 & \partial f(A_N | X) / \partial x_3 & \dots & \partial f(A_N | X) / \partial x_M \end{bmatrix}$$

Here are the corresponding solutions :

- OLS $\partial_X L = 2A^T (AX - B) \rightarrow X_{OLS} = (A^T A)^{-1} (A^T B)$
- WLS $\partial_X L = 2A^T W (AX - B) \rightarrow X_{WLS} = (A^T W A)^{-1} (A^T W B)$
- GLS $\partial_X L = 2A^T \Sigma^{-1} (AX - B) \rightarrow X_{GLS} = (A^T \Sigma^{-1} A)^{-1} (A^T \Sigma^{-1} B)$
- Tikhonov regularization $\partial_X L = 2A^T \Sigma^{-1} (AX - B) + 2\Sigma_Q^{-1} (X - X_0) \rightarrow X_{TR} = (A^T \Sigma^{-1} A + \Sigma_Q^{-1})^{-1} (A^T \Sigma^{-1} B + \Sigma_Q^{-1} X_0)$

- nonlinear - Gauss Newton*

$$\begin{aligned}
L &= (F(A|X) - B)^T \Sigma^{-1} (F(A|X) - B) \\
&= (F(A|X^{(t)}) + J_F \Delta X - B)^T \Sigma^{-1} (F(A|X^{(t)}) + J_F \Delta X - B) \\
&= (J_F \Delta X - (B - F(A|X^{(t)})))^T \Sigma^{-1} (J_F \Delta X - (B - F(A|X^{(t)}))) \\
\partial_{\Delta X} L &= 2 J_F^T \Sigma^{-1} (J_F \Delta X - (B - F(A|X^{(t)}))) \\
\Delta X &= (J_F^T \Sigma^{-1} J_F)^{-1} (J_F^T \Sigma^{-1} (B - F(A|X^{(t)})))
\end{aligned}$$
- nonlinear - Levenberg Marq*

$$\begin{aligned}
L &= (F(A|X) - B)^T \Sigma^{-1} (F(A|X) - B) + \lambda (\Delta X)^T (\Delta X) \\
&= (F(A|X^{(t)}) + J_F \Delta X - B)^T \Sigma^{-1} (F(A|X^{(t)}) + J_F \Delta X - B) + \lambda (\Delta X)^T (\Delta X) \\
&= (J_F \Delta X - (B - F(A|X^{(t)})))^T \Sigma^{-1} (J_F \Delta X - (B - F(A|X^{(t)}))) + \lambda (\Delta X)^T (\Delta X) \\
\partial_{\Delta X} L &= 2 J_F^T \Sigma^{-1} (J_F \Delta X - (B - F(A|X^{(t)}))) + 2 \lambda \Delta X \\
\Delta X &= (J_F^T \Sigma^{-1} J_F + \lambda I)^{-1} (J_F^T \Sigma^{-1} (B - F(A|X^{(t)})))
\end{aligned}$$
- non Gauss noise model - iterWLS*

$$\begin{aligned}
L &= \sum_{n=1}^N g(A_n X - b_n) & \text{where regression model } AX=B \text{ is linear} \\
\partial_{\Delta X} L &= \sum_{n=1}^N \frac{\partial g(e_n)}{\partial e_n} \frac{\partial e_n}{\partial X} & \text{where } e_n = A_n X - b_n \\
&= \sum_{n=1}^N w_n e_n \frac{\partial e_n}{\partial X} & \text{where } w_n = \frac{1}{e_n} \frac{\partial g(e_n)}{\partial e_n} \\
&= \frac{1}{2} \sum_{n=1}^N w_n \frac{\partial e_n^2}{\partial X} \\
&= \frac{1}{2} \frac{\partial}{\partial X} \sum_{n=1}^N w_n e_n^2
\end{aligned}$$
- interpretation in 2D, let's consider :*

$$A = \begin{bmatrix} x_1 & 1 \\ x_2 & 1 \\ \dots & \dots \\ x_N & 1 \end{bmatrix} \quad B = \begin{bmatrix} y_1 \\ y_2 \\ \dots \\ y_N \end{bmatrix} \quad X = \begin{bmatrix} m \\ c \end{bmatrix}$$

$$W = \text{diag}(w_1, w_2, \dots, w_N)$$

we then have :

$$\begin{aligned}
A^T W A &= \begin{bmatrix} \sum_{n=1}^N w_n x_n x_n & \sum_{n=1}^N w_n x_n \\ \sum_{n=1}^N w_n x_n & \sum_{n=1}^N w_n \end{bmatrix} = \begin{bmatrix} S_{wxx} & S_{wx} \\ S_{wx} & S_w \end{bmatrix} \\
A^T W B &= \begin{bmatrix} \sum_{n=1}^N w_n x_n y_n \\ \sum_{n=1}^N w_n y_n \end{bmatrix} = \begin{bmatrix} S_{wxy} \\ S_{wy} \end{bmatrix} \\
m &= \frac{S_{wxy} S_w - S_{wx} S_{wy}}{S_{wxx} S_w - S_{wx} S_{wx}} = \frac{\text{cov}(x, y)}{\text{var}(x)} \\
c &= \frac{S_{wxx} S_{wy} - S_{wx} S_{wxy}}{S_{wxx} S_w - S_{wx} S_{wx}} = \frac{S_{wxx} S_{wy} - S_{wx} S_{wxy}}{\text{var}(x)}
\end{aligned}$$

- interpretation in regressor space*

$$AX = \text{span of column vector } A, \text{ weighted by } X$$

then distance between span of A and vector B is minimised when span of A equals to the projection of B on A :

$$\begin{aligned}
AX_{OLS} &= \text{proj}_A(B) & (\text{visualise the case when } N \gg M = 2) \\
&= A(A^T A)^{-1} A^T B \\
\Rightarrow X_{OLS} &= (A^T A)^{-1} A^T B
\end{aligned}$$

3.3 Various constraints

We will discuss 5 constraints :

- linear constraint 1 $\min_X \|AX - B\|_W^2$ so that $X_1 = X_1^*$ where $X_1 = \text{column_matrix}(K \times 1)$
- linear constraint 2 $\min_X \|AX - B\|_W^2$ so that $X_1 = CX_2 + D$ where $X_1 = \text{column_matrix}(K \times 1)$
- linear constraint 3 $\min_X \|AX - B\|_W^2$ so that $CX = D$
- quad constraint 1 $\min_{X,y} \|AX - ly\|_W^2$ so that $X^T X = 1$ where $l = \text{ones}(N \times 1)$ and y is scalar, distance to origin
 $\rightarrow \lambda X = \text{cov}(A)X$ and $y = \frac{l^T WAX}{l^T Wl}$
- quad constraint 2 $\min_X \|AX - B\|_W^2$ so that $X^T X = 1$

Here are the corresponding solutions :

- $L = (AX - B)^T W (AX - B)$
 $= (A_1 X_1 + A_2 X_2 - B)^T W (A_1 X_1 + A_2 X_2 - B)$
 $= (A_2 X_2 - (B - A_1 X_1^*))^T W (A_2 X_2 - (B - A_1 X_1^*))$
 $0 = 2A_2^T W (A_2 X_2 - (B - A_1 X_1^*))$ differentiate L wrt X_2 , set it zero
 $X_2 = (A_2^T W A_2)^{-1} (A_2^T W (B - A_1 X_1^*))$

- $L = (AX - B)^T W (AX - B)$
 $= (A_1 X_1 + A_2 X_2 - B)^T W (A_1 X_1 + A_2 X_2 - B)$
 $= (A_1 (CX_2 + D) + A_2 X_2 - B)^T W (A_1 (CX_2 + D) + A_2 X_2 - B)$
 $= ((A_1 C + A_2) X_2 - (B - A_1 D))^T W ((A_1 C + A_2) X_2 - (B - A_1 D))$
 $0 = 2(A_1 C + A_2)^T W ((A_1 C + A_2) X_2 - (B - A_1 D))$ differentiate L wrt X_2 , set it zero
 $X_2 = ((A_1 C + A_2)^T W (A_1 C + A_2))^{-1} ((A_1 C + A_2)^T W (B - A_1 D))$

- $AX = B$ so that $CX = D$
 $AVV^T X = B$ so that $USV^T X = D$
 $A'X' = B$ so that $USX' = D$ where $A' = AV$ and $X' = V^T X$
 $X' = S^{-1} U^T D$
 $\begin{bmatrix} X'_1 \\ X'_2 \end{bmatrix} = \begin{bmatrix} S_1^{-1} \\ S_2^{-1} \end{bmatrix} U^T D$ ignore null space S_2 of constraint
 $X'_1 = S_1^{-1} U^T D$

$$\arg \min_X (AX - B)^T W (AX - B) \Rightarrow \arg \min_{X'} (A'X' - B)^T W (A'X' - B)$$

$$\text{s.t. } CX = D \quad \text{s.t. } X'_1 = S_1^{-1} U^T D$$

By transforming the problem, we can apply technique in solving linear constraint 1 :

$$X'_2 = (A'_2{}^T W A'_2)^{-1} (A'_2{}^T W (B - A'_1 X'_1))$$

$$X = VX'$$

$$= \begin{bmatrix} VX'_1 \\ VX'_2 \end{bmatrix}$$

$$= \begin{bmatrix} V(S_1^{-1} U^T D) \\ V(A'_2{}^T W A'_2)^{-1} (A'_2{}^T W (B - A'_1 X'_1)) \end{bmatrix}$$

- Setting up a Lagrangian, firstly take derivative wrt y , secondly substitute result into Lagrangian, finally take derivative wrt X :

$$L = (AX - ly)^T W(AX - ly) + \lambda(1 - X^T X)$$

$$0 = l^T W(AX - ly)$$

firstly take derivative wrt y

$$y = \frac{l^T WAX}{l^T Wl} = \bar{A}X$$

where $l^T Wl = \sum_{n=1}^N w_n = \text{scalar}$ and $l^T WA = \sum_{n=1}^N w_n A_n$

$$L = (AX - l\bar{A}X)^T W(AX - l\bar{A}X) + \lambda(1 - X^T X)$$

secondly substitute result into Lagrangian

$$= ((A - l\bar{A})X)^T W((A - l\bar{A})X) + \lambda(1 - X^T X)$$

$$0 = 2(A - l\bar{A})^T W(A - l\bar{A})X - 2\lambda X$$

finally take derivative wrt X

$$\lambda X = \text{cov}(A)X$$

where $\text{cov}(A) = (A - l\bar{A})^T W(A - l\bar{A})$

- Setting up a Lagrangian, firstly take derivative wrt X , secondly substitute result into constraint, finally solve for multiplier :

$$L = (AX - B)^T W(AX - B) + \lambda(1 - X^T X)$$

$$0 = 2A^T W(AX - B) - 2\lambda X$$

firstly take derivative wrt X

$$0 = (A^T WA - \lambda I)X - (A^T WB)$$

$$X = (A^T WA - \lambda I)^{-1} (A^T WB)$$

$$1 = X^T X$$

secondly substitute result into constraint

$$= ((A^T WA - \lambda I)^{-1} (A^T WB))^T ((A^T WA - \lambda I)^{-1} (A^T WB))$$

$$f(\lambda) = ((A^T WA - \lambda I)^{-1} (A^T WB))^T ((A^T WA - \lambda I)^{-1} (A^T WB)) - 1$$

finally solve for λ using Newton Raphson

3.4 Various applications

concentric circles fitting

$$\begin{bmatrix} 2x_1 & 2y_1 & -\delta_{c_1} \\ 2x_2 & 2y_2 & -\delta_{c_2} \\ 2x_3 & 2y_3 & -\delta_{c_3} \\ \dots & \dots & \dots \\ 2x_N & 2y_N & -\delta_{c_N} \end{bmatrix} \begin{bmatrix} x_c \\ y_c \\ r^2 - x_c^2 - y_c^2 \\ \dots \\ r_M^2 - x_c^2 - y_c^2 \end{bmatrix} = \begin{bmatrix} x_1^2 + y_1^2 \\ x_2^2 + y_2^2 \\ x_3^2 + y_3^2 \\ \dots \\ x_N^2 + y_N^2 \end{bmatrix}$$

rectangle fitting

$$\begin{bmatrix} x_1 & 1 & 0 & 0 & 0 \\ -y_2 & 0 & 1 & 0 & 0 \\ x_3 & 0 & 0 & 1 & 0 \\ -y_4 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} m \\ c_1 \\ mc_2 \\ c_3 \\ mc_4 \end{bmatrix} = \begin{bmatrix} y_1 \\ x_2 \\ y_3 \\ x_4 \end{bmatrix}$$

homo-inspect

$$\begin{bmatrix} (1-r_{x_1})(1-r_{y_1}) & (1-r_{x_1})r_{y_1} & r_{x_1}(1-r_{y_1}) & r_{x_1}r_{y_1} \\ (1-r_{x_2})(1-r_{y_2}) & (1-r_{x_2})r_{y_2} & r_{x_2}(1-r_{y_2}) & r_{x_2}r_{y_2} \\ (1-r_{x_3})(1-r_{y_3}) & (1-r_{x_3})r_{y_3} & r_{x_3}(1-r_{y_3}) & r_{x_3}r_{y_3} \\ \dots & \dots & \dots & \dots \\ (1-r_{x_N})(1-r_{y_N}) & (1-r_{x_N})r_{y_N} & r_{x_N}(1-r_{y_N}) & r_{x_N}r_{y_N} \end{bmatrix} \begin{bmatrix} a_{00} \\ a_{01} \\ a_{10} \\ a_{11} \end{bmatrix} = \begin{bmatrix} \text{ins}(x_1, y_1) \\ \text{ins}(x_2, y_2) \\ \text{ins}(x_3, y_3) \\ \dots \\ \text{ins}(x_N, y_N) \end{bmatrix}$$

template-inspect

$$\begin{bmatrix} \text{lrn}_1(x_1, y_1) & \text{lrn}_2(x_1, y_1) & \dots & \text{lrn}_M(x_1, y_1) & 1 \\ \text{lrn}_1(x_2, y_2) & \text{lrn}_2(x_2, y_2) & \dots & \text{lrn}_M(x_2, y_2) & 1 \\ \text{lrn}_1(x_3, y_3) & \text{lrn}_2(x_3, y_3) & \dots & \text{lrn}_M(x_3, y_3) & 1 \\ \dots & \dots & \dots & \dots & \dots \\ \text{lrn}_1(x_N, y_N) & \text{lrn}_2(x_N, y_N) & \dots & \text{lrn}_M(x_N, y_N) & 1 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ \dots \\ a_M \\ b \end{bmatrix} = \begin{bmatrix} \text{ins}(x_1, y_1) \\ \text{ins}(x_2, y_2) \\ \text{ins}(x_3, y_3) \\ \dots \\ \text{ins}(x_N, y_N) \end{bmatrix}$$

alignment, given cost function $L = \sum_{n=1}^N [(x_n^{\text{ins}} - x_n^{\text{lrnTrans}}) \times \cos(\alpha_n^{\text{lrn}}) + (y_n^{\text{ins}} - y_n^{\text{lrnTrans}}) \times \sin(\alpha_n^{\text{lrn}})]^2$

$$\begin{bmatrix} x_1^{\text{lrn}} \cos(\alpha_1^{\text{lrn}}) + y_1^{\text{lrn}} \sin(\alpha_1^{\text{lrn}}) & -y_1^{\text{lrn}} \cos(\alpha_1^{\text{lrn}}) + x_1^{\text{lrn}} \sin(\alpha_1^{\text{lrn}}) & \cos(\alpha_1^{\text{lrn}}) & \sin(\alpha_1^{\text{lrn}}) \\ x_2^{\text{lrn}} \cos(\alpha_2^{\text{lrn}}) + y_2^{\text{lrn}} \sin(\alpha_2^{\text{lrn}}) & -y_2^{\text{lrn}} \cos(\alpha_2^{\text{lrn}}) + x_2^{\text{lrn}} \sin(\alpha_2^{\text{lrn}}) & \cos(\alpha_2^{\text{lrn}}) & \sin(\alpha_2^{\text{lrn}}) \\ \dots & \dots & \dots & \dots \\ x_N^{\text{lrn}} \cos(\alpha_N^{\text{lrn}}) + y_N^{\text{lrn}} \sin(\alpha_N^{\text{lrn}}) & -y_N^{\text{lrn}} \cos(\alpha_N^{\text{lrn}}) + x_N^{\text{lrn}} \sin(\alpha_N^{\text{lrn}}) & \cos(\alpha_N^{\text{lrn}}) & \sin(\alpha_N^{\text{lrn}}) \end{bmatrix} \begin{bmatrix} a \\ b \\ \Delta x \\ \Delta y \end{bmatrix} = \begin{bmatrix} x_1^{\text{ins}} \cos(\alpha_1^{\text{lrn}}) + y_1^{\text{ins}} \sin(\alpha_1^{\text{lrn}}) \\ x_2^{\text{ins}} \cos(\alpha_2^{\text{lrn}}) + y_2^{\text{ins}} \sin(\alpha_2^{\text{lrn}}) \\ \dots \\ x_N^{\text{ins}} \cos(\alpha_N^{\text{lrn}}) + y_N^{\text{ins}} \sin(\alpha_N^{\text{lrn}}) \end{bmatrix}$$