# Interactive Theorem Proving and Program Verification Lecture 1

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Based on slides by Thomas Tuerk



# Part I

# Introduction



#### Motivation



- complex systems almost certainly contain bugs
- modern society increasingly depends on complex systems.
- critical systems (e.g., avionics) need to meet very high standards.
- infeasible in practice to achieve such high standards just by testing
- debugging via testing suffers from diminishing returns

"Program testing can be used to show the presence of bugs, but never to show their absence!"

— Edsger W. Dijkstra

### Famous Bugs



- Pentium FDIV bug (1994)
   (missing entry in lookup table, \$475 million damage)
- Ariane V explosion (1996) (integer overflow, \$1 billion prototype destroyed)
- Mars Climate Orbiter (1999)
   (destroyed in Mars orbit, mixup of units pound-force and newtons)
- Knight Capital Group Error in Ultra Short Time Trading (2012) (faulty deployment, repurposing of critical flag, \$440 million lost in 45 min on stock exchange)
- . . .

#### Interesting reads

http://www.cs.tau.ac.il/~nachumd/verify/horror.html https://en.wikipedia.org/wiki/List\_of\_software\_bugs

### Proof



- proof can demonstrate the absence of errors
- but proofs (usually) talk about a design, not a real system
- ullet  $\Rightarrow$  testing and proving can complement each other

"As far as the laws of mathematics refer to reality, they are not certain; and as far as they are certain, they do not refer to reality."

— Albert Einstein

#### Mathematical vs. Formal Proof



#### Mathematical Proof

- informal, convinces other mathematicians
- varying degrees of rigor
- checked by community of domain experts ("elders")
- subtle errors are hard to find
- often provide some new insight about our world
- often short, but may require creativity and brilliant ideas

#### Formal Proof

- encoded in a logical formalism
- sequence of low-level steps
- checkable by stupid machines
- trustworthy
- usually contain no new ideas or amazing insights
- often long and tedious, but have simple structure

We are interested in formal proofs in this course.

# Automated vs. Manual (Formal) Proof



### Fully Manual Proof

- very tedious; one has to grind through many trivial but detailed proofs
- easy to make mistakes
- hard to keep track of all assumptions and preconditions
- hard to maintain, if something changes (see Ariane V)

#### **Automated Proof**

- amazing successes in certain domains (e.g., SAT solving)
- still, often infeasible for interesting problems
- hard to get insights in case a proof attempt fails
- even if it works, it is often not that automated
  - run automated tool for a few days
  - ▶ abort, change command line arguments to use different heuristics
  - run again and iterate till you find a set of heuristics that prove it fully automatically in a few seconds

#### Interactive Proofs



- combine strengths of manual and automated proofs
- many different options to combine manual and automated proofs
  - mainly check existing proofs (e.g. HOL Zero)
  - user mainly provides lemma statements, computer searches for proofs using previous lemmas and a few hints (e. g. ACL2)
  - most systems are somewhere in the middle
- typically the human user
  - provides insights into the problem
  - structures the proof
  - provides main arguments
- typically the computer
  - checks the proof
  - keeps track of all used assumptions
  - provides automation to grind through lengthy, but trivial proof steps

### Typical Interactive Proving Activities



- provide precise definitions of concepts
- state properties of these concepts
- prove these properties
  - human provides insight and structure
  - computer does book-keeping and automates simple proofs
- build and use libraries of formal definitions and proofs
  - formalisations of mathematical theories like
    - ★ lists, sets, bags, . . .
    - real analysis
    - ★ probability theory
    - specifications and implementations of real-world artefacts like
      - processors
      - ★ programming languages
      - network protocols
      - ★ compilers
    - reasoning tools

There is a strong connection to programming. Lessons from software engineering apply.

#### Different Interactive Theorem Provers



- there are many different interactive provers, e.g.,
  - ► Isabelle/HOL
  - Coq
  - PVS
  - ► HOL4
  - ► HOL Light
  - ► ACL2
  - Lean
- important differences
  - the formalism used (set theory, simple types, dependent types, ...)
  - ▶ level of trustworthiness
  - level of automation
  - libraries
  - languages for proof automation
  - languages for specification
  - user interfaces

#### The Best Interactive Theorem Prover



- there is no best interactive theorem prover
- better question: which one is the best for a certain purpose?
- important points to consider
  - existing libraries
  - formalism
  - required level of automation
  - user interfaces and build tools
  - importance of development speed vs. trustworthiness
  - familiarity
  - access to experts for help
  - your personal preferences

In this course we use the HOL4 theorem prover.

#### Interactive Theorem Prover Success Stories



- CompCert verified compiler for C (Coq)
- CakeML verified compiler for ML (HOL4)
- Kepler conjecture (HOL Light)
- seL4 verified operating system kernel (Isabelle/HOL)
- Feit-Thompson theorem (Coq)
- Four color theorem (Coq)

## Part II

# Organisational Matters



#### Aims of this Course



#### Aims

- Introduction to interactive theorem proving (ITP)
- Being able to evaluate whether a problem can benefit from ITP
- Hands-on experience with HOL4
- Learn how to build a formal model
- Learn how to express and prove important properties of such a model
- Use a theorem prover on a small project

### Required Prerequisites

- Some experience with functional programming
- Knowing Standard ML syntax
- Basic knowledge about logic (e.g. First Order Logic)

#### **Dates**



- Course takes place in Periods 3/4 of the academic year 2019/2020
- Location: room 4523, except for 2020-01-29, when it is in room 1537 instead.
- Wednesdays every week, 10:00 11:45 (lectures)

#### **Exercises**



- After each lecture an exercise sheet is handed out/uploaded
- Work on these exercises alone, except if stated otherwise explicitly
- First exercise sheet is due by 23:59, Tuesday January 29, 2020
- Main purpose: understanding ITP and learn how to use HOL4
  - no detailed grading, just pass/fail
  - retries possible till pass
  - if stuck, ask us
  - we will set up office hours
- Exercises are to be handed-in electronically (email for now)

# Passing the ITP Course



- There is only a pass/fail mark
- To pass the course you need get a pass on all the exercises and a final project

#### Communication



- Information and material posted on course website: https://kth-step.github.io/itppv-course/
- Contact us directly via email:
  - ▶ Pablo Buiras, buiras@kth.se
  - Karl Palmskog, palmskog@kth.se

### Part III

# **HOL4** History and Architecture



# Interactive Theorem Proving Pre-history



- Aristotle, Prior Analytics (3rd century BCE)
- Leibniz, The Art of Discovery (1685)
- Frege, Grundgesetze der Arithmetik (1893)
- Russell & Whitehead, Principia Mathematica (1913)
- Gödel, Church, Turing (1930s)
- Davis & Putnam, Resolution proof system (1960)
- de Bruijn, Automath (1967)

# LCF History



- Stanford LCF 1971-72 by Milner et al.
- LCF formalism devised by Dana Scott in 1969
- intended to reason about recursively defined functions
- intended for computer science applications
- strengths
  - powerful simplification mechanism
  - support for backward proof
- limitations
  - proofs need a lot of memory
  - fixed, hard-coded set of proof commands



Robin Milner (1934 - 2010)

### LCF - Logic of Computable Functions II



- Milner worked on improving LCF in Edinburgh
- research assistants
  - Lockwood Morris
  - Malcolm Newey
  - Chris Wadsworth
  - Mike Gordon
- Edinburgh LCF 1979
- introduction of Meta Language (ML)
- ML was invented to write proof procedures
- ML became an influential functional programming language
- using ML allowed implementing the LCF approach

# LCF Approach



- implement an abstract datatype thm to represent theorems
- semantics of ML ensure that values of type thm can only be created using its interface
- interface is very small
  - predefined theorems are axioms
  - function with result type theorem are inferences
- interface is carefully designed and checked
  - size of interface and implementation allow careful checking
  - one checks that the interface really implements only axioms and inferences that are valid in the used logic
- However you create a theorem, there is a proof for it.
- together with similar abstract datatypes for types and terms, this forms the kernel

### LCF Approach II



### Modus Ponens Example

#### Inference Rule

$$\frac{\Gamma \vdash a \Rightarrow b \qquad \Delta \vdash a}{\Gamma \cup \Delta \vdash b}$$

#### **SML** function

val MP : thm -> thm -> thm MP(
$$\Gamma \vdash a \Rightarrow b$$
)( $\Delta \vdash a$ ) = ( $\Gamma \cup \Delta \vdash b$ )

- very trustworthy only the small kernel needs to be trusted
- efficient no need to store proofs

#### Easy to extend and automate

However complicated and potentially buggy your code is, if a value of type theorem is produced, it has been created through the small trusted interface. Therefore the statement really holds.

### LCF Style Systems



There are now many interactive theorem provers out there that use an approach similar to that of Edinburgh LCF.

- HOL family
  - ▶ HOL theorem prover
  - ► HOL Light
  - ► HOL Zero
  - Proof Power
  - **.** . . .
- Isabelle
- Nuprl
- Coq
- Lean
- . . .

### History of HOL

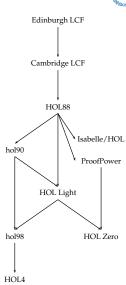


- 1979 Edinburgh LCF by Milner, Gordon, et al.
- 1981 Mike Gordon becomes lecturer in Cambridge
- 1985 Cambridge LCF
  - Larry Paulson and Gèrard Huet
  - implementation of ML compiler
  - powerful simplifier
  - various improvements and extensions
- 1988 HOL
  - Mike Gordon and Keith Hanna
  - adaption of Cambridge LCF to classical higher order logic
  - intention: hardware verification
- 1990 HOL90 reimplementation in SML by Konrad Slind at University of Calgary
- 1998 HOL98 implementation in Moscow ML and new library and theory mechanism
- since then HOL Kananaskis releases, called informally HOL 4

### Family of HOL



- ProofPower commercial version of HOL88 by Roger Jones, Rob Arthan et al.
- HOL Light lean CAML / OCaml port by John Harrison
- HOL Zero trustworthy proof checker by Mark Adams
- Isabelle
  - ▶ 1990 by Larry Paulson
  - meta-theorem prover that supports multiple logics
  - however, mainly HOL used, ZF a little
  - nowadays probably the most widely used HOL system
  - originally designed for software verification



### Part IV

# Preliminaries and HOL's Logic





- Standard ML (SML) is a statically-typed impure functional programming language with
  - Hindley-Milner type inference
  - parametric polymorphism
  - side-effects (mutable references, exceptions, IO, ...)
  - a module system
- ullet Based on the simply-typed call-by-value  $\lambda$ -calculus
- Has a formal definition and semantics



#### SML expressions

- Constants (i.e, literals): 42, true, [], 3.14, "hello", ...
- Variables: x, y, foo, ...
- Tuples: (2, 4), (true, 66), ...
- Function application: f A, f(A)
- Function abstraction: fn x => A
- Sequencing: A; B
- Conditional expressions: if A then B else C
- let-expressions: let <definitions> in A end
- case-expressions: case A of pattern => B | ...
- ...



#### SML definitions

- Variable binding: val x = 42
- Function definition: fun add\_two (x,y) = x + y
   (equivalent to val add\_two = fn (x,y) => x + y)
- Type definitions: datatype colour = red | green | blue
- ...

### Example

```
fun fact 0 = 1
| fact n = n * fact (n-1)
```



#### Algebraic lists

- List expressions: nil, [], [1,2,3], 5 :: [2,4]
- We read [] as "nil" and :: as "cons"

### Example



#### **Types**

- Base types: int, bool, ..., 1 : int
- Function types: T -> R, fact : int -> int
- Tuple types: T \* R, (1,true) : int \* bool
- User-defined types: colour, red : colour
- ...

### Algebraic type example

```
datatype 'a foo =
  constructor_1 of 'a * int
| constructor_2 of bool * ('a foo)
| constructor_3 of 'a * 'a
```



- Constructors are values too
- o constructor\_2 : bool \* ('a foo) -> 'a foo
- What is the type of the other constructors?
- Values of type A foo can be deconstructed with a case expression (pattern matching):

```
case x of
  constructor_3 (x,y) => ... x and y are bound ...
| constructor_1 => ...
| constructor_2 (true, constructor_1 (x, 4)) => ...
| ...
```

### **HOL** Logic



- the HOL theorem prover uses a version of classical higher order logic: classical higher order predicate calculus with terms from the typed lambda calculus (i.e. simple type theory)
- this sounds complicated, but is intuitive for SML programmers
- (S)ML and HOL logic designed to fit each other
- HOL is embedded in SML

HOL = functional programming + logic

#### **Ambiguity Warning**

The acronym *HOL* refers to both the *HOL* interactive theorem prover and the *HOL* logic used by it. It's also a common abbreviation for higher order logic in general.

### **Types**



- SML datatype for types
  - ▶ Type Variables ('a,  $\alpha$ , 'b,  $\beta$ , ...) Type variables are implicitly universally quantified. Theorems containing type variables hold for all instantiations of these. Proofs using type variables can be seen as proof schemata.
  - Atomic Types (c) Atomic types denote fixed types. Examples: num, bool, unit
  - ▶ Compound Types  $((\sigma_1, \ldots, \sigma_n)op)$  op is a type operator of arity n and  $\sigma_1, \ldots, \sigma_n$  argument types. Type operators denote operations for constructing types. Examples: num list or 'a # 'b.
  - ▶ Function Types  $(\sigma_1 \to \sigma_2)$  $\sigma_1 \to \sigma_2$  is the type of total functions from  $\sigma_1$  to  $\sigma_2$ .
- types are never empty in HOL, i. e. for each type at least one value exists
- all HOL functions are total

#### **Terms**



- SML datatype for terms
  - ► Variables (x, y, . . .)
  - ► Constants (c,...)
  - ► Function Application (f a)
  - ▶ Lambda Abstraction ( $\x$ . f x or  $\lambda x$ . fx) Lambda abstraction represents anonymous function definition. The corresponding SML syntax is fn x => f x.
- terms have to be well-typed
- same typing rules and same type-inference as in SML take place
- terms very similar to SML expressions
- notice: predicates are functions with return type bool, i.e. no distinction between functions and predicates, terms and formulae

### Terms II



HOL term	SML expression	type HOL / SML
0	0	num / int
x:'a	x:'a	variable of type 'a
x:bool	x:bool	variable of type bool
x + 5	x + 5	applying function + to $x$ and 5
$\x$ . x + 5	$fn x \Rightarrow x + 5$	anonymous (a. k. a. inline) function
		of type num -> num
(5, T)	(5, true)	<pre>num # bool / int * bool</pre>
[5;3;2]++[6]	[5,3,2]@[6]	num list / int list

### Free and Bound Variables / Alpha Equivalence



- in SML, the names of function arguments does not matter (much)
- similarly in HOL, the names of variables used by lambda-abstractions does not matter (much)
- the lambda-expression  $\lambda x$ . t is said to **bind** the variables x in term t
- variables that are guarded by a lambda expression are called bound
- all other variables are free
- Example: x is free and y is bound in  $(x = 5) \land (\lambda y. (y < x))$  3
- the names of bound variables are unimportant semantically
- two terms are called alpha-equivalent iff they differ only in the names of bound variables
- Example:  $\lambda x$ . x and  $\lambda y$ . y are alpha-equivalent
- Example: x and y are not alpha-equivalent

#### **Theorems**



- theorems are of the form  $\Gamma \vdash p$  where
  - Γ is a set of hypothesis
  - p is the conclusion of the theorem
  - $\blacktriangleright$  all elements of  $\Gamma$  and p are formulae, i.e. terms of type bool
- $\Gamma \vdash p$  records that using  $\Gamma$  the statement p has been proved
- the proof itself is not recorded
- theorems can only be created through a small interface in the kernel

### **HOL Light Kernel**



- the HOL kernel is hard to explain
  - for historic reasons some concepts are represented rather complicated
  - for speed reasons some derivable concepts have been added
- instead consider the HOL Light kernel, which is a cleaned-up version
- there are two predefined constants

```
> = : 'a -> 'a -> bool
> @ : ('a -> bool) -> 'a
```

- there are two predefined types
  - ▶ bool
  - ind
- the meaning of these types and constants is given by inference rules and axioms

### HOL Light Inferences I



$$\frac{\Gamma \vdash s = t}{\Gamma \vdash t = t} \text{ REFL} \qquad \qquad \frac{\Gamma \vdash s = t}{\Gamma \vdash \lambda x. \ s = \lambda x. \ t} \text{ ABS}$$

$$\frac{\Delta \vdash t = u}{\Gamma \cup \Delta \vdash s = u} \text{ TRANS}$$

$$\frac{\Gamma \vdash s = t}{\Gamma \vdash \lambda x. \ s = \lambda x. \ t} \text{ BETA}$$

$$\frac{\Gamma \vdash s = t}{\Delta \vdash u = v}$$

$$\frac{\Delta \vdash u = v}{types \ fit}$$

$$\frac{\tau \vdash s = t}{\Gamma \cup \Delta \vdash s(u) = t(v)} \text{ COMB}$$

### HOL Light Inferences II



$$\frac{\Gamma \vdash p \Leftrightarrow q \quad \Delta \vdash p}{\Gamma \cup \Delta \vdash q} \text{ EQ\_MP}$$

$$\frac{\Gamma \vdash p \quad \Delta \vdash q}{(\Gamma - \{q\}) \cup (\Delta - \{p\}) \vdash p \Leftrightarrow q} \text{ DEDUCT\_ANTISYM\_RULE}$$

$$\frac{\Gamma[x_1, \dots, x_n] \vdash p[x_1, \dots, x_n]}{\Gamma[t_1, \dots, t_n] \vdash p[t_1, \dots, t_n]} \text{ INST}$$

$$\frac{\Gamma[\alpha_1, \dots, \alpha_n] \vdash p[\alpha_1, \dots, \alpha_n]}{\Gamma[\gamma_1, \dots, \gamma_n] \vdash p[\gamma_1, \dots, \gamma_n]} \text{ INST\_TYPE}$$

### **HOL Light Axioms and Definition Principles**



3 axioms needed

ETA\_AX 
$$|-(\lambda x. t x) = t$$
  
SELECT\_AX  $|-P x \Longrightarrow P((@)P))$   
INFINITY\_AX predefined type ind is infinite

- definition principle for constants
  - constants can be introduced as abbreviations
  - constraint: no free vars and no new type vars
- definition principle for types
  - new types can be defined as non-empty subtypes of existing types
- both principles
  - lead to conservative extensions
  - preserve consistency

### HOL Light derived concepts



Everything else is derived from this small kernel.

$$T =_{def} (\lambda p. p) = (\lambda p. p)$$

$$\wedge =_{def} \lambda p q. (\lambda f. f p q) = (\lambda f. f T T)$$

$$\implies =_{def} \lambda p q. (p \wedge q \Leftrightarrow p)$$

$$\forall =_{def} \lambda P. (P = \lambda x. T)$$

$$\exists =_{def} \lambda P. (\forall q. (\forall x. P(x) \Longrightarrow q) \Longrightarrow q)$$
...

### Multiple Kernels



- Kernel defines abstract datatypes for types, terms and theorems
- one does not need to look at the internal implementation
- therefore, easy to exchange
- there are at least 3 different kernels for HOL
  - standard kernel (de Bruijn indices)
  - experimental kernel (name / type pairs)
  - OpenTheory kernel (for proof recording)

### **HOL Logic Summary**



- HOL theorem prover uses classical higher order logic
- HOL logic is very similar to SML
  - syntax
    - type system
    - type inference
- HOL theorem prover very trustworthy because of LCF approach
  - there is a small kernel
  - proofs are not stored explicitly
- you don't need to know the details of the kernel
- usually one works at a much higher level of abstraction