#### Optimization

#### 1st Problem Set

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## Problem 1

(0) Let  $f: \mathbb{R}_+ \to \mathbb{R}$ , with  $f(x) = \frac{1}{1+x}$ . Let  $x_0 \in \mathbb{R}_+$ , and define the first- and second-order Taylor approximations of f at  $x_0$  as

$$f_{(1)}(x) = f(x_0) + f'(x_0)(x - x_0),$$
  
$$f_{(2)}(x) = f(x_0) + f'(x_0)(x - x_0) + \frac{1}{2}f''(x_0)(x - x_0)^2.$$

(a) Find the analytic expressions for functions f' and f'';

Solution:

$$f'(x) = -\frac{1}{(1+x)^2}$$
 and  $f''(x) = \frac{2}{(1+x)^3}$ 

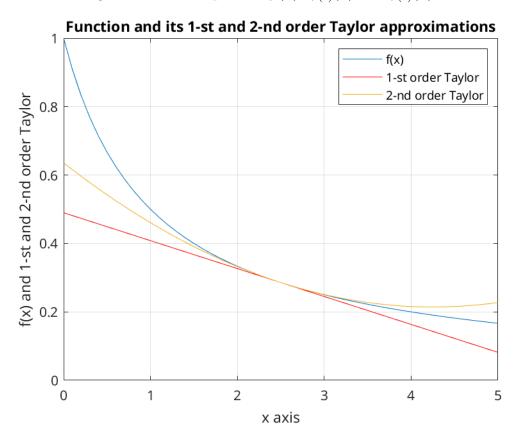
Hence the first and second order Taylor approximations will be:

$$f_{(1)}(x) = \frac{1}{(1+x_0)} - \frac{1}{(1+x_0)^2}(x-x_0)$$
$$f_{(2)}(x) = \frac{1}{(1+x_0)} - \frac{1}{(1+x_0)^2}(x-x_0) + \frac{1}{(1+x_0)^3}(x-x_0)^2.$$

(b) (0) Draw in a common plot f(x),  $f_{(1)}(x)$  and  $f_{(2)}(x)$  and, in order to understand the behavior of the approximations, consider various values of  $x_0$ .

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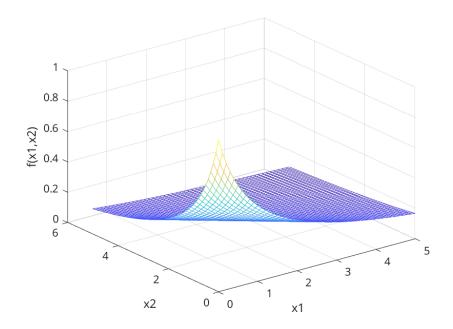
Figure 1: common plot for f(x),  $f_{(1)}(x)$  and  $f_{(2)}(x)$ .



# Problem 2

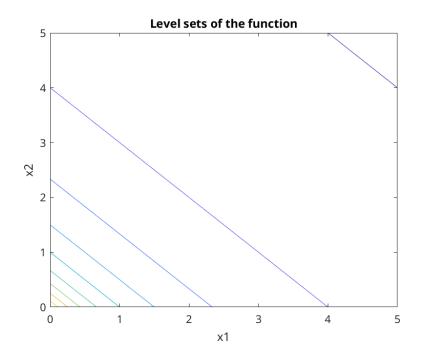
(0) Let  $f: \mathbb{R}^2_+ \to \mathbb{R}$ , with  $f(x_1, x_2) = \frac{1}{1 + x_1 + x_2}$ .

(a) (0) Compute and plot, via mesh, f for  $x_1, x_2 \in [0, x_*]$ , with  $x_* > 0$ .



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(b) (0) Plot the level sets of f , via contour. What do you observe? Can you explain the phenomenon?



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(c) (0) Compute the first- and second-order Taylor approximations of f at point

$$\mathbf{x_0} = (x_{0,1}, x_{0,2}).$$

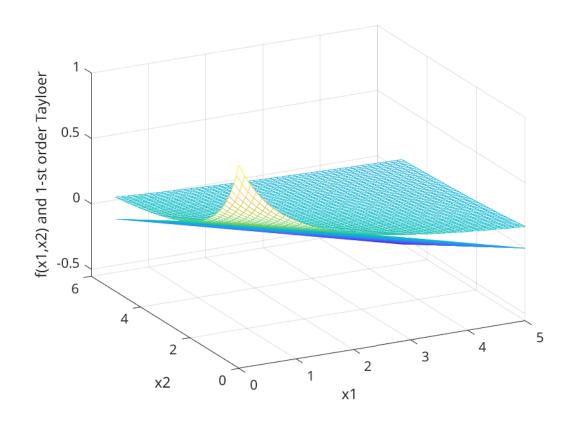
Solution:

$$Df = \left(-\frac{1}{(1+x_1+x_2)^2}, -\frac{1}{(1+x_1+x_2)^2}\right) \text{ and } D^2 f = \begin{pmatrix} \frac{2}{(1+x_1+x_2)^3} & \frac{2}{(1+x_1+x_2)^3} \\ \\ \frac{2}{(1+x_1+x_2)^3} & \frac{2}{(1+x_1+x_2)^3} \end{pmatrix}$$

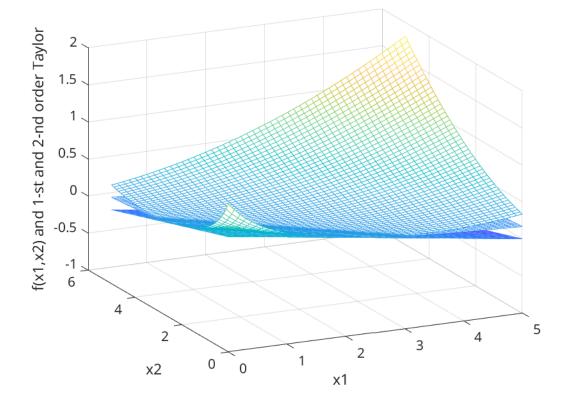
The first and second order Taylor aproxiamtions are computed as:

$$f_{(1)}(\mathbf{x}) = f(\mathbf{x_0}) + Df(\mathbf{x_0})(\mathbf{x} - \mathbf{x_0}),$$
  
$$f_{(2)}(\mathbf{x}) = f(\mathbf{x_0}) + Df(\mathbf{x_0})(\mathbf{x} - \mathbf{x_0}) + \frac{1}{2}(\mathbf{x} - \mathbf{x_0})^T D^2 f(\mathbf{x_0})(\mathbf{x} - \mathbf{x_0}).$$

### (d) (0) Draw on a common plot f and its first-order Taylor approximation.



(e) (0) Draw on a common plot f and its second-order Taylor approximation.



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# Problem 3

(20) Let 
$$\mathbb{S}_{\mathbf{a},b} = \{\mathbf{x} \in \mathbb{R}_n | \mathbf{a}^T \mathbf{x} \leq b\}$$

(a) (5) Prove that  $\mathbb{S}_{\mathbf{a},b}$  is convex.

Solution:

Let  $\mathbf{x_1}, \mathbf{x_2} \in \mathbb{S}_{\mathbf{a},b}$ 

Then

$$\left\{\begin{array}{l} \mathbf{a}^{T}\mathbf{x_{1}} \leq b \\ \mathbf{a}^{T}\mathbf{x_{2}} \leq b \end{array}\right\} \stackrel{0 < \theta_{1} < 1}{\rightleftharpoons} \left\{\begin{array}{l} \mathbf{a}^{T}\theta_{1}\mathbf{x_{1}} \leq \theta_{1}b \\ \mathbf{a}^{T}\theta_{2}\mathbf{x_{2}} \leq \theta_{2}b \end{array}\right\} \Leftrightarrow \mathbf{a}^{T}(\theta_{1}\mathbf{x_{1}} + \theta_{2}\mathbf{x_{2}}) \leq (\theta_{1} + \theta_{2})b \stackrel{\theta_{1} + \theta_{2} = 1}{\rightleftharpoons}$$

$$\overset{\theta_1+\theta_2=1}{\Longleftrightarrow} \mathbf{a}^T (\theta_1 \mathbf{x_1} + \theta_2 \mathbf{x_2}) \leq b$$

Hence  $\theta_1 \mathbf{x_1} + \theta_2 \mathbf{x_2} \in \mathbb{S}_{\mathbf{a},b}$  for  $\theta_1 + \theta_2 = 1$ 

(b) (15) Prove that  $S_{\mathbf{a},b}$  is not affine (a counterexample is sufficient).

Solution:

Let 
$$\mathbf{a} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$
 and  $b = 2$ 

then the vectors  $\mathbf{x_1} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$  and  $\mathbf{x_2} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$  lie on the hyperplane  $\mathbb{S}_{\mathbf{a},b}$  because:

$$\mathbf{a}^T \mathbf{x_1} = \begin{bmatrix} 2 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = 2 + 0 \le 2 = b$$

$$\mathbf{a}^T \mathbf{x_2} = \begin{bmatrix} 2 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = 0 + 1 \le 2 = b$$

However for a constant  $\theta = 2$  we have:

$$\mathbf{a}^{T}(\theta\mathbf{x_{1}} + (1 - \theta)\mathbf{x_{2}}) = \begin{bmatrix} 2 & 1 \end{bmatrix}(2 \begin{bmatrix} 1 \\ 0 \end{bmatrix} - 1 \begin{bmatrix} 0 \\ 1 \end{bmatrix}) = \begin{bmatrix} 2 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ -1 \end{bmatrix} = 4 - 1 = 3 \ge b$$

which proves that  $\mathbb{S}_{\mathbf{a},b}$  is **not** affine

# Problem 4

(10) Find the point  $\mathbf{x}_*$  that is co-linear with a and lies on the hyperplane  $\mathbb{H}_{a,b} := \{\mathbf{x} \in \mathbb{R}_n \mid \mathbf{a}^T \mathbf{x} = b\}.$ 

Solution:

 $\mathbf{x}_*$  is co-linear with  $\mathbf{a}$  means that  $\mathbf{x}_* = k\mathbf{a}$  (1)

if  $\mathbf{x}_*$  lies on the hyperplane  $\mathbb{H}_{\mathbf{a},b}$  then

$$\mathbf{a}^T \mathbf{x}_* = b \stackrel{(1)}{\Longleftrightarrow} \mathbf{a}^T k \mathbf{a} = b \Leftrightarrow k \|\mathbf{a}\| = b \Leftrightarrow k = \frac{b}{\|\mathbf{a}\|} (2)$$

Hence

$$\xrightarrow[(2)]{(1)} \mathbf{x}_* = b \frac{\mathbf{a}}{\|\mathbf{a}\|}$$

# Problem 5

(20) Check whether the following functions are convex or not (using, for example, the second derivative rule).

(a) (5) 
$$f: \mathbb{R}_+ \to \mathbb{R}$$
, with  $f(x) = \frac{1}{1+x}$ 

Solution:

$$\frac{\partial f(x)}{\partial x} = -\frac{1}{(1+x)^2} \Rightarrow \frac{\partial^2 f(x)}{\partial^2 x} = \frac{2}{(1+x)^3} > 0$$
 since  $x > 0$ 

(b) (5) 
$$f: \mathbb{R}^2_+ \to \mathbb{R}$$
, with  $f(x_1, x_2) = \frac{1}{1 + x_1 + x_2}$ 

Solution:

$$\nabla f = \begin{bmatrix} -\frac{1}{(1+x_1+x_2)^2} \\ -\frac{1}{(1+x_1+x_2)^2} \end{bmatrix} \Rightarrow \nabla^2 f = \begin{bmatrix} \frac{2}{(1+x_1+x_2)^3} & \frac{2}{(1+x_1+x_2)^3} \\ \\ \frac{2}{(1+x_1+x_2)^3} & \frac{2}{(1+x_1+x_2)^3} \end{bmatrix}$$

let  $\mathbf{v} = [v_1, v_2]^T \in \mathbb{R}^2$ 

Then

$$\mathbf{v}^T \nabla^2 f \mathbf{v} \Rightarrow \begin{bmatrix} v_1 & v_2 \end{bmatrix} \begin{bmatrix} \frac{2}{(1+x_1+x_2)^3} & \frac{2}{(1+x_1+x_2)^3} \\ \frac{2}{(1+x_1+x_2)^3} & \frac{2}{(1+x_1+x_2)^3} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} =$$

$$= \left[ v_1 \frac{2}{(1+x_1+x_2)^3} + v_2 \frac{2}{(1+x_1+x_2)^3} , v_1 \frac{2}{(1+x_1+x_2)^3} + v_2 \frac{2}{(1+x_1+x_2)^3} \right] \begin{vmatrix} v_1 \\ v_2 \end{vmatrix} =$$

$$= v_1^2 \frac{2}{(1+x_1+x_2)^3} + v_1 v_2 \frac{2}{(1+x_1+x_2)^3} + v_1 v_2 \frac{2}{(1+x_1+x_2)^3} + v_2^2 \frac{2}{(1+x_1+x_2)^3} =$$

$$= \frac{2}{(1+x_1+x_2)^3} (v_1^2 + 2v_1 v_2 + v_2^2) = \frac{2}{(1+x_1+x_2)^3} (v_1 + v_2)^2 > 0$$

since  $x_1, x_2 > 0$ 

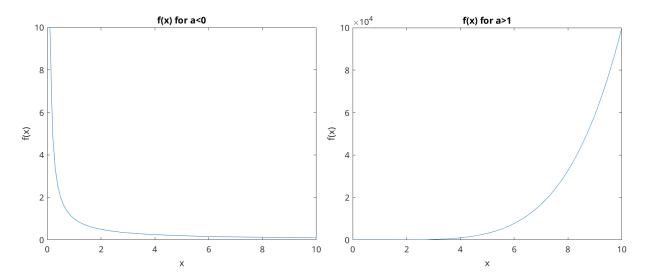
Hence  $\nabla^2 f \succeq \mathbf{O}$  which means that f is convex

(c) (5)  $f: \mathbb{R}_{++} \to \mathbb{R}$ , with  $f(x) = x^a$ , for (to get a better feeling, plot function  $x^a$ , for various values of a)

i.  $a \ge 1$  and  $a \le 0$ ;

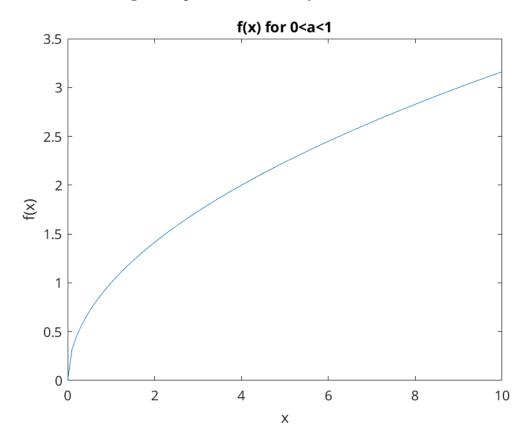
$$\frac{\partial^2 f(x)}{\partial^2 x} = a(a-1)x^{a-2} \geq 0$$
 since  $a \geq 1$  or  $a \leq 0$ 

Figure 2: plots for function f for  $a \ge 1$  and  $a \le 0$ .



ii. 
$$0 \le a \le 1$$
. 
$$\frac{\partial^2 f(x)}{\partial^2 x} = a(a-1)x^{a-2} \le 0 \text{ since } 0 \le a \le 1$$

Figure 3: plots for function f for  $0 \le a \le 1$ .



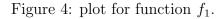
(d) (5)  $f_1, f_2 : \mathbb{R}^n \to \mathbb{R}$ , with  $f_1(\mathbf{x}) = \|\mathbf{x}\|_2$  and  $f_2(\mathbf{x}) = \|\mathbf{x}\|_2^2$  (plot the functions for n = 2).

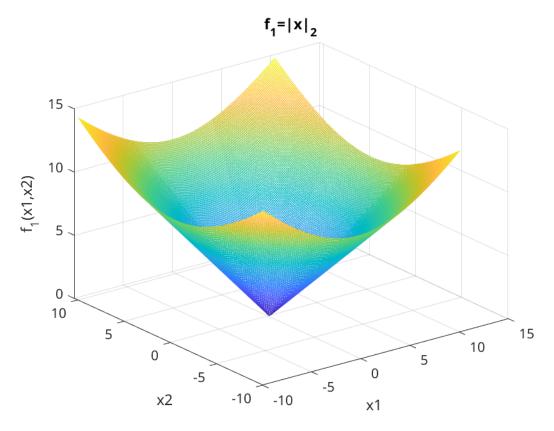
Solution:

For  $f_1(\mathbf{x}) = \|\mathbf{x}\|_2$  using the triangle inequality for  $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$  and a  $0 \le \theta \le 1$  we have

$$\|\theta \mathbf{x} + (1 - \theta)\mathbf{y}\|_{2} \le \|\theta \mathbf{x}\|_{2} + \|(1 - \theta)\mathbf{y}\|_{2} = \theta \|\mathbf{x}\|_{2} + (1 - \theta)\|\mathbf{y}\|_{2} \text{ (since } 0 \le \theta \le 1) \Leftrightarrow$$
$$\Leftrightarrow f_{1}(\theta \mathbf{x} + (1 - \theta)\mathbf{y}) \le \theta f_{1}(\mathbf{x}) + (1 - \theta)f_{1}(\mathbf{y})$$

The inequality above indicates that  $f_1$  is strictly convex





For  $f_2(\mathbf{x}) = \|\mathbf{x}\|_2^2$ :

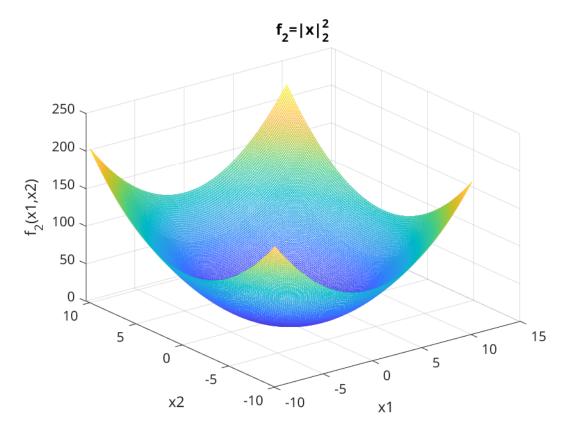
$$f_2(\mathbf{x}) = \|\mathbf{x}\|_2^2 = x_1^2 + x_2^2 + x_3^2 + \dots + x_n^2$$

$$\nabla f(\mathbf{x}) = \begin{bmatrix} \frac{\partial f(\mathbf{x})}{\partial x_1} \\ \frac{\partial f(\mathbf{x})}{\partial x_2} \\ \dots \end{bmatrix} = \begin{bmatrix} 2x_1 \\ 2x_2 \\ \dots \\ \frac{\partial f(\mathbf{x})}{\partial x_n} \end{bmatrix} = 2\mathbf{x}$$

Hence

$$\nabla^2 f(\mathbf{x}) = 2\mathbf{I} \succeq \mathbf{O}$$

Figure 5: plot for function  $f_2$ .



## Problem 6

(20) Let  $A \in \mathbb{R}^{mxn}, b \in \mathbb{R}^m$ , and  $f : \mathbb{R}^n \to \mathbb{R}$ , with  $f(x) = \|\mathbf{A}\mathbf{x} - \mathbf{b}\|_2^2$ .

(a) (10) Assume that the columns of A are linearly independent and prove that f is strictly convex (Prove that the Hessian of  $f(\mathbf{x})$  is positive definite). Solution:

Let  $\mathbf{z} = \mathbf{A}\mathbf{x} - \mathbf{b}$  and  $g(\mathbf{x}) = ||\mathbf{x}||_2^2$  then  $f(\mathbf{x}) = g(\mathbf{z})$ 

Hence

$$\frac{\partial f(\mathbf{x})}{\partial \mathbf{x}} = \frac{\partial g(\mathbf{z})}{\partial \mathbf{z}} \frac{\partial \mathbf{z}}{\partial \mathbf{x}} = \frac{\partial (\|\mathbf{z}\|_{2}^{2})}{\partial \mathbf{z}} \frac{\partial (\mathbf{A}\mathbf{x} - \mathbf{b})}{\partial \mathbf{x}} = 2\mathbf{z}^{T} \mathbf{A}(*) \Rightarrow$$

$$\Rightarrow \frac{\partial^{2} f(\mathbf{x})}{\partial^{2} \mathbf{x}} = \frac{\partial (2\mathbf{z}^{T} \mathbf{A})}{\partial \mathbf{x}} = \frac{2(\mathbf{A}\mathbf{x} - \mathbf{b})^{T} \mathbf{A}}{\partial \mathbf{x}} = \frac{2(\mathbf{x}^{T} \mathbf{A}^{T} \mathbf{A} - \mathbf{b}^{T} \mathbf{A})}{\partial \mathbf{x}} = \mathbf{A}^{T} \mathbf{A} = \nabla^{2} f$$

 $(*)\frac{\partial(\|\mathbf{x}\|_2^2)}{\partial\mathbf{x}} = \nabla(\|\mathbf{x}\|_2^2)^T = 2\mathbf{x}^T$  as proven in Problem 5 (d)

For any vector  $\mathbf{v} \in \mathbb{R}^n$  we have:

$$\mathbf{v}^T \nabla^2 f \mathbf{v} = \mathbf{v}^T \mathbf{A}^T \mathbf{A} \mathbf{v} = (\mathbf{A} \mathbf{v})^T (\mathbf{A} \mathbf{v}) \ge 0$$

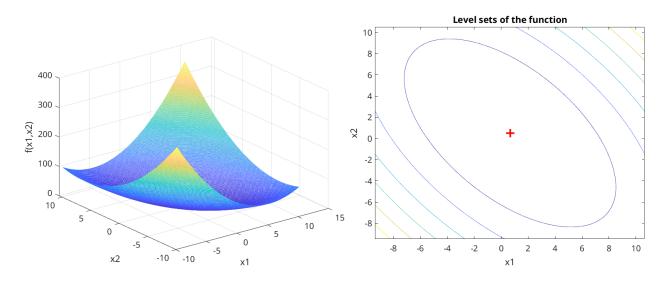
But since the columns of  $\bf A$  are linearly independent we know that there is no vector  $\bf v$  so that  $\bf A \bf v = 0$ 

Hence

$$(\mathbf{A}\mathbf{v})^T(\mathbf{A}\mathbf{v}) > 0 \Leftrightarrow \nabla^2 f \succ \mathbf{O}$$

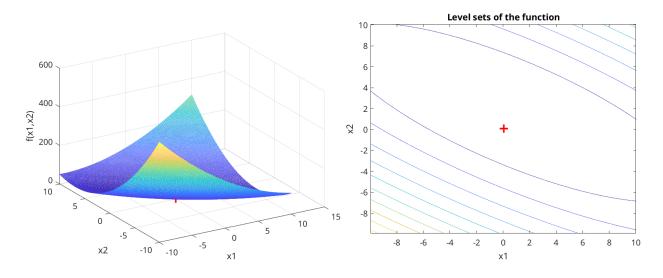
(b) (10) Plot f for m=3 and n=2. In order to generate the data, generate a random (3 × 2) matrix A, a random (2 × 1) vector x, and compute b=Ax. Then, plot, via mesh, function f in a square around the true value x - use also the contour statement. What do you observe? Repeat the above procedure by assuming that b=Ax+e, where e is a "small noise" vector. What do you observe?

Figure 6: mesh and contour plots for function f without noise. The red cross marks the true value  $\mathbf{x}$ 



We observe that function  $f(\mathbf{x})$  is indeed convex and the The value of the function attains a minimum at the point  $\mathbf{x}$  (where  $\mathbf{b} = \mathbf{A}\mathbf{x}$ )

Figure 7: mesh and contour plots for function f with noise. The red cross marks the true value  $\mathbf{x}$ 



We observe that function is still convex regardless the noise, yet the minimum of  $f(\mathbf{x})$  has been shifted away from the point  $\mathbf{x}$  (where  $\mathbf{b} = \mathbf{A}\mathbf{x}$ )