

5.254 min_dist_between_inflexion

	DESCRIPTION	LINKS	AUTOMATON
Origin	Derived from <code>inflexion</code>		
Constraint	<code>min_dist_between_inflexion(MINDIST, VARIABLES)</code>		
Arguments	<div>MINDIST : <code>int</code> VARIABLES : <code>collection(var=dvar)</code></div>		
Restrictions	<div>MINDIST ≥ 0 MINDIST ≤ VARIABLES <code>required(VARIABLES, var)</code></div>		
Purpose	<div>Given an integer value MINDIST and a sequence of variables VARIABLES enforce MINDIST to be greater than or equal to the smallest distance between two consecutive inflexions in the sequence VARIABLES, or to VARIABLES if no more than one inflexion exists. An <i>inflexion</i> of a sequence of variables VARIABLES is a set of consecutive variables $V_i, V_{i+1}, \dots, V_{j-1}, V_j$ ($i + 1 < j$) such that one of the following conditions holds:<ul style="list-style-type: none">• $V_i < V_{i+1} \wedge V_{i+1} = \dots = V_{j-1} \wedge V_{j-1} > V_j$,• $V_i > V_{i+1} \wedge V_{i+1} = \dots = V_{j-1} \wedge V_{j-1} < V_j$.In this context, the index j is the <i>position</i> of the inflexion (i.e., the first instant when the inflexion is discovered when scanning the sequence of variables VARIABLES from left to right. The <i>distance between two consecutive inflexions</i> is the absolute value of the difference of their corresponding positions.</div>		
Example	<div>(2, (2, 2, 3, 3, 2, 2, 1, 4, 4, 3))</div> <div>Figure 5.550 shows the three inflexions associated with the sequence 2, 2, 3, 3, 2, 2, 1, 4, 4, 3 and their respective positions 5, 8 and 10 in red. The <code>min_dist_between_inflexion</code> constraint holds since its first argument MINDIST = 2 is greater than or equal to the smallest distance 2 between two consecutive inflexions of the sequence of variables VARIABLES.</div>		
Typical	<div>MINDIST > 1 VARIABLES > 3 <code>range(VARIABLES.var) > 1</code></div>		
Symmetries	<ul style="list-style-type: none">• Items of VARIABLES can be <code>reversed</code>.• One and the same constant can be <code>added</code> to the <code>var</code> attribute of all items of VARIABLES.		
Counting			

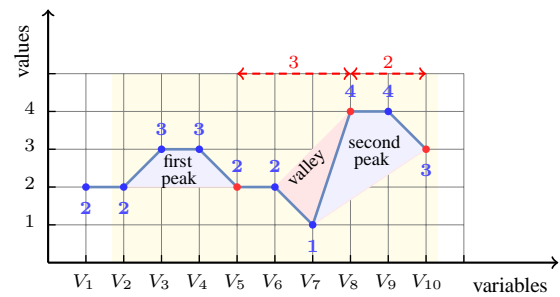
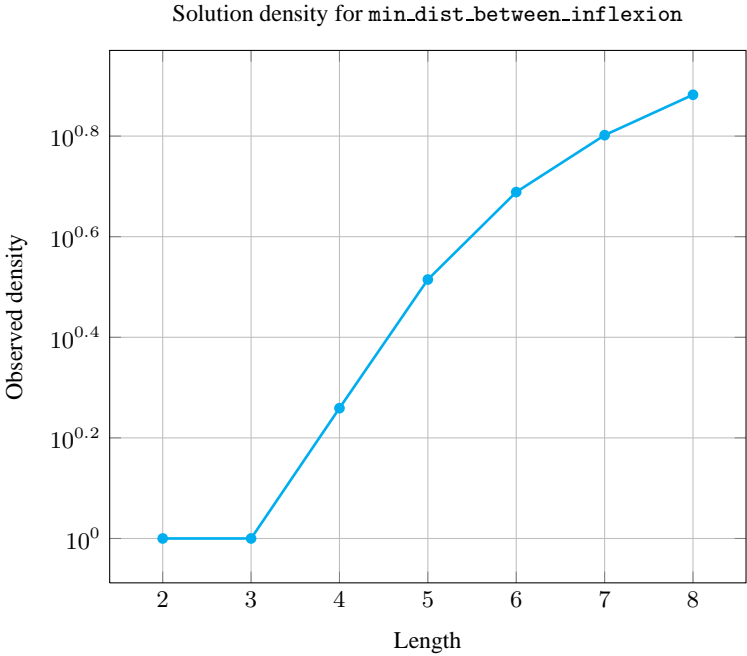
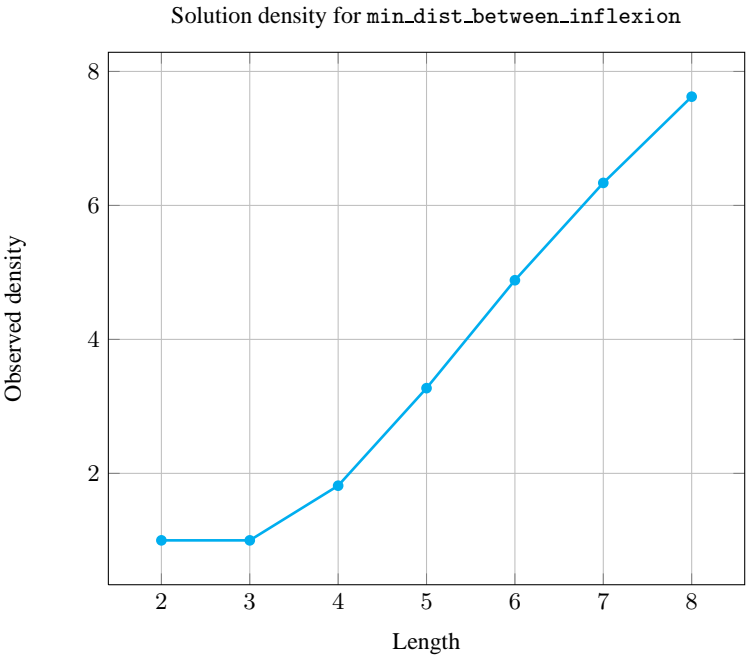


Figure 5.550: Illustration of the **Example** slot: a sequence of ten variables $V_1, V_2, V_3, V_4, V_5, V_6, V_7, V_8, V_9, V_{10}$ respectively fixed to values 2, 2, 3, 3, 2, 2, 1, 4, 4, 3 and its three inflexions, two peaks and one valley; each red point denotes an instant where a new inflexion is discovered while scanning the sequence from left to right; as shown by the rightmost arrow, the minimum distance between two consecutive inflexions is equal to 2.

Length (n)	2	3	4	5	6	7	8
Solutions	9	64	1135	25444	574483	13287476	328156407

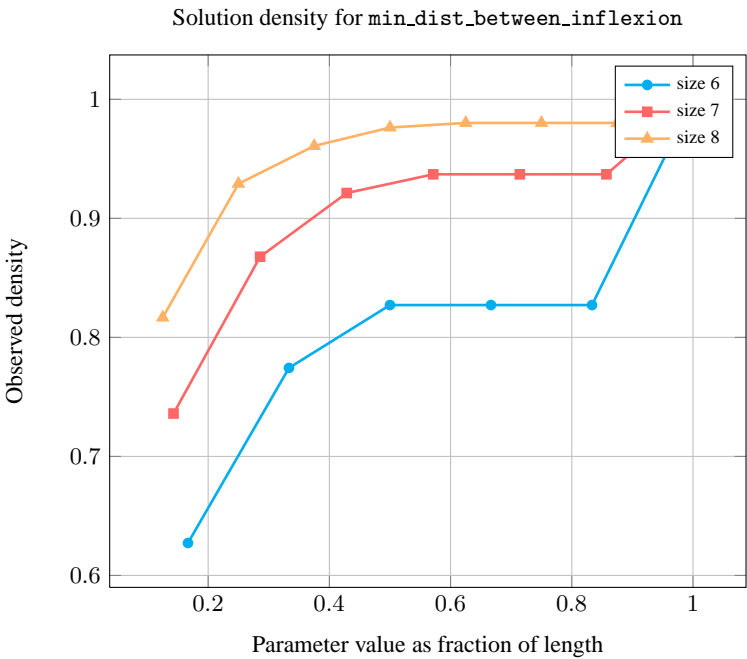
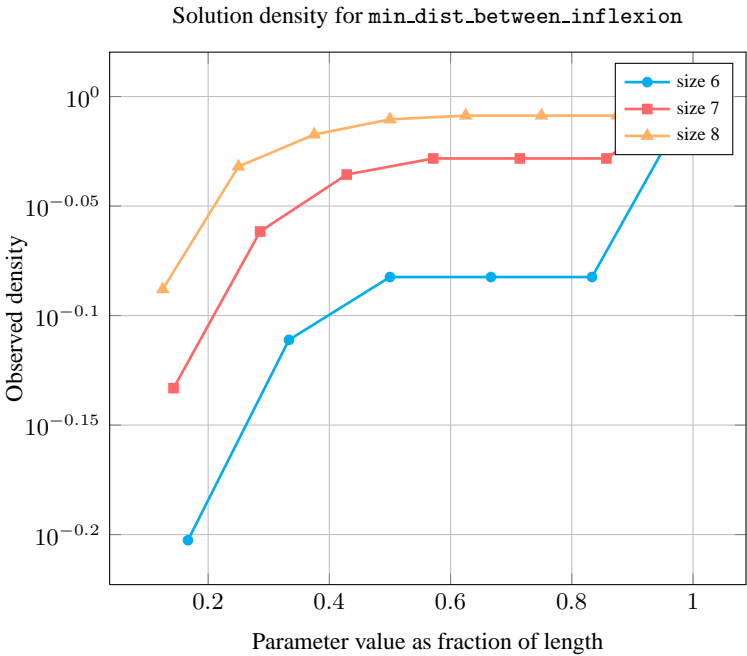
Number of solutions for min_dist_between_inflexion: domains 0.. n





Length (<i>n</i>)		2	3	4	5	6	7	8
Total		9	64	1135	25444	574483	13287476	328156407
Parameter value	1	-	-	170	3598	73794	1543512	35152278
	2	9	-	170	4690	91098	1819764	39992562
	3	-	64	170	4690	97314	1932012	41360676
	4	-	-	625	4690	97314	1965012	42025560
	5	-	-	-	7776	97314	1965012	42192870
	6	-	-	-	-	117649	1965012	42192870
	7	-	-	-	-	-	2097152	42192870
	8	-	-	-	-	-	-	43046721

Solution count for min_dist_between_inflexion: domains 0..*n*



See also

common keyword: [inflexion](#), [longest_decreasing_sequence](#),
[longest_increasing_sequence](#), [peak](#), [valley](#) (*sequence*).

Keywords

characteristic of a constraint: automaton, automaton with counters, automaton with same input symbol.
combinatorial object: sequence.
constraint network structure: sliding cyclic(1) constraint network(3).

Figure 5.551 depicts the automaton associated with the `min_dist_between_inflexion` constraint.

s	: stationary mode	$(=*)$
$i0$: increasing mode (no inflexion yet found)	$(< \{< =\}^*)$
$d0$: decreasing mode (no inflexion yet found)	$(> \{> =\}^*)$
$i1$: increasing mode (at least one inflexion already found)	$(< \{< =\}^*)$
$d1$: decreasing mode (at least one inflexion already found)	$(> \{> =\}^*)$

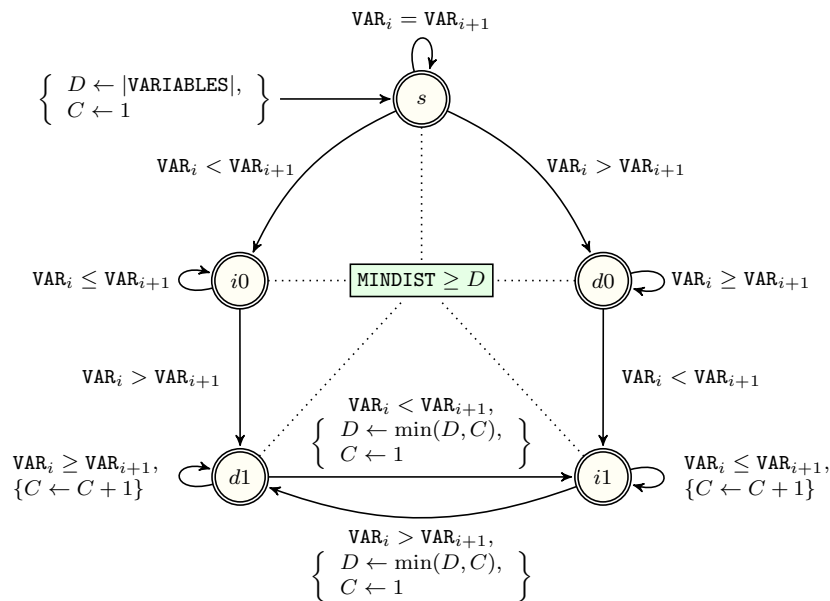


Figure 5.551: Automaton of the `min_dist_between_inflexion` constraint (state s means that we are in *stationary* mode, state $i0$ means that we are in *increasing* mode and that we did not yet found any inflexion, state $d0$ means that we are in *decreasing* mode and that we did not yet found any inflexion, state $i1$ means that we are in *increasing* mode and that we already found at least one inflexion, state $d1$ means that we are in *decreasing* mode and that we already found at least one inflexion, the minimum distance between two consecutive inflexions is updated each time we switch from $i1$ to $d1$ mode – or conversely from $d1$ to $i1$ mode – and the counter D is updated accordingly)

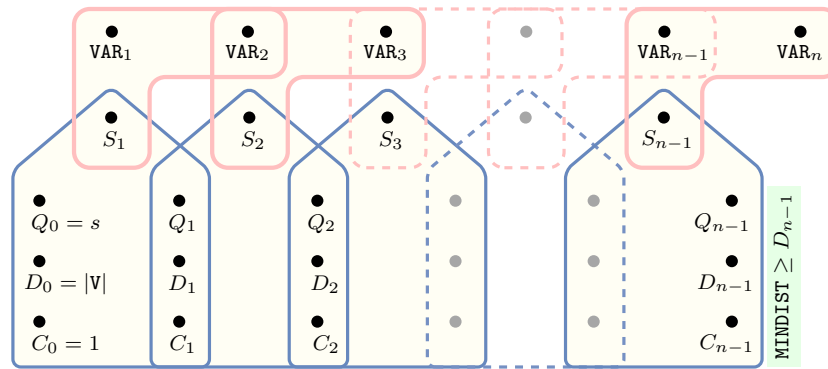


Figure 5.552: Hypergraph of the reformulation corresponding to the automaton of the `min_dist_between_inflexion` constraint where `V` is a shortcut for `VARIABLES` (since all states of the automaton are accepting there is no restriction on the last variable Q_{n-1})

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