2098  $\overline{NARC}$ , PATH

## sliding\_sum 5.352

DESCRIPTION	LINKS	GRAPH

Origin **CHIP** 

Constraint sliding\_sum(LOW, UP, SEQ, VARIABLES)

Synonym sequence.

Arguments LOW int UP int

> SE<sub>Q</sub> int VARIABLES

: collection(var-dvar)

Restrictions UP > LOW SEQ > 0

 $SEQ \le |VARIABLES|$ 

 ${\color{red} \textbf{required}}({\tt VARIABLES}, {\tt var})$ 

Constrains all sequences of SEQ consecutive variables of the collection VARIABLES so Purpose that the sum of the variables belongs to interval [LOW, UP].

Example  $(3,7,4,\langle 1,4,2,0,0,3,4\rangle)$ 

> The example considers all sliding sequences of SEQ = 4 consecutive values of  $\langle 1, 4, 2, 0, 0, 3, 4 \rangle$  collection and constraints the sum to be in [LOW, UP] = [3, 7]. The sliding\_sum constraint holds since the sum associated with the corresponding subsequences  $1\ 4\ 2\ 0$ ,  $4\ 2\ 0$ , 0,  $2\ 0\ 0$ , and  $0\ 0\ 3\ 4$  are respectively 7, 6, 5 and 7.

**Typical**  ${\tt LOW} \ge 0$ 

Algorithm

 $\mathtt{UP} > 0$ 

 ${\tt SEQ}>1$ 

SEQ < |VARIABLES|  ${\tt VARIABLES.var} \geq 0$ 

UP < sum(VARIABLES.var)</pre>

**Symmetry** Items of VARIABLES can be reversed.

Arg. properties • Contractible wrt. VARIABLES when SEQ = 1.

• Prefix-contractible wrt. VARIABLES.

• Suffix-contractible wrt. VARIABLES.

Beldiceanu and Carlsson [30] have proposed a first incomplete filtering algorithm for the sliding\_sum constraint. In 2008, Maher et al. showed in [273] that the sliding\_sum constraint has a solution "if and only there are no negative cycles in the flow graph associated with the dual linear program" that encodes the conjunction of inequalities. They derive a bound-consistency filtering algorithm from this fact.

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Systems sliding\_sum in MiniZinc.

See also common keyword: sliding\_distribution(sliding sequence constraint).

part of system of constraints: sum\_ctr.
soft variant: relaxed\_sliding\_sum.
used in graph description: sum\_ctr.

Keywords characteristic of a constraint: hypergraph, sum.

combinatorial object: sequence.

constraint type: decomposition, sliding sequence constraint, system of constraints.

filtering: linear programming, flow, bound-consistency.

 $\overline{NARC}$ , PATH

 Arc input(s)
 VARIABLES

 Arc generator
 PATH → collection

 Arc arity
 SEQ

 Arc constraint(s)
 • sum\_ctr(collection, ≥, LOW)

 • sum\_ctr(collection, ≤, UP)

 Graph property(ies)
 NARC= |VARIABLES| - SEQ + 1

## Graph model

We use sum\_ctr as an arc constraint. sum\_ctr takes a collection of domain variables as its first argument.

Parts (A) and (B) of Figure 5.706 respectively show the initial and final graph associated with the **Example** slot. Since all arc constraints hold (i.e., because of the graph property NARC = |VARIABLES| - SEQ + 1) the final graph corresponds to the initial graph.

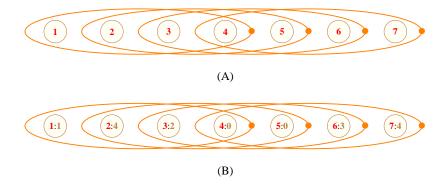


Figure 5.706: (A) Initial and (B) final graph of the sliding\_sum $(3,7,4,\langle 1,4,2,0,0,3,4\rangle)$  constraint of the **Example** slot where each ellipse represents an hyperedge involving SEQ = 4 vertices (e.g., the first ellipse represents the constraint  $1+4+2+0 \in [3,7]$ )

## Signature

Since we use the PATH arc generator with an arity of SEQ on the items of the VARIABLES collection, the expression |VARIABLES| - SEQ + 1 corresponds to the maximum number of arcs of the final graph. Therefore we can rewrite the graph property NARC = |VARIABLES| - SEQ + 1 to  $NARC \ge |VARIABLES| - SEQ + 1$  and simplify  $\overline{NARC}$  to  $\overline{NARC}$ .

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