CHAPTER 9

9.1 The flop counts for the tridiagonal algorithm in Fig. 9.6 can be summarized as

	Mult/Div	Add/Subtr	Total
Forward elimination	3(n – 1)	2(n – 1)	5(n – 1)
Back substitution	2n – 1	n – 1	3n – 2
Total	5n – 4	3n – 3	8n – 7

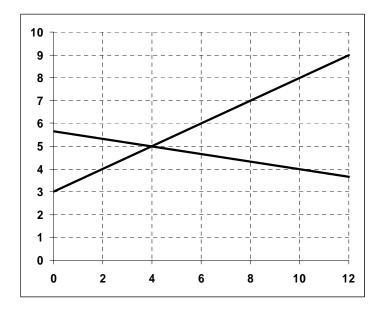
Thus, as n increases, the effort is much, much less than for a full matrix solved with Gauss elimination which is proportional to n^3 .

9.2 The equations can be expressed in a format that is compatible with graphing x_2 versus x_1 :

$$x_2 = 0.5x_1 + 3$$

$$x_2 = -\frac{1}{6}x_1 + \frac{34}{6}$$

which can be plotted as



Thus, the solution is $x_1 = 4$, $x_2 = 5$. The solution can be checked by substituting it back into the equations to give

$$4(4) - 8(5) = 16 - 40 = -24$$

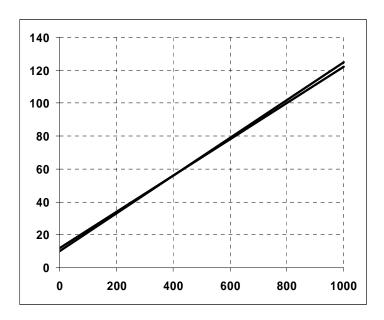
$$4 + 6(5) = 4 + 30 = 34$$

9.3 (a) The equations can be expressed in a format that is compatible with graphing x_2 versus x_1 :

$$x_2 = 0.11x_1 + 12$$

$$x_2 = 0.114943x_1 + 10$$

which can be plotted as



Thus, the solution is approximately $x_1 = 400$, $x_2 = 60$. The solution can be checked by substituting it back into the equations to give

$$-1.1(400) + 10(60) = 160 \approx 120$$

$$-2(400) + 17.4(60) = 244 \approx 174$$

Therefore, the graphical solution is not very good.

- (b) Because the lines have very similar slopes, you would expect that the system would be ill-conditioned
- (c) The determinant can be computed as

$$\begin{vmatrix} -1.1 & 10 \\ -2 & 17.4 \end{vmatrix} = -1.1(17.2) - 10(-2) = -19.14 + 20 = 0.86$$

This result is relatively low suggesting that the solution is ill-conditioned.

9.4 (a) The determinant can be evaluated as

$$D = 0 \begin{bmatrix} 2 & -1 \\ -2 & 0 \end{bmatrix} - (-3) \begin{bmatrix} 1 & -1 \\ 5 & 0 \end{bmatrix} + 7 \begin{bmatrix} 1 & 2 \\ 5 & -2 \end{bmatrix}$$

$$D = 0(-2) + 3(5) + 7(-12) = -69$$

(b) Cramer's rule

$$x_1 = \frac{\begin{vmatrix} 2 & -3 & 7 \\ 3 & 2 & -1 \\ 2 & -2 & 0 \end{vmatrix}}{-69} = \frac{-68}{-69} = 0.9855$$

$$x_2 = \frac{\begin{vmatrix} 0 & 2 & 7 \\ 1 & 3 & -1 \\ 5 & 2 & 0 \end{vmatrix}}{-69} = \frac{-101}{-69} = 1.4638$$

$$x_3 = \frac{\begin{vmatrix} 0 & -3 & 2 \\ 1 & 2 & 3 \\ 5 & -2 & 2 \end{vmatrix}}{-69} = \frac{-63}{-69} = 0.9130$$

(c) Pivoting is necessary, so switch the first and third rows,

$$5x_1 - 2x_2 = 2$$

$$x_1 + 2x_2 - x_3 = 3$$

$$-3x_2 + 7x_3 = 2$$

Multiply pivot row 1 by 1/5 and subtract the result from the second row to eliminate the a_{21} term.

$$5x_1 - 2x_2 = 2$$

$$2.4x_2 - x_3 = 2.6$$

$$-3x_2 + 7x_3 = 2$$

Pivoting is necessary so switch the second and third row,

$$5x_1 - 2x_2 = 2$$

$$-3x_2 + 7x_3 = 2$$

$$2.4x_2 - x_3 = 2.6$$

Multiply pivot row 2 by 2.4/(-3) and subtract the result from the third row to eliminate the a_{32} term.

$$5x_1 - 2x_2 = 2$$

$$-3x_2 + 7x_3 = 2$$

$$4.6x_3 = 4.2$$

The solution can then be obtained by back substitution

$$x_3 = \frac{4.2}{4.6} = 0.913043$$

$$x_2 = \frac{2 - 7(0.913043)}{-3} = 1.463768$$

$$x_1 = \frac{2 + 2(1.463768)}{5} = 0.985507$$

(d)
$$-3(1.463768) + 7(0.913043) = 2$$

$$0.985507 + 2(1.463768) - (0.913043) = 3$$

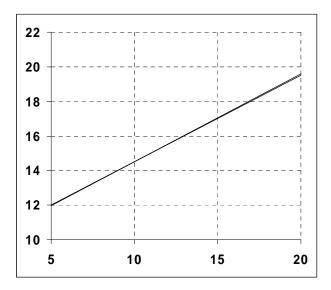
$$5(0.985507) - 2(1.463768) = 2$$

9.5 (a) The equations can be expressed in a format that is compatible with graphing x_2 versus x_1 :

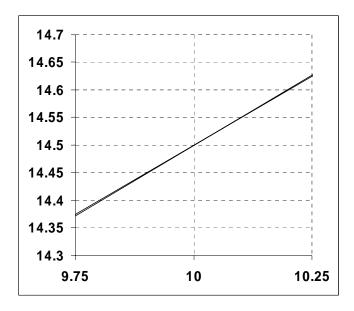
$$x_2 = 0.5x_1 + 9.5$$

$$x_2 = 0.51x_1 + 9.4$$

The resulting plot indicates that the intersection of the lines is difficult to detect:



Only when the plot is zoomed is it at all possible to discern that solution seems to lie at about $x_1 = 14.5$ and $x_2 = 10$.



(b) The determinant can be computed as

$$\begin{vmatrix} 0.5 & -1 \\ 1.02 & -2 \end{vmatrix} = 0.5(-2) - (-1)(1.02) = 0.02$$

which is close to zero.

- (c) Because the lines have very similar slopes and the determinant is so small, you would expect that the system would be ill-conditioned
- (d) Multiply the first equation by 1.02/0.5 and subtract the result from the second equation to eliminate the x_1 term from the second equation,

$$0.5x_1 - x_2 = -9.5$$

$$0.04x_2 = 0.58$$

The second equation can be solved for

$$x_2 = \frac{0.58}{0.04} = 14.5$$

This result can be substituted into the first equation which can be solved for

$$x_1 = \frac{-9.5 + 14.5}{0.5} = 10$$

(e) Multiply the first equation by 1.02/0.52 and subtract the result from the second equation to eliminate the x_1 term from the second equation,

$$0.52x_1 - x_2 = -9.5$$
$$-0.03846x_2 = -0.16538$$

The second equation can be solved for

$$x_2 = \frac{-0.16538}{-0.03846} = 4.3$$

This result can be substituted into the first equation which can be solved for

$$x_1 = \frac{-9.5 + 4.3}{0.52} = -10$$

Interpretation: The fact that a slight change in one of the coefficients results in a radically different solution illustrates that this system is very ill-conditioned.

9.6 (a) Multiply the first equation by -3/10 and subtract the result from the second equation to eliminate the x_1 term from the second equation. Then, multiply the first equation by 1/10 and subtract the result from the third equation to eliminate the x_1 term from the third equation.

$$10x_1 + 2x_2 - x_3 = 27$$
$$-5.4x_2 + 1.7x_3 = -53.4$$
$$0.8x_2 + 5.1x_3 = -24.2$$

Multiply the second equation by 0.8/(-5.4) and subtract the result from the third equation to eliminate the x_2 term from the third equation,

$$10x_1 + 2x_2$$
 $-x_3 = 27$
 $-5.4x_2$ $+1.7x_3 = -53.4$
 $5.351852x_3 = -32.11111$

Back substitution can then be used to determine the unknowns

$$x_3 = \frac{-32.11111}{5.351852} = -6$$

$$x_2 = \frac{(-53.4 - 1.7(-6))}{-5.4} = 8$$

$$x_1 = \frac{(27 - 6 - 2(8))}{10} = 0.5$$

(b) Check:

$$10(0.5) + 2(8) - (-6) = 27$$
$$-3(0.5) - 6(8) + 2(-6) = -61.5$$
$$0.5 + 8 + 5(-6) = -21.5$$

9.7 (a) Pivoting is necessary, so switch the first and third rows,

$$-8x_1 + x_2 - 2x_3 = -20$$
$$-3x_1 - x_2 + 7x_3 = -34$$
$$2x_1 - 6x_2 - x_3 = -38$$

Multiply the first equation by -3/(-8) and subtract the result from the second equation to eliminate the a_{21} term from the second equation. Then, multiply the first equation by 2/(-8) and subtract the result from the third equation to eliminate the a_{31} term from the third equation.

$$-8x_1 + x_2 -2x_3 = -20$$

$$-1.375x_2 + 7.75x_3 = -26.5$$

$$-5.75x_2 -1.5x_3 = -43$$

Pivoting is necessary so switch the second and third row,

$$-8x_1 + x_2 -2x_3 = -20$$

$$-5.75x_2 -1.5x_3 = -43$$

$$-1.375x_2 + 7.75x_3 = -26.5$$

Multiply pivot row 2 by -1.375/(-5.75) and subtract the result from the third row to eliminate the a_{32} term.

$$-8x_1 + x_2 -2x_3 = -20$$

$$-5.75x_2 -1.5x_3 = -43$$

$$8.108696x_3 = -16.21739$$

The solution can then be obtained by back substitution

$$x_3 = \frac{-16.21739}{8.108696} = -2$$

$$x_2 = \frac{-43 + 1.5(-2)}{-5.75} = 8$$

$$x_1 = \frac{-20 + 2(-2) - 1(8)}{-8} = 4$$

(b) Check:

$$2(4) - 6(8) - (-2) = -38$$

$$-3(4)-(8)+7(-2)=-34$$

$$-8(4) + (8) - 2(-2) = -20$$

9.8 Multiply the first equation by -0.4/0.8 and subtract the result from the second equation to eliminate the x_1 term from the second equation.

$$\begin{bmatrix} 0.8 & -0.4 \\ & 0.6 & -0.4 \\ & -0.4 & 0.8 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 41 \\ 45.5 \\ 105 \end{bmatrix}$$

Multiply pivot row 2 by -0.4/0.6 and subtract the result from the third row to eliminate the x_2 term.

$$\begin{bmatrix} 0.8 & -0.4 \\ & 0.6 & -0.4 \\ & & 0.533333 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 41 \\ 45.5 \\ 135.3333 \end{bmatrix}$$

The solution can then be obtained by back substitution

$$x_3 = \frac{135.3333}{0.5333333} = 253.75$$

$$x_2 = \frac{45.5 - (-0.4)253.75}{0.6} = 245$$

$$x_1 = \frac{41 - (-0.4)245}{0.8} = 173.75$$

(b) Check:

$$0.8(173.75) - 0.4(245) = 41$$

$$-0.4(173.75) + 0.8(245) - 0.4(253.75) = 25$$

$$-0.4(245) + 0.8(253.75) = 105$$

9.9 Mass balances can be written for each of the reactors as

$$500 - Q_{13}c_1 - Q_{12}c_1 + Q_{21}c_2 = 0$$
$$Q_{12}c_1 - Q_{21}c_2 - Q_{23}c_2 = 0$$

$$200 + Q_{13}c_1 + Q_{23}c_2 - Q_{33}c_3 = 0$$

Values for the flows can be substituted and the system of equations can be written in matrix form as

$$\begin{bmatrix} 130 & -30 & 0 \\ -90 & 90 & 0 \\ -40 & -60 & 120 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 500 \\ 0 \\ 200 \end{bmatrix}$$

The solution can then be developed using MATLAB,

```
>> A=[130 -30 0;-90 90 0;-40 -60 120];

>> B=[500;0;200];

>> C=A\B

C =

5.0000

5.0000

5.8333
```

9.10 Let x_i = the volume taken from pit i. Therefore, the following system of equations must hold

$$0.55x_1 + 0.25x_2 + 0.25x_3 = 4800$$

 $0.30x_1 + 0.45x_2 + 0.20x_3 = 5800$
 $0.15x_1 + 0.30x_2 + 0.55x_3 = 5700$

MATLAB can be used to solve this system of equations for

```
>> A=[0.55 0.25 0.25;0.3 0.45 0.2;0.15 0.3 0.55];
>> b=[4800;5800;5700];
>> x=A\b

x =
    1.0e+003 *
    2.4167
    9.1933
    4.6900
```

Therefore, we take $x_1 = 2416.667$, $x_2 = 9193.333$, and $x_3 = 4690$ m³ from pits 1, 2 and 3 respectively.

9.11 Let c_i = component i. Therefore, the following system of equations must hold

$$15c_1 + 17c_2 + 19c_3 = 3890$$
$$0.30c_1 + 0.40c_2 + 0.55c_3 = 95$$
$$1.0c_1 + 1.2c_2 + 1.5c_3 = 282$$

These can then be solved for $c_1 = 90$, $c_2 = 60$, and $c_3 = 80$.

9.12 Centered differences (recall p. 101 and 103) can be substituted for the derivatives to give

$$0 = D \frac{c_{i-1} - 2c_i + c_{i+1}}{\Delta x^2} - U \frac{c_{i+1} - c_{i-1}}{2\Delta x} - kc_i$$

collecting terms yields

$$-(D+0.5U\Delta x)c_{i-1} + (2D+k\Delta x^{2})c_{i} - (D-0.5U\Delta x)c_{i+1} = 0$$

Assuming $\Delta x = 1$ and substituting the parameters gives

$$-2.5c_{i-1} + 4.2c_i - 1.5c_{i+1} = 0$$

For the first interior node (i = 1),

$$4.2c_1 - 1.5c_2 = 200$$

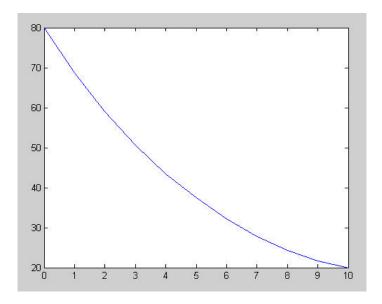
For the last interior node (i = 9)

$$-2.5c_8 + 4.2c_9 = 30$$

These and the equations for the other interior nodes can be assembled in matrix form as

$$\begin{bmatrix} 4.2 & -1.5 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ -2.5 & 4.2 & -1.5 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -2.5 & 4.2 & -1.5 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & -2.5 & 4.2 & -1.5 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -2.5 & 4.2 & -1.5 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & -2.5 & 4.2 & -1.5 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & -2.5 & 4.2 & -1.5 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & -2.5 & 4.2 & -1.5 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & -2.5 & 4.2 & -1.5 \\ 0 & 0 & 0 & 0 & 0 & 0 & -2.5 & 4.2 & -1.5 \\ 0 & 0 & 0 & 0 & 0 & 0 & -2.5 & 4.2 & -1.5 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & -2.5 & 4.2 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \\ c_5 \\ c_6 \\ c_7 \\ c_8 \\ c_9 \end{bmatrix} = \begin{bmatrix} 200 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 30 \end{bmatrix}$$

The following script generates and plots the solution:



9.13 For the first stage, the mass balance can be written as

$$F_1 y_{\text{in}} + F_2 x_2 = F_2 x_1 + F_1 x_1$$

Substituting x = Ky and rearranging gives

$$-\left(1 + \frac{F_2}{F_1}K\right)y_1 + \frac{F_2}{F_1}Ky_2 = -y_{\text{in}}$$

Using a similar approach, the equation for the last stage is

$$y_4 - \left(1 + \frac{F_2}{F_1}K\right)y_5 = -\frac{F_2}{F_1}x_{\text{in}}$$

For interior stages,

$$y_{i-1} - \left(1 + \frac{F_2}{F_1}K\right)y_i + \frac{F_2}{F_1}Ky_{i+1} = 0$$

These equations can be used to develop the following system,

$$\begin{bmatrix} 9 & -8 & 0 & 0 & 0 \\ -1 & 9 & -8 & 0 & 0 \\ 0 & -1 & 9 & -8 & 0 \\ 0 & 0 & -1 & 9 & -8 \\ 0 & 0 & 0 & -1 & 9 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ y_5 \end{bmatrix} = \begin{bmatrix} 0.1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

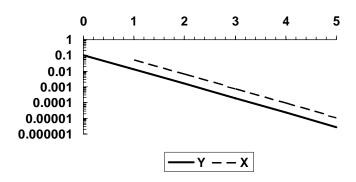
The solution can be developed with MATLAB,

```
>> format long
>> A=[9 -8 0 0 0;
-1 9 -8 0 0;
0 -1 9 -8 0;
0 0 -1 9 -8;
0 0 0 -1 9];
>> B=[0.1;0;0;0;0];
>> Y=A\B

Y =
    0.01249966621272
    0.00156212448931
    0.00019493177388
    0.00002403268445
    0.00000267029827
```

Note that the corresponding values of X can be computed as

Therefore, $y_{\text{out}} = 0.0000026703$ and $x_{\text{out}} = 0.05$. In addition, here is a logarithmic plot of the simulation results versus stage,



9.14 Assuming a unit flow for Q_1 , the simultaneous equations can be written in matrix form as

$$\begin{bmatrix} -2 & 1 & 2 & 0 & 0 & 0 \\ 0 & 0 & -2 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 & -2 & 3 \\ 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & -1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 & -1 & -1 \end{bmatrix} \begin{vmatrix} Q_2 \\ Q_3 \\ Q_4 \\ Q_5 \\ Q_6 \\ Q_7 \end{vmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

These equations can then be solved with MATLAB,

```
>> A=[-2 1 2 0 0 0;

0 0 -2 1 2 0;

0 0 0 0 -2 3;

1 1 0 0 0 0;

0 1 -1 -1 0 0;

0 0 0 1 -1 -1];

>> B=[0 0 0 1 0 0]';

>> Q=A\B

Q =

0.5059

0.4941

0.2588

0.2353

0.1412

0.0941
```

9.15 The solution can be generated with MATLAB,

```
>> A=[1 0 0 0 0 0 0 1 0;
       0 0 1 0 0 0 0 1 0 0;
       0 1 0 3/5 0 0 0 0 0 0;
       -1 0 0 -4/5 0 0 0 0 0;
       0 -1 0 0 0 0 3/5 0 0 0;
       0 \ 0 \ 0 \ 0 \ -1 \ 0 \ -4/5 \ 0 \ 0 \ 0;
       0 \ 0 \ -1 \ -3/5 \ 0 \ 1 \ 0 \ 0 \ 0;
       0 0 0 4/5 1 0 0 0 0 0;
       0 \ 0 \ 0 \ 0 \ 0 \ -1 \ -3/5 \ 0 \ 0 \ 0;
       0 0 0 0 0 0 4/5 0 0 1];
>> B=[0 0 -74 0 0 24 0 0 0 0]';
>> x=A\setminus B
x =
   37.3333
  -46.0000
   74.0000
  -46.6667
   37.3333
   46.0000
  -76.6667
  -74.0000
  -37.3333
   61.3333
```

Therefore, in kN

```
AB = 37.3333 BC = -46 AD = 74 BD = -46.6667 CD = 37.3333 DE = 46 CE = -76.6667 A_x = -74 A_y = -37.3333 E_y = 61.3333
```

9.16

```
function x=pentasol(A,b)
% pentasol: pentadiagonal system solver banded system
   x=pentasol(A,b):
       Solve a pentadiagonal system Ax=b
% input:
   A = pentadiagonal matrix
   b = right hand side vector
% output:
   x = solution vector
% Error checks
[m,n]=size(A);
if m~=n,error('Matrix must be square');end
if length(b)~=m,error('Matrix and vector must have the same number of
rows');end
x=zeros(n,1);
% Extract bands
d=[0;0;diaq(A,-2)];
e=[0;diaq(A,-1)];
f=diaq(A);
q=diaq(A,1);
h=diag(A,2);
delta=zeros(n,1);
epsilon=zeros(n-1,1);
gamma=zeros(n-2,1);
alpha=zeros(n,1);
c=zeros(n,1);
z=zeros(n,1);
% Decomposition
delta(1)=f(1);
epsilon(1)=g(1)/delta(1);
gamma(1)=h(1)/delta(1);
alpha(2)=e(2);
delta(2)=f(2)-alpha(2)*epsilon(1);
epsilon(2) = (g(2) - alpha(2) * gamma(1)) / delta(2);
gamma(2)=h(2)/delta(2);
for k=3:n-2
  alpha(k)=e(k)-d(k)*epsilon(k-2);
 delta(k)=f(k)-d(k)*gamma(k-2)-alpha(k)*epsilon(k-1);
  epsilon(k) = (g(k) - alpha(k) * gamma(k-1)) / delta(k);
  gamma(k)=h(k)/delta(k);
end
alpha(n-1)=e(n-1)-d(n-1)*epsilon(n-3);
delta(n-1)=f(n-1)-d(n-1)*gamma(n-3)-alpha(n-1)*epsilon(n-2);
{\tt epsilon(n-1)=(g(n-1)-alpha(n-1)*gamma(n-2))/delta(n-1);}
alpha(n)=e(n)-d(n)*epsilon(n-2);
```

```
delta(n)=f(n)-d(n)*gamma(n-2)-alpha(n)*epsilon(n-1);
% Forward substitution
c(1)=b(1)/delta(1);
c(2)=(b(2)-alpha(2)*c(1))/delta(2);
for k=3:n
  c(k) = (b(k)-d(k)*c(k-2)-alpha(k)*c(k-1))/delta(k);
end
% Back substitution
x(n)=c(n);
x(n-1)=c(n-1)-epsilon(n-1)*x(n);
for k=n-2:-1:1
 x(k)=c(k)-epsilon(k)*x(k+1)-gamma(k)*x(k+2);
Test of function:
>> A = [8 -2 -1 0 0]
-2 9 -4 -1 0
-1 3 7 -1 -2
0 -4 -2 12 -5
0 0 -7 -3 15];
>> b=[5 2 1 1 5]';
>> x=pentasol(A,b)
x =
    0.7993
    0.5721
    0.2503
    0.5491
    0.5599
```