Lecture 21 – Turing Machines (TMs)

COSE215: Theory of Computation

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PLRG

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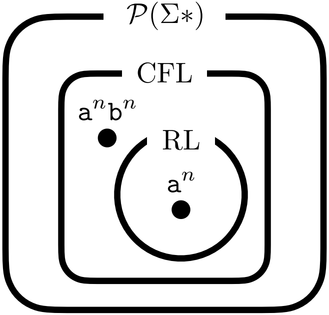
Recall

- A **pushdown automaton (PDA)** is an extension of FA with a **stack**.



PDA_{FS}
(by final states)

$\parallel$

PDA_{ES}
(by empty stacks)

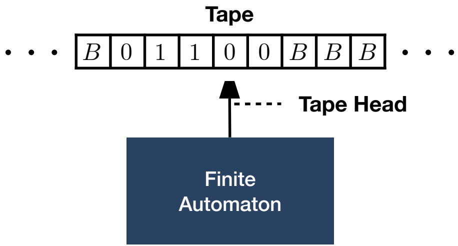
$\parallel$

CFG

- Then, how about extensions of finite automata with other structures?
- Do they still represent the class of **context-free languages (CFLs)**?

Contents

Turing Machines



A **Turing machine (TM)** is a **deterministic** FA with a **tape**.

- A **tape** is an infinite sequence of cells containing **tape symbols**. (The **blank symbol** B is a special symbol representing an empty cell.)
- A **tape head** points to the current cell.
- A **transition** performs the following operations depending on the current 1) **state** and 2) **tape symbol** pointed by the tape head:
  - **Change** the current **state**.
  - **Replace** the current **tape symbol** pointed by the tape head.
  - **Move** the **tape head** left or right.

Definition of Turing Machines

Definition (Turing Machines)

A **Turing machine (TM)** is a 7-tuple

$$M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$$

where

- Q is a finite set of **states**.
- Σ is a finite set of **input symbols**.
- Γ is a finite set of **tape symbols** containing input symbols ($\Sigma \subseteq \Gamma$).
- $\delta : Q \times \Gamma \rightharpoonup Q \times \Gamma \times \{L, R\}$ is a **transition function**.
- $q_0 \in Q$ is the **initial state**.
- $B \in \Gamma \setminus \Sigma$ is the **blank symbol**.
- $F \subseteq Q$ is the set of **final states**.

Note that $\rightharpoonup$ denotes a **partial function** (i.e., a function that may not be defined for some inputs).

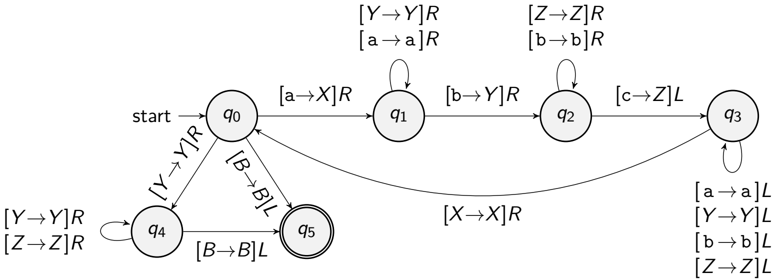
Definition of Turing Machines – Example

$$M_1 = (\{q_0, q_1, q_2\}, \{0, 1\}, \{0, 1, B\}, \delta, q_0, B, \{q_2\})$$

$$\begin{array}{lll}
\delta(q_0, \mathtt{a}) = (q_1, X, R) & \delta(q_0, Y) = (q_4, Y, R) & \delta(q_0, B) = (q_5, B, L) \\
\delta(q_1, \mathtt{a}) = (q_1, \mathtt{a}, R) & \delta(q_1, Y) = (q_1, Y, R) & \delta(q_1, \mathtt{b}) = (q_2, Y, R) \\
\delta(q_2, \mathtt{b}) = (q_2, \mathtt{b}, R) & \delta(q_2, Z) = (q_2, Z, R) & \delta(q_2, \mathtt{c}) = (q_3, Z, L) \\
\delta(q_3, \mathtt{a}) = (q_3, \mathtt{a}, L) & \delta(q_3, Y) = (q_3, Y, L) & \delta(q_3, \mathtt{b}) = (q_3, \mathtt{b}, L) \\
\delta(q_3, Z) = (q_3, Z, L) & \delta(q_3, X) = (q_0, X, R) & \delta(q_4, Y) = (q_4, Y, R) \\
\delta(q_4, Z) = (q_4, Z, R) & \delta(q_4, B) = (q_5, B, L) &
\end{array}$$

The **transition diagram** of M_1 is as follows:

$M_1 =$



Turing Machines in Scala

$$M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$$

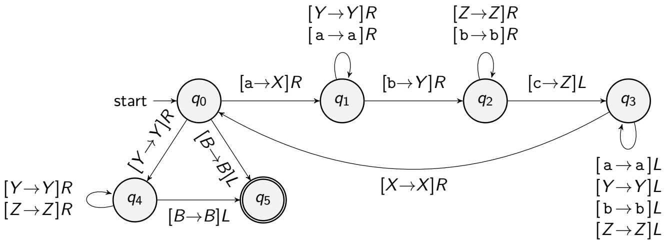
$$\delta : Q \times \Gamma \rightharpoonup Q \times \Gamma \times \{L, R\}$$

```scala
type State = Int
type Symbol = Char
type TapeSymbol = Char
enum HeadMove { case L, R }
import HeadMove.*

// The definition of Turing machines
case class TM(
  states: Set[State],
  symbols: Set[Symbol],
  tapeSymbols: Set[TapeSymbol],
  trans: Map[(State, TapeSymbol), (State, TapeSymbol, HeadMove)],
  initState: State,
  blank: TapeSymbol,
  finalStates: Set[State],
)
```

Turing Machines in Scala – Example

$M_1 =$




```scala
val tm1: TM = TM(
  states = Set(0, 1, 2, 3, 4, 5), symbols = Set('a', 'b', 'c'),
  tapeSymbols = Set('a', 'b', 'c', 'X', 'Y', 'Z', 'B'),
  trans = Map(
    (0, 'a') -> (1, 'X', R),  (0, 'Y') -> (4, 'Y', R),  (0, 'B') -> (5, 'B', L),
    (1, 'a') -> (1, 'a', R),  (1, 'Y') -> (1, 'Y', R),  (1, 'b') -> (2, 'Y', R),
    (2, 'b') -> (2, 'b', R),  (2, 'Z') -> (2, 'Z', R),  (2, 'c') -> (3, 'Z', L),
    (3, 'a') -> (3, 'a', L),  (3, 'b') -> (3, 'b', L),  (3, 'Y') -> (3, 'Y', L),
    (3, 'Z') -> (3, 'Z', L),  (3, 'X') -> (0, 'X', R),  (4, 'Y') -> (4, 'Y', R),
    (4, 'Z') -> (4, 'Z', R),  (4, 'B') -> (5, 'B', L),
  ),
  initState = 0, blank = 'B', finalStates = Set(5),
)
```

Configurations

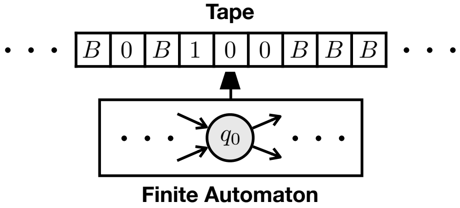
Definition (Configurations of Turing Machines)

A **configuration** of a Turing machine M is in the form of

$$X_1 \cdots X_{i-1} \; qX_i \; X_{i+1} \cdots X_n$$

where

- $q \in Q$ is the **current state**.
- $X_1 \cdots X_n \in \Gamma^*$ is the **sub-tape** between the left- and the right-most 1) non-blank symbols or 2) the symbol under the tape head.
- $X_i \in \Gamma$ is the **current tape symbol** under the tape head.



$\equiv$ $0B1 \; q_0 0 \; 0$

Configurations

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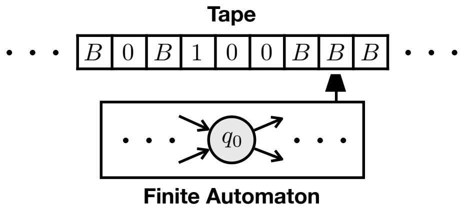


$$\equiv \quad 0B100B \, q_0 B$$

One-Step Moves

Definition (One-Step Moves of Turing Machines)

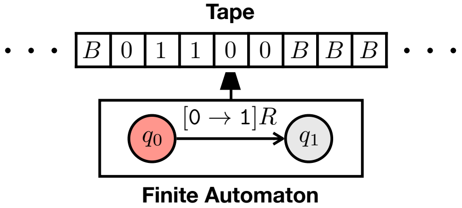
A **one-step move** ($\vdash$) of a Turing machine M is a transition from a configuration to another configuration.

- If $\delta(q, X_i) = (p, Y, L)$,

$$X_1 \cdots X_{i-1} \; qX_i \; X_{i+1} \cdots X_n \vdash X_1 \cdots \; pX_{i-1} \; YX_{i+1} \cdots X_n$$

- If $\delta(q, X_i) = (p, Y, R)$,

$$X_1 \cdots X_{i-1} \; qX_i \; X_{i+1} \cdots X_n \vdash X_1 \cdots X_{i-1} Y \; pX_{i+1} \cdots X_n$$



$011 \; q_0 0 \; 0$

One-Step Moves

Definition (One-Step Moves of Turing Machines)

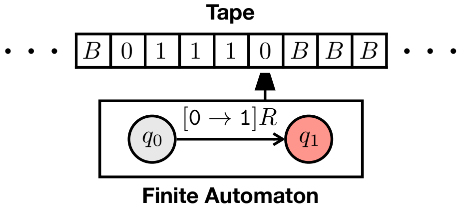
A **one-step move** ($\vdash$) of a Turing machine M is a transition from a configuration to another configuration.

- If $\delta(q, X_i) = (p, Y, L)$,

$$X_1 \cdots X_{i-1}\, qX_i\, X_{i+1} \cdots X_n \vdash X_1 \cdots pX_{i-1}\, YX_{i+1} \cdots X_n$$

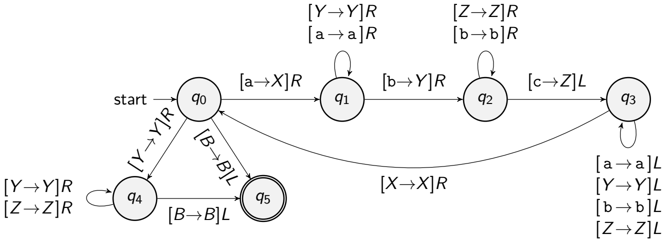
- If $\delta(q, X_i) = (p, Y, R)$,

$$X_1 \cdots X_{i-1}\, qX_i\, X_{i+1} \cdots X_n \vdash X_1 \cdots X_{i-1} Y\, pX_{i+1} \cdots X_n$$



$$011\, q_0 0\, 0 \vdash 0111\, q_1 0$$

One-Step Moves

$M_1 =$ 

$$
\begin{array}{rlll}
q_0\mathtt{a}\,\mathtt{bc} & \vdash & X\,q_1\mathtt{b}\,\mathtt{c} & (\because \delta(q_0, \mathtt{a}) = (q_1, X, R)) \\
 & \vdash & XY\,q_2\mathtt{c} & (\because \delta(q_1, \mathtt{b}) = (q_2, Y, R)) \\
 & \vdash & X\,q_3Y\,Z & (\because \delta(q_2, \mathtt{c}) = (q_3, Z, L)) \\
 & \vdash & q_3X\,YZ & (\because \delta(q_3, Y) = (q_3, Y, L)) \\
 & \vdash & X\,q_0Y\,Z & (\because \delta(q_3, X) = (q_0, X, R)) \\
 & \vdash & XY\,q_4Z & (\because \delta(q_0, Y) = (q_4, Y, R)) \\
 & \vdash & XYZ\,q_4B & (\because \delta(q_4, Z) = (q_4, Z, R)) \\
 & \vdash & XY\,q_5Z & (\because \delta(q_4, B) = (q_5, B, L)) \\
 & \not\vdash & &
\end{array}
$$

Halting of Turing Machines

Definition (Halting of Turing Machines)

A Turing machine $M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$ **halts** on input w if there is a sequence of one-step moves from the **initial configuration** $q_0\ w$ to a configuration having no more possible moves:

$$q_0 w \vdash^* \alpha q \beta \nvdash$$

for some $\alpha, \beta \in \Gamma^*$ and $q \in Q$.

For example, the Turing machine M_1 halts on input abc:

$$q_0\mathtt{a}\,\mathtt{bc} \vdash^* XY\, q_5 Z \nvdash$$

Language of Turing Machines

Definition (Acceptance by Turing Machines)

For a given Turing machine $M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$, M accepts a word $w \in \Sigma^*$ if M **halts** on w with a **final state**:

$$q_0 \; w \vdash^* \alpha \; q_f \; \beta \not\vdash$$

for some $q_f \in F$ and $\alpha, \beta \in \Gamma^*$.

Definition (Language of Turing Machines)

For a given Turing machine $M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$, the **language** of M is defined as follows:

$$L(M) = \{w \in M \text{ accepts } w\}$$

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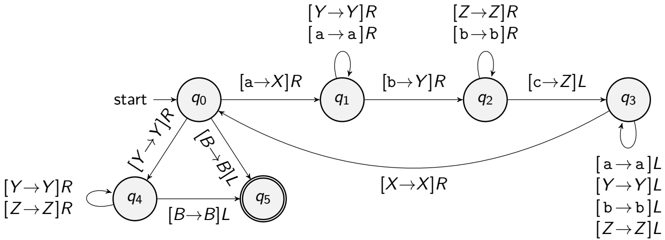
Definition (Recursively Enumerable Languages (RELs))

A language L is **recursively enumerable** if there exists a Turing machine M such that $L = L(M)$.

For example, what is the language of the Turing machine M_1?

$M_1 =$



It accepts the following language. Thus, L is **recursively enumerable**:

$$L(M_1) = L = \{\mathtt{a}^n\mathtt{b}^n\mathtt{c}^n \mid n \geq 0\}$$

Language of Turing Machines

```
type Tape = String
case class Config(state: State, tape: Tape, index: Int)

case class TM(...):
  // A one-step move in a Turing machine
  def move(config: Config): Option[Config] = ...

  // The initial configuration of a Turing machine
  def init(word: Word): Config = word match
    case a <| x => Config(initState, word, 0)
    case _      => Config(initState, blank.toString, 0)

  // The configuration at which the TM halts
  final def haltsAt(config: Config): Config = move(config) match
    case None       => config
    case Some(next) => haltsAt(next)

  // The acceptance of a word by TM
  def accept(w: Word): Boolean = finalStates.contains(haltsAt(init(w)).state)

tm1.accept("abc")     // true
tm1.accept("aabbcc")  // true
tm1.accept("abab")    // false
```

Turing Machines as Computing Machines

Definition (Turing Computable Functions)

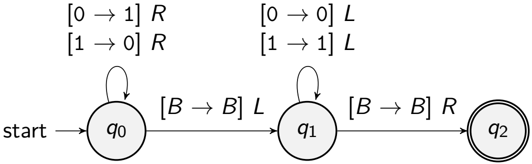
A partial function $f : \Sigma^* \rightharpoonup \Sigma^*$ is **Turing-computable** if there exists a Turing machine $M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$ such that

$$q_0 \; w \vdash^* q_f \; f(w) \nvdash$$

for some $q_f \in F$ and all $w \in \Sigma^*$, such that $f(w)$ is defined.

Turing Machines as Computing Machines

$M_2 =$



For example, TM M_2 defines the following function $f : \{0, 1\}^* \to \{0, 1\}^*$:

$$f(w) = (\text{the flip of each bit in } w)$$

For example, `0110` is transformed to `1001` by M_2:

$$q_0\ \texttt{0110} \vdash^* q_2\ \texttt{1001} \nvdash$$

and `1011100` is transformed to `0100011` by M_2[1]:

$$q_0\ \texttt{1011100} \vdash^* q_2\ \texttt{0100011} \nvdash$$

So, f is a **Turing-computable** function.

[1] https://plrg.korea.ac.kr/courses/cose215/materials/tm-flip.pdf

```scala
case class TM(...):
  // The computation with a given word by TM
  def compute(word: Word): Option[Word] =
    val Config(state, tape, k) = haltsAt(init(word))
    val (n, x) = (tape.size, tape(k))
    if (k == 0 && finalStates.contains(state)) {
      if (x == blank && n == 1) Some("")
      else if (tape.forall(symbols.contains)) Some(tape.mkString)
      else None
    } else None

val tm2: TM = TM(
  states = Set(0, 1, 2), symbols = Set('0', '1'),
  tapeSymbols = Set('0', '1', 'B'),
  trans = Map(
    (0, '0') -> (0, '1', R),  (0, '1') -> (0, '0', R),  (0, 'B') -> (1, 'B', L),
    (1, '0') -> (1, '0', L),  (1, '1') -> (1, '1', L),  (1, 'B') -> (2, 'B', R),
  ),
  initState = 0, blank = 'B', finalStates = Set(2),
)
tm2.compute("0110")    // Some("1001")
tm2.compute("1011100") // Some("0100011")
```

Summary

Next Lecture

- Examples of Turing Machines

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