

Lecture 10 – Fault Localization

AAA705: Software Testing and Quality Assurance

Jihyeok Park



2024 Spring

Recall

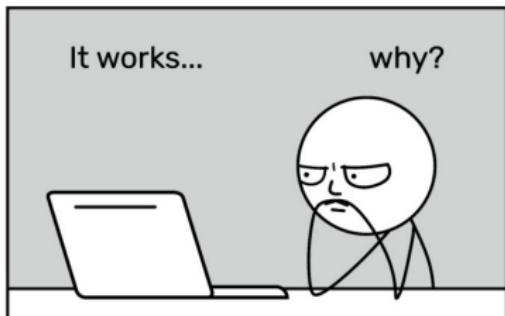
- **Regression Testing**

- Regression Fault
- Test Suite Minimization
- Test Case Selection
- Test Case Prioritization
- Regression Testing in Practice

Fault Localization

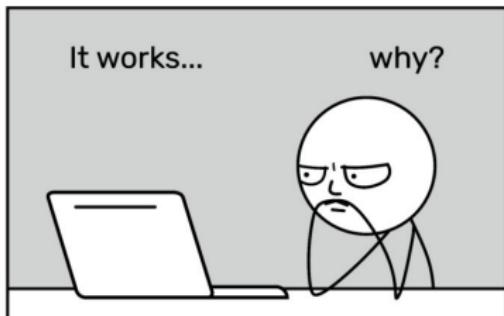


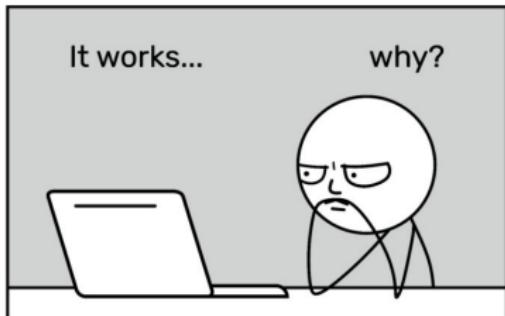
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- Before fixing the bug, we need to know **where it is**.





- We found a bug by running a test suite!
- Before fixing the bug, we need to know **where it is**.
- **Fault Localization** is the process of identifying the **location** of a fault in the code.

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- **Breakpoints** – Using a debugger to pause the program execution and inspect the state.

There are several basic **manual approaches** to fault localization:

- **Logging** – Inserting print statements to trace the program execution.
- **Assertions** – Inserting assertions to check the program state.
- **Breakpoints** – Using a debugger to pause the program execution and inspect the state.
- **Profiling** – Profiling the execution speed and memory usage of the program typically to find performance and memory usage bugs.

Contents

1. Delta Debugging (DD)

Recursive Delta Debugging – ddmin

Hierarchical Delta Debugging

Probabilistic Delta Debugging (ProbDD)

Delta Debugging for Program Debloating

2. Information Retrieval based Fault Localization (IRFL)

Vector Space Model (VSM)

Tf-Idf

Cleansing Bug Reports and Source Code

VSM and Similarity

3. Spectrum-based Fault Localization (SBFL)

Genetic Algorithm for SBFL

Theoretical Analysis

Method-level Aggregation

Hybrid SBFL

4. Mutation-based Fault Localization (MBFL)

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4. Mutation-based Fault Localization (MBFL)

Motivation

Following HTML code caused Firefox to crash. What is the actual cause?

```
<td align=left valign=top>
<SELECT NAME="op sys" MULTIPLE SIZE=7>
<OPTION VALUE="All">All <OPTION VALUE="Windows 3.1">Windows 3.1
<OPTION VALUE="Windows 95">Windows 95 <OPTION VALUE="Windows 98">Windows 98
<OPTION VALUE="Windows ME">Windows ME <OPTION VALUE="Windows 2000">Windows 2000
<OPTION VALUE="Windows NT">Windows NT <OPTION VALUE="Mac System 7">Mac System 7
<OPTION VALUE="Mac System 7.5">Mac System 7.5 <OPTION VALUE="Mac System 7.6.1">Mac System 7.6.1
<OPTION VALUE="Mac System 8.0">Mac System 8.0 <OPTION VALUE="Mac System 8.5">Mac System 8.5
<OPTION VALUE="Mac System 8.6">Mac System 8.6 <OPTION VALUE="Mac System 9.x">Mac System 9.x
<OPTION VALUE="MacOS X">MacOS X <OPTION VALUE="Linux">Linux
<OPTION VALUE="BSDI">BSDI <OPTION VALUE="FreeBSD">FreeBSD
<OPTION VALUE="NetBSD">NetBSD <OPTION VALUE="OpenBSD">OpenBSD
<OPTION VALUE="AIX">AIX <OPTION VALUE="BeOS">BeOS
<OPTION VALUE="HP-UX">HP-UX <OPTION VALUE="IRIX">IRIX
<OPTION VALUE="Neutrino">Neutrino <OPTION VALUE="OpenVMS">OpenVMS
<OPTION VALUE="OS/2">OS/2 <OPTION VALUE="OSF/1">OSF/1
<OPTION VALUE="Solaris">Solaris <OPTION VALUE="SunOS">SunOS
<OPTION VALUE="other">other</SELECT></td> <td align=left valign=top>
<SELECT NAME="priority" MULTIPLE SIZE=7>
<OPTION VALUE="--">-- <OPTION VALUE="P1">P1
<OPTION VALUE="P2">P2 <OPTION VALUE="P3">P3
<OPTION VALUE="P4">P4 <OPTION VALUE="P5">P5</SELECT> </td> <td align=left valign=top>
<SELECT NAME="bug severity" MULTIPLE SIZE=7> <OPTION VALUE="blocker">blocker
<OPTION VALUE="critical">critical <OPTION VALUE="major">major <OPTION VALUE="normal">normal
<OPTION VALUE="minor">minor <OPTION VALUE="trivial">trivial
<OPTION VALUE="enhancement">enhancement </ SELECT>
</tr> </table>
```

Delta Debugging (DD)



- **Not all parts** of the test case are necessary to cause the failure.

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 - **Easier debugging** – A smaller test case result in smaller states and shorter executions.

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- The simplified test case has the following benefits:
 - **Ease of communication** – A simplified test case is easier to communicate.
 - **Easier debugging** – A smaller test case result in smaller states and shorter executions.
 - **Identify duplicates** – Simplified test cases subsume several duplicates.

Delta Debugging

Basic approach of delta debugging is just **binary search**:



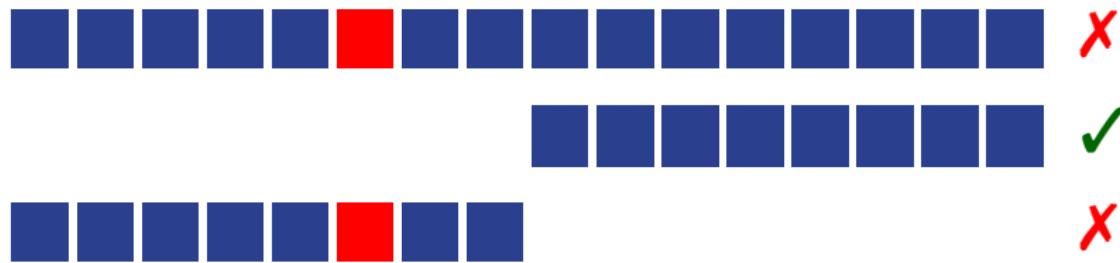
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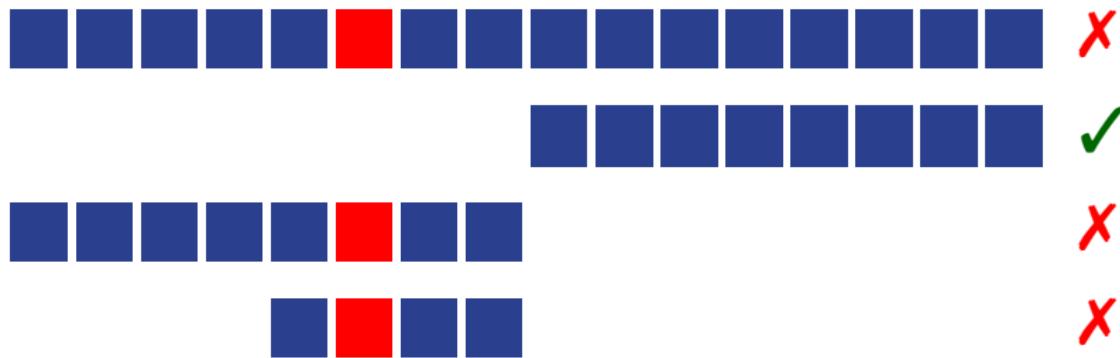
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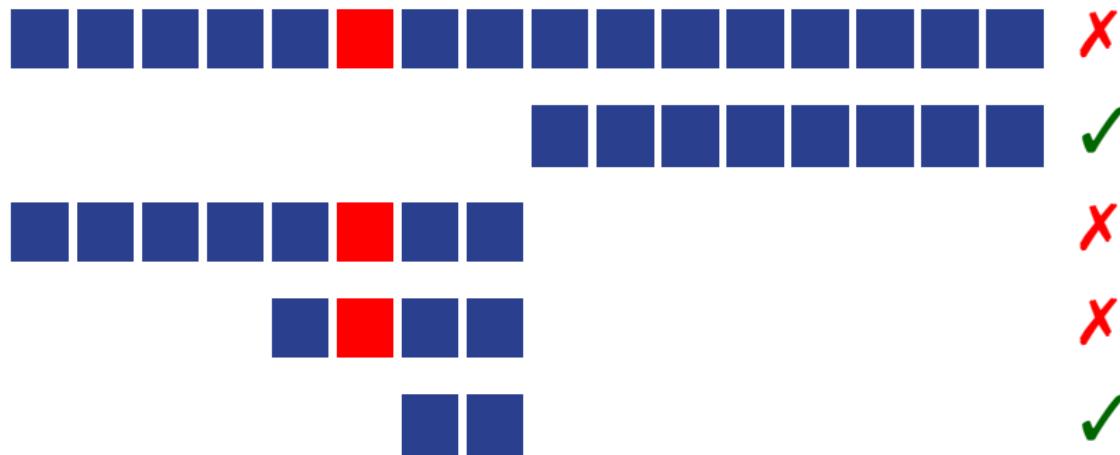
Delta Debugging

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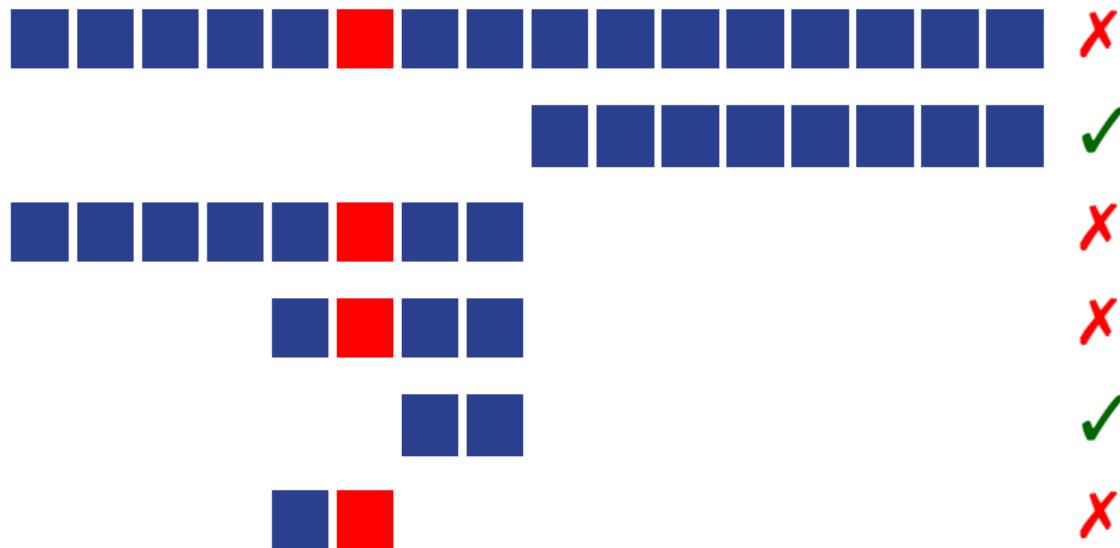
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Basic approach of delta debugging is just **binary search**:



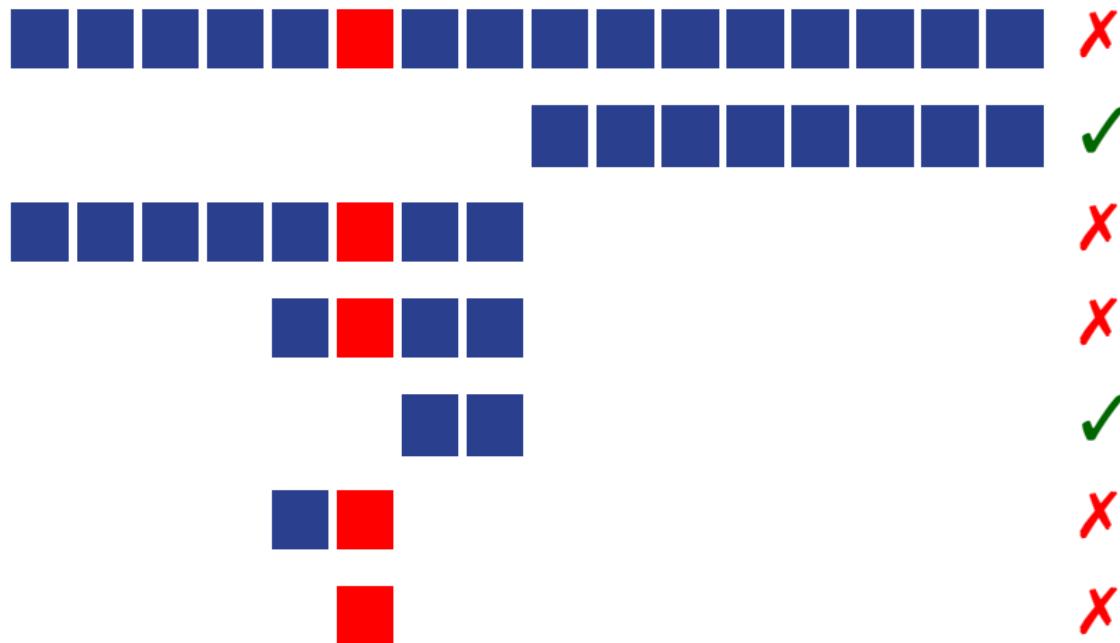
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Delta Debugging

However, what if the failure is caused by a combination of multiple parts?



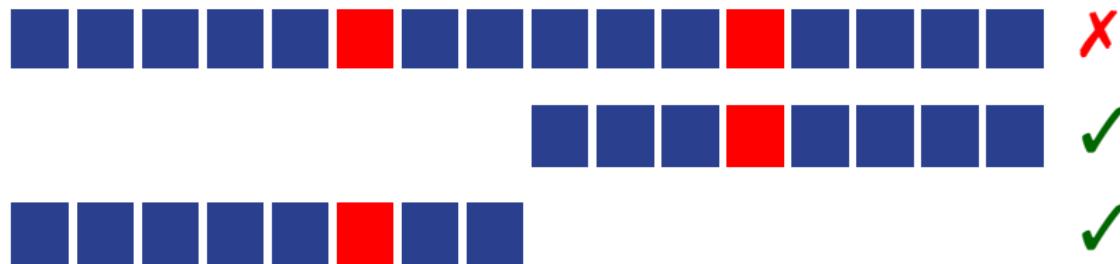
Delta Debugging

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Delta Debugging

However, what if the failure is caused by a combination of multiple parts?



Recursive Delta Debugging – ddmin

Recursively split the test into smaller parts and perform DD on each part.

Algorithm Recursive Delta Debugging – ddmin

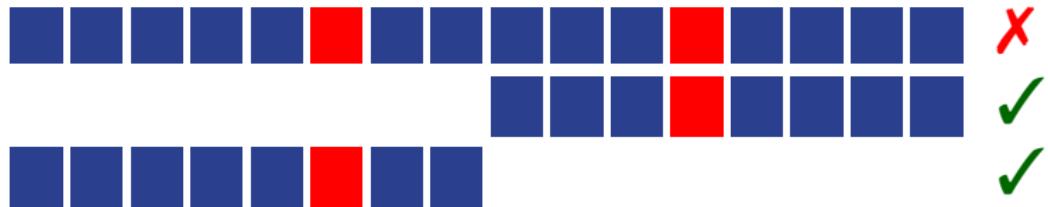
Input: A test case t that causes a failure

Output: A minimal test case that still causes the failure t'

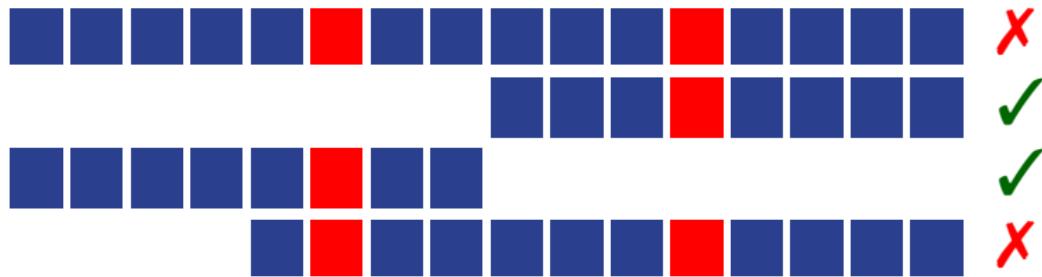
```
1: function DDMIN( $t$ )
2:    $L \leftarrow$  the list of elements in  $t$ 
3:    $n \leftarrow 2$ 
4:   while  $n \geq |L|$  do
5:      $\langle c_1, \dots, c_n \rangle \leftarrow$  split  $L$  into  $n$  chunks
6:     if  $\exists i \in [1, n]. \text{test}(L \setminus c_i) = \text{X}$  then
7:        $\langle L, n \rangle \leftarrow \langle L \setminus c_i, n - 1 \rangle$ 
8:     else if Possible to split  $c_i$  into two chunks  $c'_i$  and  $c''_i$  then
9:        $\langle L, n \rangle \leftarrow \langle \langle c'_1, c''_1, \dots, c'_n, c''_n \rangle, 2n \rangle$ 
10:    else
11:      break
12:   return a test case  $t'$  that corresponds to  $L$ 
```

A. Zeller and R. Hildebrandt. Simplifying and isolating failure-inducing input.
IEEE Transactions on Software Engineering, 28(2):183–200, Feb. 2002

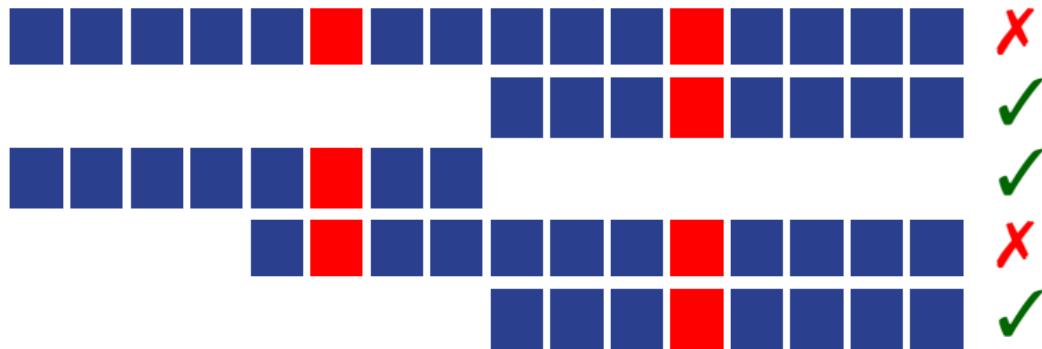
Recursive Delta Debugging – ddmin



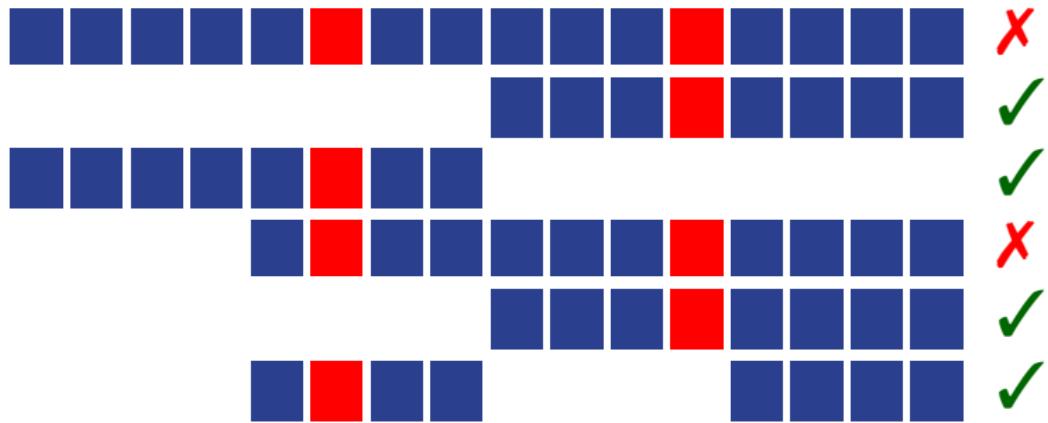
Recursive Delta Debugging – ddmin



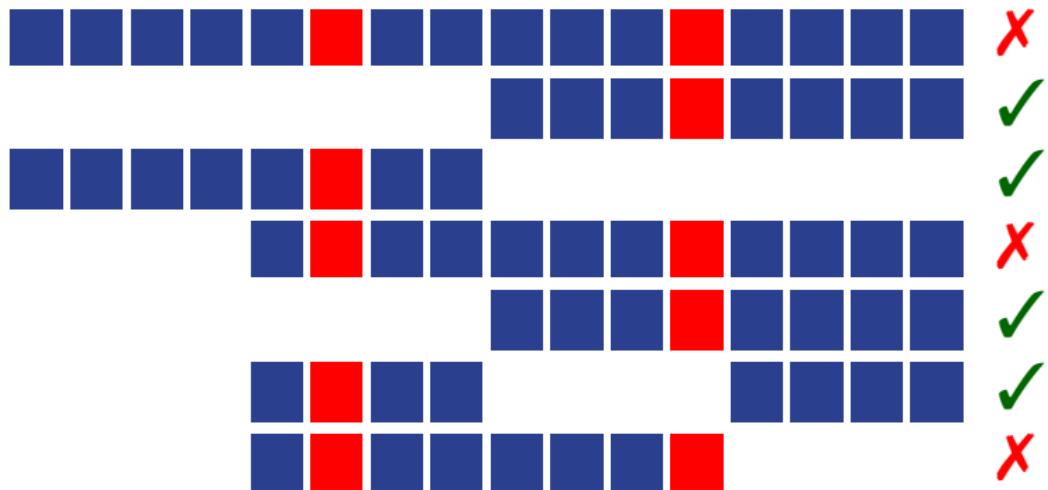
Recursive Delta Debugging – ddmin



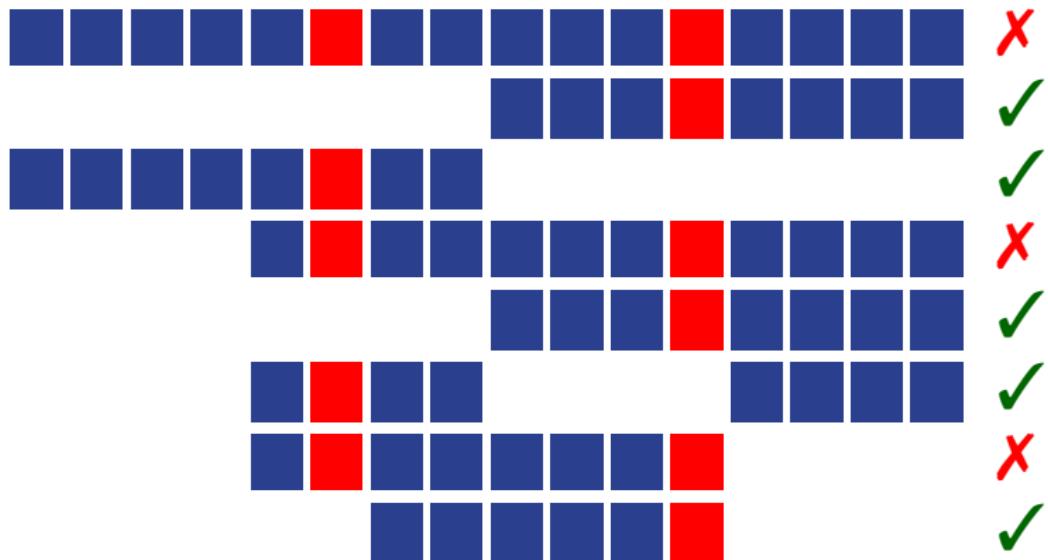
Recursive Delta Debugging – ddmin



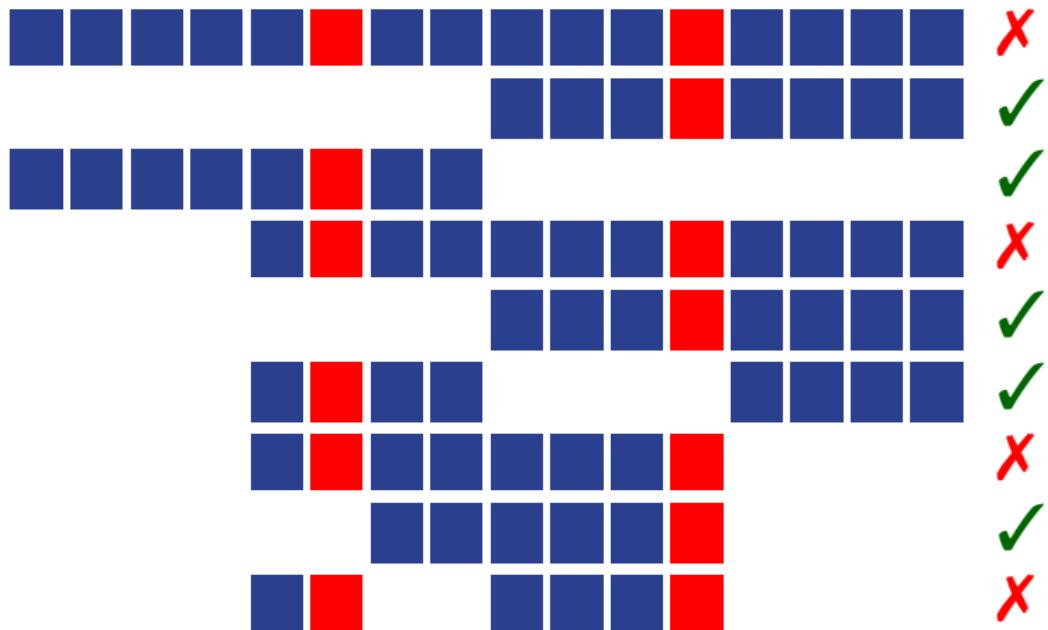
Recursive Delta Debugging – ddmin



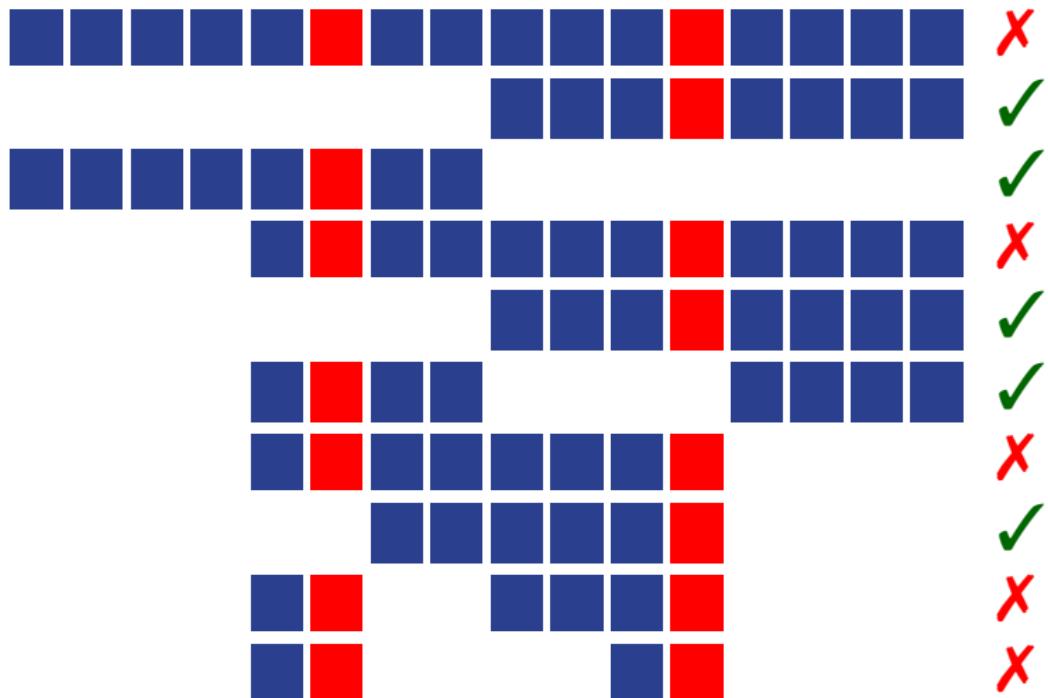
Recursive Delta Debugging – ddmin



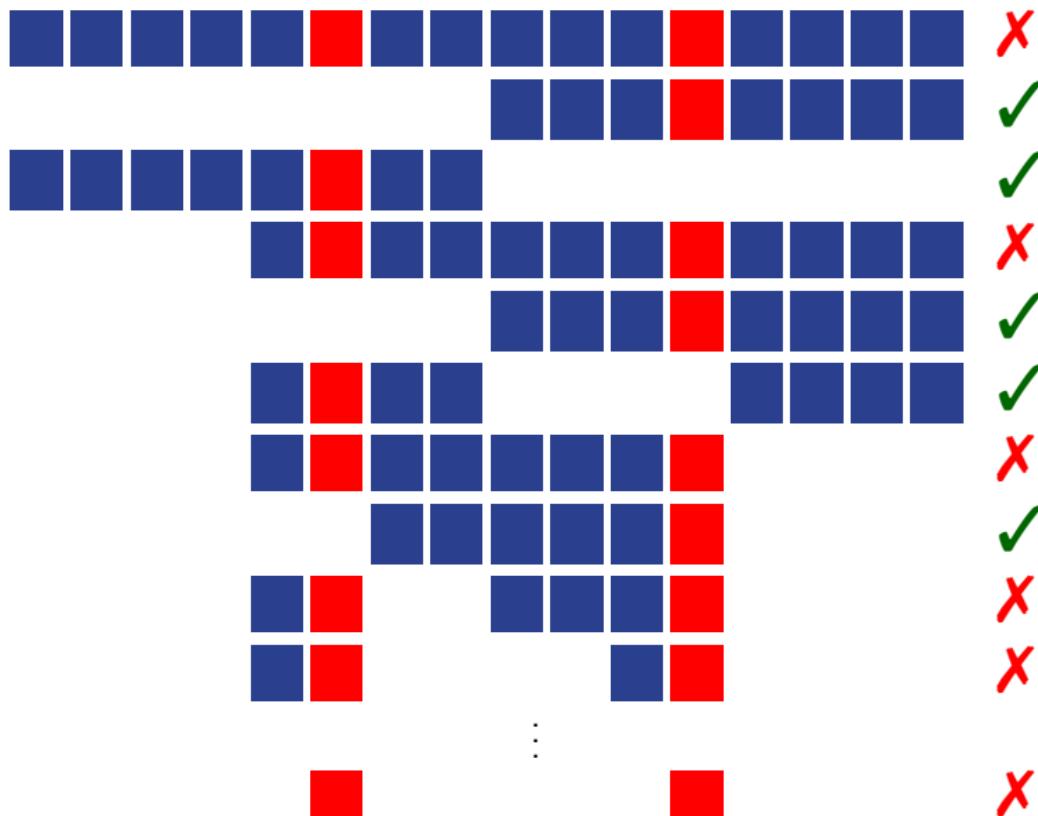
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Hierarchical Delta Debugging (HDD)



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- If we delete a part of the program regardless of the grammar, the resulting program **most likely** will be an **invalid** program.

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- For example, if our target software is a JavaScript **interpreter**, test cases are JavaScript **programs** following the JavaScript **grammar**.
- If we delete a part of the program regardless of the grammar, the resulting program **most likely** will be an **invalid** program.
- **Hierarchical Delta Debugging (HDD)** is a variant of DD that takes the structure of the test case into account. It recursively goes into deeper nested structures instead of just splitting the test case into chunks.
 - G. Misherghi and Z. Su. HDD: Hierarchical delta debugging. In Proceedings of the 28th International Conference on Software Engineering, ICSE '06, pages 142–151, New York, NY, USA, 2006. ACM.

Hierarchical Delta Debugging (HDD)

First, we can consider the **function-level** structure of the test case.

```
int copy(double to[], double from[], int count)
{
    int n= (count+7)/8;
    switch (count%8) do {
        case 0: *to++ = *from++;
        case 7: *to++ = *from++;
        case 6: *to++ = *from++;
        case 5: *to++ = *from++;
        case 4: *to++ = *from++;
        case 3: *to++ = *from++;
        case 2: *to++ = *from++;
        case 1: *to++ = *from++;
    } while (--n > 0);
    return (int)mult(to,2);
}
```

```
double mult( double z[], int n )
{
    int i;
    int j;
    for (j= 0; j< n; j++) {
        i= i+j+1;
        z[i]=z[i]*(z[0]+0);
    }
    return z[n];
}
int main( int argc, char *argv[] )
{
    double x[20], y[20];
    double *px= x;
    while (px < x + 20)
        *px++ = (px-x)*(20+1.0);
    return copy(y,x,20);
}
```

Hierarchical Delta Debugging (HDD)

Then, let's consider the **statement-level** structure of the test case.

```
double mult( double z[], int n )
{
    int i;
    int j;
    for (j= 0; j< n; j++) {
        i= i+j+1;
        z[i]=z[i]*(z[0]+0);
    }
    return z[n];
}
```

Hierarchical Delta Debugging (HDD)

Then, let's consider the **expression-level** structure of the test case.

```
double mult( double z[], int n )
{
    int i;
    int j;
    for (j= 0; j< n; j++) {
        i= i+j+1;
        z[i]=z[i]*(z[0]+0);
    }
}
```

Hierarchical Delta Debugging (HDD)

The final result of HDD is as follows:

```
double mult( double z[], int n )
{
    int i;
    int j;
    for (;;) {
        i= i+j+1;
        z[i]=z[i]*(z[0]+0);
    }
}
```

- The fixed way to split the test case may be **not the best way** to find the minimal test case.

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- Then, let's consider a **probabilistic** way to split the test case.

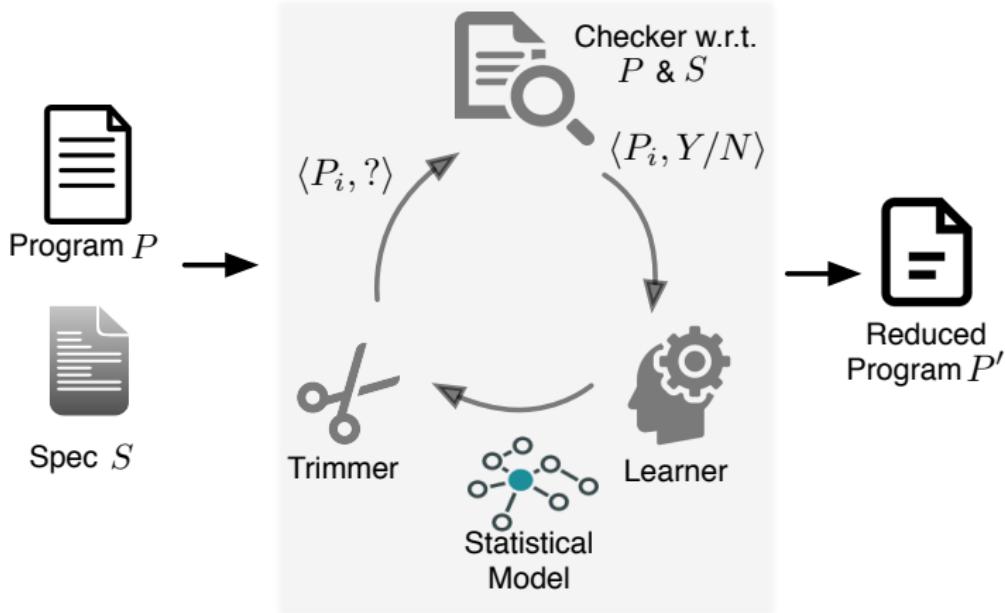
- The fixed way to split the test case may be **not the best way** to find the minimal test case.
- Then, let's consider a **probabilistic** way to split the test case.
- **Probabilistic Delta Debugging (ProbDD)** is a variant of DD that **randomly selects** the sequential parts to select the next part and **updates** the **probabilistic model** based on the previous results.
 - G. Wang, R. Shen, J. Chen, Y Xiong, and L Zhang. Probabilistic delta debugging. In Proceedings of the 2021 Joint Meeting on European Software Engineering Conference and Symposium on the Foundations of Software Engineering, ESEC/FSE 2021.

Probabilistic Delta Debugging (ProbDD)

	s1	s2	s3	s4	s5	s6	s7	s8	
1	0.2500	0.2500	0.2500	0.2500	0.2500	0.2500	0.2500	0.2500	
	s1	s2	s3	s4	s5	s6	s7	s8	F
	0.3657	0.3657	0.3657	0.2500	0.2500	0.2500	0.2500	0.3657	
2	s1	s2	s3	s4	s5	s6	s7	s8	T
	0.3657	0.3657	0.3657	0	0	0	0	0.3657	
3	s1	s2	s3	s4	s5	s6	s7	s8	F
	0.6119	0.3657	0.3657	0	0	0	0	0.6119	
4	s1	s2	s3	s4	s5	s6	s7	s8	F
	0.6119	0.6119	0.6119	0	0	0	0	0.6119	
5	s1	s2	s3	s4	s5	s6	s7	s8	T
	0.6119	0	0.6119	0	0	0	0	0.6119	
6	s1	s2	s3	s4	s5	s6	s7	s8	F
	0.6119	0	1	0	0	0	0	0.6119	
7	s1	s2	s3	s4	s5	s6	s7	s8	T
	0	0	1	0	0	0	0	0.6119	
8	s1	s2	s3	s4	s5	s6	s7	s8	F
	0	0	1	0	0	0	0	1	

Delta Debugging for Program Debloating

- We can utilize DD technique to **debloat** a program.
 - K. Heo, W. Lee, P. Pashakhanloo, and M. Naik. Effective Program Debloating via Reinforcement Learning. In proceedings of the 2018 Conference on Computer and Communications Security, CCS 2018.



Delta Debugging for Program Debloating

Let's consider the following program:

```
int f1() { return 0; }

int f2() { return 1; }

int f3() { return 1; }

int f4() { return 1; }

int f5() { return 1; }

int f6() { return 1; }

int f7() { return 1; }

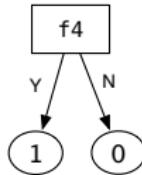
int main() { return f1(); }
```

Delta Debugging for Program Debloating

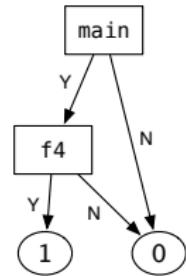
	f1	f2	f3	f4	f5	f6	f7	main	✓
1	f1	f2	f3	f4	f5	f6	f7	main	✗
2	f1	f2	f3	f4	f5	f6	f7	main	✗
3	f1	f2	f3	f4	f5	f6	f7	main	✗
4	f1	f2	f3	f4	f5	f6	f7	main	✗
5	f1	f2	f3	f4	f5	f6	f7	main	✗
6	f1	f2	f3	f4	f5	f6	f7	main	✗
7	f1	f2	f3	f4	f5	f6	f7	main	✗
8	f1	f2	f3	f4	f5	f6	f7	main	✓
9	f1	f2	f3	f4	f5	f6	f7	main	✓
10	f1	f2	f3	f4	f5	f6	f7	main	✗
11	f1	f2	f3	f4	f5	f6	f7	main	✗
12	f1	f2	f3	f4	f5	f6	f7	main	✗
13	f1	f2	f3	f4	f5	f6	f7	main	✗
14	f1	f2	f3	f4	f5	f6	f7	main	✗
15	f1	f2	f3	f4	f5	f6	f7	main	✓
16	f1	f2	f3	f4	f5	f6	f7	main	✓

Delta Debugging for Program Debloating

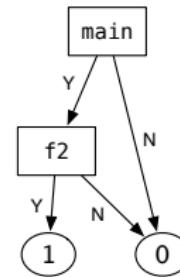
	f1	f2	f3	f4	f5	f6	f7	main	✓
1	f1	f2	f3	f4	f5	f6	f7	main	✗
2	f1	f2	f3	f4	f5	f6	f7	main	✗
3	f1	f2	f3	f4	f5	f6	f7	main	✗
4	f1	f2	f3	f4	f5	f6	f7	main	✓
5	f1	f2	f3	f4	f5	f6	f7	main	✓
6	f1	f2	f3	f4	f5	f6	f7	main	✗
7	f1	f2	f3	f4	f5	f6	f7	main	✓
8	f1	f2	f3	f4	f5	f6	f7	main	✓
9	f1	f2	f3	f4	f5	f6	f7	main	✗
10	f1	f2	f3	f4	f5	f6	f7	main	✗



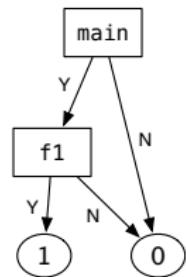
Iteration 1



Iteration 2



Iteration 3



Iteration 6

- DD.py – a Python implementation of Delta Debugging
- Lithium – a Python implementation of a Hierarchical Delta Debugging
- C-Reduce – a tool that reduces source files written in C/C++ using the Delta algorithms

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Motivation

Can we utilize **information** in the **bug report** for **fault localization**?

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Can we utilize **information** in the **bug report** for **fault localization**?

For example, this is a real bug report for Firefox:

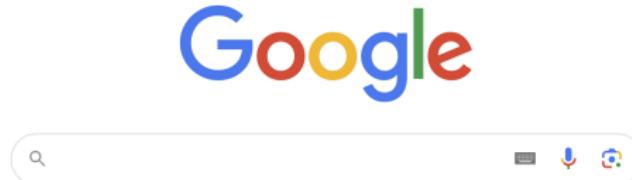
The screenshot shows a Bugzilla bug report for Firefox, ID 1001903. The report is from reporter 'thorsteini_42' and was filed 5 years ago. The user agent is Mozilla/5.0 (X11; Ubuntu; Linux x86_64; rv:28.0) Gecko/20100101 Firefox/28.0 (Beta/Release). The build ID is 20140410211200. The steps to reproduce are: 1. create a folder in the bookmarks-toolbar and fill it with some bookmarks (one is enough) 2. opening the folder per mouse-leftclick works flawlessly but per touch-click it just opens for a fraction of a second and is immediately collapsed again. (Tested with installed ubuntu 14.04 and untouched live version on t440s with touchscreen). The actual results are that bookmarks-folders is immediately closed again if opened per touchscreen. The expected results are that it should just open the folder and show the contents.

https://bugzilla.mozilla.org/show_bug.cgi?id=1001903

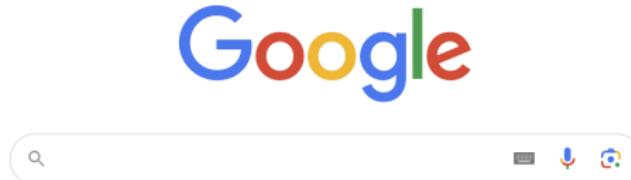
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- While we do not know the internal structure of the Firefox source code, we **can guess** which parts of the code are **most likely to be related** to the fault.

- **Information Retrieval (IR)** techniques help a user to quickly obtain resources relevant to an information need, from a large collection of information resources.



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- **Fault localization** can be thought of as finding a resource (a program element) that is relevant to an information need (the reported symptoms of the failure), from a large collection of information resources (the entire system).
 - The **bug report** becomes our **query**.
 - The entire **source code** becomes our **collection of documents**.
 - **Fault localization** is to **find** the source code that matches the bug report the best.

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- **Vector Space Model (VSM)** is one of the most popular ways to represent queries and documents as vectors in a high-dimensional space.
- It allows us to calculate the **similarity** between the query and the documents easily.

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- There are many ways to set the non-zero values. Let's study **tf-idf**.

Tf-Idf

- **Term-Frequency Inverse Document Frequency (Tf-Idf)** is a numerical statistic that reflects how important a term is to a document in a collection or corpus.

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- **Term Frequency (tf)**, $tf(t, d)$, is the number of times the term t appears in the document d divided by the total number of terms in the document d .

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- **Inverse Document Frequency (idf)**, $idf(t, D)$, is the logarithm of the ratio of the total number of documents in the corpus D to the number of documents containing the term t .

$$idf(t, D) = \log \left(\frac{|D|}{|\{d \in D \mid t \in d\}|} \right)$$

- **Term-Frequency Inverse Document Frequency (Tf-Idf)** is just a product of the **term frequency** and the **inverse document frequency**.

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Cleansing Bug Reports



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- There are many widely used libraries that will perform these tasks.

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- In source code, **reserved keywords** can be considered as **stop words**.
- In addition, we need to apply additional normalization for identifiers:
 - **CamelCase** normalization – For example, “getFileName” becomes “get”, “file”, and “name”.
 - **SnakeCase** normalization – For example, “get_file_name” becomes “get”, “file”, and “name”.

VSM and Similarity

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- The **similarity** between the bug report and the source code can be calculated using the **cosine similarity**:

$$\cos(d_j, q) = \frac{d_j \cdot q}{\|d_j\| \times \|q\|} = \frac{\sum_{i=1}^N w_{i,j} \times w_{i,q}}{\sqrt{\sum_{i=1}^N w_{i,j}^2} \times \sqrt{\sum_{i=1}^N w_{i,q}^2}}$$

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- Finally, we can select the source code file that has the **highest cosine similarity** to the bug report as the **fault location**.

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- **Weaknesses**

- Requires a **high-quality** and **detailed** bug report.
- Suffers from the **inherent limit to the accuracy** because the document to be matched (i.e., the unit of localization) needs to be of certain size (otherwise lexical similarity becomes more random).

Contents

1. Delta Debugging (DD)

Recursive Delta Debugging – ddmin

Hierarchical Delta Debugging

Probabilistic Delta Debugging (ProbDD)

Delta Debugging for Program Debloating

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Vector Space Model (VSM)

Tf-Idf

Cleansing Bug Reports and Source Code

VSM and Similarity

3. Spectrum-based Fault Localization (SBFL)

Genetic Algorithm for SBFL

Theoretical Analysis

Method-level Aggregation

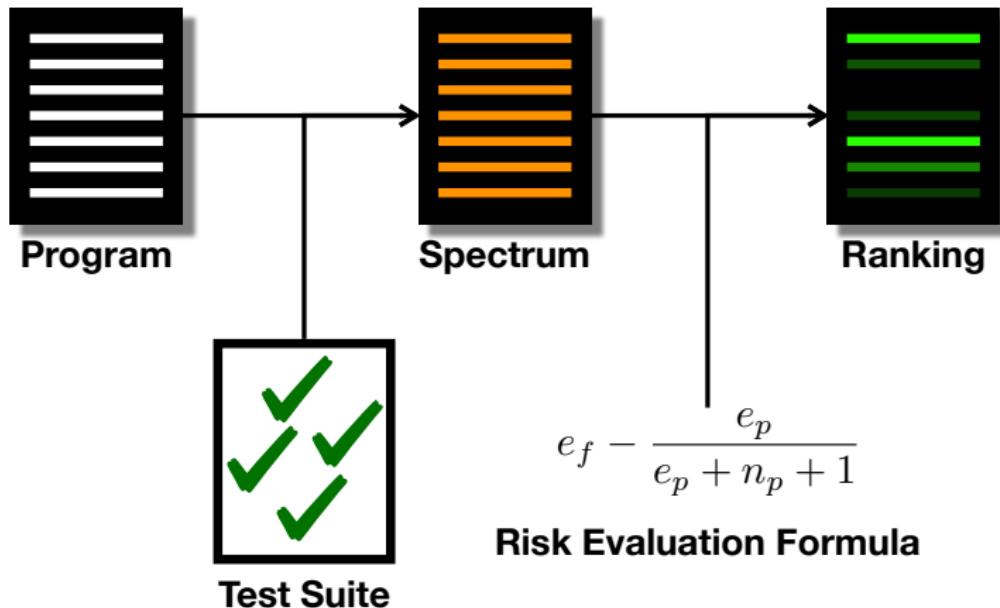
Hybrid SBFL

4. Mutation-based Fault Localization (MBFL)

- **Intuition** – If a program has a **faulty line**, a test case that **executes** the faulty line is more likely to **fail** than a test case that does not execute the faulty line.

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- It means that we want to utilize **statistical information** about the program's execution to **localize** the fault.
- We need to reflect this intuition to a **computable form** to automate the fault localization process.



- **Program Spectrum** – for each structural unit (e.g., statement, branch, predicate), summarize the test result and coverage into a tuple of the following four numbers:
 - e_p – # test cases that **execute** the unit e and **pass**.
 - e_f – # test cases that **execute** the unit e and **fail**.
 - n_p – # test cases that do **not execute** the unit e and **pass**.
 - n_f – # test cases that do **not execute** the unit e and **fail**.

Tarantula (2001)

The following is the initial formula for SBFL called **Tarantula**:

$$\text{Tarantula}(e) = \frac{\frac{e_f}{e_f + n_f}}{\frac{e_f}{e_f + n_f} + \frac{e_p}{e_p + n_p}}$$

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On the other hand, the following part represents the how many test cases are **associated** with the unit e among the **passing** test cases:

$$\frac{e_p}{e_p + n_p}$$

Tarantula (2001)

While it originally was meant as a **visualization** technique, it has been widely used as a fault localization technique.

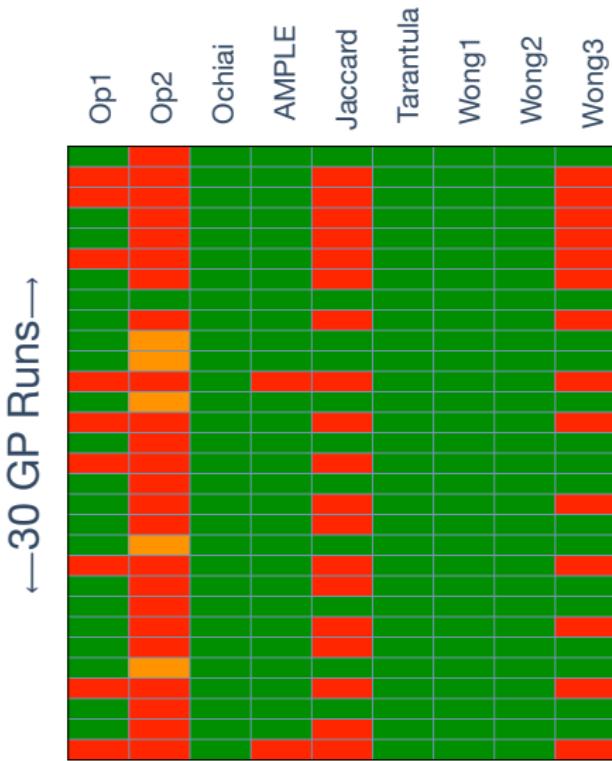


Diverse Risk Evaluation Formulae

While over 30 formulae have been proposed, none of them is universally superior to others and no best formula for all types of faults.

Name	Formula	Name	Formula	Name	Formula
ER1 _a	$\begin{cases} -1 & \text{if } n_f > 0 \\ n_p & \text{otherwise} \end{cases}$	ER1 _b	$e_f - \frac{e_p}{e_p + n_p + 1}$	Wong3	$e_f - h, h = \begin{cases} e_p & \text{if } e_p \leq 2 \\ 2 + 0.1(e_p - 2) & \text{if } 2 < e_p \leq 10 \\ 2.8 + 0.01(e_p - 10) & \text{if } e_p > 10 \end{cases}$
ER5 _a	$e_f - \frac{e_f}{e_f + n_f + n_p + 1}$	ER5 _b	$\frac{e_f}{e_f + n_f + e_p + n_p}$	Ochiai2	$\frac{e_f n_p}{\sqrt{(e_f + e_p)(n_f + n_p)(e_f + n_p)(e_p + n_f)}}$
ER5 _c	$\begin{cases} 0 & \text{if } e_f < F \\ 1 & \text{otherwise} \end{cases}$	GP2	$2(e_f + \sqrt{e_p + n_p}) + \sqrt{e_p}$	Zoltar	$\frac{10000 n_f e_p}{e_f + e_p + n_f + \frac{10000 n_f e_p}{e_f}}$
Ochiai	$\frac{e_f}{(e_f + n_f)(e_f + e_p)}$	GP3	$\sqrt{ e_f^2 - \sqrt{e_p} }$		
Jaccard	$\frac{e_f}{e_f + n_f + e_p}$	GP13	$e_f (1 + \frac{1}{2e_p + e_f})$		
AMPLE	$ \frac{e_f}{F} - \frac{e_p}{P} $	GP19	$e_f \sqrt{\frac{e_p - e_f + F - P}{e_f}}$		
Hamann	$\frac{e_f + n_p - e_p - n_f}{P + F}$	Tarantula	$\frac{\frac{e_f}{e_f + n_f}}{\frac{e_f}{e_f + n_f} + \frac{e_p}{e_p + n_p}}$		
Dice	$\frac{2e_f}{e_f + e_p + n_f}$	RusselRao	$\frac{e_f}{e_p + e_f + n_p + n_f}$		
M1	$\frac{e_f + n_p}{n_f + e_p}$	SørensenDice	$\frac{2e_f}{2e_f + e_p + n_f}$		
M2	$\frac{e_f}{e_f + n_p + 2n_f + 2e_p}$	Kulczynski1	$\frac{e_f}{n_f + e_p}$		
Hamming	$e_f + n_p$	Kulczynski2	$\frac{1}{2}(\frac{e_f}{e_f + n_f} + \frac{e_f}{e_f + e_p})$		
Goodman	$\frac{2e_f - n_f - e_p}{2e_f + n_f + e_p}$	SimpleMatching	$\frac{e_f + n_p}{e_p + e_f + n_p + n_f}$		
Euclid	$\sqrt{e_f + n_p}$	RogersTanimoto	$\frac{e_f + n_p}{e_f + n_p + 2n_f + 2e_p}$		
Wong1	e_f	Sokal	$\frac{2e_f + 2n_p + n_f + e_p}{2e_f + 2n_p}$		
Wong2	$e_f - e_p$	Anderberg	$\frac{e_f}{e_f + 2e_p + 2n_f}$		

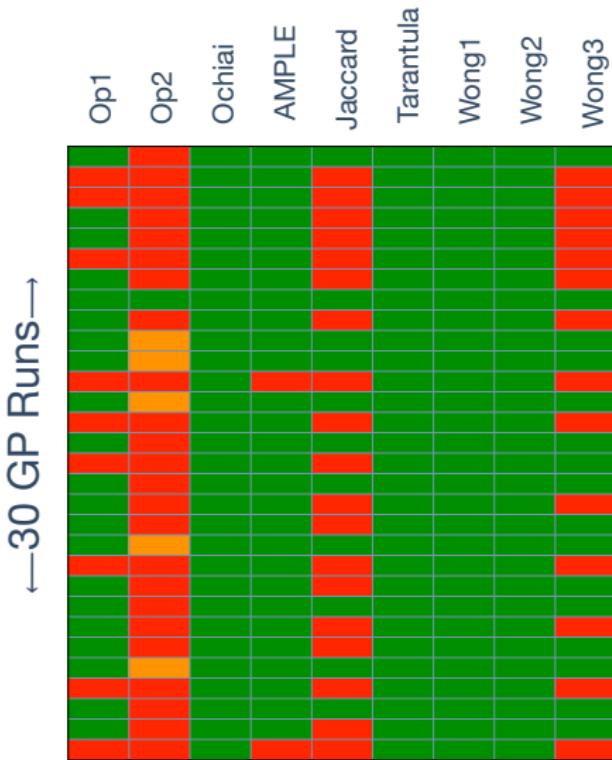
Genetic Algorithm for SBFL



4 Unix tools w/ 92 faults: 20 for training, 72 for evaluation.

- Let's apply the **Genetic Algorithm (GA)** to **optimize** the formula for SBFL.

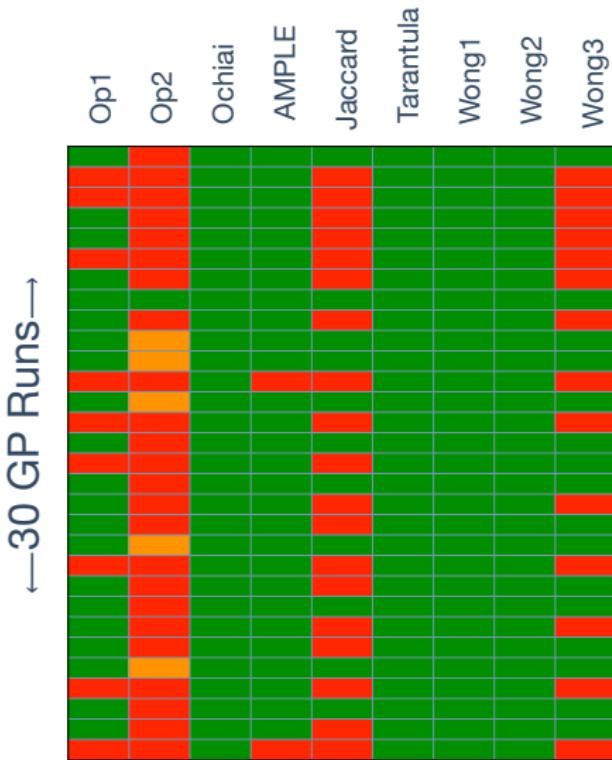
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- Let's apply the **Genetic Algorithm (GA)** to **optimize** the formula for SBFL.
- 30 formulae** are generated.
 - Green – GP **outperforms** the other.
 - Orange – GP **exactly matches** the other.
 - Red – the other **outperforms** GP.

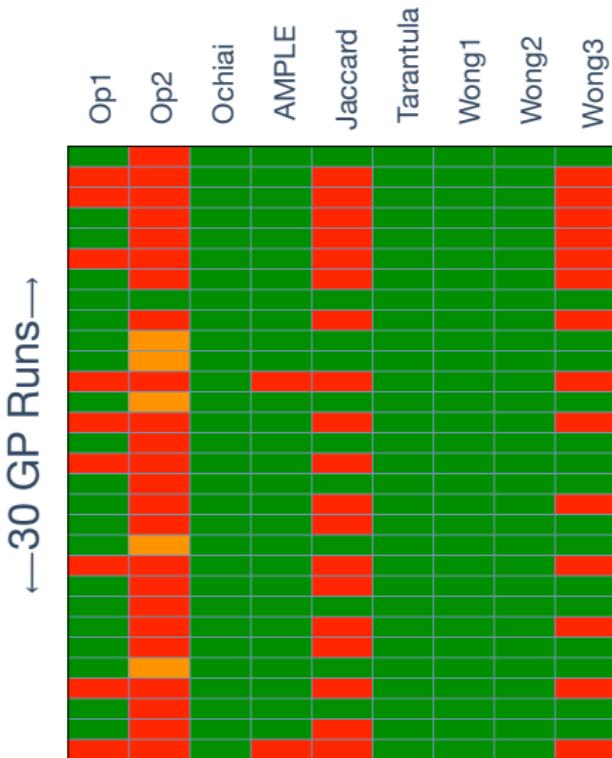
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- GP **completely outperforms** Ochiai, Tarantula, Wong 1, and Wong 2.

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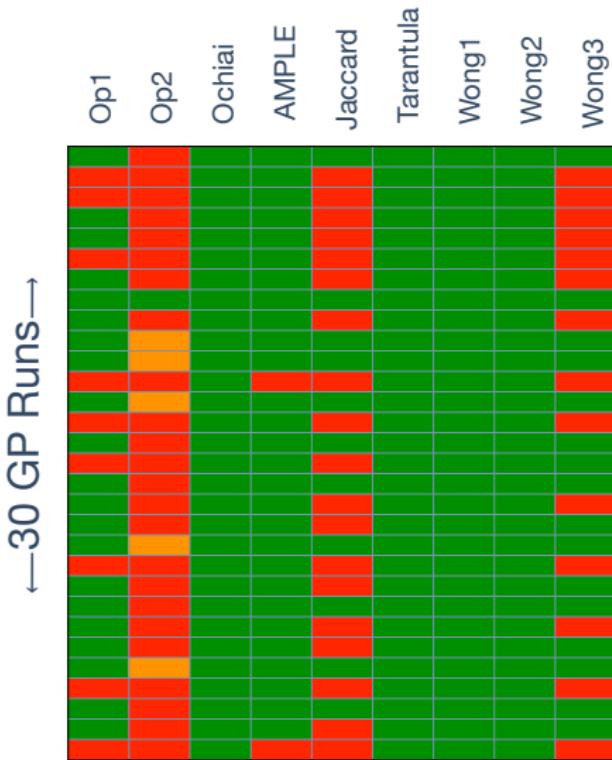
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- GP **mostly outperforms** AMPLE.
- Op1, Jaccard, and Wong 3 are **tough to beat**.
- Op2 is very good but it is **not impossible to do better**.

Genetic Algorithm for SBFL

ID	Refined Formula	ID	Refined Formula
GP01	$e_f(n_p + e_f(1 + \sqrt{e_f}))$	GP16	$\sqrt{e_f^{\frac{3}{2}} + n_p}$
GP02	$2(e_f + \sqrt{n_p}) + \sqrt{e_p}$	GP17	$\frac{2e_f + n_f}{e_f - n_p} + \frac{n_p}{\sqrt{e_f}} - e_f - e_f^2$
GP03	$\sqrt{ e_f^2 - \sqrt{e_p} }$	GP18	$e_f^3 + 2n_p$
GP04	$\sqrt{\frac{n_p}{e_p - n_p} - e_f}$	GP19	$e_f \sqrt{ e_p - e_f + n_f - n_p }$
GP05	$\frac{(e_f + n_p)\sqrt{e_f}}{(e_f + e_p)(n_p n_f + \sqrt{e_p})(e_p + n_p)\sqrt{ e_p - n_p }}$	GP20	$2(e_f + \frac{n_p}{e_p + n_p})$
GP06	$e_f n_p$	GP21	$\sqrt{e_f + \sqrt{e_f + n_p}}$
GP07	$2e_f(1 + e_f + \frac{1}{2n_p}) + (1 + \sqrt{2})\sqrt{n_p}$	GP22	$e_f^2 + e_f + \sqrt{n_p}$
GP08	$e_f^2(2e_p + 2e_f + 3n_p)$	GP23	$\sqrt{e_f}(e_f^2 + \frac{n_p}{e_f} + \sqrt{n_p} + n_f + n_p)$
GP09	$\frac{e_f \sqrt{n_p}}{n_p + n_p} + n_p + e_f + e_f^3$	GP24	$e_f + \sqrt{n_p}$
GP10	$\sqrt{ e_f - \frac{1}{n_p} }$	GP25	$e_f^2 + \sqrt{n_p} + \frac{\sqrt{e_f}}{\sqrt{ e_p - n_p }} + \frac{n_p}{(e_f - n_p)}$
GP11	$e_f^2(e_f^2 + \sqrt{n_p})$	GP26	$2e_f^2 + \sqrt{n_p}$
GP12	$\sqrt{e_p + e_f + n_p - \sqrt{e_p}}$	GP27	$\frac{n_p \sqrt{(n_p n_f - e_f)}}{e_f + n_p n_f}$
GP13	$e_f(1 + \frac{1}{2e_p + e_f})$	GP28	$e_f(e_f + \sqrt{n_p} + 1)$
GP14	$e_f + \sqrt{n_p}$	GP29	$e_f(2e_f^2 + e_f + n_p) + \frac{(e_f - n_p)\sqrt{n_p e_f}}{e_p - n_p}$
GP15	$e_f + \sqrt{n_f + \sqrt{n_p}}$	GP30	$\sqrt{ e_f - \frac{n_f - n_p}{e_f + n_f} }$

- Given a test suite and a formula R , a program P consists of n elements (s_1, s_2, \dots, s_n) .
- The set of elements can be divided into three subsets:
 - S_B^R – set of elements **ranked higher** than the faulty element s_f .

$$S_B^R = \{s_i \mid 1 \leq i \leq n \wedge R(s_i) > R(s_f)\}$$

- S_F^R – set of elements **tied** to the faulty element s_f .

$$S_F^R = \{s_i \mid 1 \leq i \leq n \wedge R(s_i) = R(s_f)\}$$

- S_A^R – set of elements **ranked lower** than the faulty element s_f .

$$S_A^R = \{s_i \mid 1 \leq i \leq n \wedge R(s_i) < R(s_f)\}$$

- Formula R_1 **dominates** formula R_2 (i.e., $R_1 \rightarrow R_2$) if, for each element s_i , R_1 gives a **better ranking comparison result** with the faulty element s_f than R_2 .

$$S_B^{R_1} \subseteq S_B^{R_2} \wedge S_A^{R_2} \subseteq S_A^{R_1}$$

Theoretical Analysis

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- Formula R_1 **equivalent** to formula R_2 (i.e., $R_1 \equiv R_2$) if they give the **same ranking comparison result** with the faulty element s_f .

$$S_B^{R_1} = S_B^{R_2} \wedge S_F^{R_1} = S_F^{R_2} \wedge S_A^{R_1} = S_A^{R_2}$$

- It means that $R_1 \equiv R_2$ if and only if $R_1 \rightarrow R_2$ and $R_2 \rightarrow R_1$.

Method-level Aggregation

```
public void testMe(int a) {  
    util();  
    if (a % 3 == 0) {  
        ... // faulty code  
    } else {  
        ...  
    }  
}  
  
public void util() {  
    ...  
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- The util method is called by the testMe method.

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- The util method is called by the testMe method.
- If we target **functions** as the unit of localization, the util method **might be tied** to the testMe method having the faulty code.
- **Method-level aggregation** is a technique to **aggregate** the statement- or branch-level ranks to the method level to get a more **accurate** fault localization result.

J. Sohn and S. Yoo. FLUCCS: Using Code and Change Metrics to Improve Fault Localization. In Proceedings of the 2017 International Symposium on Software Testing and Analysis, ISSTA 2017.

- People are realising that a **single formula** is **strongly limited**.

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- Hybridization
 - Use **multiple formulae** at the same time.
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- Hybridization
 - Use **multiple formulae** at the same time.
 - Use SBFL formulae with some **additional input features**.
- As we accept more diverse input, fault localization become a learning problem, instead of design-a-technique problem.

- **Xuan & Monperrus (ICSME 2014)**

- Simultaneously use **25 SBFL formulae**, using the **weighted sum** method.
- Use a **learning-to-rank** technique to train the raking model (i.e., to optimize the weights that yield best ranks for training set faults)

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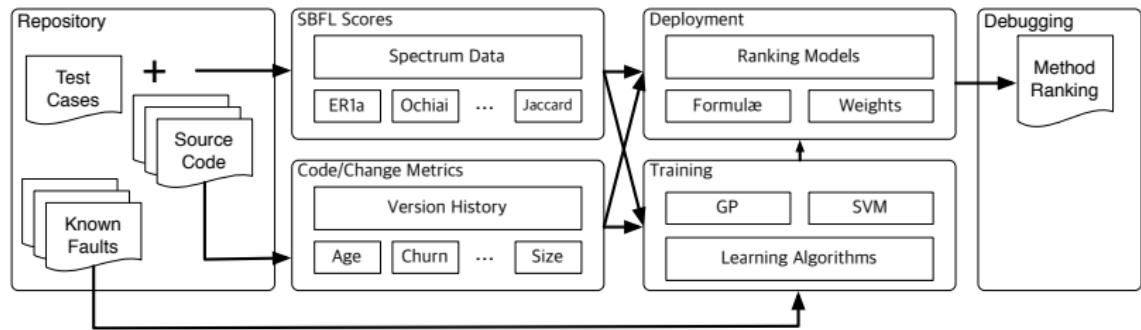
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- **Le et al. (ISSTA 2016)**

- In addition to **35 SBFL formulae**, Savant use **invariant differences**.
- Use Daikon to infer method invariants twice: with passing tests, and with failing test.
- For the faulty method, two sets of invariant will tend to be more different.

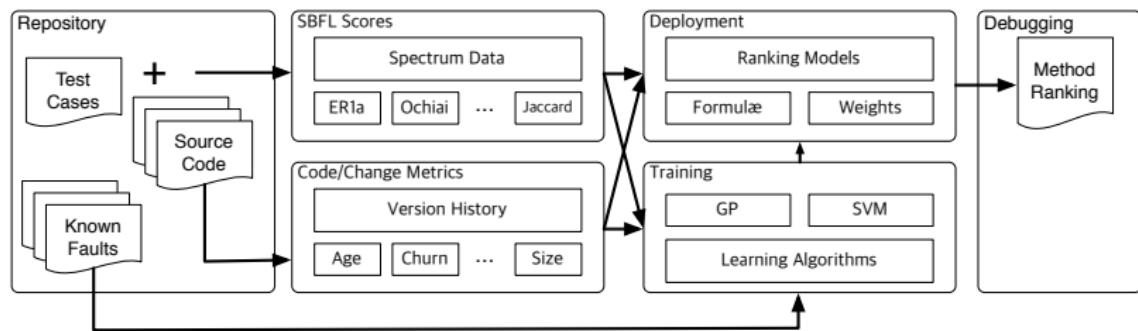
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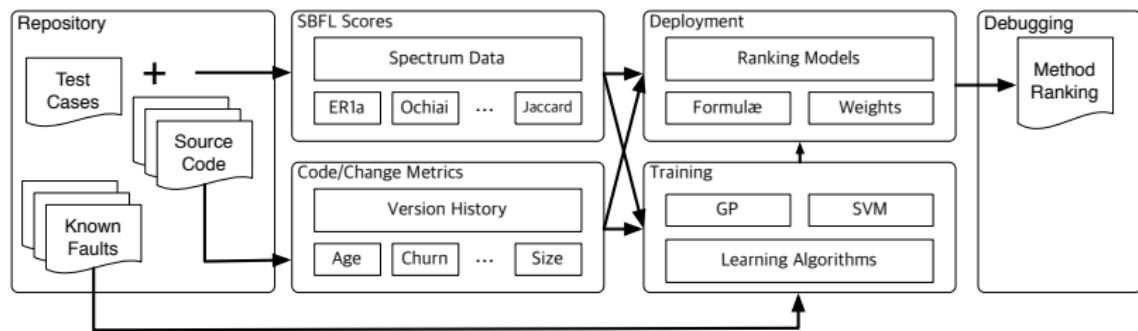
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- **Code and Change Metrics Features**

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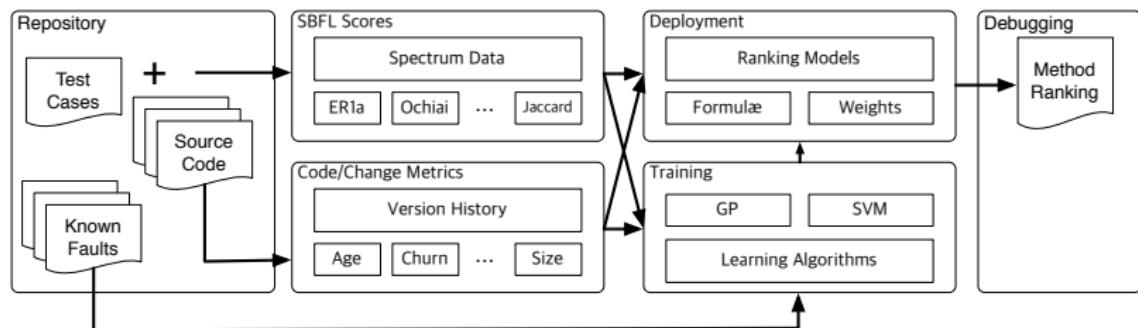


- **Code and Change Metrics Features**

- **Age** – how long has the given element existed in the code?

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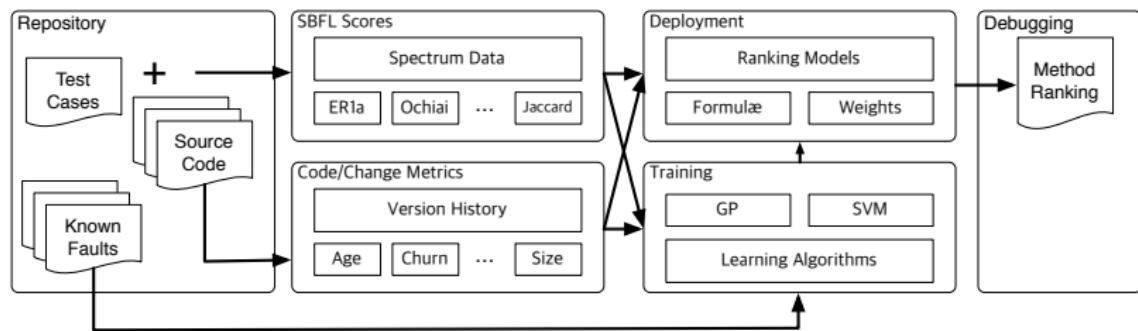


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- **Code and Change Metrics Features**

- **Age** – how long has the given element existed in the code?
- **Churn** – how frequently has the given element been changed?
- **Complexity** – how complex is the given element?

- **Strengths**

- Only requires what is already there: **coverage** and **test results**.
- Relatively **intuitive**.

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- **Weaknesses**

- **Single formulae** are usually **limited**.
- Does not work against **omission faults**
- Does not work well against **multiple faults**.

Contents

1. Delta Debugging (DD)

Recursive Delta Debugging – ddmin

Hierarchical Delta Debugging

Probabilistic Delta Debugging (ProbDD)

Delta Debugging for Program Debloating

2. Information Retrieval based Fault Localization (IRFL)

Vector Space Model (VSM)

Tf-Idf

Cleansing Bug Reports and Source Code

VSM and Similarity

3. Spectrum-based Fault Localization (SBFL)

Genetic Algorithm for SBFL

Theoretical Analysis

Method-level Aggregation

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4. Mutation-based Fault Localization (MBFL)

- **Mutation testing** is a technique to evaluate the quality of a test suite by generating **mutants** of the program and checking whether the test suite can **kill** the mutants.

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- **Mutation testing** is a technique to evaluate the quality of a test suite by generating **mutants** of the program and checking whether the test suite can **kill** the mutants.
- Can we use **mutants** for **fault localization**?
- What would happen if we **mutate** a program having a **known fault**?

- Consider a **faulty program** P .

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Mutation-based Fault Localization (MBFL)



S. Moon, Y. Kim, M. Kim, and S. Yoo. Ask the Mutants: Mutating Faulty Programs for Fault Localization. International Conference on Software Testing, Verification, and Validation, ICST 2014. (**MUSE** – MUtation-baSEd fault localization technique)

$$\mu(s) = \frac{1}{|mut(s)|} \sum_{m \in mut(s)} \left(\frac{|f_P(s) \cap p_m|}{|f_P|} - \alpha \cdot \frac{|p_P(s) \cap f_m|}{|p_P|} \right)$$

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where α is the **balancing factor**:

$$\alpha = \frac{f2p}{|mut(P)| \cdot |f_P|} \cdot \frac{|mut(P)| \cdot |p_P|}{p2f}$$

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Next Lecture

- Testing Oracles

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