Transition Systems and Invariants

EECS 755—Software Systems Modeling

Dr. Perry Alexander

Information and Telecommunication Technology Center
Electrical Engineering and Computer Science
The University of Kansas
palexand@ku.edu



Presentation Outline

- Review access control modeling objectives
 - modeling platform MAC
 - modeling local access control
- ► Overview access control policy definition
 - design and modeling assumptions
 - platform boot policy definition
 - ► local policy definitions
- Overview models
 - domain and system models
 - communication model
 - theorems and status
- Identify next steps
 - runtime and moving beyond the SVP line
 - adding M&A detail



Access Control Modeling Objectives

What we're about here

Reporting joint work with Geoffrey Brown, Indiana University (submitted) in which we verify two physical layer protocols.

- ► Biphase Mark Protocol (BMP)
- ► 8N1 Protocol

These protocols are used in data transmission for CDs, Ethernet, and Tokenring, etc. as well as UARTs.

- Correctness is reasonably difficult to prove due to many real-time constraints.
- ► Many previous formal modeling/verification efforts for these protocols.



Columns and Blocks

Trying figures next to lists

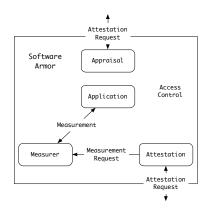
Some normal text goes here just for introduction

- ► Appraisal
- ▶ Measurement
- Attestation
- ▶ vTPM

Why is this column getting higher?

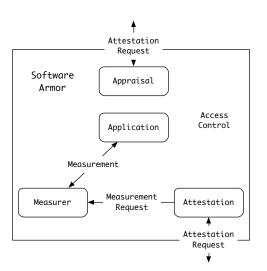
Maybe it's not Center alignment seems best. I like this for two column test and graphics

Getting higher???





Big Picture Armor Architecture



Simple Block

Introduction to LATEX

"Beamer is a LaTeX class for creating presentations that are held using a projector..."

This is a definition



Proofs

Not really a proof.

1. This is a step



Proofs

Not really a proof.

- 1. This is a step
- 2. This is another step



Proofs

Not really a proof.

- 1. This is a step
- 2. This is another step
- 3. This is a third step
- 4. This is a third step
- 5. This is a third step
- 6. This is a third step



List with Overlays

► Item 1 followed by a pause



List with Overlays

- ► Item 1 followed by a pause
- ► Item 3 followed by a pause



List with Overlays

- ► Item 1 followed by a pause
- ► Item 2 followed by a pause
- ► Item 3 followed by a pause



Previous Efforts

- ► BMP has been verified in PVS twice and required
 - 37 invariants and 4000 individual proof directives (initially) in the one effort
 - ▶ 5 hours just to *check* the proofs in the other effort
 - A formal specification and verification of an independent real-time model in both efforts
- BMP has been verified in (the precursor to) ACL2 by J. Moore and required
 - ► A significant conceptual effort to fit the problem in the logic, arguably omitting some salient features of the model
 - The statement and proof of many antecedent results
 - J. Moore reports this as one of his "best ideas" in his career



Not Your Father's Theorem-Prover

The verifications are carried out in the SAL infinite-state bounded model-checker that combines SAT-solving and SMT decision procedures to *prove* safety properties about infinite-state models.

- ► Theorem-proving efforts took multiple engineer-months if not years to complete.
- Our initial effort in SAL consumed about two engineer-days. ...and we found a significant bug in a UART application note.



Parameterized Timing Constraints

The University of Kansas

SMT allows for *parameterized* proofs of correctness. The following are example constaints from the BMP verification:

```
TIME: TYPE = REAL;
TPERIOD: TIME = 16:
TSAMPLE: INTEGER = 23;
TSETTLE: \{x: TIME \mid 0 \le x\}
                    AND (x + TPERIOD < TSAMPLE)
                    AND (x + TSAMPLE + 1 < 2 * TPERIOD);
TSTABLE: TIME = TPERIOD - TSETTLE;
ERROR: \{x: TIME \mid (0 \le x)\}
                  AND (TPERIOD + TSETTLE < TSAMPLE*(1-x))
                  AND (TSAMPLE*(1+x) + (1+x) + TSETTLE < 2 * TPERIOD)};
RSAMPMAX: TIME = TSAMPLE * (1 + ERROR):
RSAMPMIN: TIME = TSAMPLE * (1 - ERROR);
RSCANMAX: TIME = 1 + ERROR;
RSCANMIN: TIME = 1 - ERROR:
```

SRI's SAL Toolset

- ▶ Parser
- Simulator
- ► Symbolic model-checker (BDDs)
- ► Witness symbolic model-checker
- ▶ Bounded model-checker
- ▶ Infinite-state bounded model-checker
- ► Future releases include:
 - Explicit-state model-checker
 - MDD-based symbolic model-checking

All of which are "state-of-the-art"



k-Induction

Please direct your attention to the whiteboard.



Timeout Automata¹ (Semantics)

An explicit real-time model.

- ► Vocabulary:
 - A set of state variables.
 - ▶ A global clock, $c \in \mathbb{R}^{0 \le 1}$.
 - ▶ A set of *timeout* variables T such that for $t \in T$, $t \in \mathbb{R}^{0 \le 1}$.
- ► Construct a transition system $\langle S, S^0, \rightarrow \rangle$:
 - States are mappings of all variables to values.
 - ► Transitions are either *time transitions* or *discrete transitions*.
 - ► Time transitions are enabled if the clock is less than all timeouts. Updates clock to least timeout.
 - ▶ Discrete transitions are enabled if the clock equals some timeout. Updates state variables and timeouts.



Disjunctive Invariants

Even with k-induction, getting a sufficiently strong invariant is still hard! *Disjunctive invariants* help. A disjunctive invariant can be built iteratively from the counterexamples returned for the hypothesized invariant being verified.

```
t0: THEOREM system |-

G( (phase = Settle)

AND (rstate = tstate + 1)

AND (rclk - tclk - TPERIOD > 0)

AND (tclk + TPERIOD + TSTABLE - rclk > 0))

OR

(phase = Stable)

AND (rstate = tstate + 1)

AND (rclk - tclk - TSETTLE > 0)

AND (tclk + TPERIOD - rclk > 0)

AND (rdata = tdata))
```

