

Kuya Takami

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EDUCATION

Virginia Polytechnic Institute and State University 2015
Ph.D. Mechanical Engineering
Thesis: "Non-Field-of-View Acoustic Target Estimation"
Advisor: Professor Tomonari Furukawa

University of Wisconsin-Madison 2011
M.S. Mechanical Engineering
Advisor: Professor Scott Sanders
University of Wisconsin-Madison 2008
B.S. Biomedical Engineering (Biomechanics)

APPOINTMENTS

VIRGINIA POLYTECHNIC INSTITUTE AND STATE UNIVERSITY Blacksburg, VA (10/2015 - Present)
Postdoctoral Researcher

Graduate Research Assistant/ *Graduate Teaching Assistant (08/2011 - 09/2015)

- Developed non-line-of-sight (NLOS) hybrid optical/acoustical target localization scheme to model and predict the state of sound source in a complex environment.
- Modeled sound reflection/diffraction based NLOS target estimation for mobile robot localization.
- Assisted underwater autonomous navigation project on sonar localization simulation using simultaneous localization and mapping (SLAM) for NSF Naval Research Laboratory.
- Worked on real-time autonomous driving using Grid-based SLAM in collaboration with ZMP and University of Technology, Sydney.
- Worked on tire noise prediction model entailing mathematical formulations, and fluid-solid interaction modeling funded by NSF Center for Tire Research.
- *Instructor (ME 2024-Engineering Design and Economics): Lectured mechanical engineering students on product development.
- *Project Advisor (ME4015/4016): Supervised senior design project on autonomous driving, and automotive alternator design and experimental validation.

BRIDGESTONE AMERICAS, INC Akron, OH (05 - 08/2014)
Advanced Tire Technology - Research intern

- Developed tire noise analysis procedure and designed and implemented tire noise experimental device based on an FPGA controller.

ZMP, INC Tokyo, Japan (01 - 07/2013)
Research Engineer in Autonomous Vehicles

- Assisted programming and hardware development for an autonomous driving vehicle, including data acquisition, implementation of SLAM, and vehicle modeling/control.
- Designed and constructed a quadrupedal machine learning-based evolving robot by calculating kinematics and specifying components.

UNIVERSITY OF WISCONSIN-MADISON Madison, WI (03/2009 - 08/2011)
Graduate Research Assistant for Engine Research Center

- Conducted laser and fiber optics centered research optimizing optical element design in harsh environments.
- Developed a noninvasive laser grid tomography temperature measurement system for jet and IC engines.

UNIVERSITY OF WISCONSIN HOSPITAL Madison, WI (08/2007 - 12/2008)
MRI Research Assistant for Radiology Department

- Studied MRI-based knee analysis, quantified quality of the image, and determined change of cartilage volumes.

HONORS AND AWARDS

2007	Most Outstanding Physics Award [†]	2011	Pratt Graduate Fellowship [‡]
2012	Pratt Graduate Fellowship [‡]	2014	Pratt Graduate Fellowship [‡]
2015	ASME:IDETC/CIE Best Student Paper Award		

†: Scholarship to the best student in two semester physics courses at University of Wisconsin-EC

‡: Awarded to students who are aggressively recruited by other top engineering colleges

TECHNICAL STRENGTH

Computer Languages:	C/C++, Java	System:	Windows, Linux, OS X
Software:	ROS, MATLAB, Visual Studio	Languages:	Japanese (native)
CAD & FEA:	SolidWorks, PTC Creo, Abaqus		

EXTRACURRICULAR EXPERIENCE

Organization	Mechanical Engineering Graduate Student Council (2013-2015) Mechanical Engineering Graduate Ambassador (2013-2015) President of VT Slackline Club (2011-2014) President of Japanese Conversation Group (2012-2015) President of Japanese Cultural Society in University of Wisconsin-EC (2005-2006)
Volunteer	Graduate student mentor (2014-Present)
Society	National Society of Leadership and Success, Biomedical Engineering Society

PUBLICATIONS

K. Takami, T. Furukawa, M. Kumon, D. Kimoto, and G. Dissanayake. "Estimation of a nonvisible field-of-view mobile target incorporating optical and acoustic sensors," *Autonomous Robots*, 2015.

K. Takami, T. Furukawa, M. Kumon, and G. Dissanayake. "Non-Field-of-View Acoustic Target Estimation in Complex Indoor Environment," *Springer Tracts in Advanced Robotics*, 2015.

K. Takami, T. Furukawa, M. Kumon, and L. Mak, "Non-Field-of-View Indoor Sound Source Localization based on Reflection and Diffraction," *Multi-sensor Integration and Fusion*, IEEE, 2015.

K. Takami, T. Furukawa, M. Kumon, and G. Dissanayake. "Non-Field-of-View Acoustic Target Estimation in Complex Indoor Environment," *Field and Service Robotics*, 2015.

T. Furukawa, **K. Takami**, X. Tong, D. Watman, A. Hamed, R. Ranasinghe and G. Dissayanake, "Map-based Navigation of an Autonomous Car Using Grid-based Scan-to-Map Matching," *ASME IDETC*, 2015.

K. Takami and T. Furukawa, "High-Resolution Deformation Measurement System for Fast Rotating Tire," *ASME IDETC/CIE*, 2015.

K. Takami and T. Furukawa, "High-Resolution Deformation Measurement System for Fast Rotating Tires Towards Noise Prediction," *Euronoise.*, 2015.

M. Kumon, D. Kimoto, **K. Takami** and T. Furukawa, "Acoustic recursive Bayesian estimation for non-field-of-view targets," In *Image Analysis for Multimedia Interactive Services (WIAMIS)*, IEEE, 2013.

M. Kumon, D. Kimoto, **K. Takami** and T. Furukawa. "Bayesian non-field-of-view target estimation incorporating an acoustic sensor," In *Intelligent Robots and Systems*, IEEE/RSJ International Conference, 2013.

K. Takami, S. Taheri, M. Taheri and T. Furukawa, "Prediction of Railroad Track Foundation Defects Using Wavelets," *Joint Rail Conference*, ASME, 2013.

J. M. Whitney, **K. Takami**, S. T. Sanders, and Y. Okura. "Design of system for rugged, low-noise fiber-optic access to high-temperature, high-pressure environments," *Sensors Journal*, IEEE, 2011.

A. Xinliang, T. Kraetschmer, **K. Takami**, S. T. Sanders, L. Ma, et al. "Validation of temperature imaging by H₂O absorption spectroscopy using hyperspectral tomography in controlled experiments," *Journal of Applied Optics*, 2011.