# Kuya Takami

Website: http://www.cmsvt.org/Kuya

## EDUCATION

Phone: 540.230.3932 Email: kuya@vt.edu 460 Old Turner St. 100S Randolph Hall Blacksburg, VA 24061

University of Wisconsin-Madison

2011

M.S. Mechanical Engineering Advisor: Professor Scott Sanders

University of Wisconsin-Madison

2008

B.S. Biomedical Engineering (Biomechanics)

#### **APPOINTMENTS**

Ph.D. Mechanical Engineering

## VIRGINIA POLYTECNIC INSTITUTE AND STATE UNIVERSITY Postdoctoral Researcher

Advisor: Professor Tomonari Furukawa

Blacksburg, VA (09/2015 - Present)

#### Graduate Research Assistant/\*Graduate Teaching Assistant

Virginia Polytechnic Institute and State University 2015

Thesis: "Non-Field-of-View Acoustic Target Estimation"

(08/2011 - 09/2015)

- Developed non-line-of-sight (NLOS) hybrid optical/acoustical target localization scheme to model and predict the state of sound source in a complex environment.
- Modeled sound reflection/diffraction based NLOS target estimation for mobile robot localization.
- Assisted underwater autonomous navigation project on sonar localization simulation using simultaneous localization and mapping (SLAM) for NSF Naval Research Laboratory.
- Worked on real-time autonomous driving using Grid-based SLAM in collaboration with ZMP and University of Technology, Sydney.
- Worked on tire noise prediction model entailing mathematical formulations, and fluid-solid interaction modeling funded by NSF Center for Tire Research.
- \*Instructor (ME 2024-Engineering Design and Economics): Lectured mechanical engineering students on product development.
- \*Project Advisor (ME4015/4016): Supervised senior design project on autonomous driving, and automotive alternator design and experimental validation.

#### **BRIDGESTONE AMERICAS, INC**

Akron, OH (05 - 08/2014)

#### Advanced Tire Technology - Research intern

 Developed tire noise analysis procedure and designed and implemented tire noise experimental device based on an FPGA controller.

#### ZMP, INC Research Engineer in Autonomous Vehicles

Tokyo, Japan (01 - 07/2013)

- Assisted programming and hardware development for an autonomous driving vehicle, including data acquisition, implementation of SLAM, and vehicle modeling/control.
- Designed and constructed a quadrupedal machine learning-based evolving robot by calculating kinematics and specifying components.

#### UNIVERSITY OF WISCONSIN-MADISON

Madison, WI (03/2009 - 08/2011)

#### Graduate Research Assistant for Engine Research Center

- Conducted laser and fiber optics centered research optimizing optical element design in harsh environments.
- Developed a noninvasive laser grid tomography temperature measurement system for jet and IC engines.

#### UNIVERSITY OF WISCONSIN HOSPITAL

Madison, WI (08/2007 - 12/2008)

#### MRI Research Assistant for Radiology Department

• Studied MRI-based knee analysis, quantified quality of the image, and determined change of cartilage volumes.

#### HONORS AND AWARDS

2007 Most Outstanding Physics Award<sup>†</sup>
2012 Pratt Graduate Fellowship<sup>‡</sup>
2015 ASME:IDETC/CIE Best Student Paper Award

2011 Pratt Graduate Fellowship<sup>‡</sup>
2014 Pratt Graduate Fellowship<sup>‡</sup>

†: Scholarship to the best student in two semester physics courses at University of Wisconsin-EC

‡: Awarded to students who are aggressively recruited by other top engineering colleges

#### TECHNICAL STRENGTH

Computer Languages: C/C++, Java

Software: ROS, MATLAB, Visual Studio SolidWorks, PTC Creo, Abaqus System: Windows, Linux, OS X Languages: Japanese (native)

#### EXTRACURRICULAR EXPERIENCE

Organization Mechanical Engineering Graduate Student Council (2013-2015)

Mechanical Engineering Graduate Ambassador (2013-2015)

President of VT Slackline Club (2011-2014)

President of Japanese Conversation Group (2012-2015)

President of Japanese Cultural Society in University of Wisconsin-EC (2005-2006)

Volunteer Graduate student mentor (2014-Present)

Society National Society of Leadership and Success, Biomedical Engineering Society

### **PUBLICATIONS**

**K. Takami**, T. Furukawa, M. Kumon, D. Kimoto, and G. Dissanayake. "Estimation of a nonvisible field-of-view mobile target incorporating optical and acoustic sensors," Autonomous Robots, 2015.

**K. Takami**, T. Furukawa, M. Kumon, and G. Dissanayake. "Non-Field-of-View Acoustic Target Estimation in Complex Indoor Environment," Springer Tracts in Advanced Robotics, 2015.

**K. Takami**, T. Furukawa, M. Kumon, and L. Mak, "Non-Field-of-View Indoor Sound Source Localization based on Reflection and Diffraction," Multi-sensor Integration and Fusion, IEEE, 2015.

**K. Takami**, T. Furukawa, M. Kumon, and G. Dissanayake. "Non-Field-of-View Acoustic Target Estimation in Complex Indoor Environment," Field and Service Robotics, 2015.

T. Furukawa, **K. Takami**, X. Tong, D. Watman, A. Hamed, R. Ranasinghe and G. Dissayanake, "Map-based Navigation of an Autonomous Car Using Grid-based Scan-to-Map Matching," ASME IDETC, 2015.

**K. Takami** and T. Furukawa, "High-Resolution Deformation Measurement System for Fast Rotating Tire," ASME IDETC/CIE, 2015.

**K. Takami** and T. Furukawa, "High-Resolution Deformation Measurement System for Fast Rotating Tires Towards Noise Prediction," Euronoise., 2015.

M. Kumon, D. Kimoto, **K. Takami** and T. Furukawa, "Acoustic recursive Bayesian estimation for non-field-of-view targets," In Image Analysis for Multimedia Interactive Services (WIAMIS), IEEE, 2013.

M. Kumon, D. Kimoto, **K. Takami** and T. Furukawa. "Bayesian non-field-of-view target estimation incorporating an acoustic sensor," In Intelligent Robots and Systems, IEEE/RSJ International Conference, 2013.

**K. Takami**, S. Taheri, M. Taheri and T. Furukawa, "Prediction of Railroad Track Foundation Defects Using Wavelets," Joint Rail Conference, ASME, 2013.

J. M. Whitney, **K. Takami**, S. T. Sanders, and Y. Okura. "Design of system for rugged, low-noise fiber-optic access to high-temperature, high-pressure environments," Sensors Journal, IEEE, 2011.

A. Xinliang, T. Kraetschmer, **K. Takami**, S. T. Sanders, L. Ma, et al. "Validation of temperature imaging by  $H_2O$  absorption spectroscopy using hyperspectral tomography in controlled experiments," Journal of Applied Optics, 2011.