EE230 – HW2 Report CMOS VCO

(@ 1.9 GHz & using 45nm CMOS Technology)

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1. Schematic Setup:

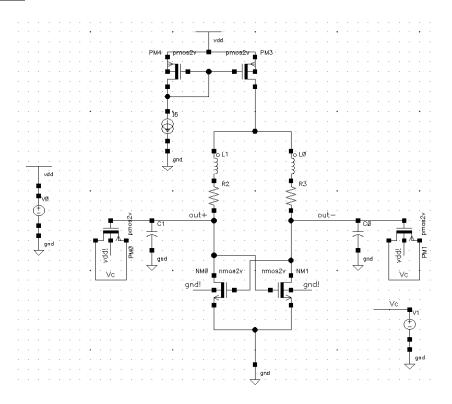


Fig. 1. LC VCO schematic

Table 1. Transistor parameters

Transistor	W [um]	L [um]	Multiplicity
NM0, NM1	1	0.3	13
PM0, PM1	2	1.2	12
PM4	5	1.2	1
PM3	5	1.2	24

Table 2. Component values

Component	Value	
L0, L1	10 nH	
R2, R3	20 Ohms	
C0, C1	500 fF	
IBias	100 uA	
Vc	1.3 V	
VDD	1.8 V	

2. Transient Simulation:

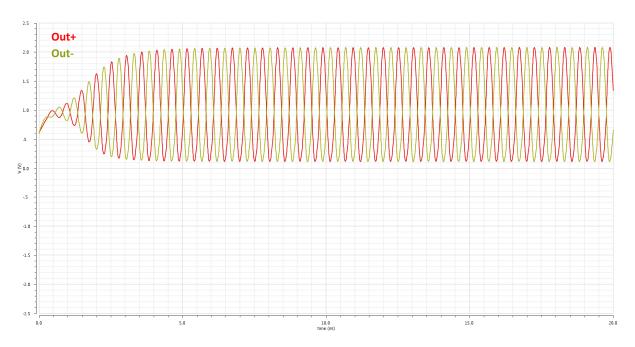


Fig. 2. Transient response of the VCO's single-ended outputs

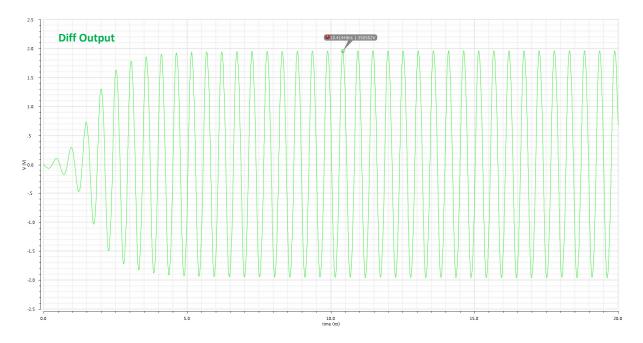


Fig. 3. Transient response of the VCO's differential output

3. PSS Simulation:

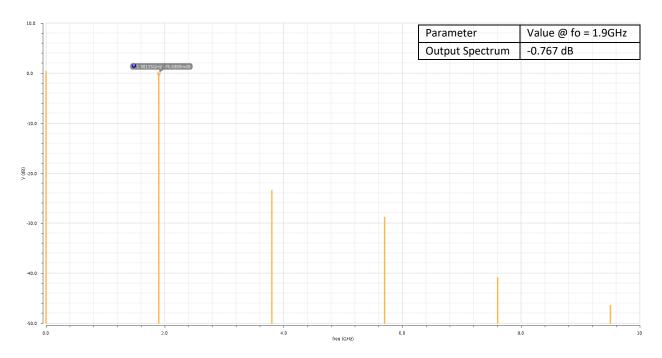


Fig. 4. VCO Output Spectrum

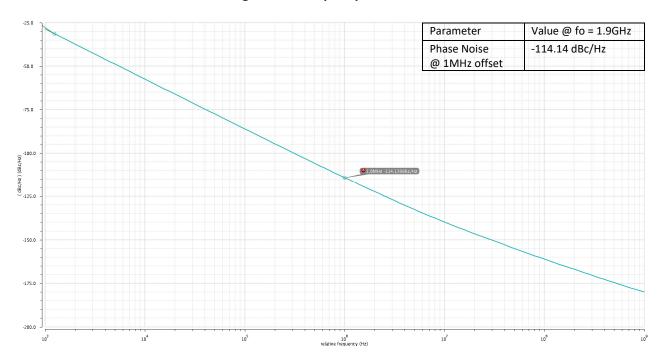


Fig. 5. VCO Phase Noise

4. Parametric Simulation:

> Freq Vs Vc sweep:

Equation used:

average(freq(clip((vtime('tran "/out+") - vtime('tran "/out-")) 15n 20n) "rising" ?xName "time" ?mode "auto" ?threshold 0))

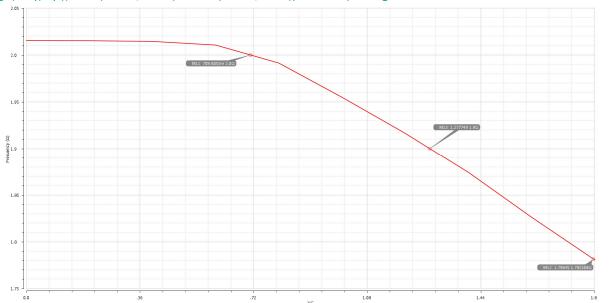


Fig. 6. Oscillation Frequency Vs Vc

> Amplitude Vs Vc sweep:

Equation used:

ymax(clip((vtime('tran "/out+") - vtime('tran "/out-")) 15n 20n))

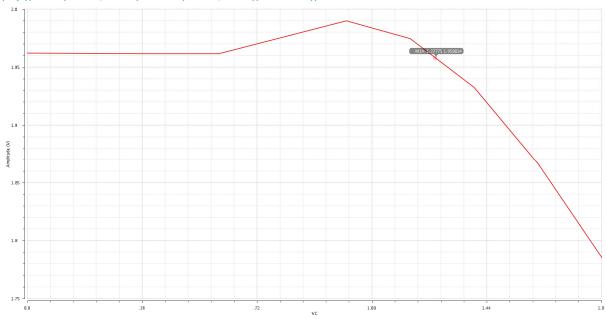


Fig. 7. Output Amplitude Vs Vc

Phase Noise Vs Vc sweep:

Equation used:

value(pn('pnoise) 1M)

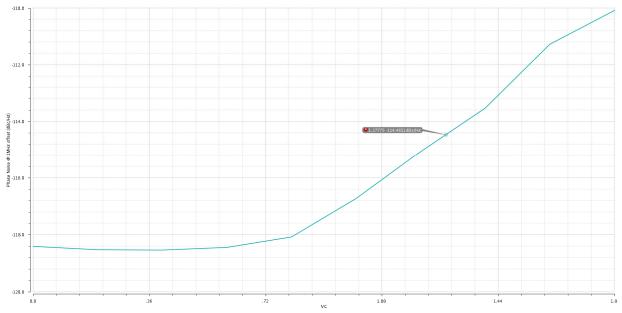


Fig. 8. Phase Noise at 1MHz offset Vs Vc

5. VCO Analysis:

5.1 Explain the role of varactors on VCO performance such as tuning range, quality factor, linearity of gain, etc.

➤ The varactor's main role in the circuit is to provide a variable capacitance to change the frequency of oscillation. Here, a normal inversion-type PMOS is used as a varactor, so increasing V_c from 0 to V_{DD} results in a bigger C_{var} that gives a smaller f_{osc}.

Assuming the varactor capacitance range is $C_{var2} - C_{var1}$, the tuning range can be approximated to:

$$\Delta\omega_{osc} \approx \frac{1}{\sqrt{L_1C_1}} \frac{C_{var2} - C_{var1}}{2C_1}$$

The tuning range trades with the Q of the varactor & the whole tank (hence with the phase noise). Longer channels result in larger range but lower Q. The dimensions of the PMOSs will vary the values of C_{var2} & C_{var1} , changing the K_{VCO} .

5.2 Explain how each of the main design variables (bias current, gm of the cross-coupled transistors and Q factor of the LC tank) affect the oscillation amplitude and the phase noise. For a given bias current, what are the trade-offs involved in the choice of the W/L for the nmos transistors?

- \triangleright The amplitude is increased by increasing I_{Bias} & Q, & is decreased by increasing g_m (by increasing W/L).
- \triangleright The phase noise follows an opposite behavior, so it decreases by increasing I_{Bias} & Q, & is increased by increasing g_m (by increasing W/L).
- For a given bias current, increasing W/L increases gm which in turn causes a faster startup & a higher operating frequency, but a lower amplitude & a higher phase noise.

- 5.3 Change the Q factor of the modeled inductor from 5 to 9 and obtain parametric plots like the ones shown in section 4. How much does the phase noise change? By how much do you need to change the bias current to obtain the same phase noise as with a Q of 5?
- > To change the Q to 9, R_S is changed to:

$$R_S = \frac{w_o \cdot L}{Q} = \frac{2\pi \ x \ 1.9G \ x \ 10n}{9} \approx 13 \ Ohms$$

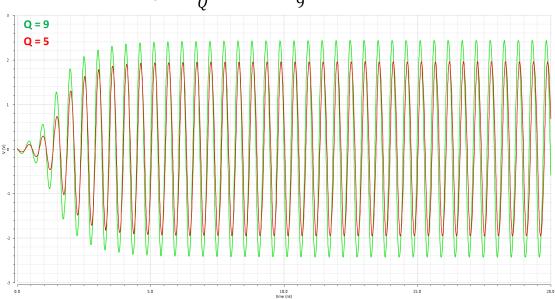


Fig. 9. Transient response of the VCO's differential output at Q = 9 & Q = 5

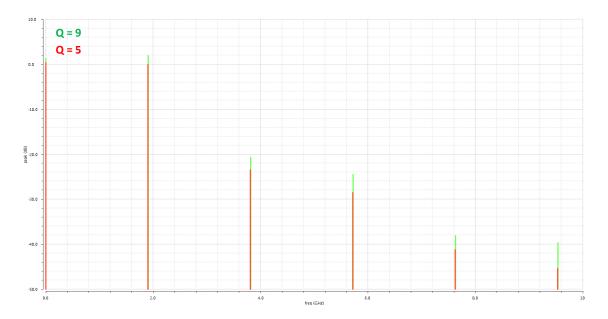


Fig. 10. VCO Output Spectrum at Q = 9 & Q = 5

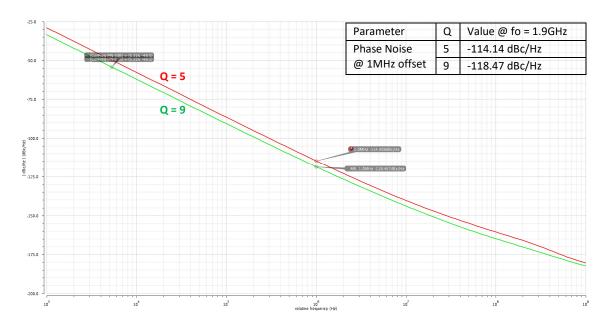


Fig. 11. Phase Noise at Q = 9 & Q = 5

- For the phase noise at Q=9 to reach that at Q=5, I_{Bias} will have to decrease by 0.764 mA. So, with Q=9 & a phase noise \approx -114 dBc/Hz, the power dissipation will decrease to 1.686 mA x 1.8 V = 3.03 mW.
- 5.4 Measure the Q of the tank. From the measured Q and the gm, and I_{Bias} obtained from a DC simulation,

The phase noise can be estimated by the following equation:

$$\begin{split} S(\Delta\omega) &= \frac{\pi^2}{2} \frac{kT}{I_{SS}^2} \left(\frac{3}{8} \gamma g_m + \frac{2}{R_p} \right) \frac{\omega_0^2}{4Q^2 \Delta \omega^2} \\ &= \frac{\pi^2}{2} \cdot \frac{(1.38 \, x \, 10^{-23}) \cdot (273 + 27)}{(2.35 \, x \, 10^{-3})} \cdot \left(\left(\frac{3}{8} \, x \, 1 \, x \, 3.98 \, x \, 10^{-3} \right) + \frac{2}{20 \, (5.97^2 + 1)} \right) \cdot \left(\frac{(2\pi \, x \, 1.9 \, x \, 10^9)^2}{4 \, (5.97^2) (2\pi \, x \, 1 \, x \, 10^6)^2} \right) \end{split}$$

$$S_{in dB} = 10 \log(S(\Delta\omega)) = 10 \log(3.957 \times 10^{-13}) \approx -124.026 \text{ dBc/Hz}$$

The estimated phase noise is lower than the obtained phase noise, which is expected, since we neglected the noise coming from other components, i.e. the varactors & the current tail transistors.

6. Summary of the results:

Parameter	Value @ fo = 1.9 GHz	
Amplitude	1.958 V	
Phase Noise	- 114 dBc/Hz	
Power Dissipation	2.45 mA * 1.8 V = 4.41 mW	
Tuning Range	1.781 GHz – 2.015 GHz	