Milestone 2

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1 Your Contribution to the Group

I worked on vision with Peter and Kuba. Set up the camera settings (contrast, brightness, hue, saturation, chroma) by using last year's code as a basis, and then trial and error. Worked out on detecting the 2 robots.

2 High Points of Your Contribution

• Rewrote a new method to implement the code such that it needs to process the image only once.

3 Areas to Improve

• The object detection is not final, still needs testing, and my method needs to be finalized.

4 Points Awarded to Each Member (out of 5)

- Peter Macgregor 4
- Patricia Dragan 3.5
- Egidijus Skinkys 4
- Andrew Leith 3.5
- Nursultan Askarbekuly 3.5

- Peak Limpiti 3
- Zhang Chen 4
- Aris Tsialos 4
- Kuba Kaszyk 4.5

5 Additional Information