# Adversarial Attacks and Defenses in Images, Graphs and Text: A Review

• 2020, 108 citations

I hope I can turn these notes into the Preliminaries thesis section

## Vulnerable networks

- CNN
- FC DNN
- RNN
- GCN (graph convolutional networks) used in fraud detection
  - only necessary to change couple of edges

## Counter-measures

- · Gradient masking
- · Robust optimization
- · Adversary detection

Deep neural-nets reason differntly -> understanding adversarial attacks should help understand this difference

# **Definitions and notations**

# Threat model

## Adversary's goal

- Poisoning attack change the behavior of DNN by modifying/inserting few train examples
  - o public honeypot collection of training data for malware detectors
- evasion attack craft fake examples classifier cannot recognize
  - targeted
  - untargeted

# Adversary's knowledge

- White-box attack widely studied, easily analyzed mathematically
- Black-box attack practical
- Semi-white (gray) box attack train generative model in white-box setting, then use in blackbox scenario (TREMBA)

## Victim models

- conventional machine learning models SVM, Naive-Bayes
- DNN not well understood how they work, studying security necessary
  - FC
  - CNN sparse version of FC
  - GCN
  - RNN

# **Security evaluation**

# Robustness

- Minimal pertubation The smallest pertubation to fool the network
  - $\circ \hspace{0.1cm} \delta_{min} = rg \min \lVert \delta 
    Vert \hspace{0.1cm} ext{s.t.} \hspace{0.1cm} F(x+\delta) 
    eq y$
- Robustness The norm of minimal pertubation on particular example
  - $\circ \ \ r(x,F) = \|\delta_{min}\|$

• Global robustness - Expectation of robustness over the whole dataset

$$m{\circ} \;\; 
ho(F) = \mathop{\mathbb{E}}_{x \sim \mathcal{D}} r(x,F)$$

# Adversarial risk (loss)

- Most-adversarial example Given classifier F, datapoint x and  $\epsilon$  ball,  $x_{adv}$  is the adversarial example with the largest loss
  - $\circ \;\; x_{adv}$  is the point, where the classifier is the most likely to be fooled

$$\circ \ \ x_{adv} = rg\max_{x'} \mathcal{L}(x\,F) ext{ s.t. } \|x'-x\| \leq \epsilon$$

• Adversarial loss - Loss value of the most-adversarial example

ullet Global adversarial loss (adversarial risk) - The expectation of adversarial loss over the data distribution  ${\cal D}$ 

$$ullet \ \mathcal{R}_{adv}(F) = \mathop{\mathbb{E}}_{x \sim \mathcal{D}} \mathcal{L}_{adv}(x) = \mathop{\mathbb{E}}_{x \sim \mathcal{D} | |x' - x|| < \epsilon} \mathcal{L}( heta, x', y)$$

## Adversarial risk vs. risk

- The concept of Adversarial risk is similar to the definition of classifier risk (empirical risk)
  - $ullet \mathcal{R}(F) = \underset{x \sim \mathcal{D}}{\mathbb{E}} \mathcal{L}( heta, x, y)$
  - Global adversarial risk (loss) is in a sense empirical risk but on the most adversarial examples, low empirical risk doesn't have to mean low adversarial risk

# Generating adversarial examples

Studying adversarial examples in the image domain essential, because: - perceptual similarity between fake and original is intuitive (unlike in other domains - graphs, audio) - imaga data have simple structure

#### Studied datasets

- MNIST
- CIFAR10
- ImageNet

All attacks summarization table

## White-box attacks

Given classifier C (model F), victim sample (x,y), synthesize fake image x', that is perceputally similar to original x, but fools the classifier C - find x' satisfying  $\|x'-x\| \leq \epsilon$ , such that  $C(x') = t \neq y$  -  $\|\cdot\|$  usually  $l_p$  norm

## Biggio's attack

- ECML 2013
- adversarial examples on MNIST targeting SVMs and 3-layer FC DNNs
- inspired studies on safety of deep learning

## Szegedy's limited-memory BFGS (L-BFGS)

- Dec 2013
- · first to attack image classifiers
- find minimally distorted adversarial example  $x^\prime$  by solving:

$$ullet \min \lVert x - x' 
Vert_2^2,$$
 s.t.  $C(x') = t$  and  $x' \in [0,1]^m$ 

• loss function:

$$| \cdot | \min c \|x - x'\|_2^2 + \mathcal{L}(\theta, x', t), \text{ s.t. } x' \in [0, 1]^m$$

ullet by increasing constant c throughout the optimization, while keeping the adversarial example outside of the correct decision boundary, we can approximately find adversarial example with minimal pertubation

# Fast gradient sign method (FGSM)

• Dec 2014, Goodfellow et al.

## non-target

$$x' = x + \epsilon \operatorname{sgn}(\nabla_x \mathcal{L}(\theta, x, y))$$

• maximise loss of correct classification

#### target

$$x' = x - \epsilon \operatorname{sgn}(\nabla_x \mathcal{L}(\theta, x, t))$$

- minimize loss of target class
- For targeted attack setting, this can be framed as one-step 1-bit-precision gradient descent to solve:

$$ullet \min \mathcal{L}( heta, x', t)$$
 s.t.  $\|x' - x\|_{\infty} \leq \epsilon$  and  $x' \in [0, 1]^m$ 

- $\circ~$  resulting x' is vertex (extreme point) of  $\epsilon$  hypercube around x
- · only one backprop, very fast
- used for producing samples for adversarial training

# **Deep Fool**

- Nov 2015
- hyperplane of decision boundary

• 
$$f(x) = F(x)_y - F(x)_t = 0$$

• they linearize this hyperplane using Taylor expansion

$$ullet f'(x)pprox f(x_0)+\langle 
abla_x f(x_0),(x-x_0)
angle=0$$

- they find orthogonal vector  $\omega$  from  $x_0$  to the hyperplane and move along its direction
- for instance LeNet can be fooled on over 90% test samples with  $l_{\infty} \leq 0.1$

# Jacobian-based saliency map attack (JSMA)

• Nov 2015, Papernot et al.