

Derive the steps that lead to the physically realistic equation of updating the u .
 (i.e. $u_{\text{new}} = u_{\text{old}} + (\Delta t)(\sqrt{2gh}) / \text{mag}(dp/du)$)

assume: h_{max} is the maximum height of the track, h is the current height of the roller coaster.

g is the gravity constant

Δt is the time step

p is a function of u that computes the position of the roller coaster at $u = u_{\text{current}}$

$\frac{dp}{du}$ is the derivative of $p(u)$

$\text{mag} = \sqrt{x^2 + y^2 + z^2}$ (the size of vector (x, y, z))

$\left\| \frac{dp}{du} \right\|$ is the magnitude of the vector $\frac{dp}{du}$

$$S = \frac{1}{2}at^2, \quad a = \frac{v}{t} = \frac{\Delta h}{\Delta t} \neq$$

First, $H = \frac{1}{2}gt^2$ and $H = h_{\text{max}} - h$, t is the duration of falling to end

Second, derive both sides by t , $\frac{dH}{dt} = \frac{1}{2}g \times 2t \Rightarrow \frac{dH}{dt} = gt \Rightarrow dH = dt \times gt$

Third, add the velocity, $v = gt$ — ①

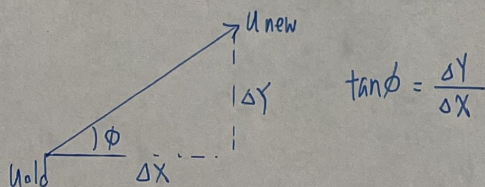
Fourth, $H = \frac{1}{2}gt^2 \Rightarrow t = \sqrt{\frac{2H}{g}}$ — ②

Fifth, put t ② into ①, $v = g\sqrt{\frac{2H}{g}} = \sqrt{2gH}$ — ③

Sixth, $dH = dt \times gt$, and ① = ③ = v , $dH = dt \times \sqrt{2gH}$

Seventh, $p(u)$ is the position of roller coaster, $\Delta u = u_{\text{new}} - u_{\text{old}}$, $p(\Delta u)$ is the distance between u

Eighth, use tangent vector to build the relation.



Ninth, $p(\Delta u) = p(u_{\text{new}}) - p(u_{\text{old}})$, $\left\| \text{vector } \frac{dp}{du} \right\| = \text{hypotenuse} = |\vec{u}|$

$v = \frac{dx}{dt}$ is the derivative of $x \Rightarrow \frac{dH}{dt} = v = gt = \sqrt{2gH}$

$a = g = \frac{dv}{dt}$ is the derivative of v

Tenth, $\frac{d(\Delta u)}{dt} = v = \sqrt{2gH} \Rightarrow d(\Delta u) = dt \cdot \sqrt{2gH} = v \cdot dt$

Eleventh, integral of $d(\Delta u)$ to get rid of d

$d(\Delta u) = v dt$, integrating, $\int d(\Delta u) = \int v dt \Rightarrow \Delta u = \int v dt = tv + C = \Delta tv + C$ (C is constant)

Twelfth, $p(u)$ computes the position of roller coaster u

$p'(u) = \frac{dp}{du} = \text{velocity} \Rightarrow \frac{v}{|\vec{v}|} = \text{unit vector (so it will increase linearly)}$

Thus, according to 11th,

$\Delta u = \Delta t V \Rightarrow \Delta u = \Delta t \frac{v}{|\vec{v}|}$ and then put into $v = \sqrt{2gH}$, $|\vec{v}| = \text{mag}(\frac{dp}{du})$, $H = h_{\text{max}} - h$
 $\Delta u = u_{\text{new}} - u_{\text{old}}$

We can finally derive the formula

$$\Delta u = \Delta t \frac{\sqrt{2gH}}{\left\| \frac{dp}{du} \right\|} \Rightarrow u_{\text{new}} - u_{\text{old}} = \Delta t \frac{\sqrt{2g(h_{\text{max}} - h)}}{\left\| \frac{dp}{du} \right\|}$$

$$\Rightarrow u_{\text{new}} = u_{\text{old}} + \Delta t \frac{\sqrt{2g(h_{\text{max}} - h)}}{\left\| \frac{dp}{du} \right\|}$$

Also as $\Rightarrow u_{\text{new}} = u_{\text{current}} + \Delta t \frac{\sqrt{2g(h_{\text{max}} - h)}}{\left\| \frac{dp}{du} \right\|}$ #