

```
shared_ptr< FuzzyControl  
System >
```

```
static constexpr auto
```

- \_\_fuzzy\_system\_stage  
\_1  
- \_\_fuzzy\_system  
\_stage\_2

- \_\_FUZZY\_S1\_JSON  
- \_\_FUZZY\_S2\_JSON

SmartEvasion

```
+ SmartEvasion()  
+ ~SmartEvasion()  
+ evade()  
- __getClosestObstaclePoint()  
- __getFurthestObstaclePoint()  
- __getDifference()
```